



# CIE4801 Transportation and spatial modelling

## Congested assignment

Rob van Nes, Transport & Planning  
31-08-18



# Content

- Comments/questions uncongested assignment
  - Plus remaining part
- Modelling component 5: Assignment: congested conditions
  - Congested case
  - Your comments/questions on Chapter 10 and 11
  - [Use of the assignment map](#)
  - Practical issues

# 1.

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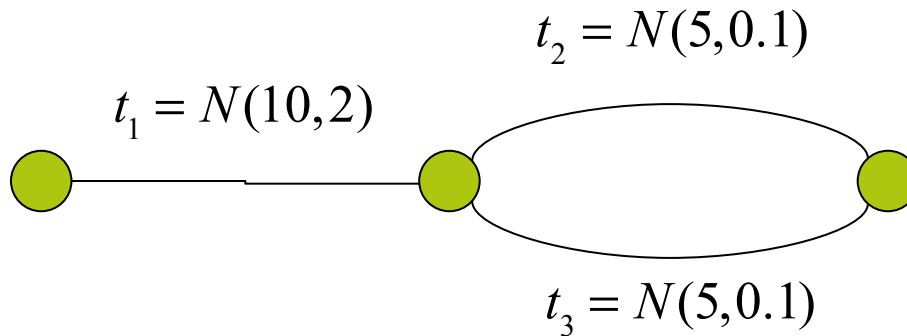
*Comments/questions last lecture*

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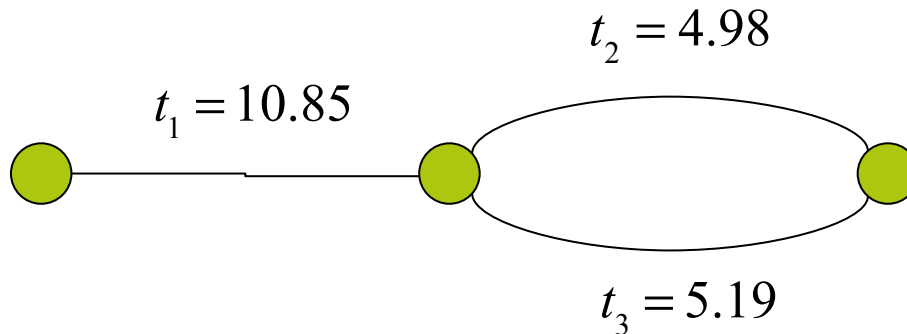
# Comments/questions

- Uncongested assignment
  - Shortest path algorithm
  - All-or-nothing
  - Assignment map
  - Probit and logit
- Remaining part
  - Link level versus route level

# Example link level

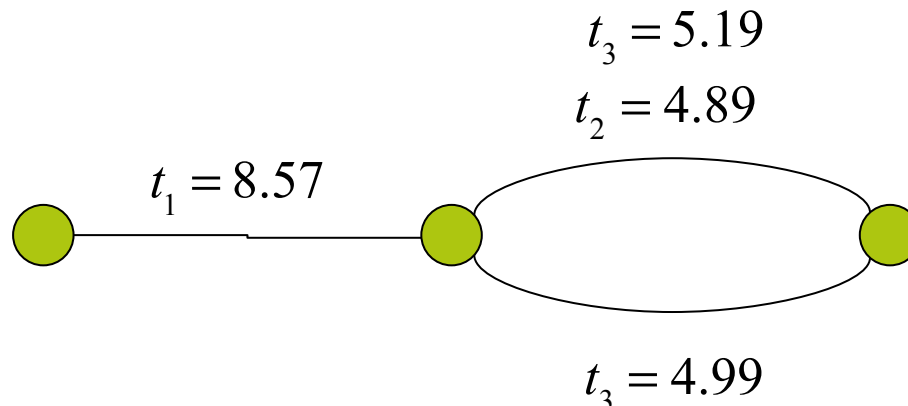


State 1



Route 1=15.83  
Route 2=16.04

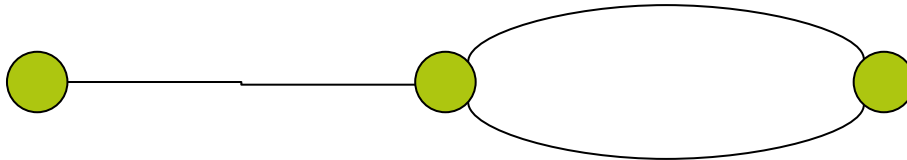
State 2



Route 1=13.46  
Route 2=13.56

# Switch from link level to route level

$$t_{r_1} = N(15,2)$$

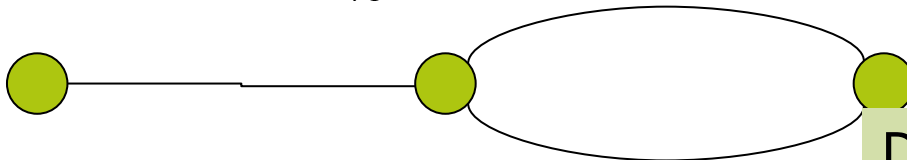


Thus sampling route travel times instead of link travel times

$$t_{r_2} = N(15,2)$$

$$t_{r_1} = 15.85$$

State 1



Route 1 = 15.83

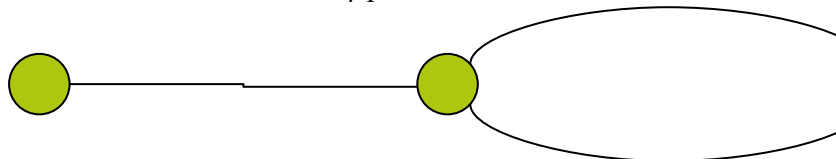
Route 2 = 16.04

$$t_{r_2} = 14.24$$

$$t_{r_1} = 16.78$$

Differences between routes is much larger due to (implicit) different assumption for time of link 1 within a given state

State 2

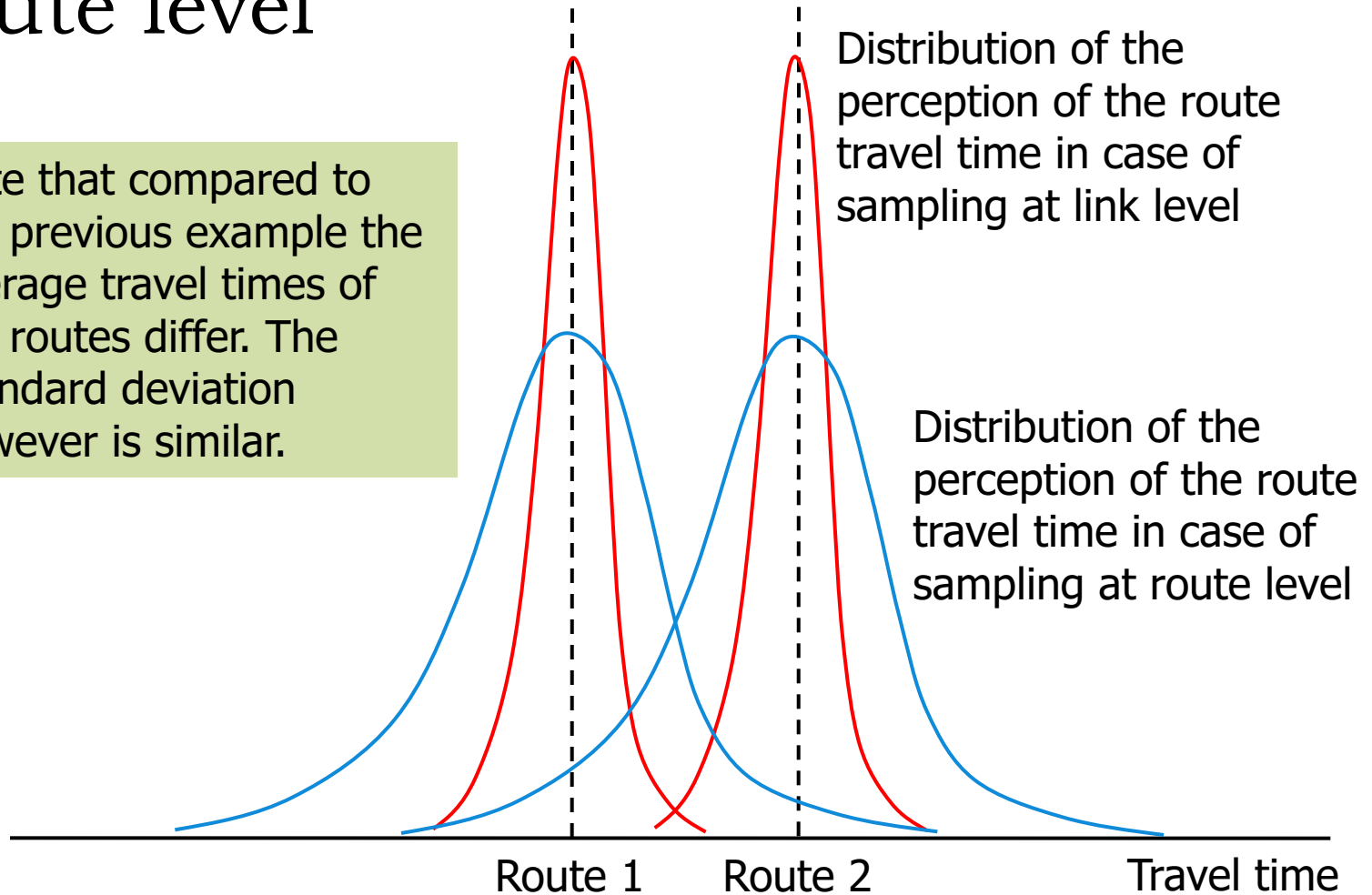


$$t_{r_2} = 13.57$$

This approach is therefore not correct

# Effect of sampling at link level versus route level

Note that compared to the previous example the average travel times of the routes differ. The Standard deviation however is similar.

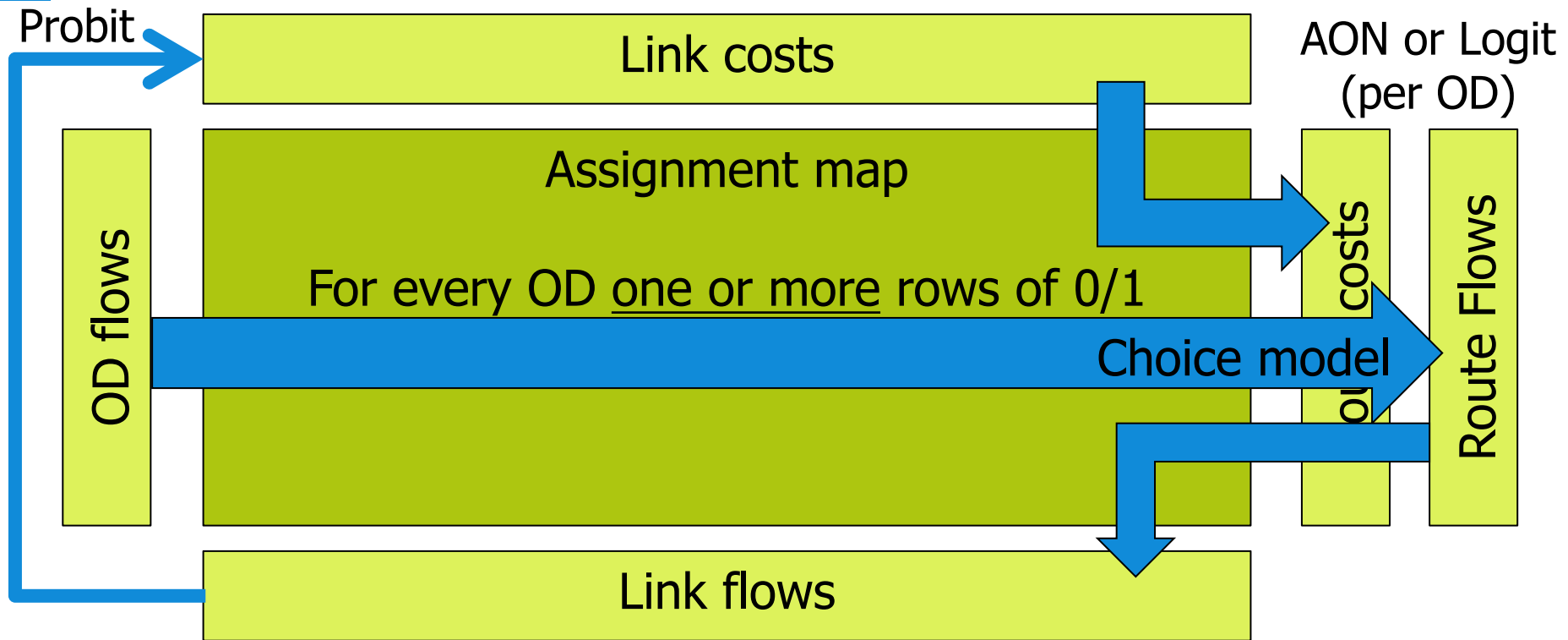


# Stochastic assignment and path representation

- Iterative scheme as in Probit is tailor-made for tree search algorithms (or vice versa)
- Assignment map approach can be used as well, especially for Logit
  - Generate routes first, e.g. manually or using repetitive shortest path searches while systematically eliminating or penalizing links (k-shortest path algorithm)
  - Check whether routes are realistic (e.g. large or very short detours)
- Advantage of assignment map is that you can check for overlap!



# Assignment map and stochastic assignment



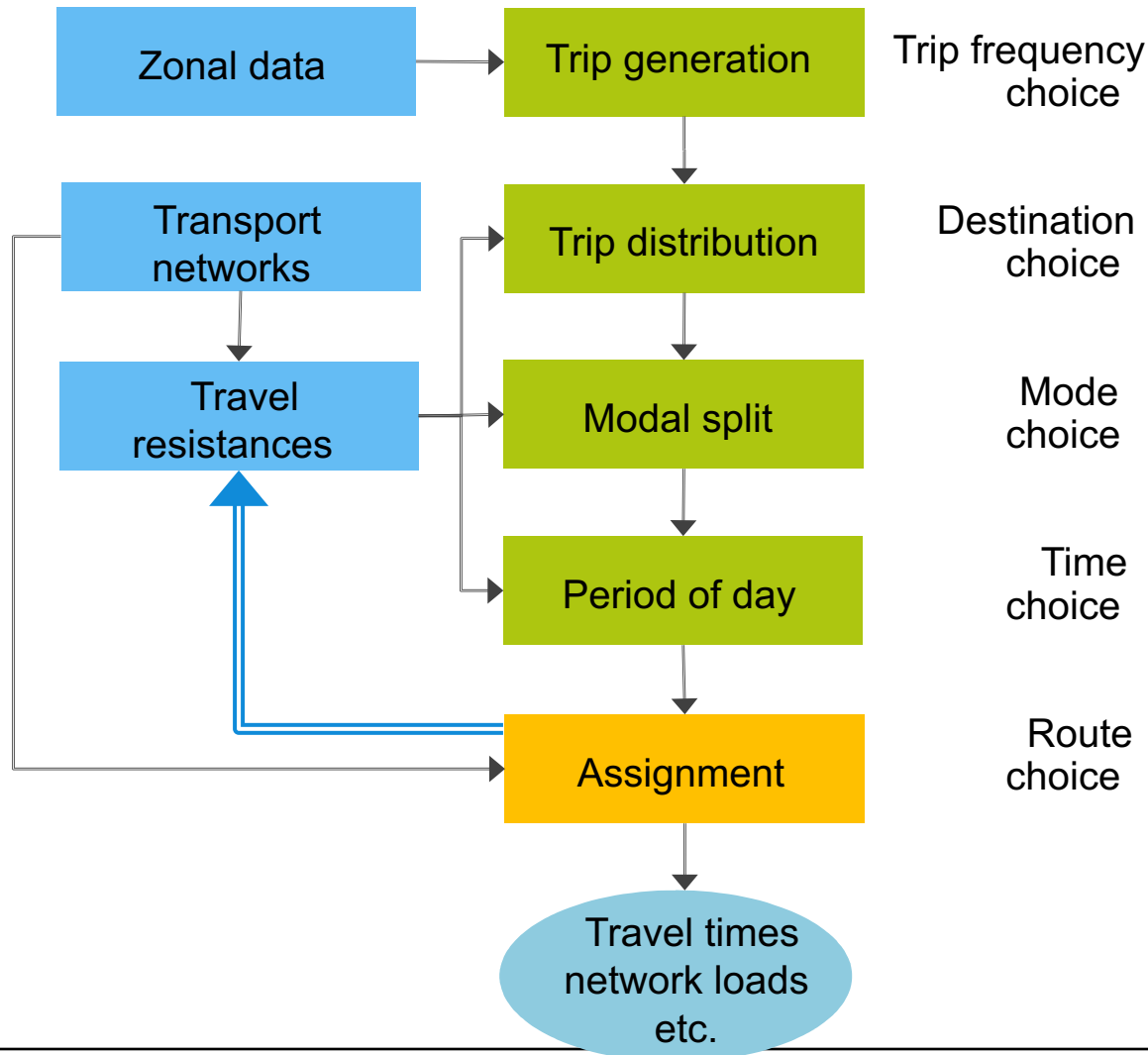
# 2.

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## *Congested assignment*

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# Introduction congested assignment



# Topics for discussion

- What does this modelling component do? What's its output and what's its input? How does it fit in the framework?
- The main concepts
  - Wardrop's equilibrium, speed-flow curves
- The modelling methods
  - Iterative scheme: Method successive averages (MSA)
  - Convergence criteria: Relative or Duality Gap
  - Mathematical programming approach
  - Frank-Wolfe algorithm versus MSA
  - [Route based assignment](#)
  - Stochastic equilibrium assignment (SUE)
    - [NB Probit or Logit makes quite a difference!](#)
  - [Braess's paradox](#)
- Practical issues
- Are these models appropriate?

# 3.0

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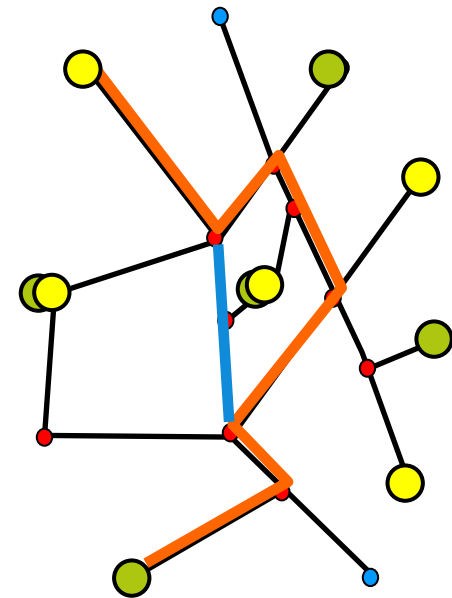
*Generic formulation of the network assignment problem*

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# General network assignment problem: Main elements

Indices:

origin  $i$   
destination  $j$   
route  $f$   
link  $a$



# Network assignment variables (comment on changes)?

$T_{ij}$  OD travel demand

$\alpha_{ijr}^a$  link-route incidence matrix  
(assignment map)

$t_a(q_a)$  link travel time function

$\Theta$  flow dispersion parameter  
of the stochastic component

INPUT

$T_{ijr}$  route flow

$\phi_{ijr}$  route choice proportion

$t_{ijr}$  route travel time

$q_a$  link flow

$t_a$  link travel time

OUTPUT

# Relationships between variables

## 1. Link travel times $t_a$

$$t_a = t_a(q_a)$$

## 2. Route choice proportions $\phi_{ijr}$

$$\phi_{ijr} = \phi_{ijr}(\Theta, t_{ijr})$$

## 3. Route travel times $t_{ijr}$

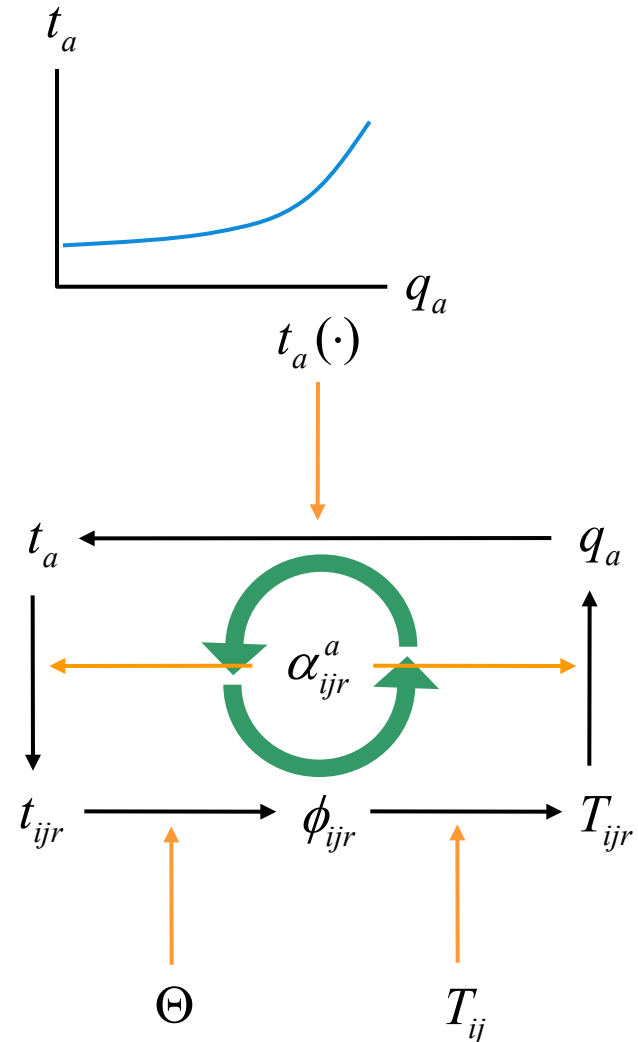
$$t_{ijr} = \sum_a \alpha_{ijr}^a t_a$$

## 4. Route flows $T_{ijr}$

$$T_{ijr} = \phi_{ijr} T_{ij}$$

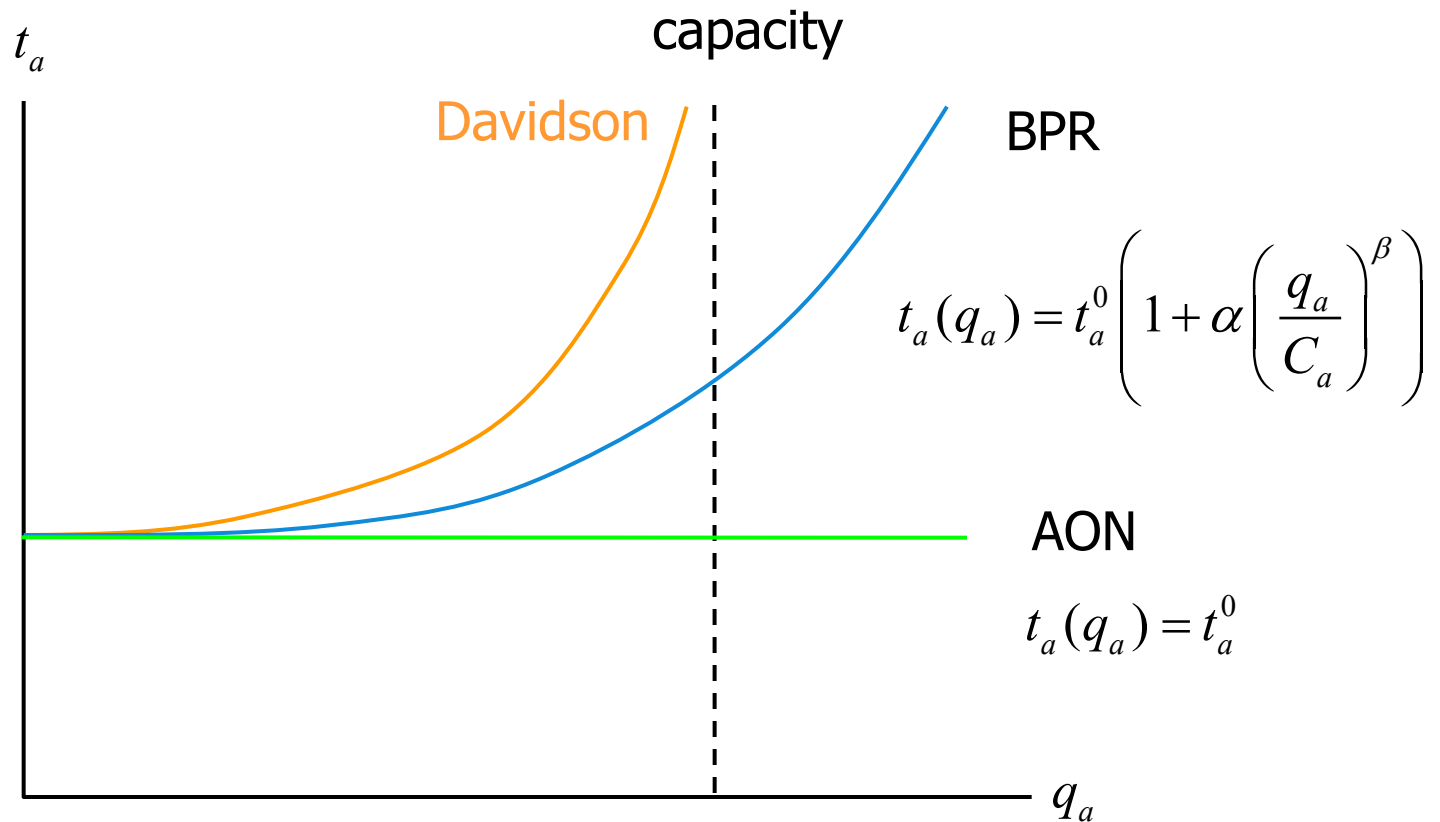
## 5. Link flows $q_a$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr}$$

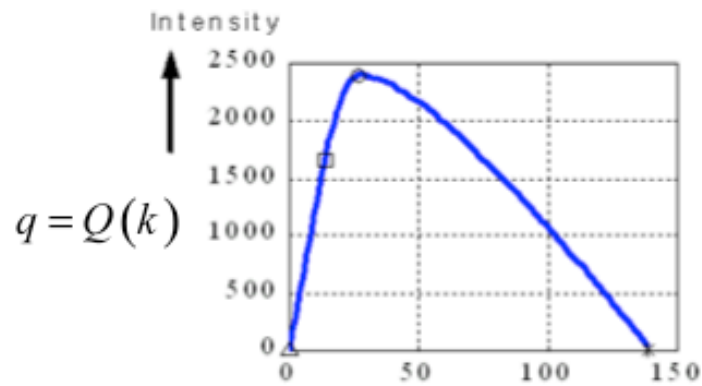




# Link performance functions

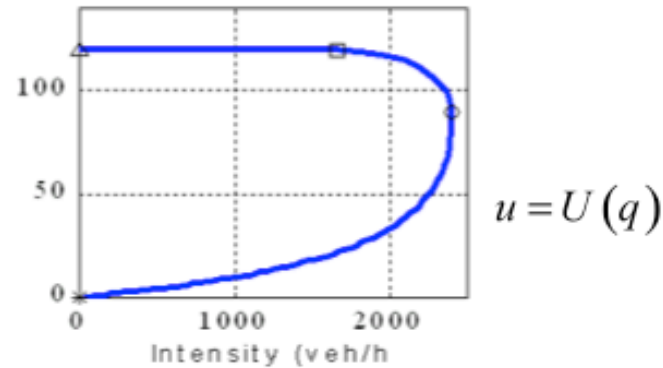
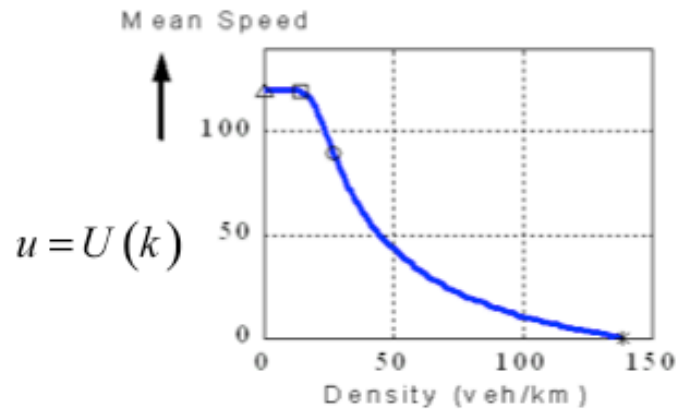


# Traffic flow theory: Fundamental diagram



- △ Empty Road
- Max q with  $u = u_0$
- Capacity Point
- \* Jam Point

$q$  = flow (veh/hr)  
 $k$  = density (veh/km)  
 $u$  = speed (km/hr)





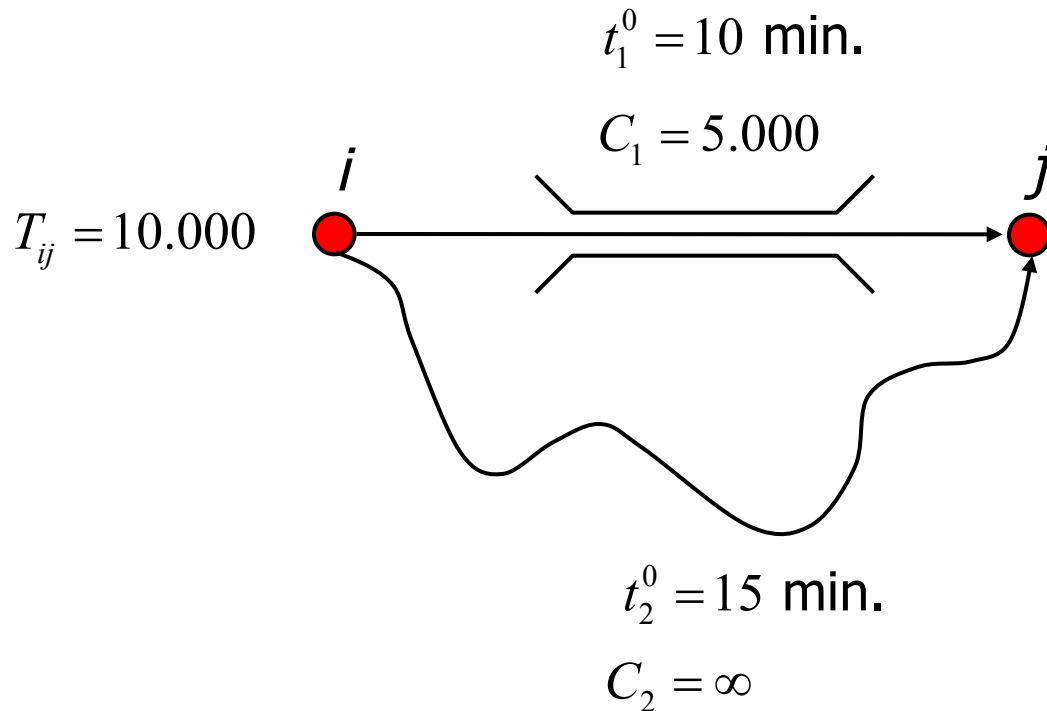
# 3.1

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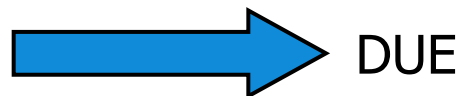
*DUE: Deterministic user equilibrium assignment: main concept*

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# Route choice with congestion effects



When congestion is taken into account,  
how long will the trip from  $i$  to  $j$  take along route 1? 15 min.!



# DUE assignment

1. Link travel times  $t_a$

$$t_a = t_a(q_a)$$

2. Route choice proportions  $\phi_{ijr}$

$$\phi_{ijr} = \phi_{ijr}(t_{ijr})$$

3. Route travel times  $t_{ijr}$

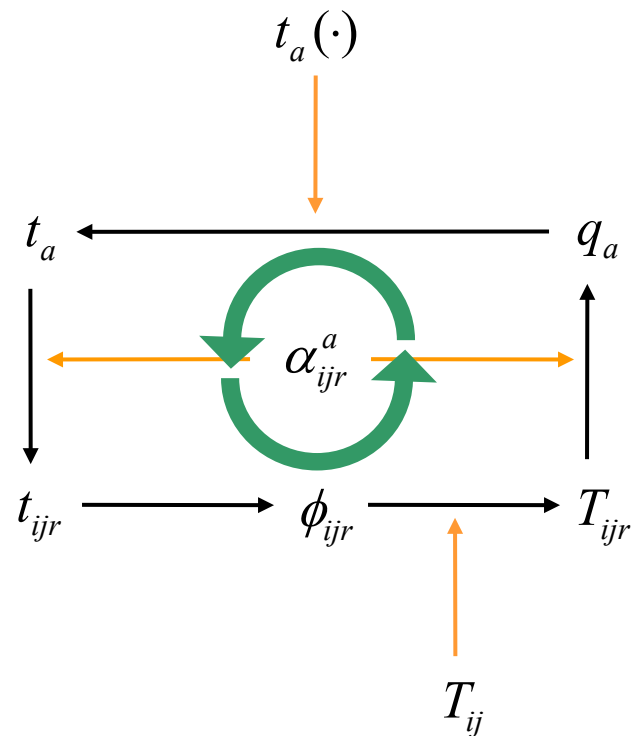
$$t_{ijr} = \sum_a \alpha_{ijr}^a t_a$$

4. Route flows  $T_{ijr}$

$$T_{ijr} = \phi_{ijr} T_{ij}$$

5. Link flows  $q_a$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr}$$



# Main principle

Deterministic user-equilibrium (DUE) takes **congestion effects** into account and is defined as:

## Wardrop's equilibrium law

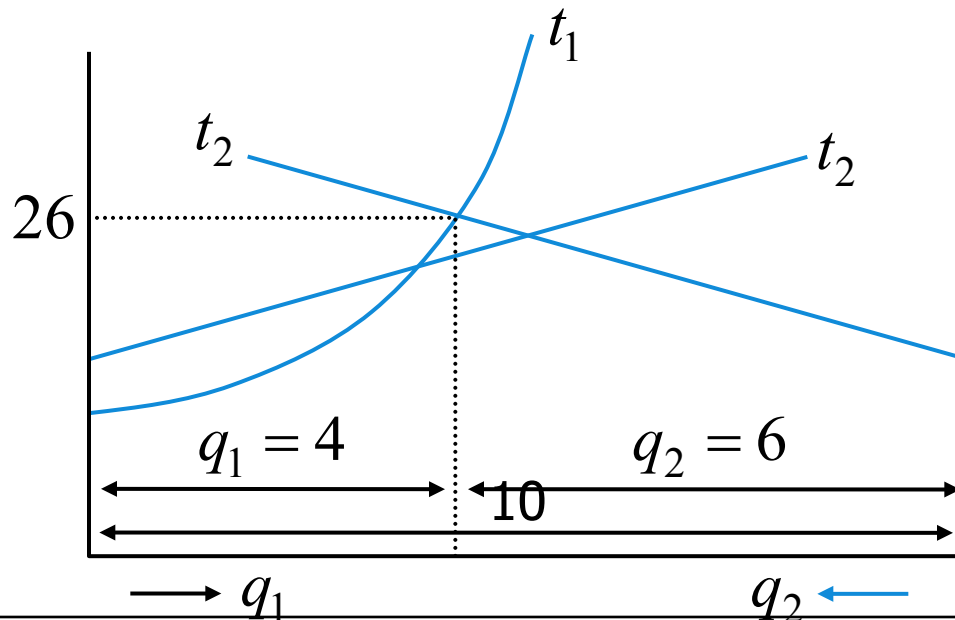
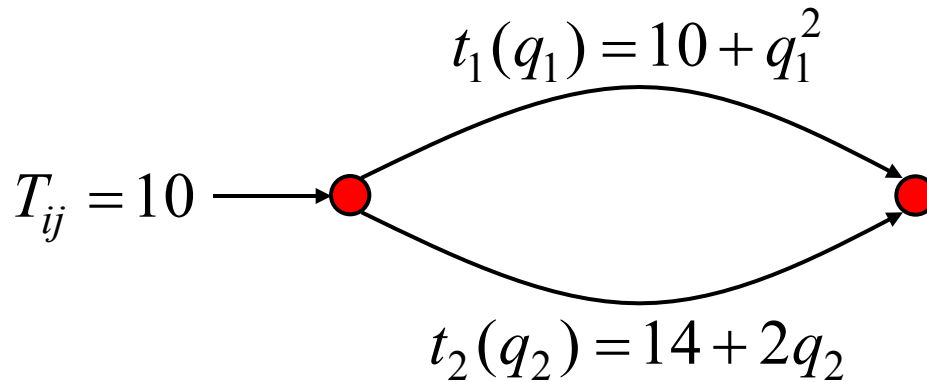
All travellers choose their optimal route, such that no traveller can improve his/her travel time by unilaterally changing routes.

This equilibrium is reached if the following condition holds:

## Wardrop's first principle

All used routes have the same travel time which is not greater than the travel time on any unused route.

# Example DUE assignment





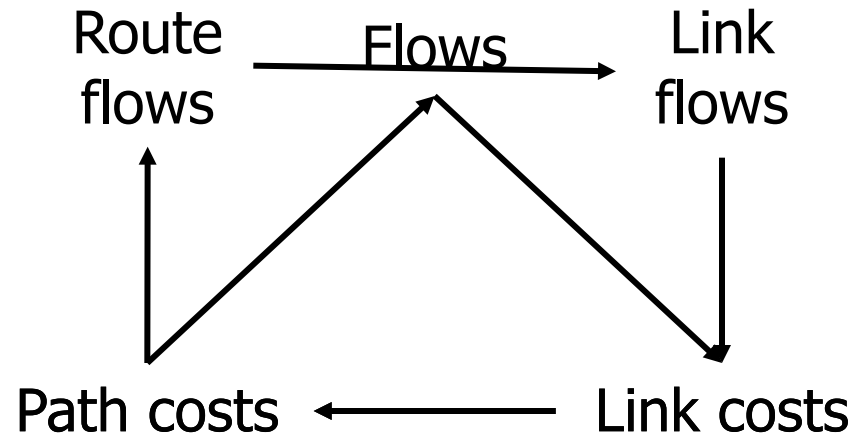
# 3.2

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*DUE: Algorithms: MSA*

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# Key point assignment problem



## General solution scheme:

- Start with an assumption on e.g. link costs
- Follow the arrows until convergence is achieved

# Solution principle

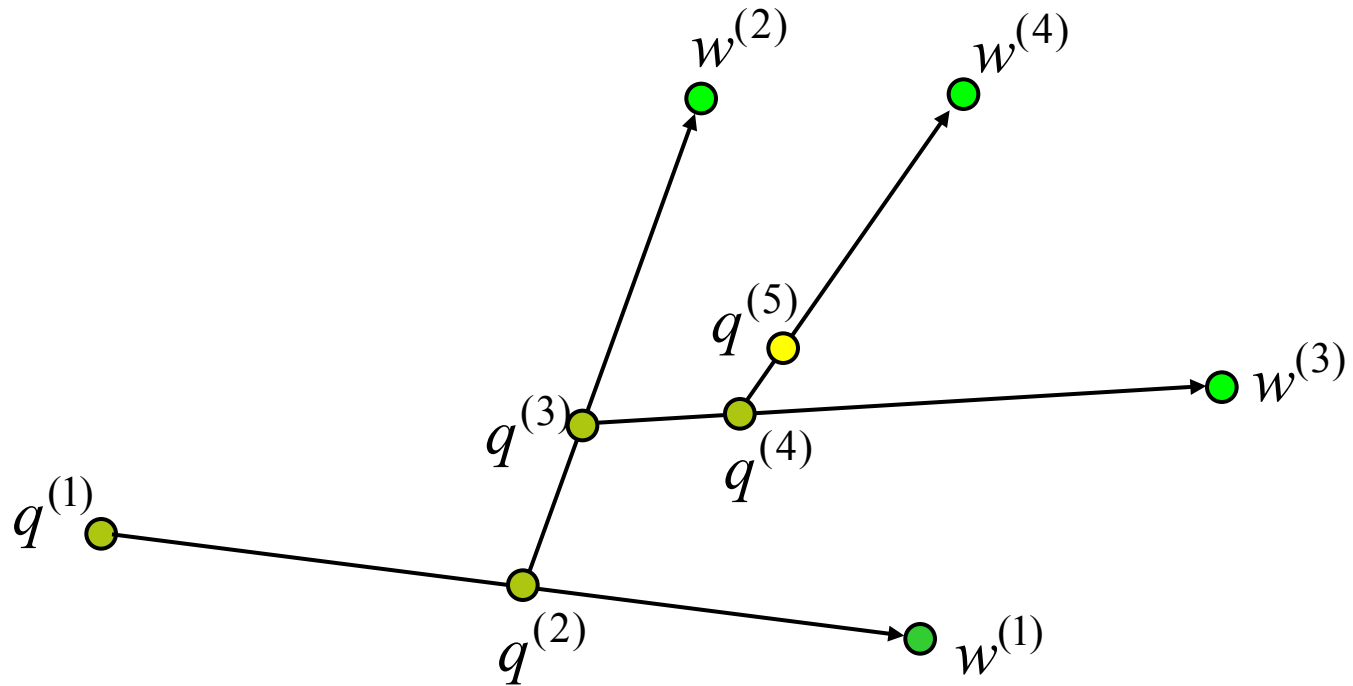
1. Set flows of all links equal to 0
2. Determine link costs based on the link flows
  - In first iteration use free flow travel times
3. Perform an assignment (AON)
4. Determine link flows
5. Return to step 2

Different approaches for step 4

- Naive: Repeat again and again
- Simple: Average flows with previous results ( $1/n$ )
- Smart: Average with optimal step sizes

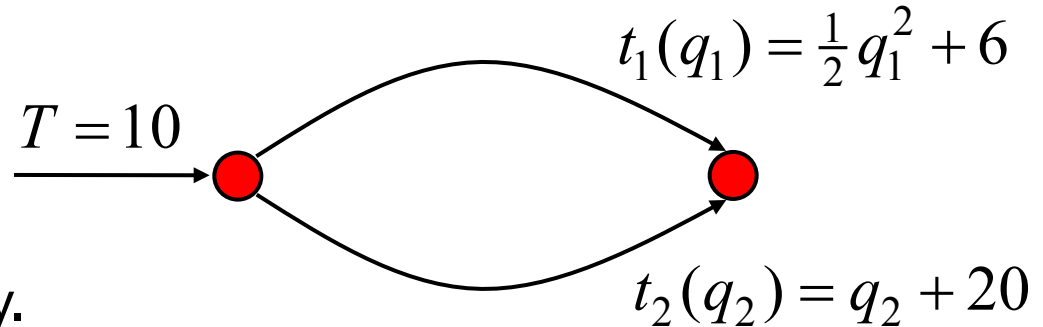
=> Don't  
=> MSA  
=> Frank-Wolfe

# Illustration MSA algorithm



# MSA: Example

Network



Find DUE iteratively.

$q_1$	$q_2$	$t_1$	$t_2$	$w_1$	$w_2$	$\alpha$	$q_a^{(i+1)} = q_a^{(i)} + \frac{1}{i}(w_a^{(i)} - q_a^{(i)})$
0	0	6	20	10	0	1	$\begin{pmatrix} q_1 \\ q_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \frac{1}{1} \cdot \left[ \begin{pmatrix} 10 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right] = \begin{pmatrix} 10 \\ 0 \end{pmatrix}$
10	0	56	20	0	10	1/2	$\begin{pmatrix} q_1 \\ q_2 \end{pmatrix} = \begin{pmatrix} 10 \\ 0 \end{pmatrix} + \frac{1}{2} \cdot \left[ \begin{pmatrix} 0 \\ 10 \end{pmatrix} - \begin{pmatrix} 10 \\ 0 \end{pmatrix} \right] = \begin{pmatrix} 5 \\ 5 \end{pmatrix}$
5	5	18.5	25	10	0	1/3	$\begin{pmatrix} q_1 \\ q_2 \end{pmatrix} = \begin{pmatrix} 5 \\ 5 \end{pmatrix} + \frac{1}{3} \cdot \left[ \begin{pmatrix} 10 \\ 0 \end{pmatrix} - \begin{pmatrix} 5 \\ 5 \end{pmatrix} \right] = \begin{pmatrix} 6\frac{2}{3} \\ 3\frac{1}{3} \end{pmatrix}$
6.7	3.3	28.2	23.3	0	10	1/4	$\vdots$
5	5	18.5	25	10	0	1/5	$\vdots$
6	4	24	24	-	-	-	

# 3.3

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*DUE: MSA and convergence*

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# Convergence criteria

- Number of iterations
- Equality of path costs
- Successive link flows (FA):  $(q^i - q^{i-1}) / q^{i-1} < d$

- Duality gap 
$$\sum_a t_a^i \cdot q_a^i - \sum_o \sum_d T_{od} \cdot \tau_{od}^i$$

i.e. total travel time based on links minus total travel time based on (latest) shortest paths

# 3.4

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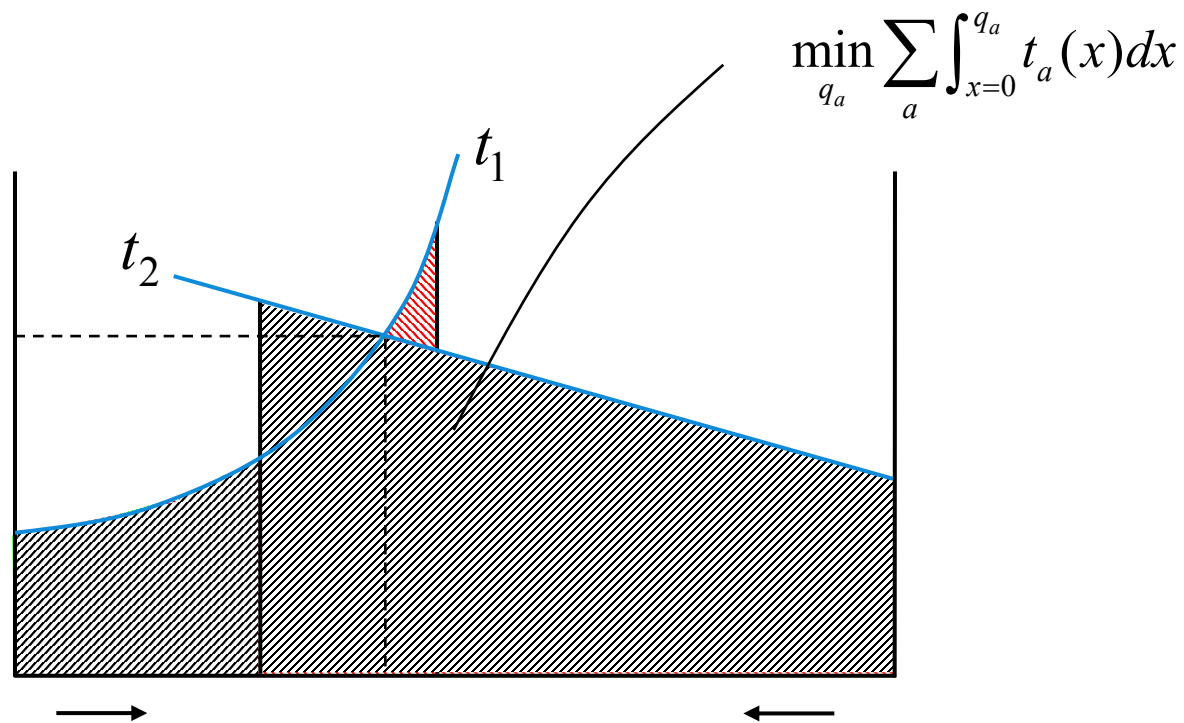
*DUE: Mathematical formulation*

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# DUE assignment: Mathematical formulation

What is the objective function?



# Mathematical programming formulation

$$\min_{q_a} \sum_a \int_{x=0}^{q_a} t_a(x) dx$$

subject to:  $\sum_r T_{ijr} = T_{ij} \quad \forall i, j$  (flow conservation)

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr} \quad \forall a$$
 (definition)

$$T_{ijr} \geq 0 \quad \forall i, j, r$$
 (non negativity)



non-linear programming problem

# Everything in time?

People do not only decide on **travel times**, but may also take other factors into account:

- fuel costs
- toll costs
- ... etc

How to take these factors into account?

Replace  $t_a(q_a)$  with generalized costs  $c_a(q_a)$

For example, 
$$c_a(q_a) = \eta \cdot t_a(q_a) + \kappa_a$$

value-of-time (VoT)      travel time      toll

 
$$\min_{q_a} \sum_a \int_{x=0}^{q_a} c_a(x) dx$$

# 3.5

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*DUE: Algorithm: Frank-Wolfe*

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# Frank-Wolfe algorithm

A nonlinear programming problem can be solved using a *steepest descent algorithm*.

The *convex combinations algorithm*, also known as the *Frank-Wolfe algorithm* (1956), is a common (formal!) algorithm to solve the DUE assignment problem.

## Main principle:

- Find an initial feasible solution
- Linearise the objective function
- Find a new intermediate solution
- Determine a new solution in the direction of the intermediate solution
- Iterate until the new solution does not change anymore

# Frank-Wolfe algorithm 1 / 4

$$\min_{q_a} Z = \sum_a \int_{x=0}^{q_a} t_a(x) dx \quad (1)$$

subject to: 
$$\sum_r T_{ijr} = T_{ij} \quad \forall i, j \quad (2)$$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr} \quad \forall a \quad (3)$$

$$T_{ijr} \geq 0 \quad \forall i, j, r \quad (4)$$

Step 1: Find an initial feasible solution (iteration 1)

We have to find a solution that satisfies constraints (2), (3), and (4).

An AON assignment yields a feasible solution  $q^{(1)}$

# Frank-Wolfe algorithm 2/4

$$\min_{q_a} Z = \sum_a \int_{x=0}^{q_a} t_a(x) dx \quad (1)$$

subject to: 
$$\sum_r T_{ijr} = T_{ij} \quad \forall i, j \quad (2)$$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr} \quad \forall a \quad (3)$$

$$T_{ijr} \geq 0 \quad \forall i, j, r \quad (4)$$

Step 2: Linearise the objective function (iteration  $i$ )

$$\begin{aligned} \tilde{Z}(w^{(i)}) &= Z(q^{(i)}) + \sum_a \frac{\partial Z(q^{(i)})}{\partial q_a} (w_a - q_a^{(i)}) \\ &= Z(q^{(i)}) + \sum_a t_a(q_a^{(i)}) (w_a - q_a^{(i)}) \end{aligned}$$

(first-order expansion Taylor polynomial)

# Frank-Wolfe algorithm 3/4

$$\min_{q_a} Z = \sum_a \int_{x=0}^{q_a} t_a(x) dx \quad (1)$$

subject to: 
$$\sum_r T_{ijr} = T_{ij} \quad \forall i, j \quad (2)$$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr} \quad \forall a \quad (3)$$

$$T_{ijr} \geq 0 \quad \forall i, j, r \quad (4)$$

Step 3: Solve the linearised problem (iteration  $i$ )

$$\min_{w_a^{(i)}} \tilde{Z}(w^{(i)}) = \min_{w_a^{(i)}} \left\{ Z(q^{(i)}) + \sum_a t_a(q_a^{(i)})(w_a - q_a^{(i)}) \right\}$$

An AON assignment using  $t_a(q_a^{(i)})$  yields a feasible solution  $w_a$   $\min_{w_a^{(i)}} \sum_a t_a(q_a^{(i)}) w_a^{(i)}$  subject to (2), (3), and (4)



# Frank-Wolfe algorithm 4/4

$$\min_{q_a} Z = \sum_a \int_{x=0}^{q_a} t_a(x) dx \quad (1)$$

subject to:

$$\sum_r T_{ijr} = T_{ij} \quad \forall i, j \quad (2)$$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr} \quad \forall a \quad (3)$$

$$T_{ijr} \geq 0 \quad \forall i, j, r \quad (4)$$

Step 4: Find the new solution (iteration  $i$ )

$$\tilde{\alpha}^{(i)} = \arg \min_{0 \leq \alpha \leq 1} Z(q^{(i)} + \alpha(w^{(i)} - q^{(i)})) \quad \alpha = \text{optimal stepsize}$$

$$\Rightarrow q^{(i+1)} = q^{(i)} + \tilde{\alpha}^{(i)} (w^{(i)} - q^{(i)})$$

# Frank-Wolfe algorithm

Step 1:  $i:=1$ . Set  $q_a^{(i)} = 0$  (assume empty network)

Step 2: Perform a shortest-path AON assignment based on  $t_a^{(i)} = t_a(q_a^{(i)})$  yielding link flows  $w_a^{(i)}$

Step 3: Compute new solution  $q_a^{(i+1)} = q_a^{(i)} + \alpha^{(i)} (w_a^{(i)} - q_a^{(i)})$   
with  $\tilde{\alpha}^{(i)} = \arg \min_{0 \leq \alpha \leq 1} Z(q^{(i)} + \alpha(w^{(i)} - q^{(i)}))$

Step 4: If no convergence yet, set  $i:=i+1$  and return to Step 2.

N.B. Using  $\alpha^{(i)} = 1/i$  is called:  
Method of Successive Averages (MSA)  
(see earlier slides)

# 3.6

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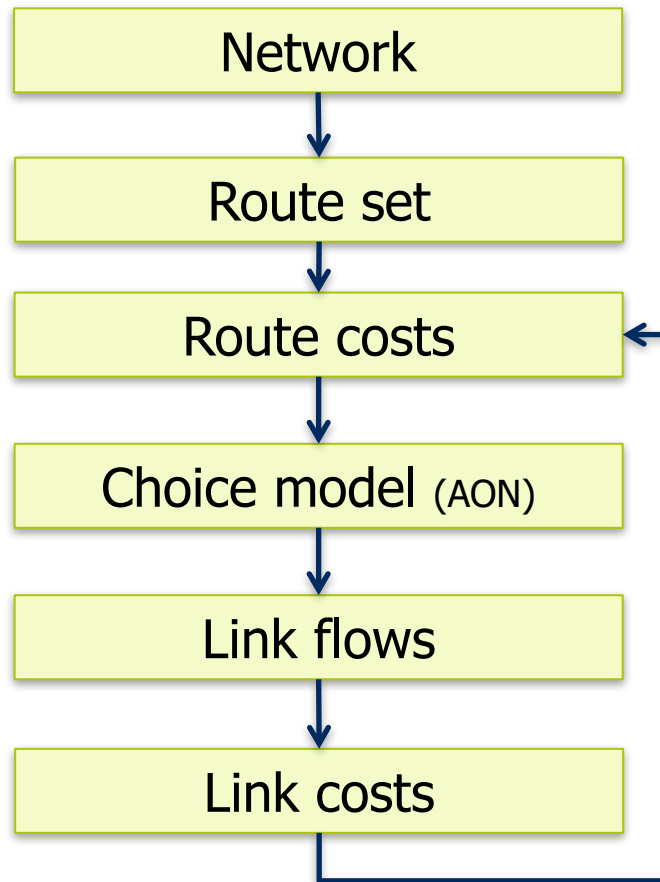
*DUE: Route based approach*

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# Link based versus route based

- Previous slides all referred to a link based formulation
- i.e. repetitive tree searches
- What if you have a set of possible routes?
- Then there's no need to search for routes at each MSA-step!

# Route based approach: Generic procedure



# Generic solution scheme

## Route flow averaging

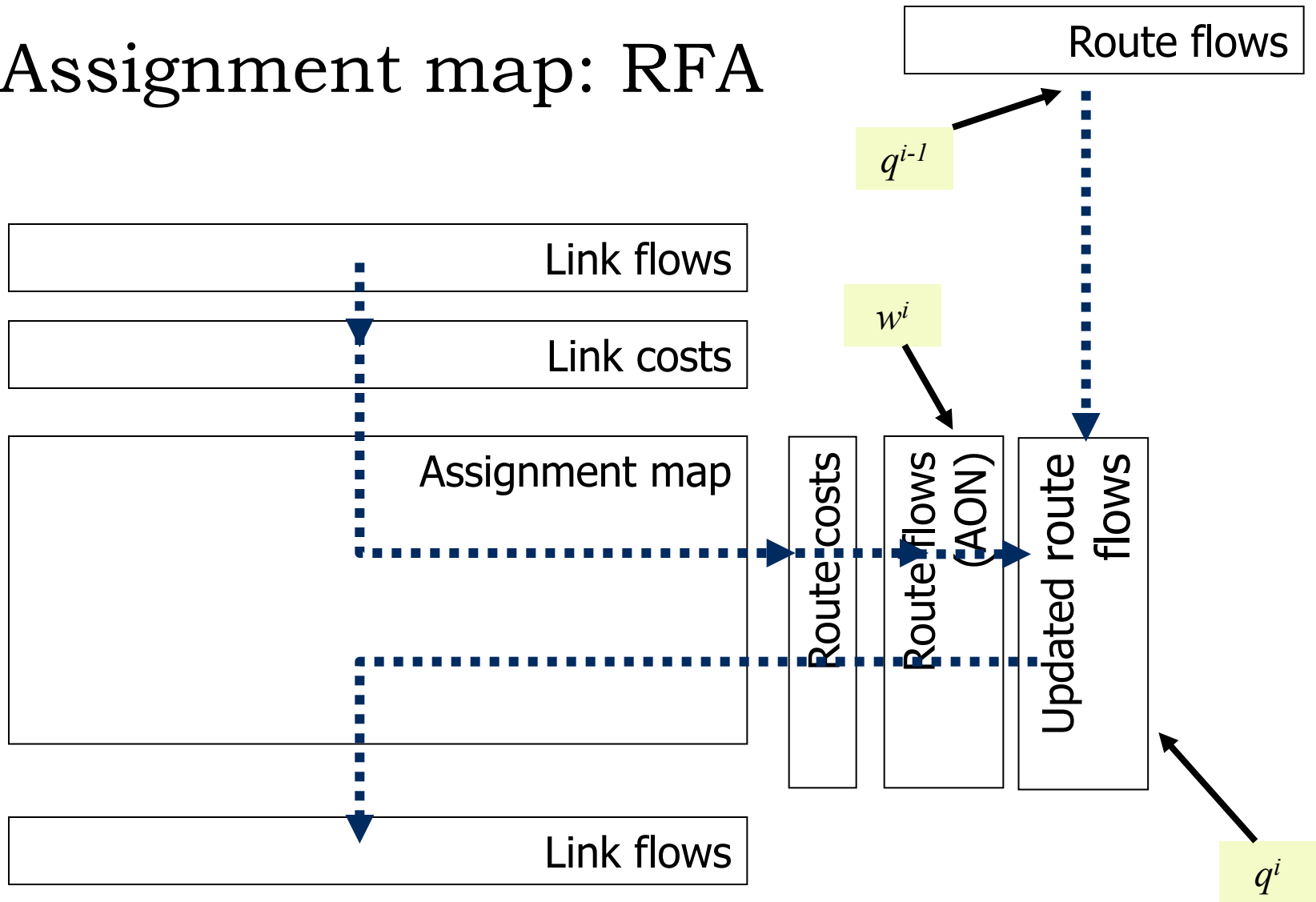
1. Specify routes/choice sets
2. Calculate path costs
3. Assign OD (AON) $\Rightarrow$  route flows
4. Recalculate route flows (MSA)

$$q_r^i = q_r^{i-1} + (w_r^i - q_r^{i-1}) / i$$

where  $w_r^i$  = route flow of the intermediate solution

5. Calculate link flows
6. Check convergence
7. Go to step 2 or stop

# Assignment map: RFA



# Benefits of a route-based approach

- Full control of routes that are used
- Freedom in route choice modelling (see SUE)
- Overlapping routes can explicitly be dealt with
- Reduced computational efforts in equilibrium assignment
- Suitable for all kind of network concepts e.g. multimodal networks
  
- So, why isn't route-based assignment used in practice?



# 3.7

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*SUE: Stochastic user equilibrium assignment*

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# Stochastic user equilibrium

- Combination of two concepts
- Congestion: travel time is function of flow  
=> equilibrium modelling
- Perception: travellers consider a set of routes  
=> route choice
- Adjustment Wardrop  
All travellers choose their optimal route, such that no traveller can improve his/her **perceived** travel time by unilaterally changing routes.

# Stochastic equilibrium assignment

## 1. Link travel times $t_a$

$$t_a = t_a(q_a)$$

## 2. Route choice proportions $\phi_{ijr}$

$$\phi_{ijr} = \phi_{ijr}(\Theta, t_{ijr})$$

## 3. Route travel times $t_{ijr}$

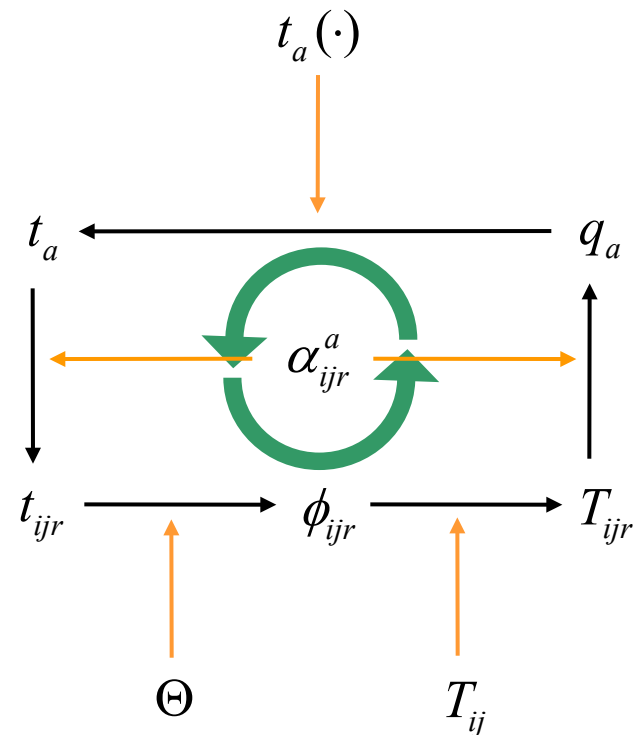
$$t_{ijr} = \sum_a \alpha_{ijr}^a t_a$$

## 4. Route flows $T_{ijr}$

$$T_{ijr} = \phi_{ijr} T_{ij}$$

## 5. Link flows $q_a$

$$q_a = \sum_i \sum_j \sum_r \alpha_{ijr}^a T_{ijr}$$



# Generic solution scheme

## Route flow averaging

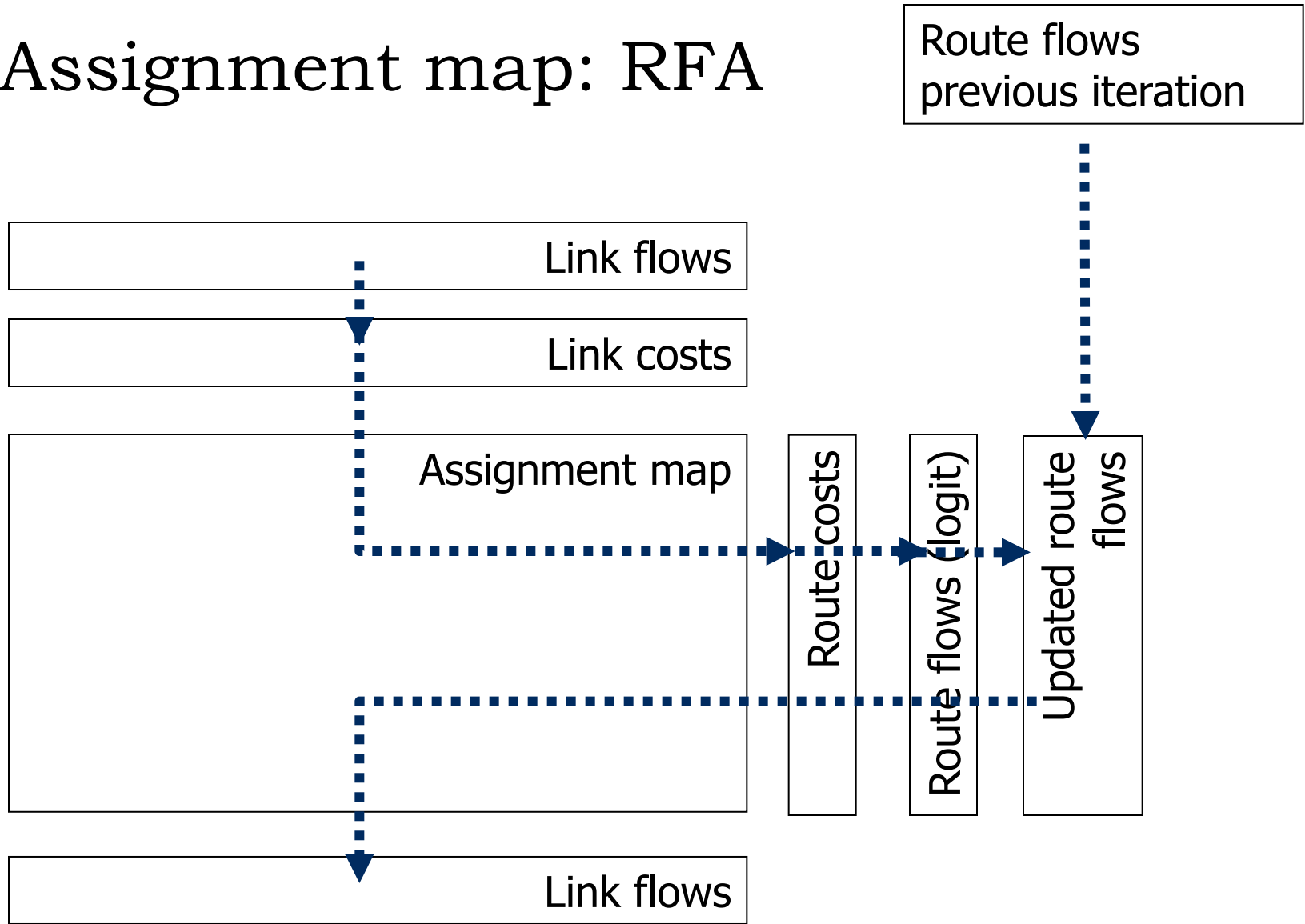
1. Specify paths/choice sets
2. Calculate path costs
3. Assign OD (Logit, Probit) $\Rightarrow$  route flows
4. Recalculate route flows (MSA)

$$q_r^i = q_r^{i-1} + (w_r^i - q_r^{i-1}) / i$$

where  $w_r^i$  = route flow of the intermediate solution

5. Calculate link flows
6. Check convergence
7. Go to step 2 or stop

# Assignment map: RFA



# Alternative solution scheme

## Link flow averaging

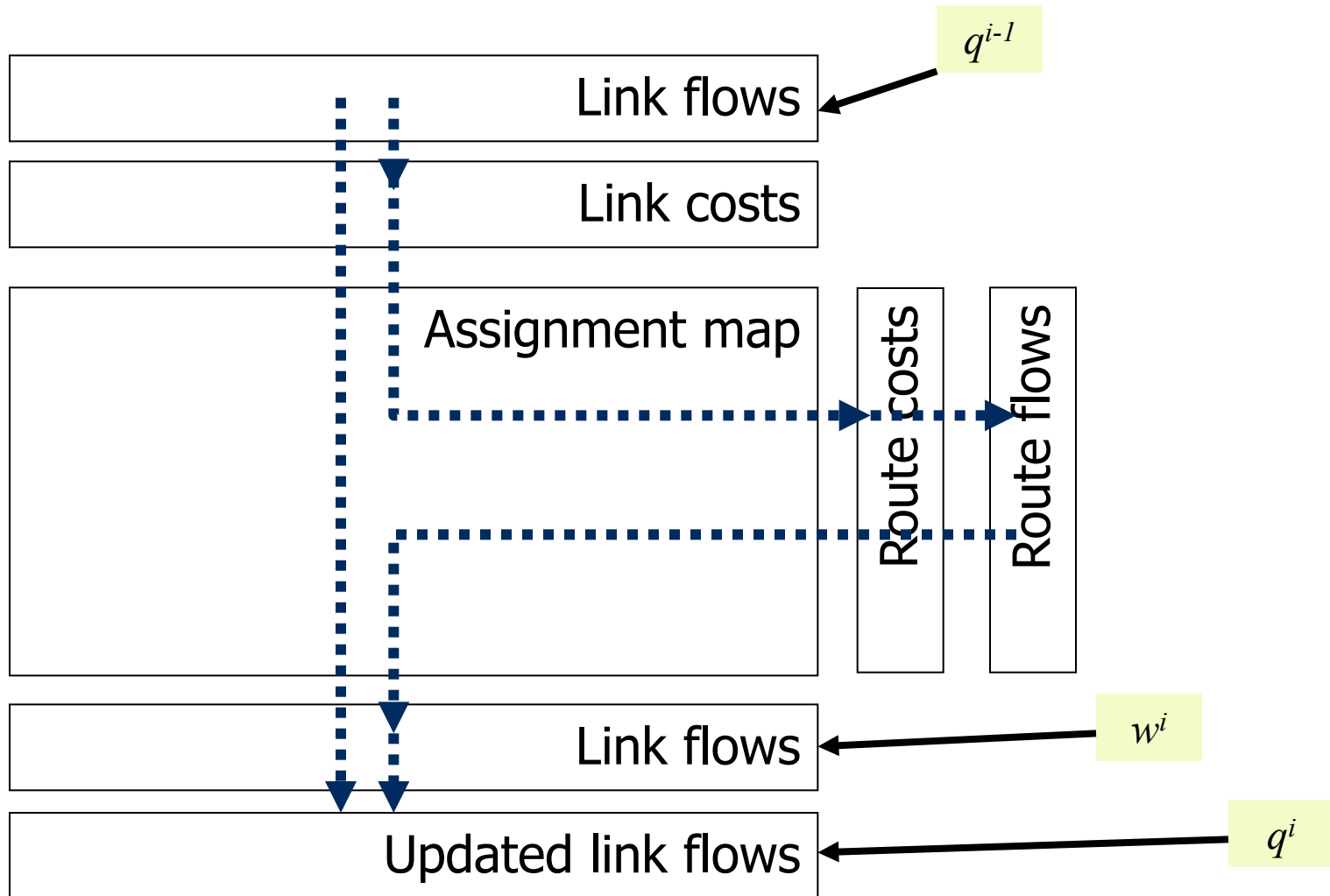
1. Specify paths/choice sets
2. Calculate path costs
3. Assign OD (Probit, Logit)=> route flows
4. Calculate link flows
5. Recalculate link flows (MSA)

$$q_a^i = q_a^{i-1} + (w_a^i - q_a^{i-1}) / i$$

where  $w_a^i$  = link flow of the intermediate solution

6. Check convergence
7. Go to step 2 or stop

# Assignment map: LFA



# 3.8

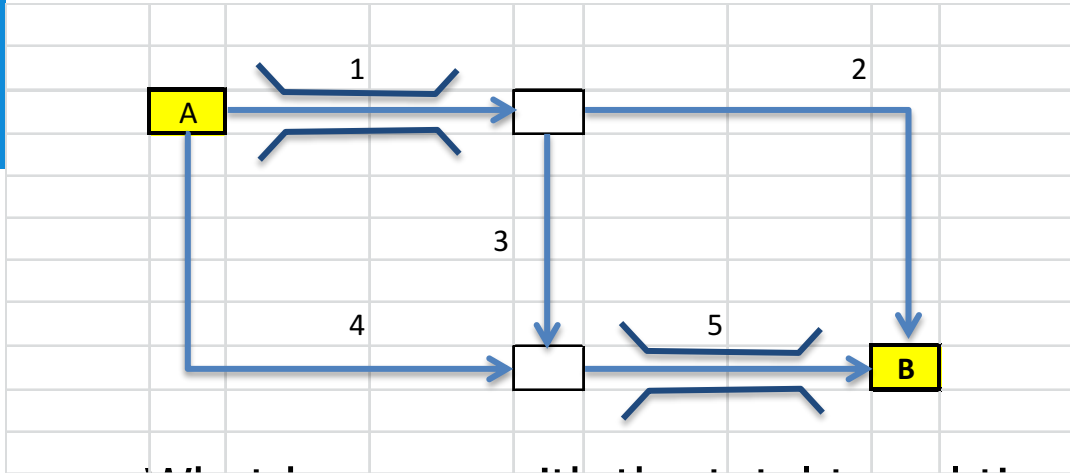
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## *Braess's paradox*

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# Braess's paradox



- What happens with the total travel time if link 3 is open for traffic?
- Explore spreadsheet Braess (on Blackboard)
- Check internet, e.g. YouTube!

# 4.

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## *Practical issues*

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# Practical topics

- Trucks
- Convergence speed DUE and SUE
- Duality gap SUE
- Frank-Wolfe or MSA?
- Values for parameters in BPR
- Where's the congestion?

# Trucks

## Three options

- Sum the OD-matrices of car and truck into OD-matrix vehicles or using a PCU-value
- Assign trucks before performing equilibrium assignment, e.g. using multiple routing, and use the flows as a preload (PCU!)
- Assign trucks and cars simultaneously (again using a PCU-value), i.e. multi-user class assignment

# Convergence speed DUE and SUE

- In an equilibrium assignment you distribute traffic over a set of routes
- In a DUE you have a single route per MSA-step, in a SUE you have multiple routes per MSA-step  
=> SUE needs less MSA-steps
- However, if you use a Probit for SUE, you need iterations for a single MSA-step  
=> SUE with Probit takes more computation time  
=> SUE with Logit is faster than DUE

# Duality gap SUE

- Duality gap in words:  
total travel time based on links minus total travel time based on (latest) shortest paths
- For DUE the duality gap should become zero (Wardrop principle)
- In a SUE travellers opt routes that are longer but they perceive to be shortest  
=> Total travel time for SUE is higher than for DUE  
=> Duality gap  $> 0$

# Frank-Wolfe or MSA

- Frank-Wolfe algorithm is a generic mathematical tool
- Theoretically it is only justified if the travel time on a link is a function of the flow on the link  
=> so what about intersections?
- MSA is a pragmatic approach, which proves to be rather robust

# Values for parameters in BPR

- BPR-function:  $t_a(q_a) = t_a^0 \left( 1 + \alpha \left( \frac{q_a}{C_a} \right)^\beta \right)$
- Commonly mentioned values:  $\alpha = 0.15$  and  $\beta = 4$
- However, function differs per road type:  
e.g. 0.15 is used for freeways, for regional and urban roads higher values are more suitable



# Where's the congestion?

- Net result of assignment: network with flows
- Common unit for analysis: flow-capacity ( $q/c$ ) ratio
- For which  $q/c$ -ratio there is congestion?
- Practice:  
 $q/c$ -ratio  $> 0.85$ : congestion  
(N.B.  $q$  represents average flow, thus  $q/c=1$  implies 50% congestion)
- Where's the queue?