

Dredging Processes

Dr.ir. Sape A. Miedema

3. Cutting Introduction





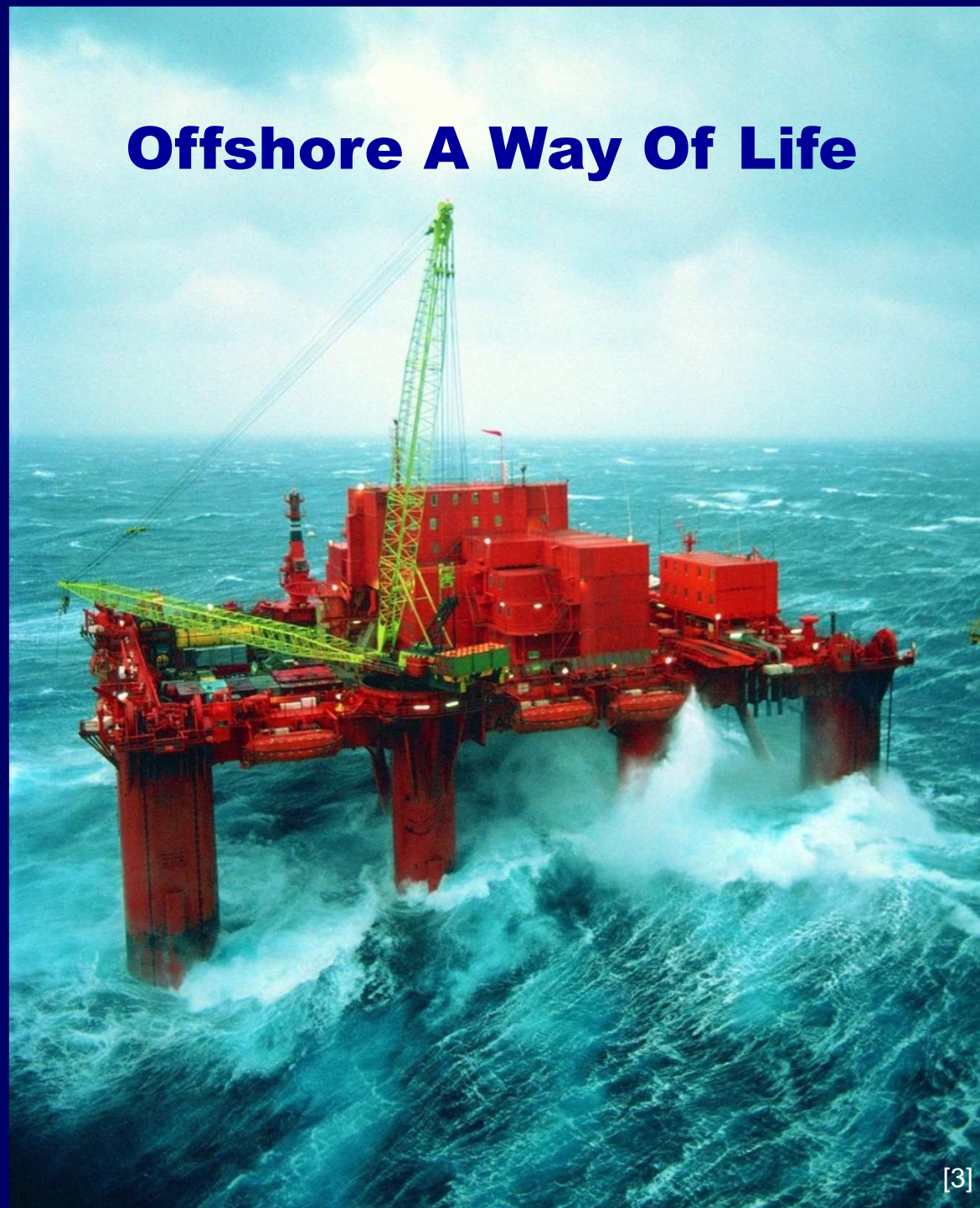
[1]

Dredging A Way Of Life





[2]



[3]

Offshore A Way Of Life



Offshore & Dredging Engineering

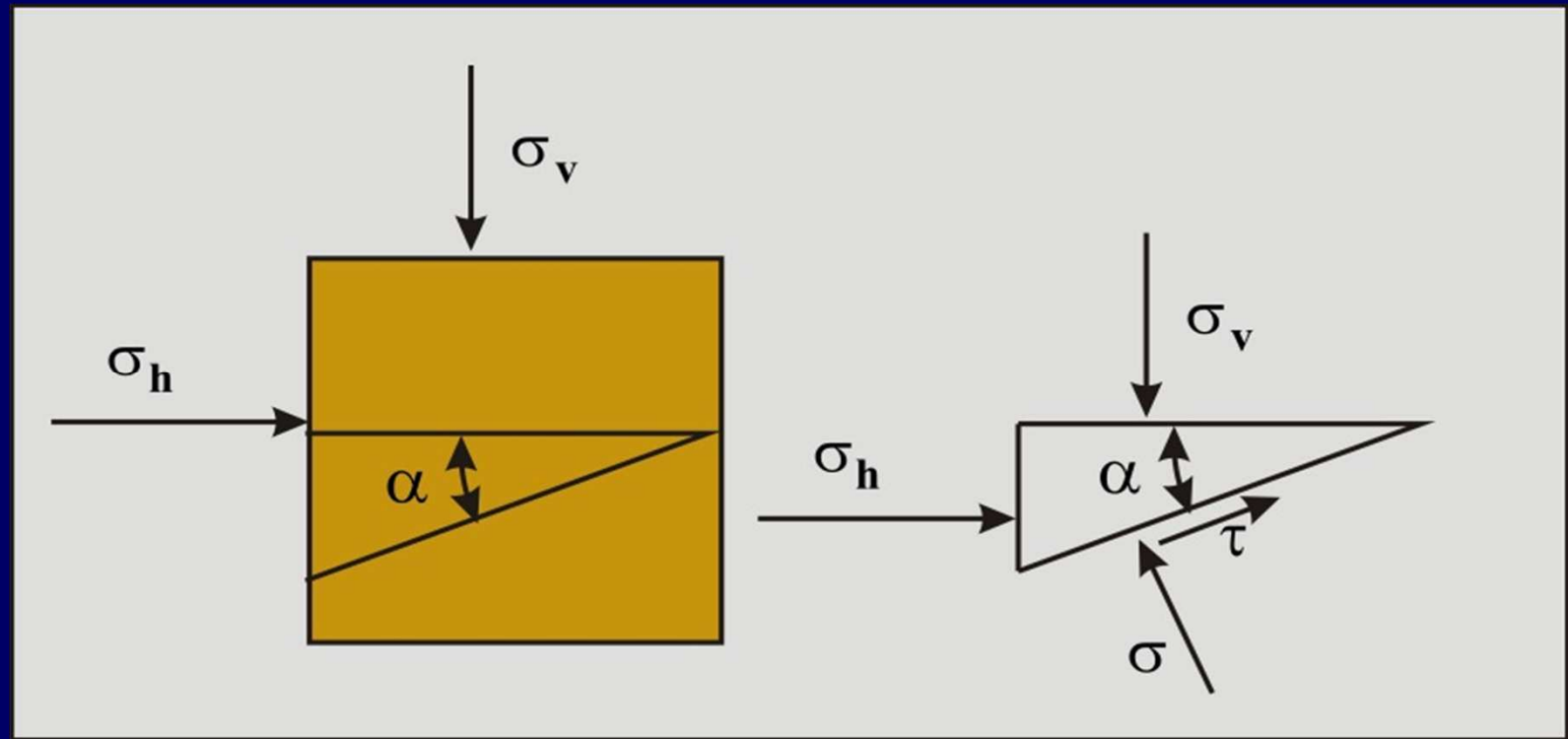
Dr.ir. Sape A. Miedema
Educational Director





Mohr Circle

Mohr Circle 1



Vertical Equilibrium of Forces

$$\sigma_v \cdot \cos(\alpha) = \sigma \cdot \cos(\alpha) + \tau \cdot \sin(\alpha)$$

Horizontal Equilibrium of Forces

$$\sigma_h \cdot \sin(\alpha) = \sigma \cdot \sin(\alpha) - \tau \cdot \cos(\alpha)$$

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Mohr Circle 2

$$\sigma_v \cdot \cos(\alpha) \cdot \cos(\alpha) = \sigma \cdot \cos(\alpha) \cdot \cos(\alpha) + \tau \cdot \sin(\alpha) \cdot \cos(\alpha)$$

$$\sigma_h \cdot \sin(\alpha) \cdot \sin(\alpha) = \sigma \cdot \sin(\alpha) \cdot \sin(\alpha) - \tau \cdot \cos(\alpha) \cdot \sin(\alpha)$$

$$\sigma_v \cdot \cos^2(\alpha) + \sigma_h \cdot \sin^2(\alpha) = \sigma$$

$$\cos^2(\alpha) = \frac{1 + \cos(2 \cdot \alpha)}{2}$$

$$\sin^2(\alpha) = \frac{1 - \cos(2 \cdot \alpha)}{2}$$

$$\sigma = \left(\frac{\sigma_v + \sigma_h}{2} \right) + \left(\frac{\sigma_v - \sigma_h}{2} \right) \cdot \cos(2 \cdot \alpha)$$

Mohr Circle 3

$$\sigma_v \cdot \cos(\alpha) \cdot \sin(\alpha) = \sigma \cdot \cos(\alpha) \cdot \sin(\alpha) + \tau \cdot \sin(\alpha) \cdot \sin(\alpha)$$

$$-\sigma_h \cdot \sin(\alpha) \cdot \cos(\alpha) = -\sigma \cdot \sin(\alpha) \cdot \cos(\alpha) + \tau \cdot \cos(\alpha) \cdot \cos(\alpha)$$

$$(\sigma_v - \sigma_h) \cdot \sin(\alpha) \cdot \cos(\alpha) = \tau$$

$$\tau = \left(\frac{\sigma_v - \sigma_h}{2} \right) \cdot \sin(2 \cdot \alpha)$$



Mohr Circle 4

$$\sigma - \left(\frac{\sigma_v + \sigma_h}{2} \right) = \left(\frac{\sigma_v - \sigma_h}{2} \right) \cdot \cos(2 \cdot \alpha)$$

$$\tau = \left(\frac{\sigma_v - \sigma_h}{2} \right) \cdot \sin(2 \cdot \alpha)$$

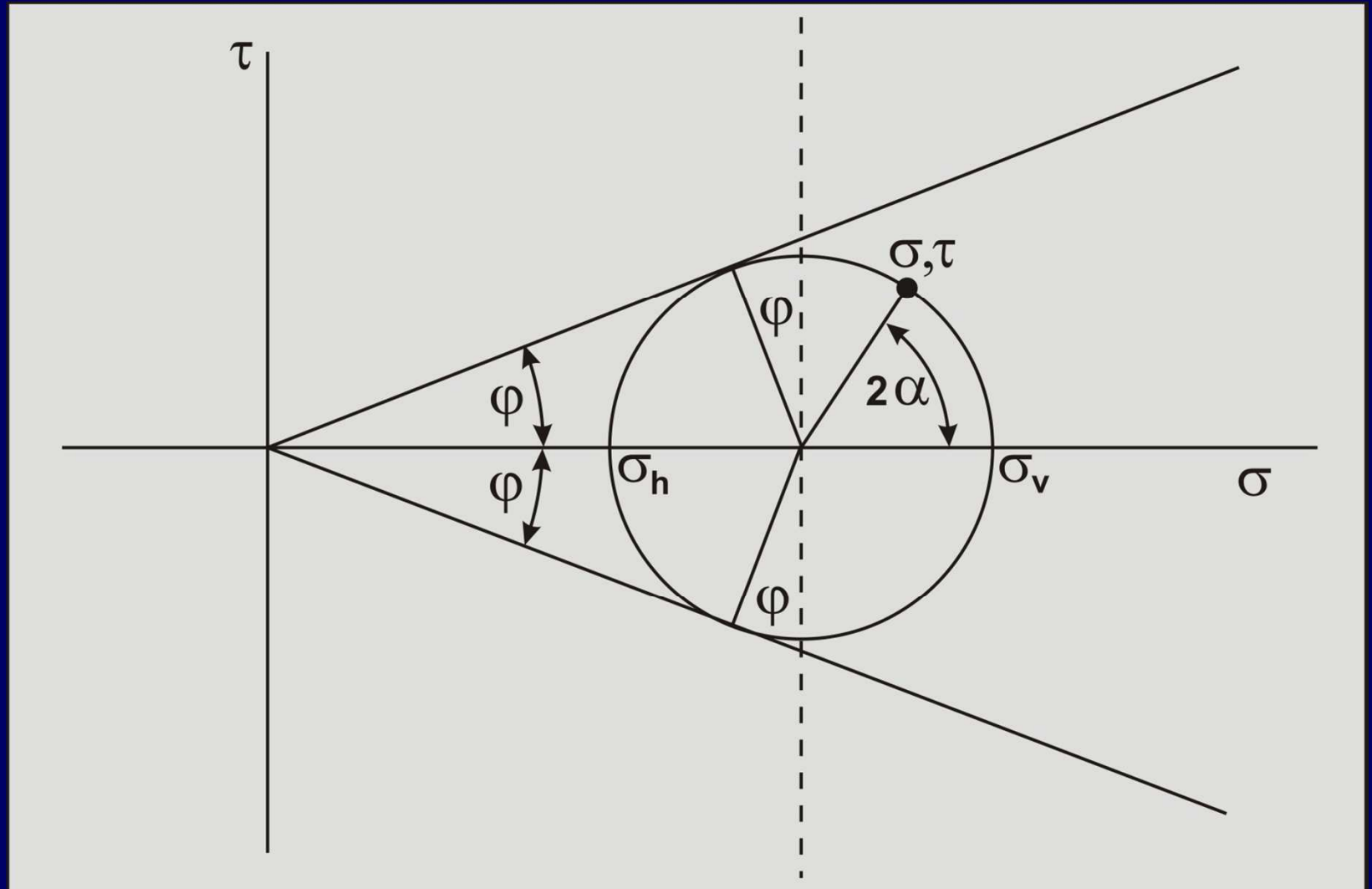
$$\left(\sigma - \left(\frac{\sigma_v + \sigma_h}{2} \right) \right)^2 = \left(\frac{\sigma_v - \sigma_h}{2} \right)^2 \cdot \cos^2(2 \cdot \alpha)$$

$$\tau^2 = \left(\frac{\sigma_v - \sigma_h}{2} \right)^2 \cdot \sin^2(2 \cdot \alpha)$$

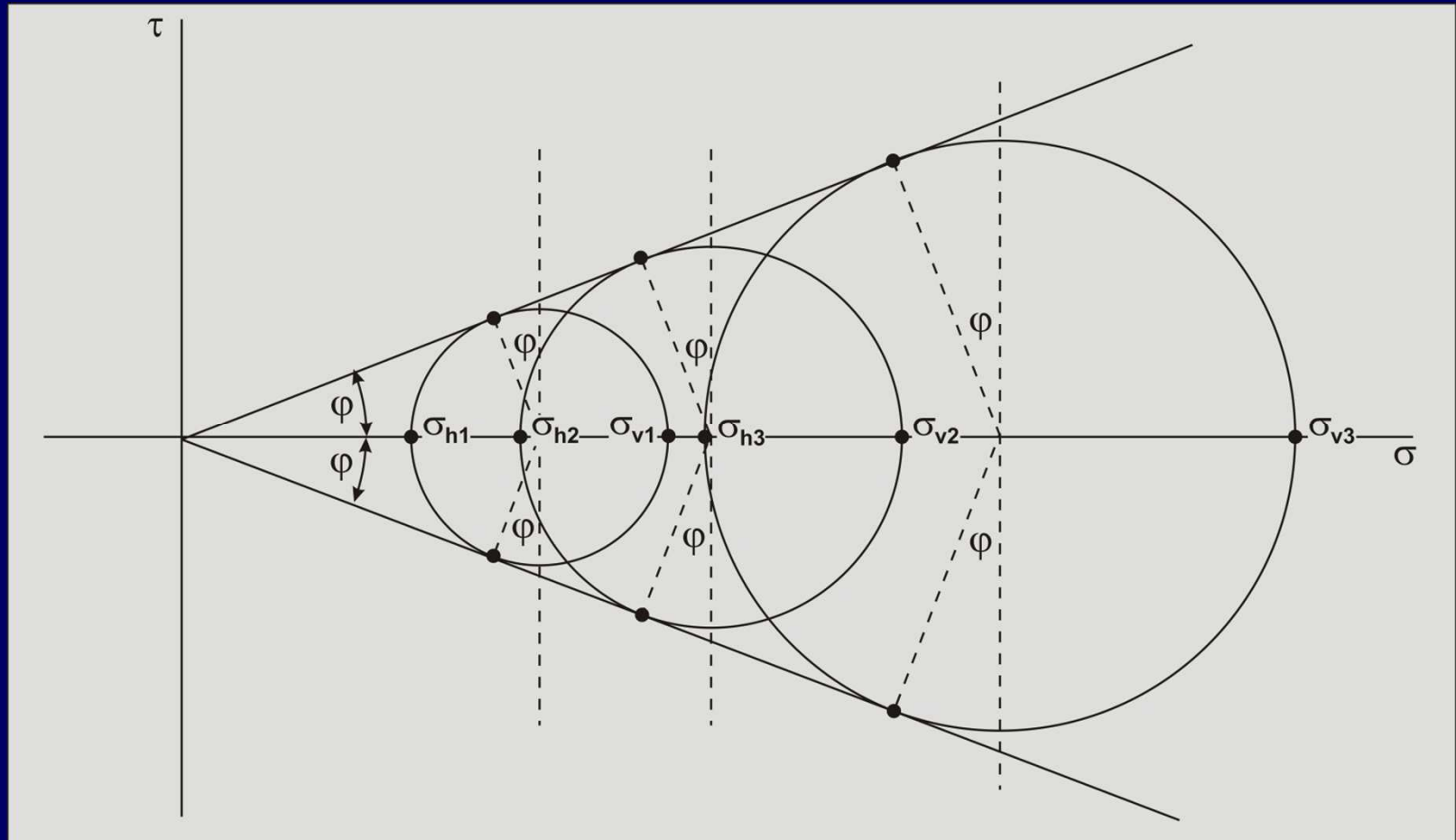
$$\left(\sigma - \left(\frac{\sigma_v + \sigma_h}{2} \right) \right)^2 + \tau^2 = \left(\frac{\sigma_v - \sigma_h}{2} \right)^2$$



Mohr Circle 5

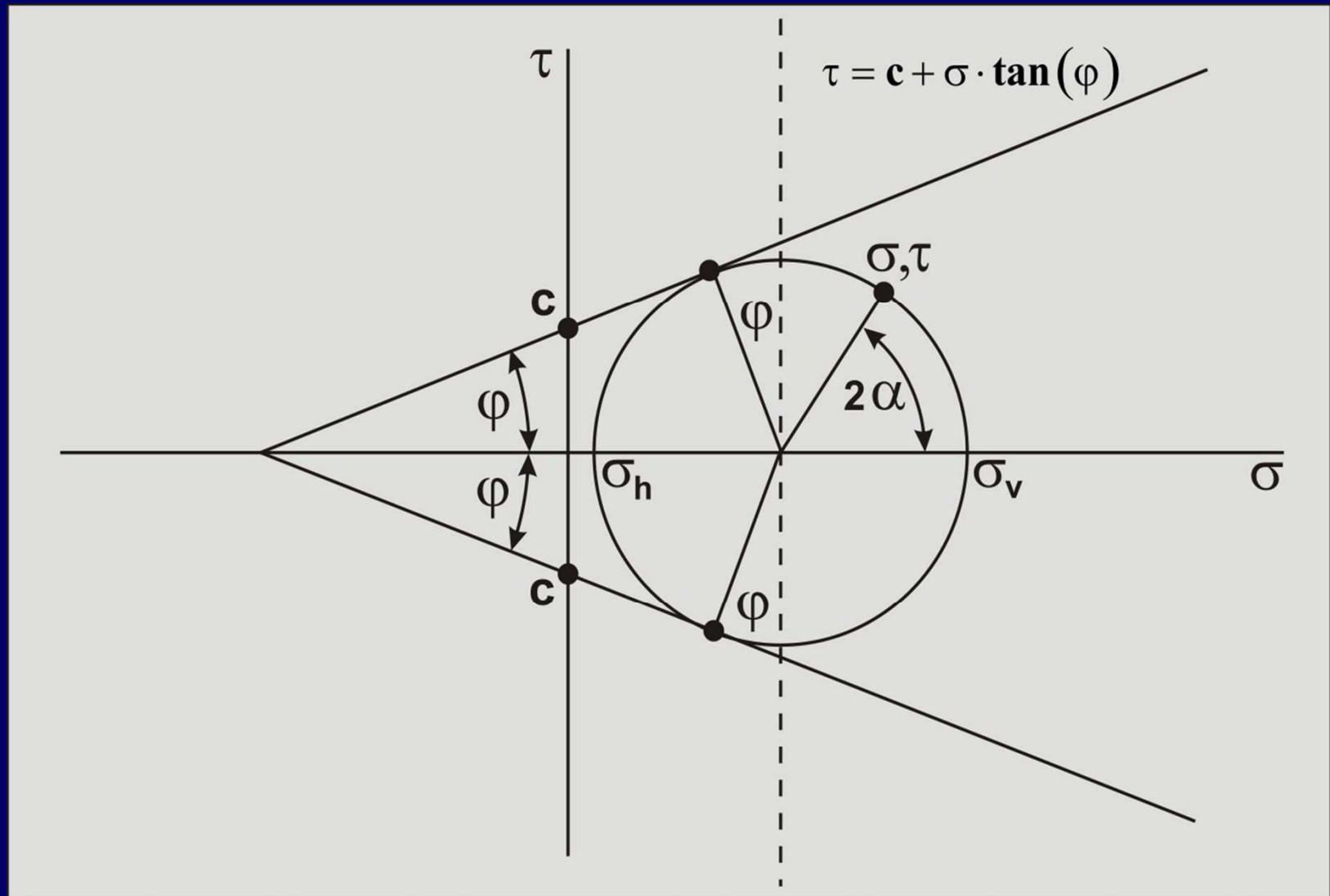


Mohr Circle From Triaxial Tests

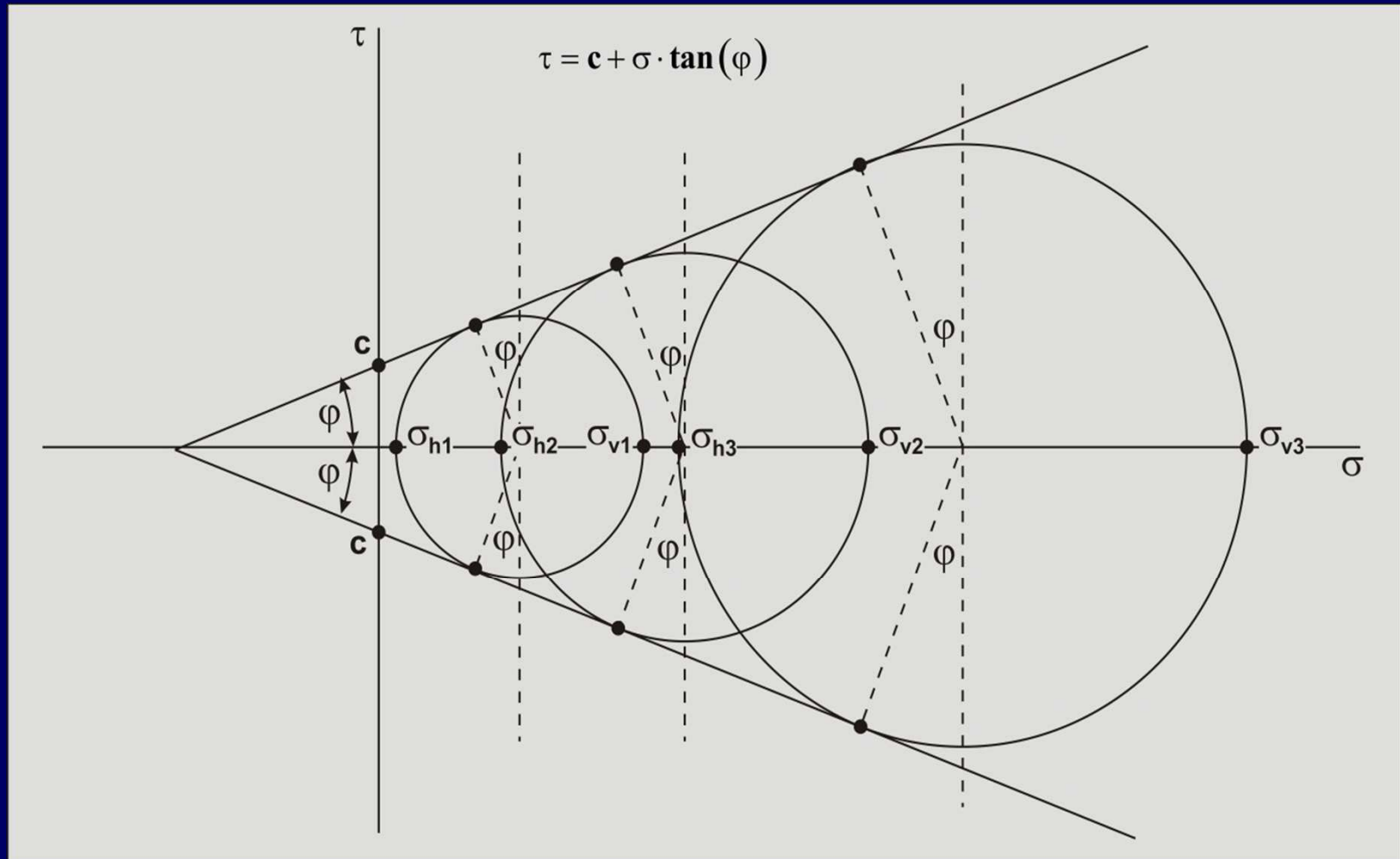


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Mohr Circle With Cohesion



Mohr Circle From Triaxial Tests

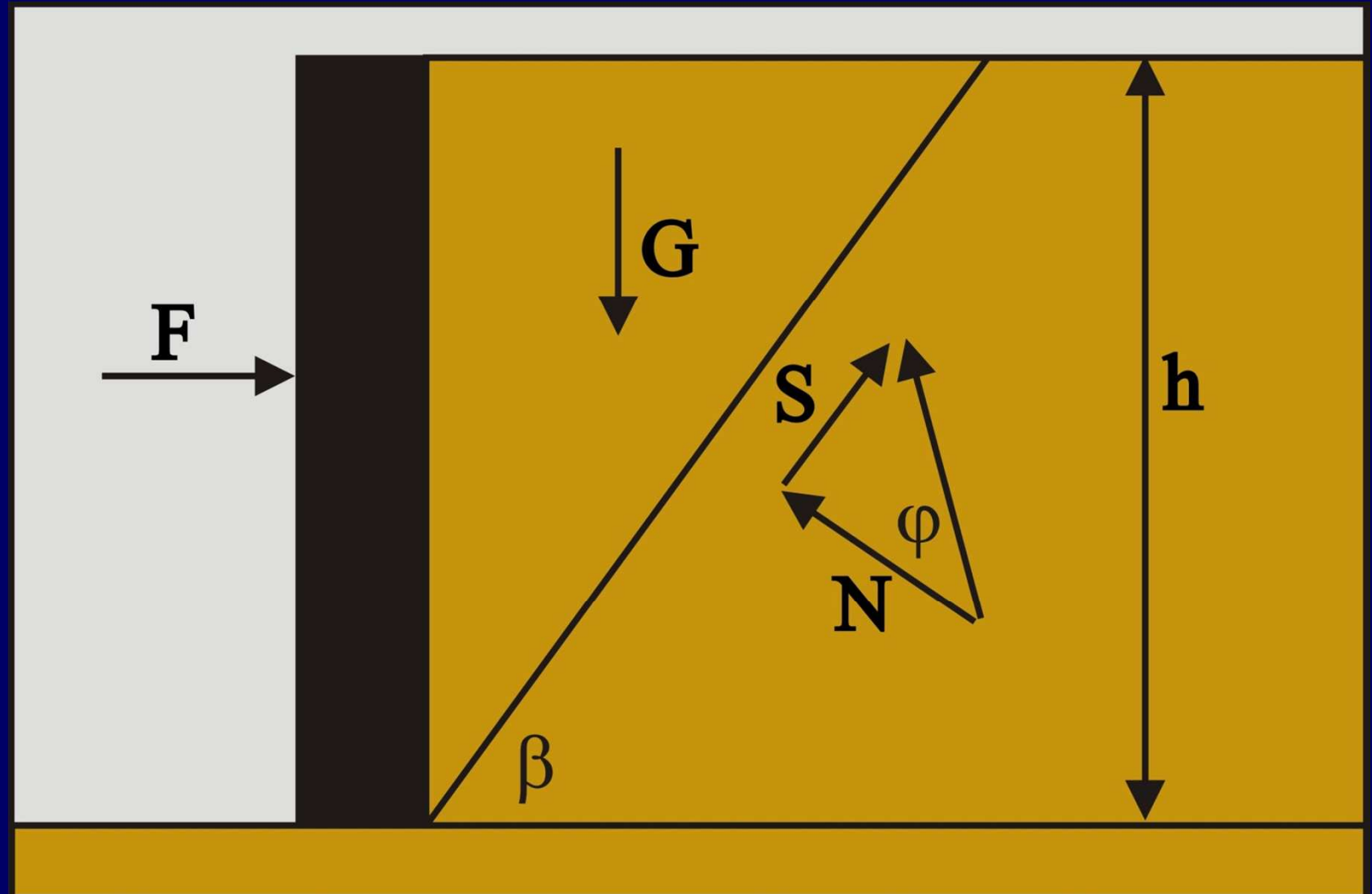


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Active Soil Failure

Active Soil Failure 1



Active Soil Failure 2

$$G = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \cot(\beta)$$

$$S = N \cdot \tan(\varphi)$$

No cohesion $\Rightarrow c=0$

No adhesion $\Rightarrow a=0$

Smooth wall $\Rightarrow \delta=0$

$$\text{Horizontal} \Rightarrow F + S \cdot \cos(\beta) - N \cdot \sin(\beta) = 0$$

$$\text{Vertical} \Rightarrow G - N \cdot \cos(\beta) - S \cdot \sin(\beta) = 0$$

Active Soil Failure 3

$$F = -G \cdot \tan(\varphi - \beta)$$

$$G = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \cot(\beta)$$

$$F = -\frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \frac{\cos(\beta) \cdot \sin(\varphi - \beta)}{\sin(\beta) \cdot \cos(\varphi - \beta)}$$

F at maximum if:

$$\frac{dF}{d\beta} = 0$$

$$\frac{d^2F}{d\beta^2} < 0$$

$$F = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \left(1 - \frac{\sin(\varphi)}{\sin(\beta) \cdot \cos(\varphi - \beta)} \right)$$

$$f = \sin(\beta) \cdot \cos(\beta - \varphi) \Rightarrow F \text{ maximum if } f \text{ maximum}$$

Intermezzo

$$\frac{\cos(\beta) \cdot \sin(\varphi - \beta)}{\sin(\beta) \cdot \cos(\varphi - \beta)} =$$

$$\frac{\cos(\beta) \cdot \sin(\varphi - \beta)}{\sin(\beta) \cdot \cos(\varphi - \beta)} - 1 + 1 =$$

$$\frac{\cos(\beta) \cdot \sin(\varphi - \beta)}{\sin(\beta) \cdot \cos(\varphi - \beta)} - \frac{\sin(\beta) \cdot \cos(\varphi - \beta)}{\sin(\beta) \cdot \cos(\varphi - \beta)} + 1 =$$

$$1 - \frac{\sin(\varphi)}{\sin(\beta) \cdot \cos(\varphi - \beta)}$$



Active Soil Failure 4

$$\frac{df}{d\beta} = \cos(2 \cdot \beta - \varphi)$$

$$\frac{d^2f}{d\beta^2} = -2 \cdot \sin(2 \cdot \beta - \varphi)$$

$$\frac{df}{d\beta} = 0 \Rightarrow \beta = \frac{\pi}{4} + \frac{1}{2} \cdot \varphi$$

$$\frac{d^2f}{d\beta^2} = -2 \text{ for } \beta = \frac{\pi}{4} + \frac{1}{2} \cdot \varphi$$

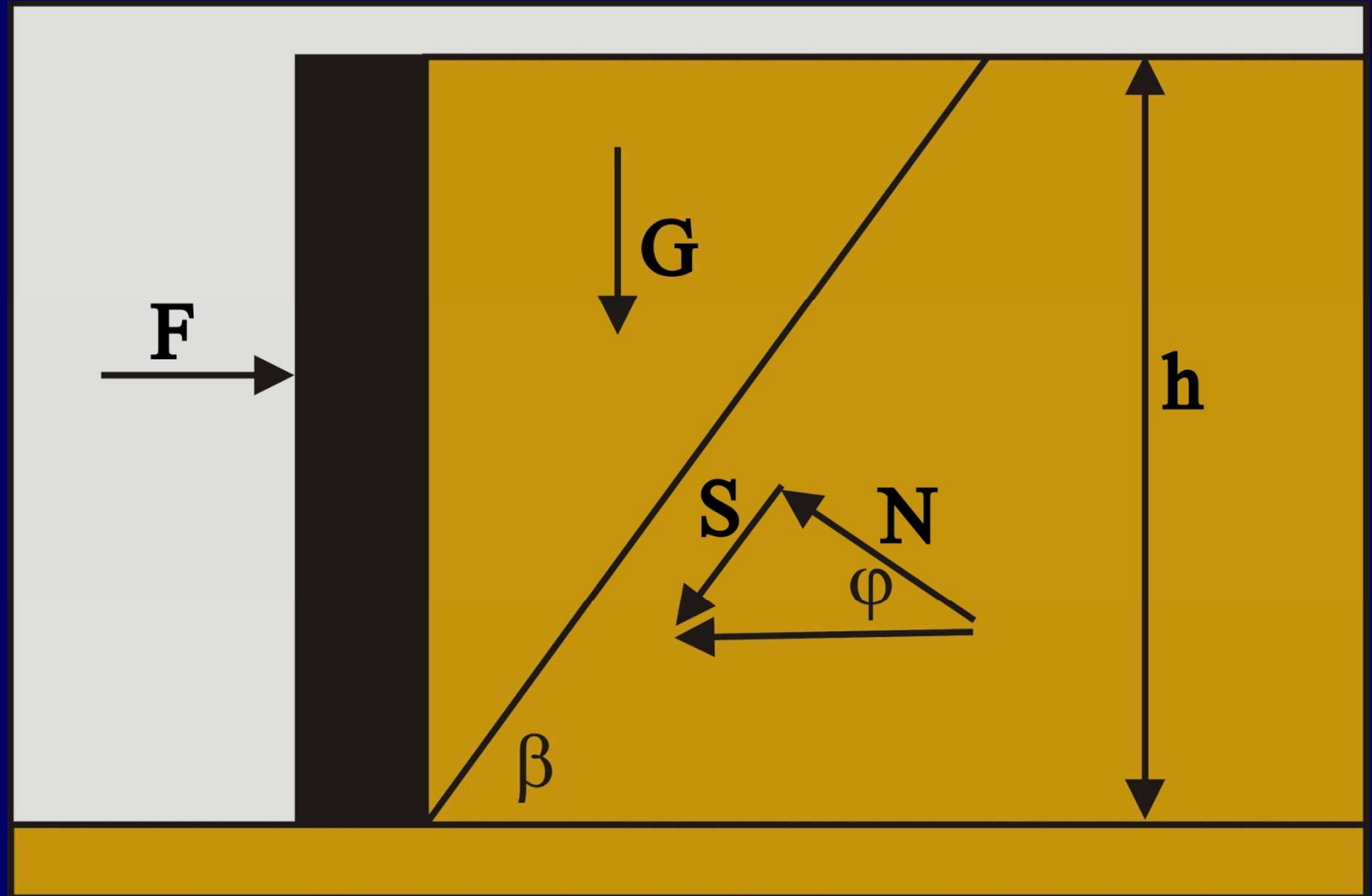
$$F = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \left(\frac{1 - \sin(\varphi)}{1 + \sin(\varphi)} \right) = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot K_a$$

$$K_A = \frac{1 - \sin \varphi}{1 + \sin \varphi} = \tan^2(45 - \varphi / 2)$$

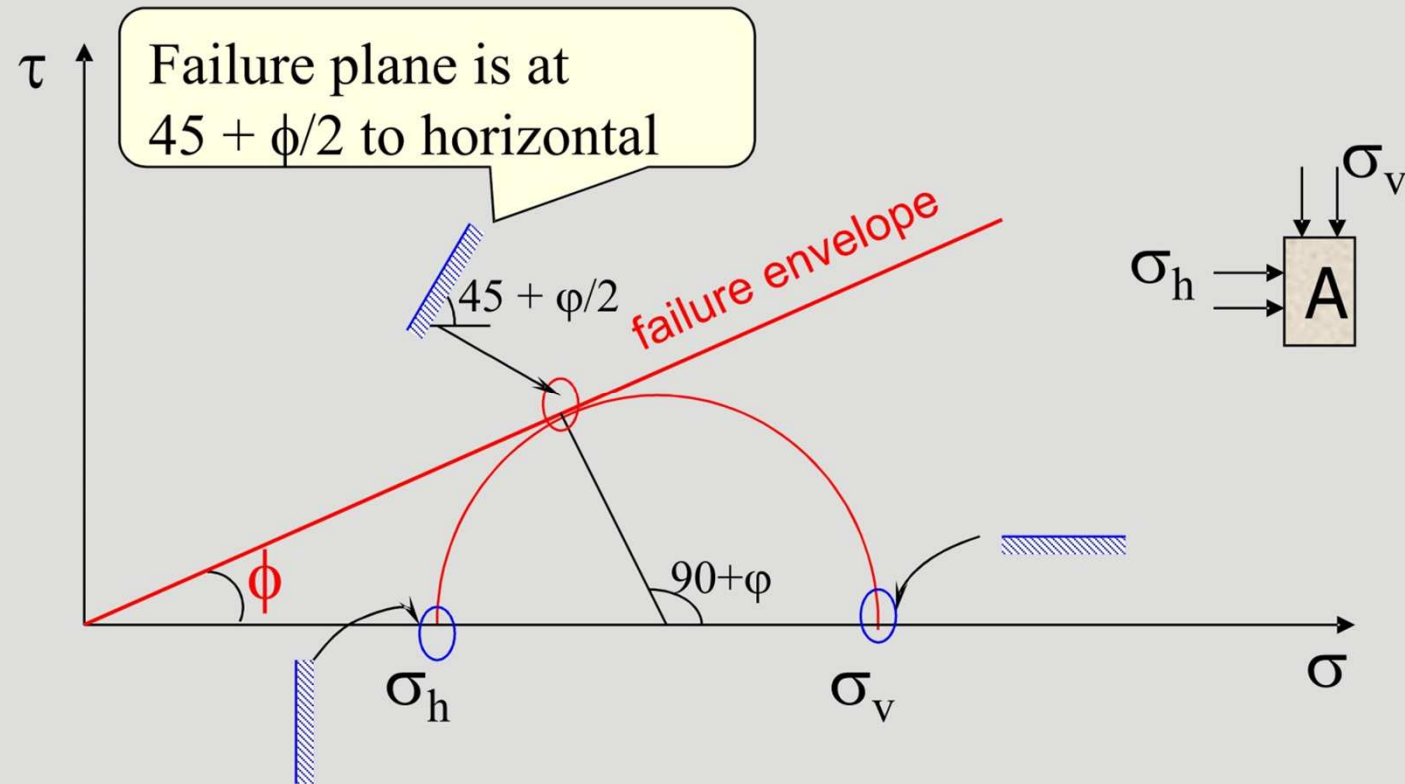
$$\sigma_h = K_A \cdot \sigma_v$$



Passive Soil Failure 1



Active Soil Failure 5





Passive Soil Failure

Passive Soil Failure 2

$$G = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \cot(\beta)$$

$$S = N \cdot \tan(\varphi)$$

No cohesion $\Rightarrow c=0$

No adhesion $\Rightarrow a=0$

Smooth wall $\Rightarrow \delta=0$

$$\text{Horizontal} \Rightarrow F - S \cdot \cos(\beta) - N \cdot \sin(\beta) = 0$$

$$\text{Vertical} \Rightarrow G - N \cdot \cos(\beta) + S \cdot \sin(\beta) = 0$$

Passive Soil Failure 3

$$F = G \cdot \tan(\varphi + \beta)$$

$$G = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \cot(\beta)$$

$$F = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \frac{\cos(\beta) \cdot \sin(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)}$$

F at minimum if:

$$\frac{dF}{d\beta} = 0$$

$$\frac{d^2F}{d\beta^2} > 0$$

$$F = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \left(1 + \frac{\sin(\varphi)}{\sin(\beta) \cdot \cos(\varphi + \beta)} \right)$$

$$f = \sin(\beta) \cdot \cos(\beta + \varphi) \Rightarrow F \text{ minimum if } f \text{ maximum}$$

Intermezzo

$$\frac{\cos(\beta) \cdot \sin(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)} = \frac{\cos(\beta) \cdot \sin(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)} - 1 + 1 =$$

$$\frac{\cos(\beta) \cdot \sin(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)} - \frac{\sin(\beta) \cdot \cos(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)} + 1 =$$

$$\frac{\cos(-\beta) \cdot \sin(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)} + \frac{\sin(-\beta) \cdot \cos(\varphi + \beta)}{\sin(\beta) \cdot \cos(\varphi + \beta)} + 1 =$$

$$1 + \frac{\sin(\varphi)}{\sin(\beta) \cdot \cos(\varphi + \beta)}$$



Passive Soil Failure 4

$$\frac{df}{d\beta} = \cos(2 \cdot \beta + \varphi)$$

$$\frac{d^2f}{d\beta^2} = -2 \cdot \sin(2 \cdot \beta + \varphi)$$

$$\frac{df}{d\beta} = 0 \Rightarrow \beta = \frac{\pi}{4} - \frac{1}{2} \cdot \varphi$$

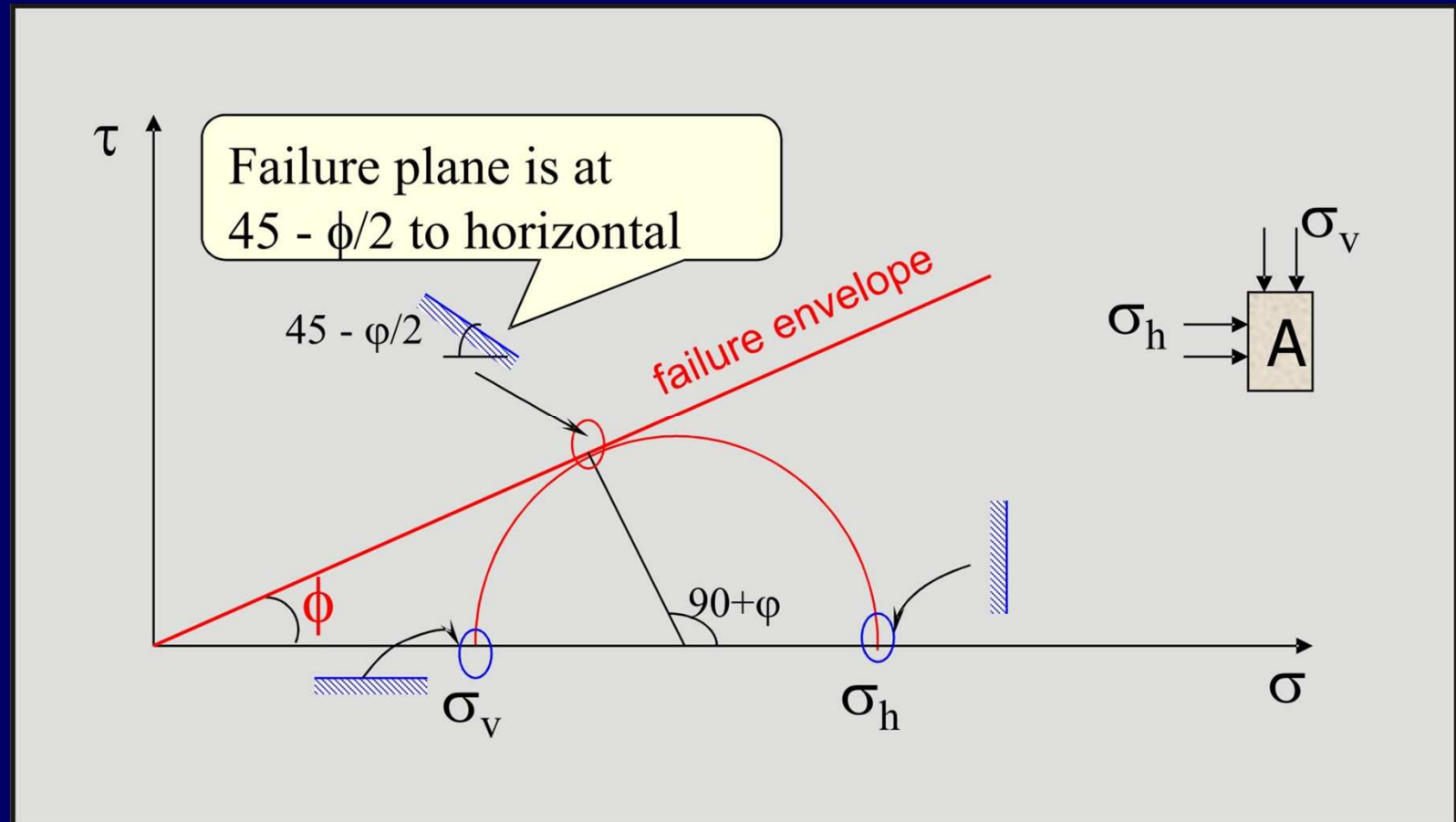
$$\frac{d^2f}{d\beta^2} = -2 \text{ for } \beta = \frac{\pi}{4} - \frac{1}{2} \cdot \varphi$$

$$F = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot \left(\frac{1 + \sin(\varphi)}{1 - \sin(\varphi)} \right) = \frac{1}{2} \cdot \rho_g \cdot g \cdot h^2 \cdot K_p$$

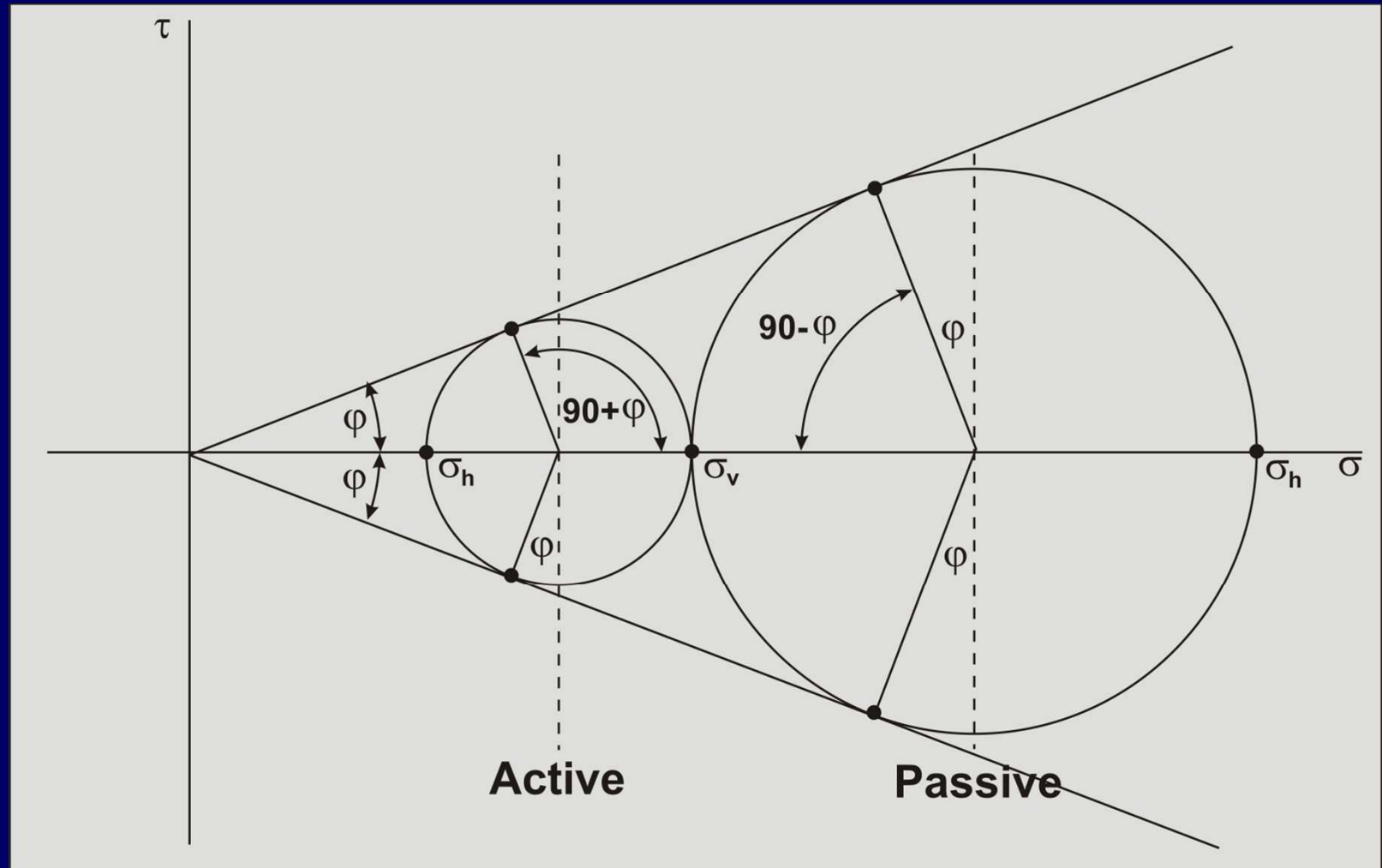
$$K_p = \frac{1 + \sin \varphi}{1 - \sin \varphi} = \tan^2(45 + \varphi / 2)$$

$$\sigma_h = K_p \cdot \sigma_v$$

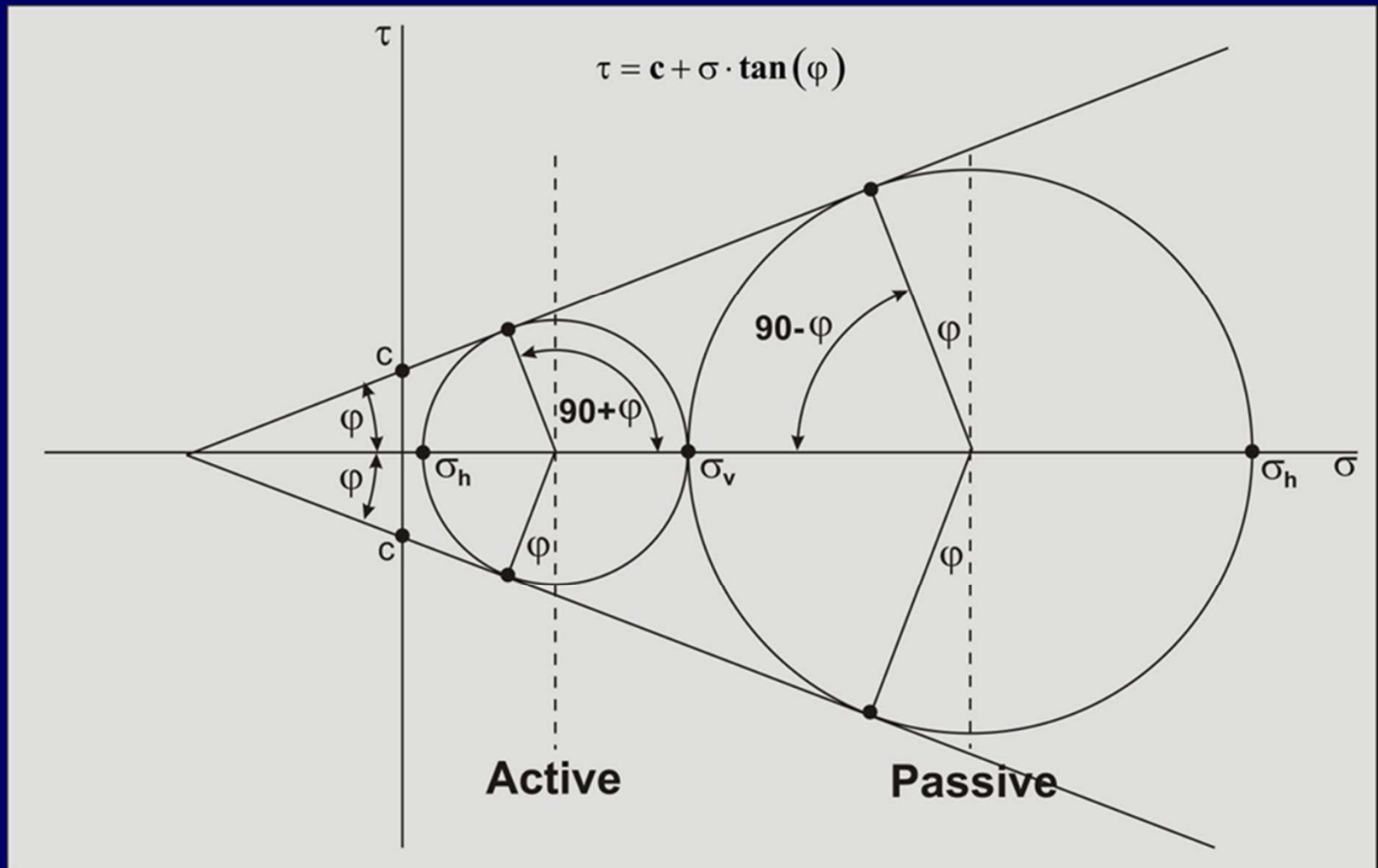
Passive Soil Failure 5



Active & Passive Soil Failure



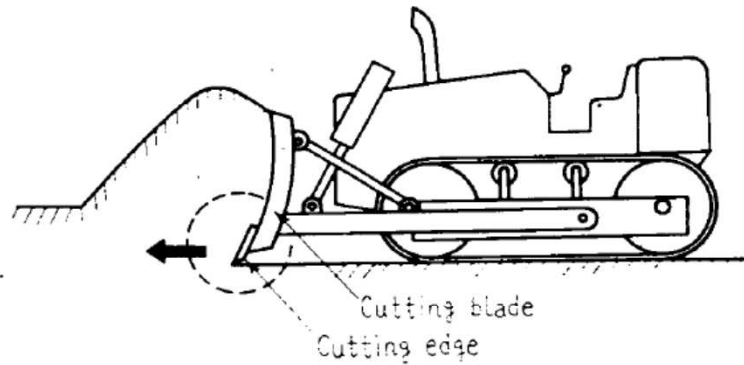
Active & Passive Soil Failure, Cohesion



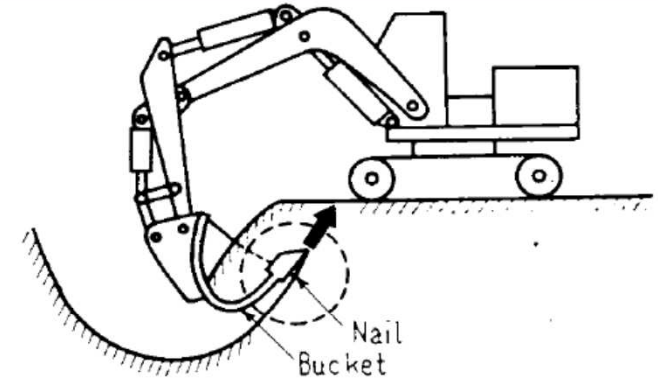


Cutting Mechanisms

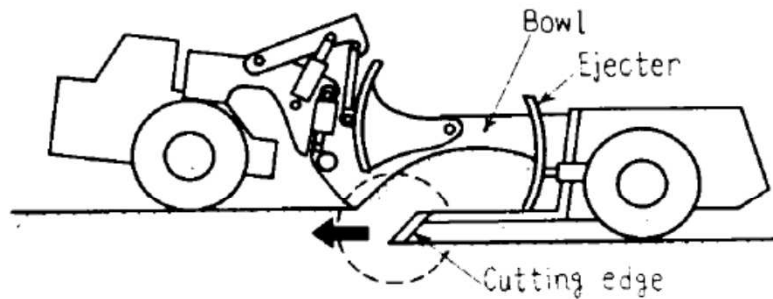
Hatamura Chijiwa Equipment



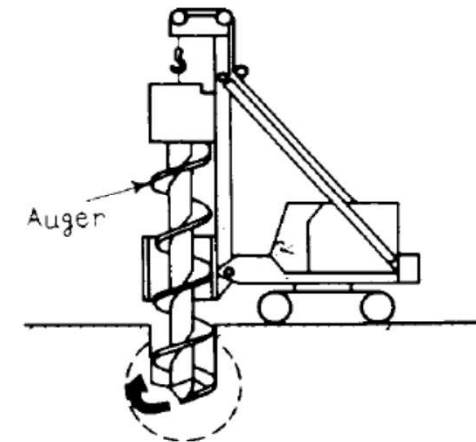
(a) Bulldozer



(b) Power shovel



(c) Scraper



(d) Earth-auger



Hatamura Chijiwa Test Facility

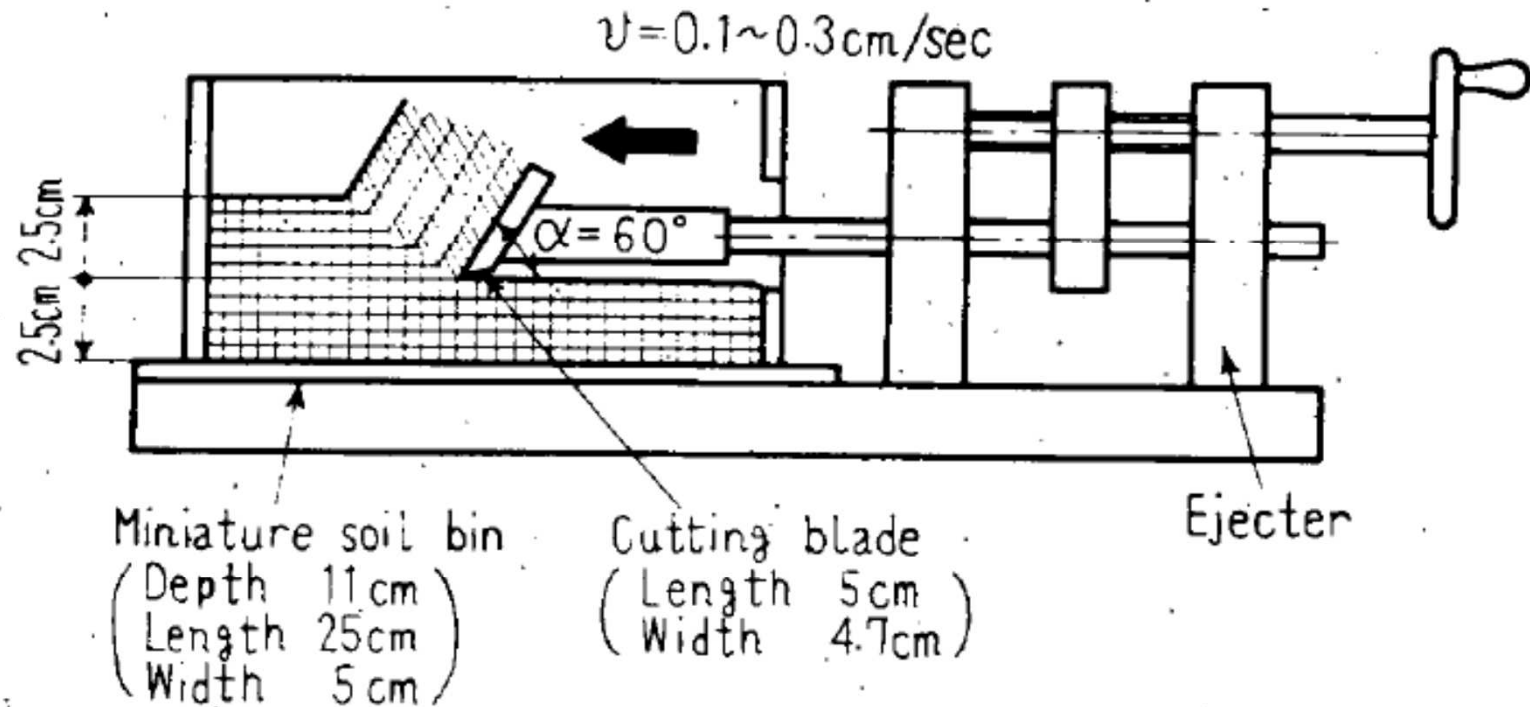
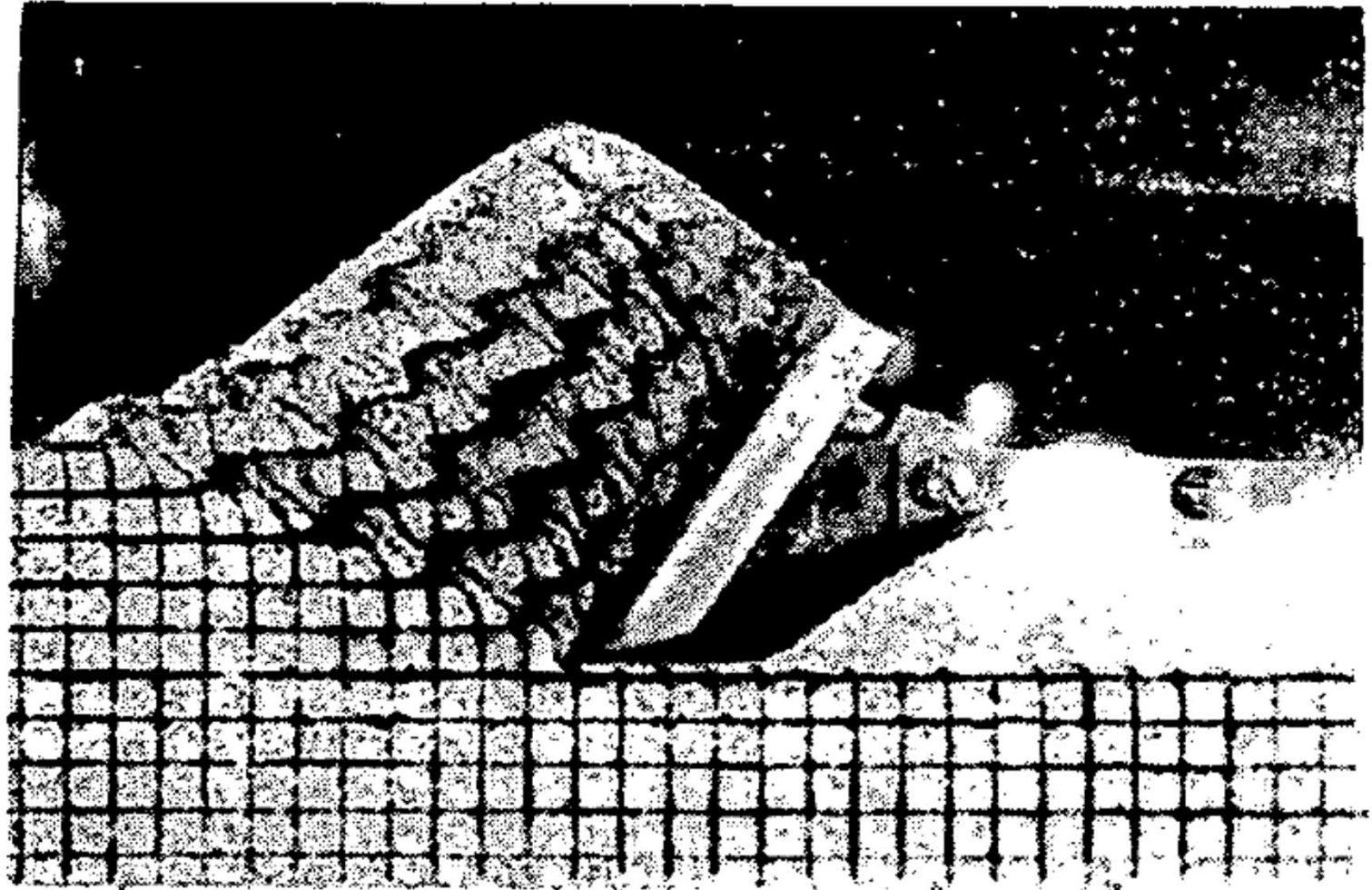


Fig. 2 Apparatus for investigating the deformation of soil by cutting.

Hatamura Chijiwa Dry Quarts Sand

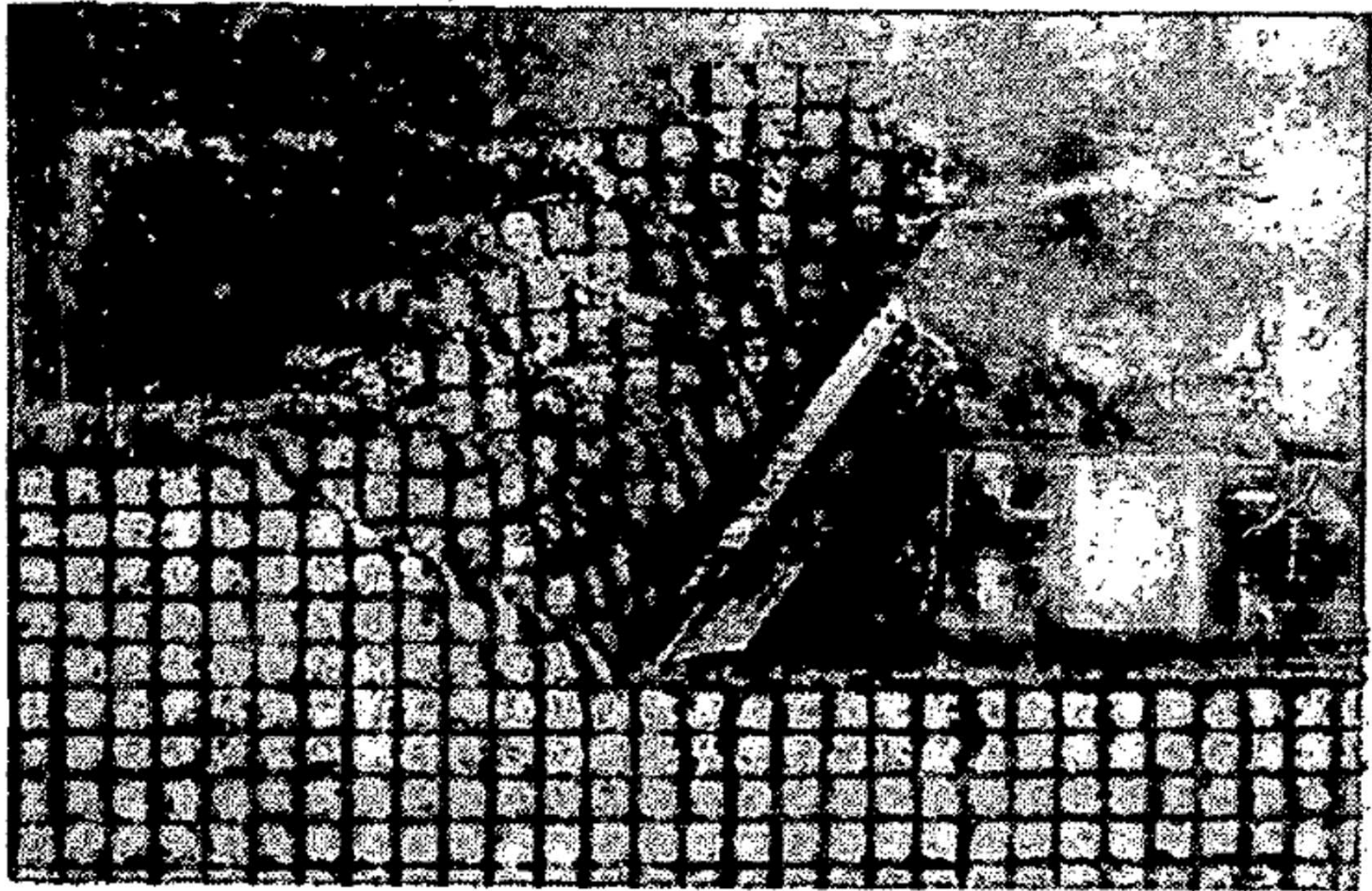


(a) Dry quartz sand

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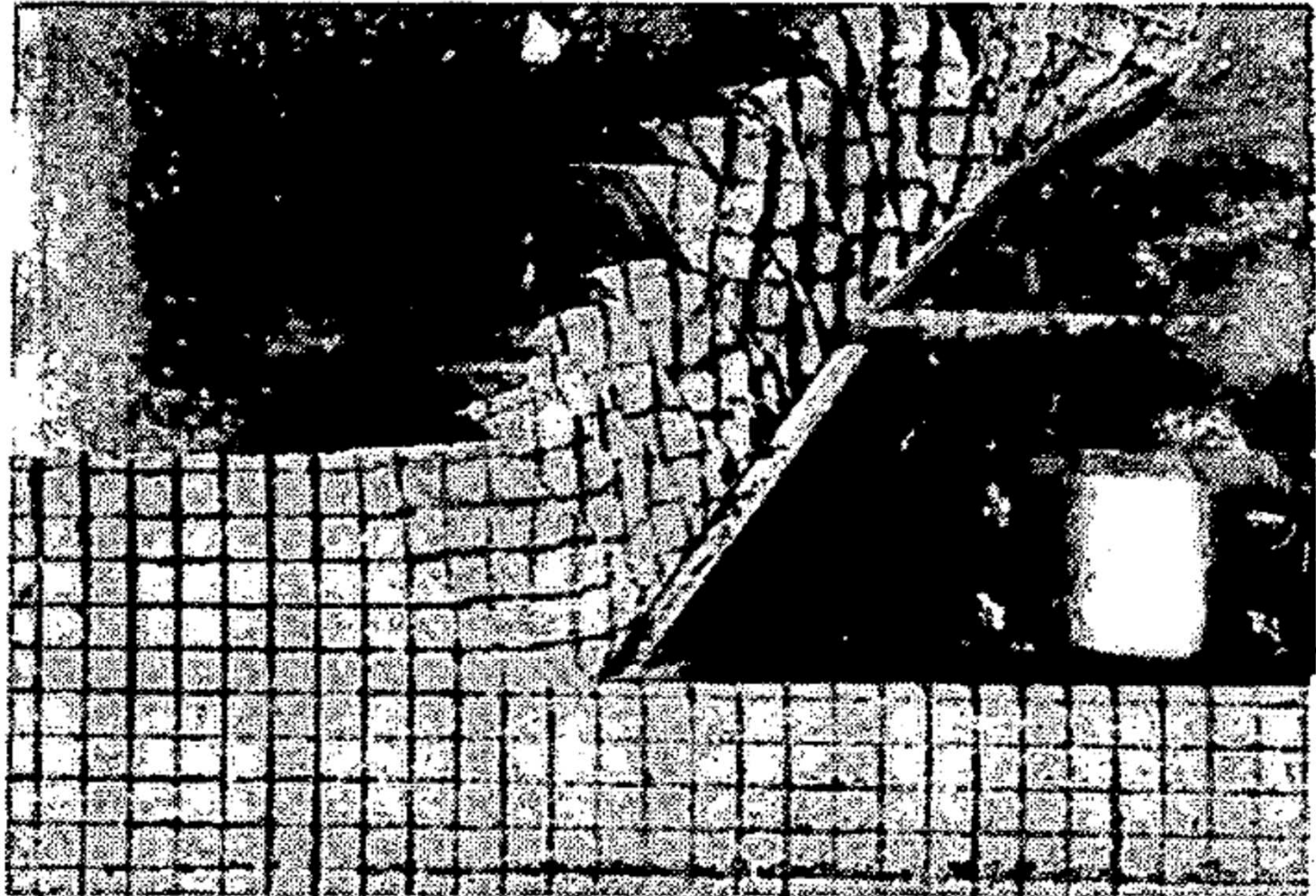
Hatamura Chijiwa Wet Quarts Sand



(b) Wet quartz sand



Hatamura Chijiwa Plastic Bentonite

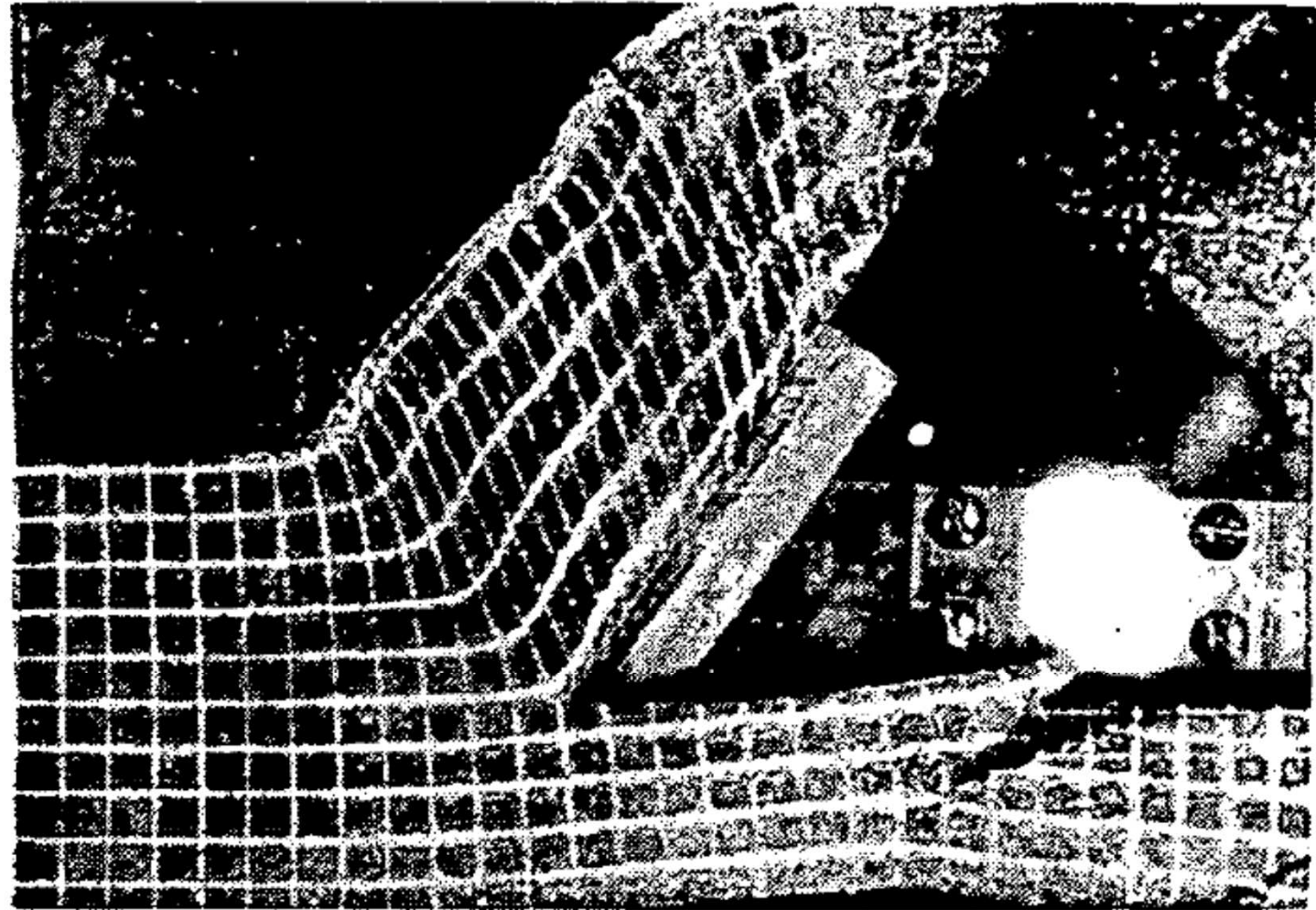


(c) Plastic bentonite

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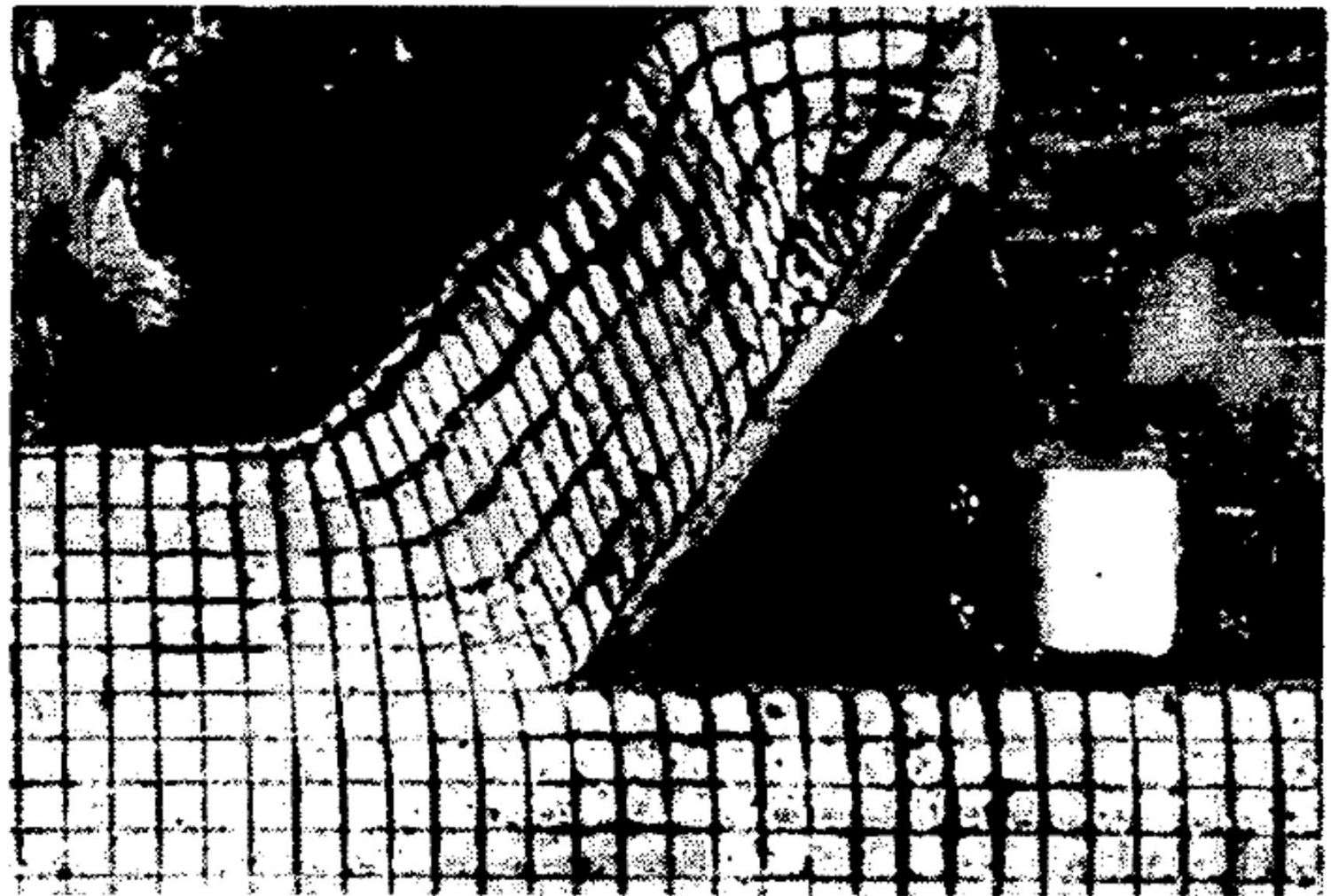
Hatamura Chijiwa Plastic Loam



(d) Plastic loam

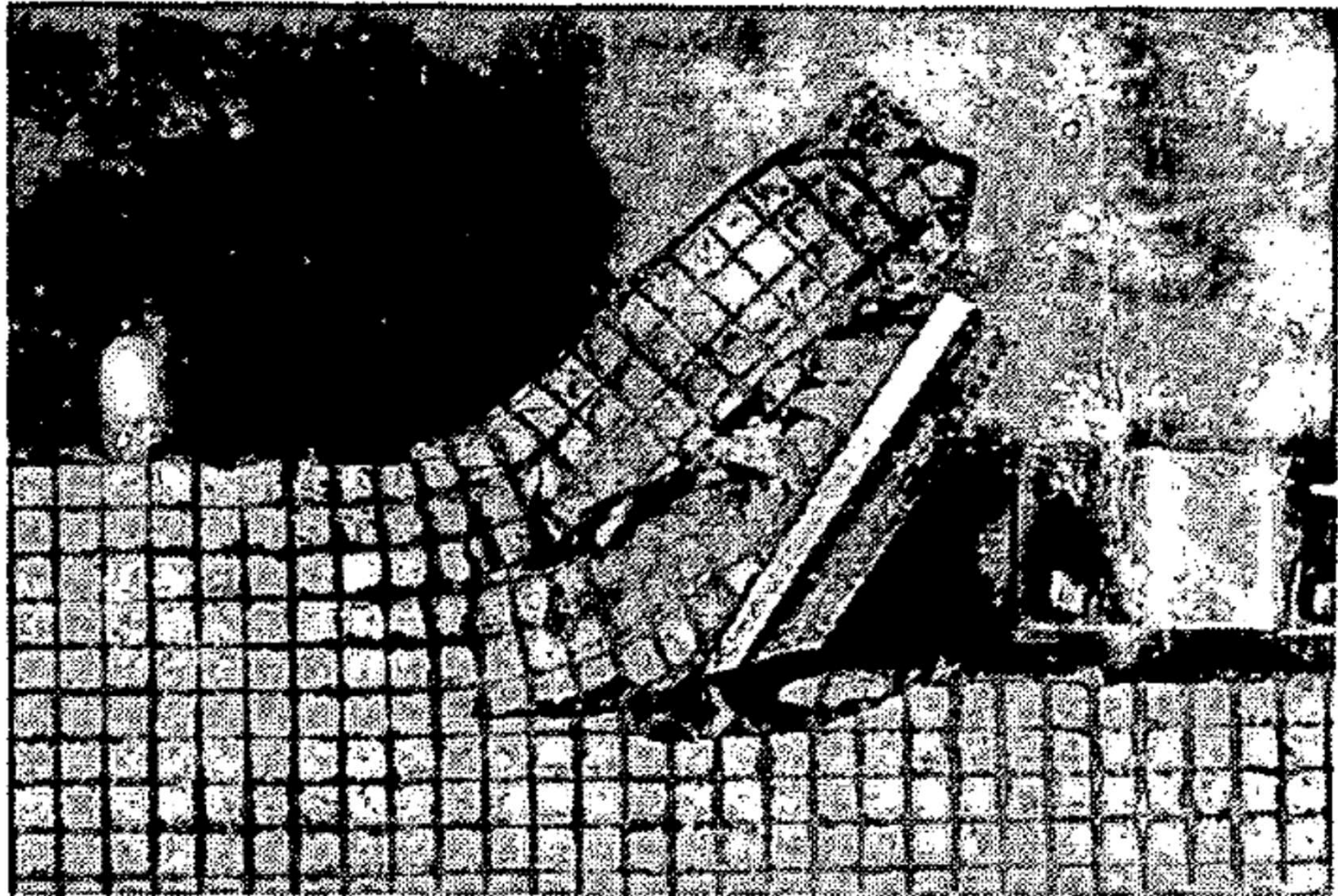
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Hatamura Chijiwa Plastic Clay



(e) Plastic clay

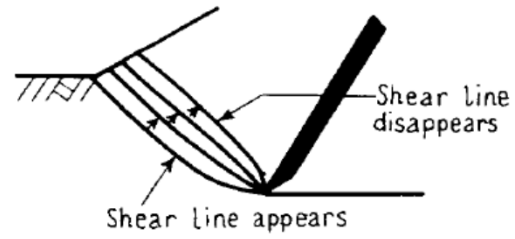
Hatamura Chijiwa Compacted Loam



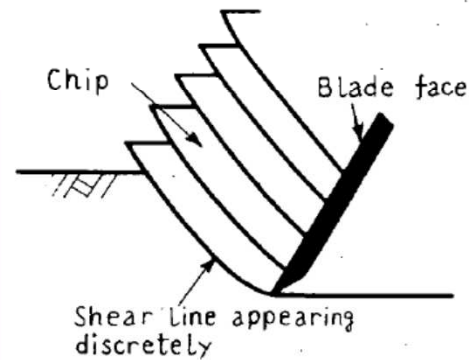
(f) Compacted loam

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Hatamura Chijiwa Failure Types



(a) Appearance of shear line



(b) Accumulation of chips

Fig. 4 Shear type

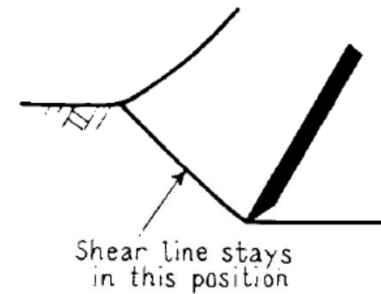


Fig. 5 Flow type

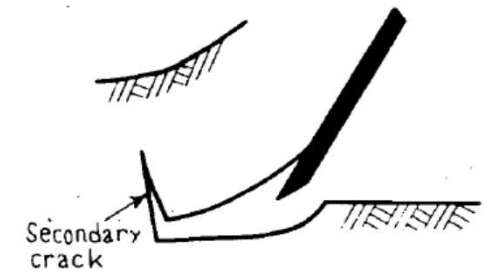
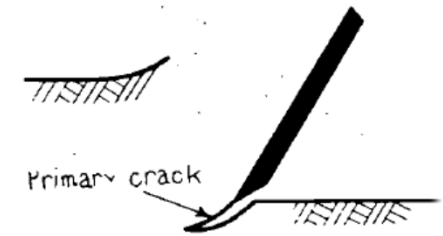
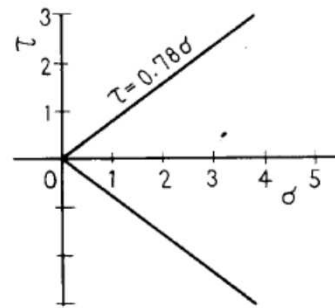
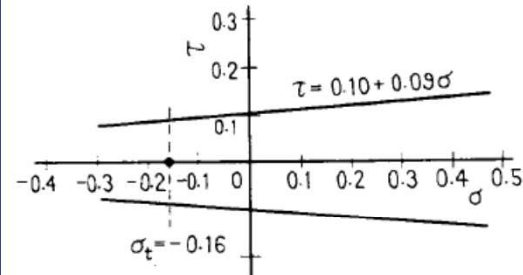


Fig. 6 Tear type

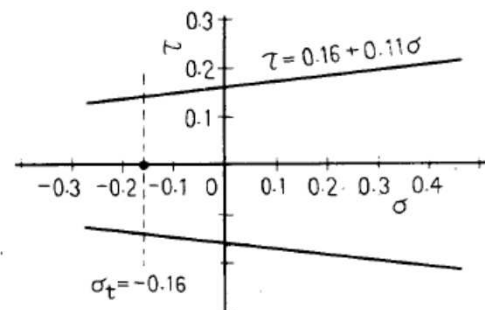
Hatamura Chijiwa Mohr Circles



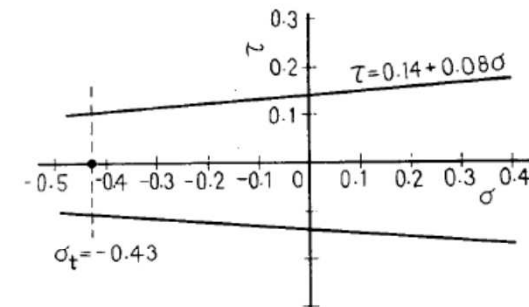
(1) Dry quartz sand



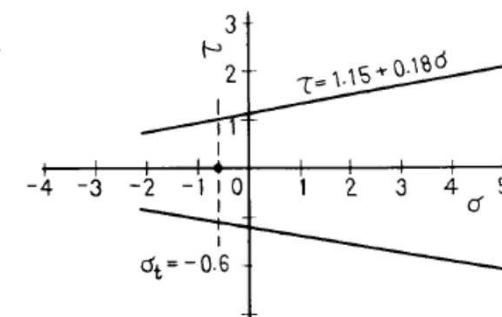
(2) Plastic bentonite



(3) Plastic loam



(4) Plastic clay



(5) Compacted loam

τ : shearing stress
 σ : normal stress
 σ_t : tensile strength

} kg/cm^2

Fig. 11 Failure conditions of soils

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Hatamura Chijiwa Conditions

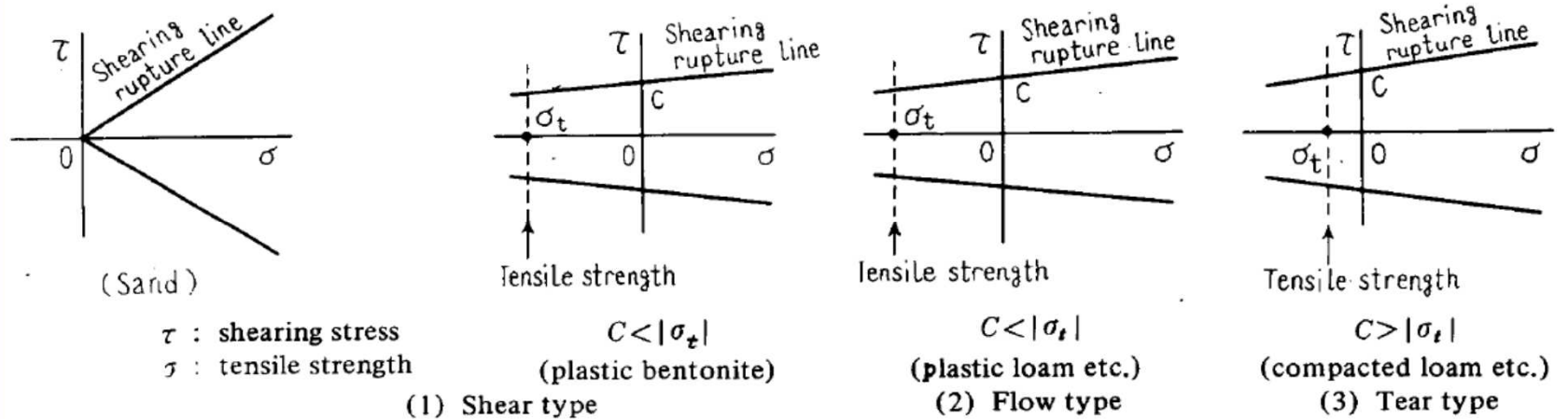


Fig. 12 Relationship between cutting types and failure conditions of soils

Hatamura Chijiwa Stresses

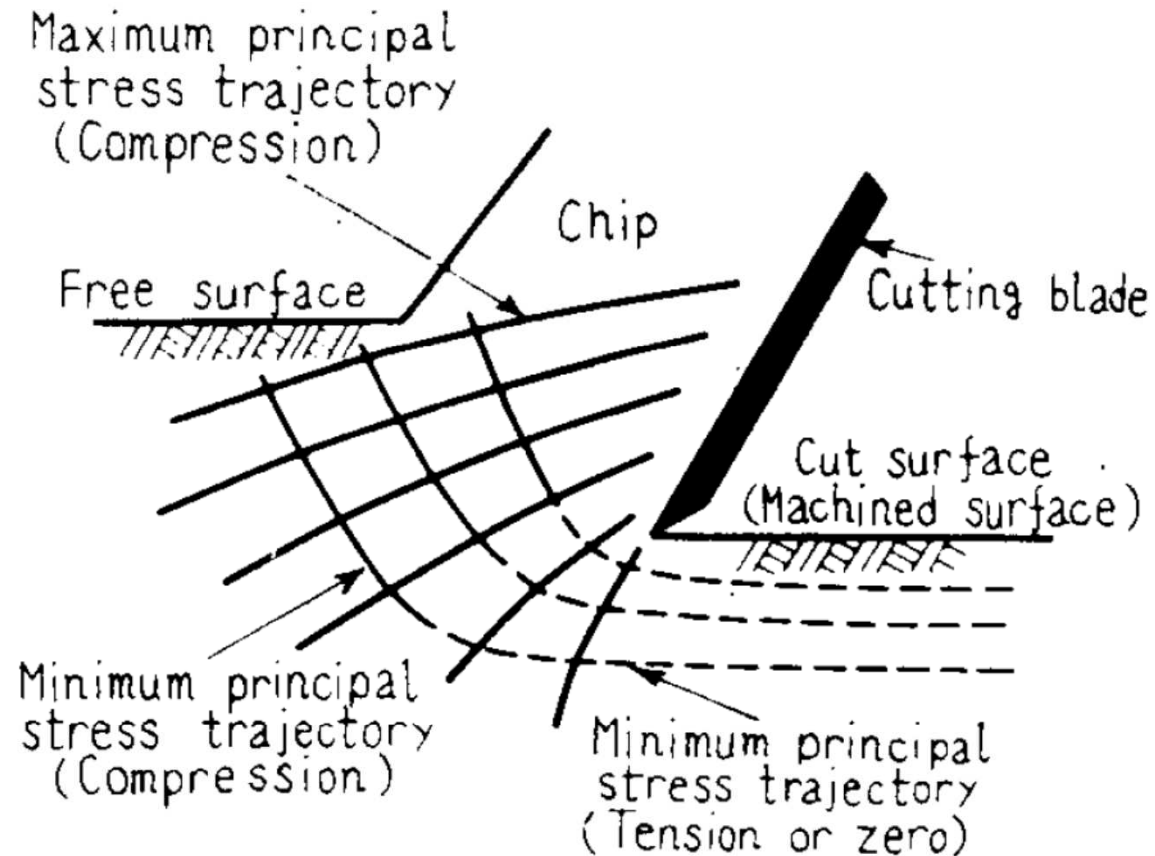
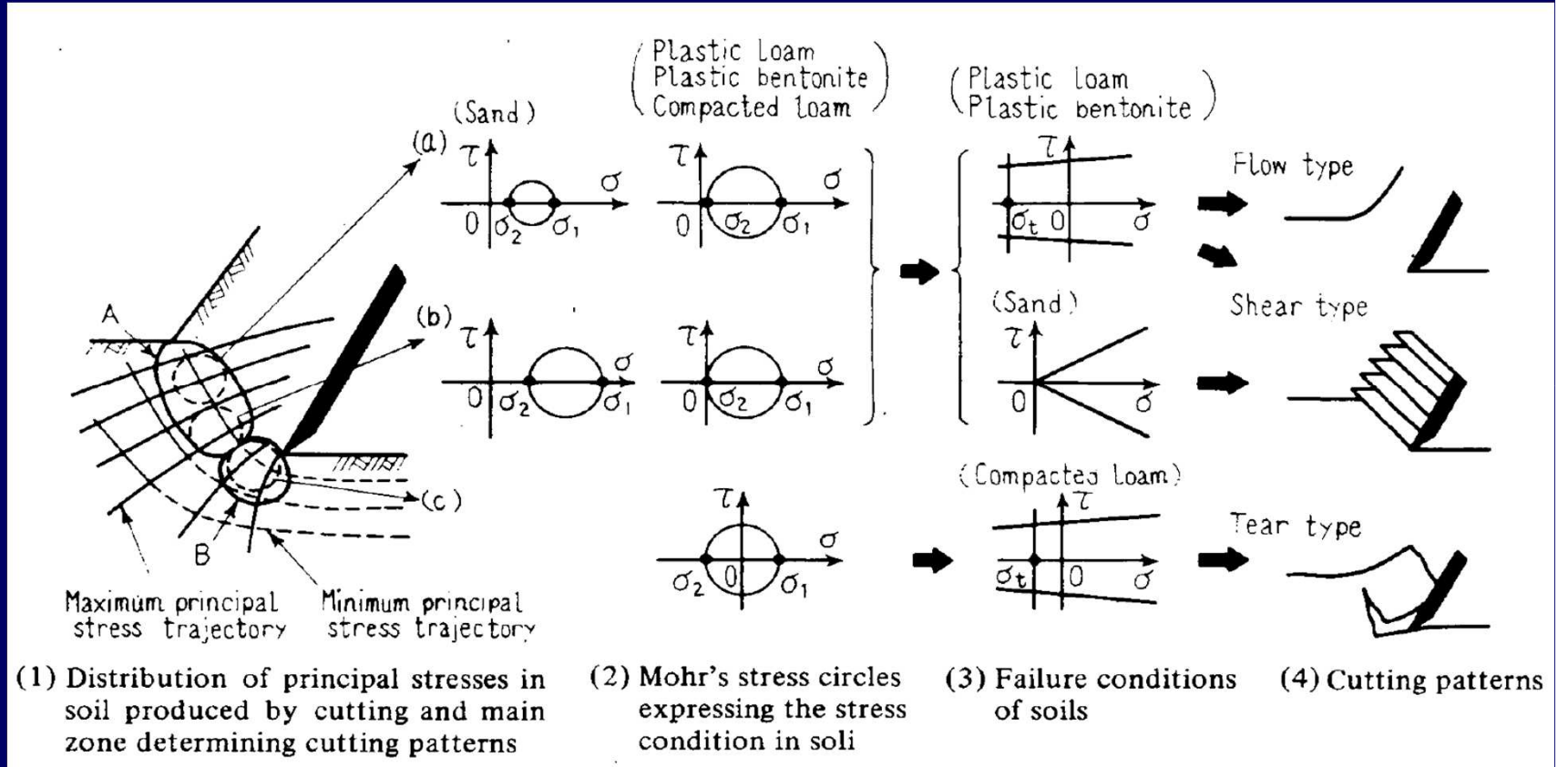
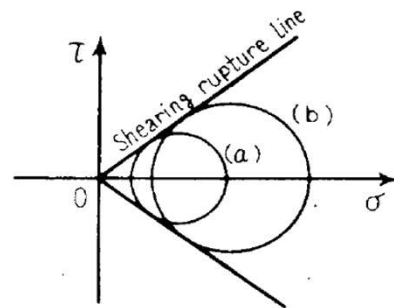


Fig. 14 Idealized distribution of principal stresses in soil produced by cutting

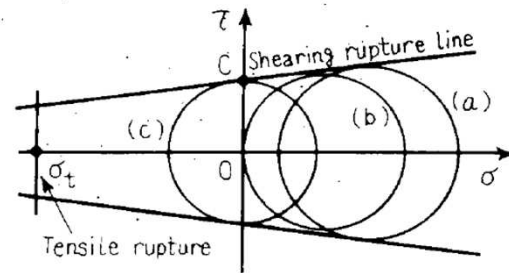
Hatamura Chijiwa Mechanisms



Hatamura Chijiwa Types



(a) Sand etc.



(b) Plastic bentonite etc.

Fig. 16 Relationship between failure conditions and stress situations in soil presenting shear type

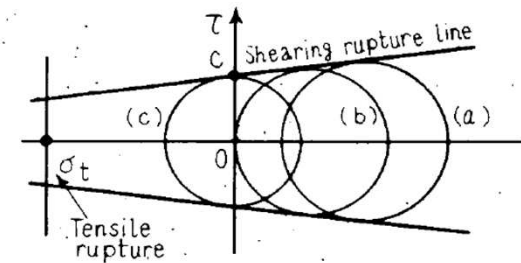


Fig. 17 Relationship between rupture conditions and stress situations in soil presenting flow type

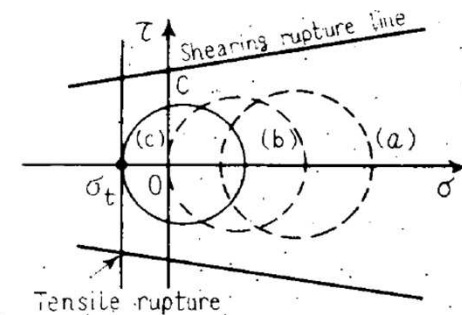
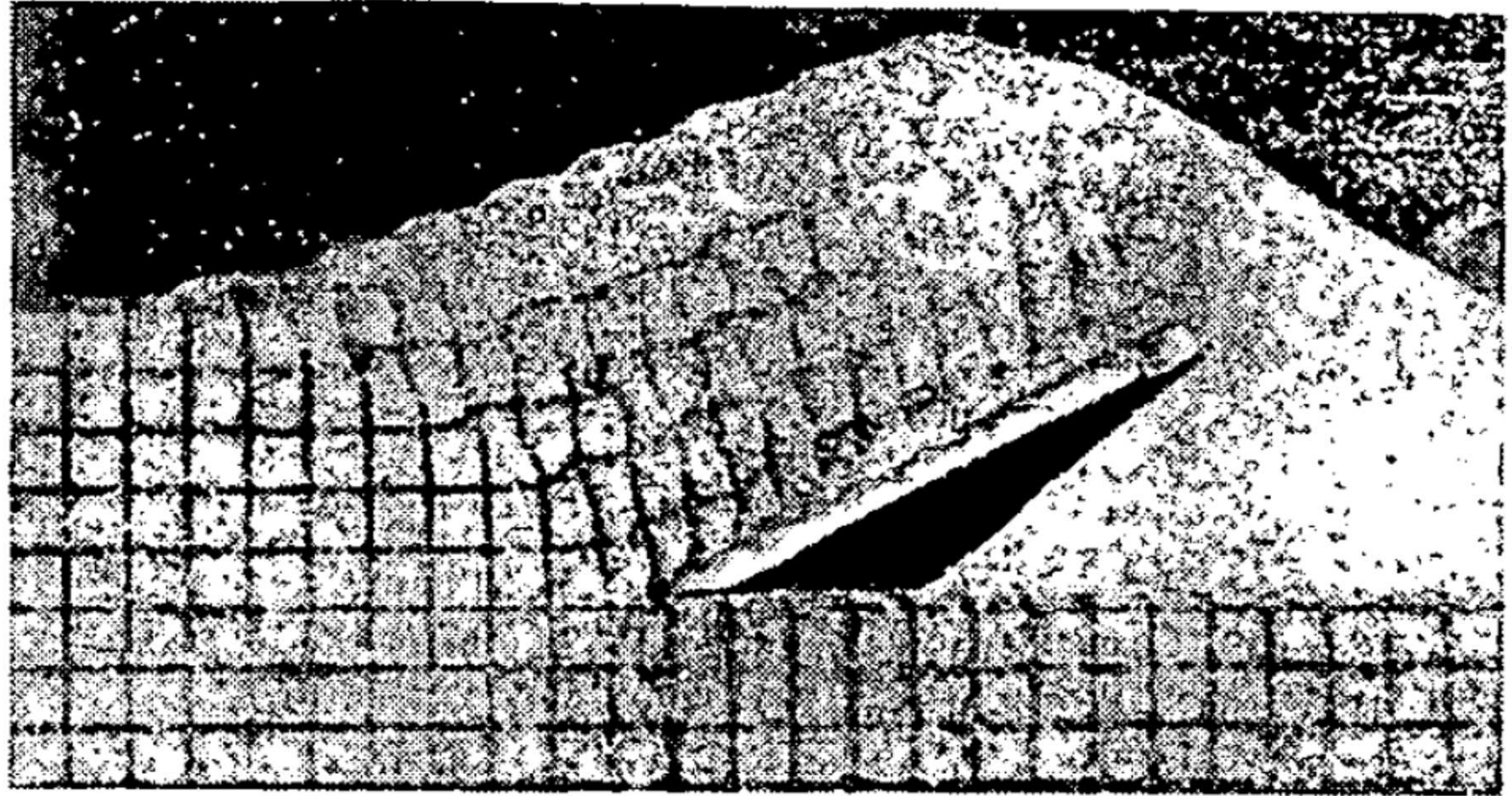


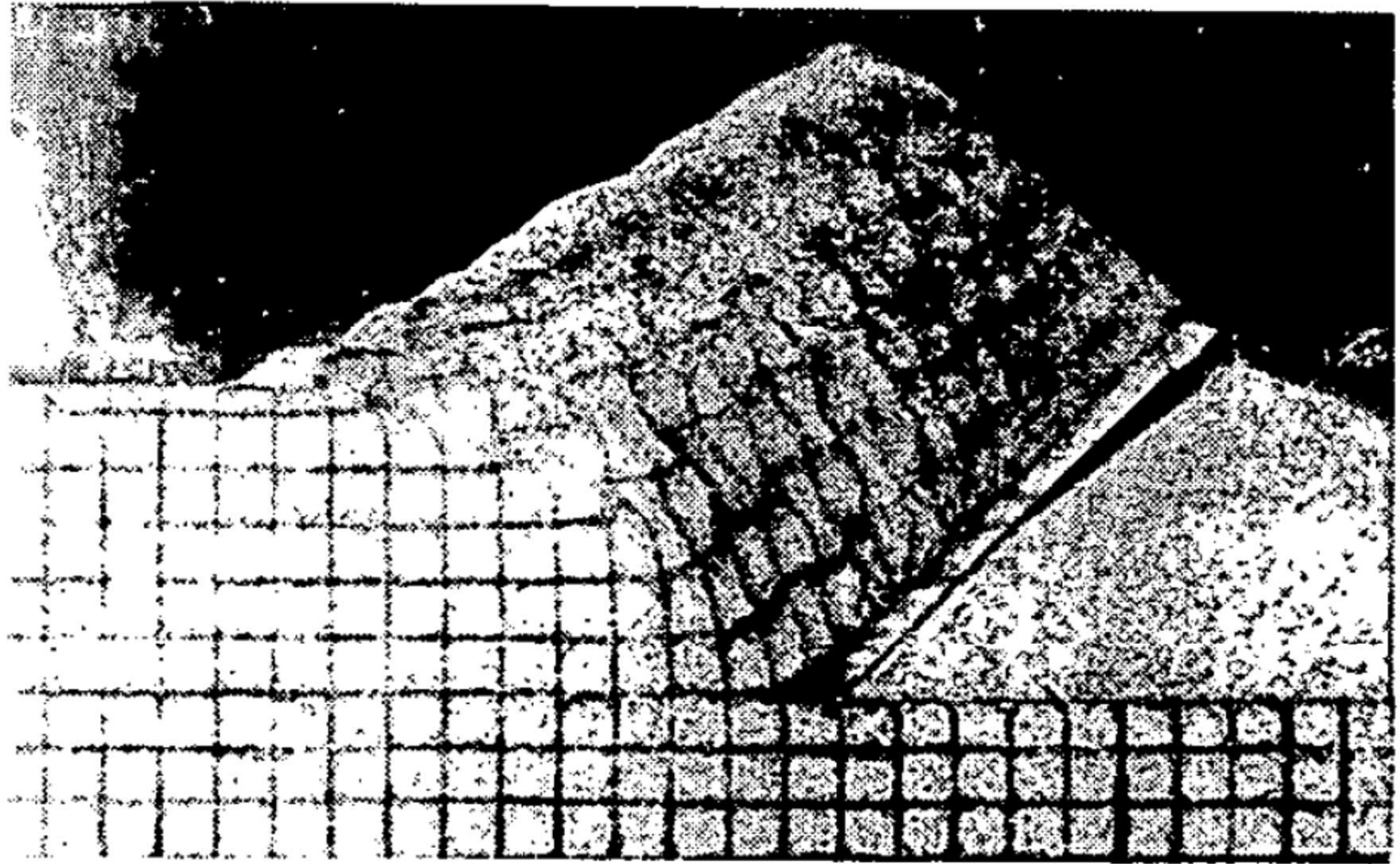
Fig. 18 Relationship between failure conditions and stress situations in soil presenting tear type

Hatamura Chijiwa Dry Sand 30 deg.



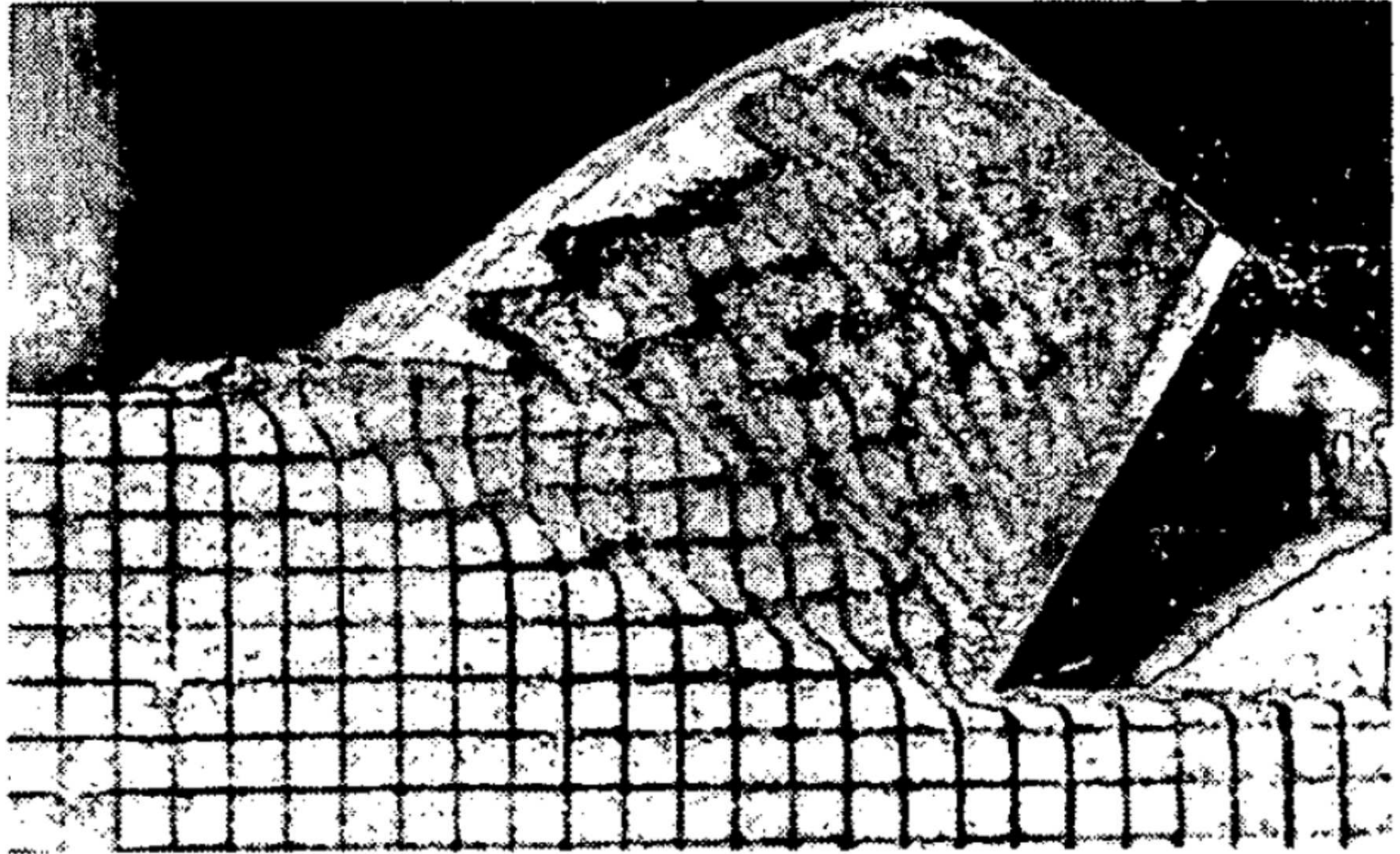
(a) Cutting angle $\alpha = 30^\circ$

Hatamura Chijiwa Dry Sand 45 deg.



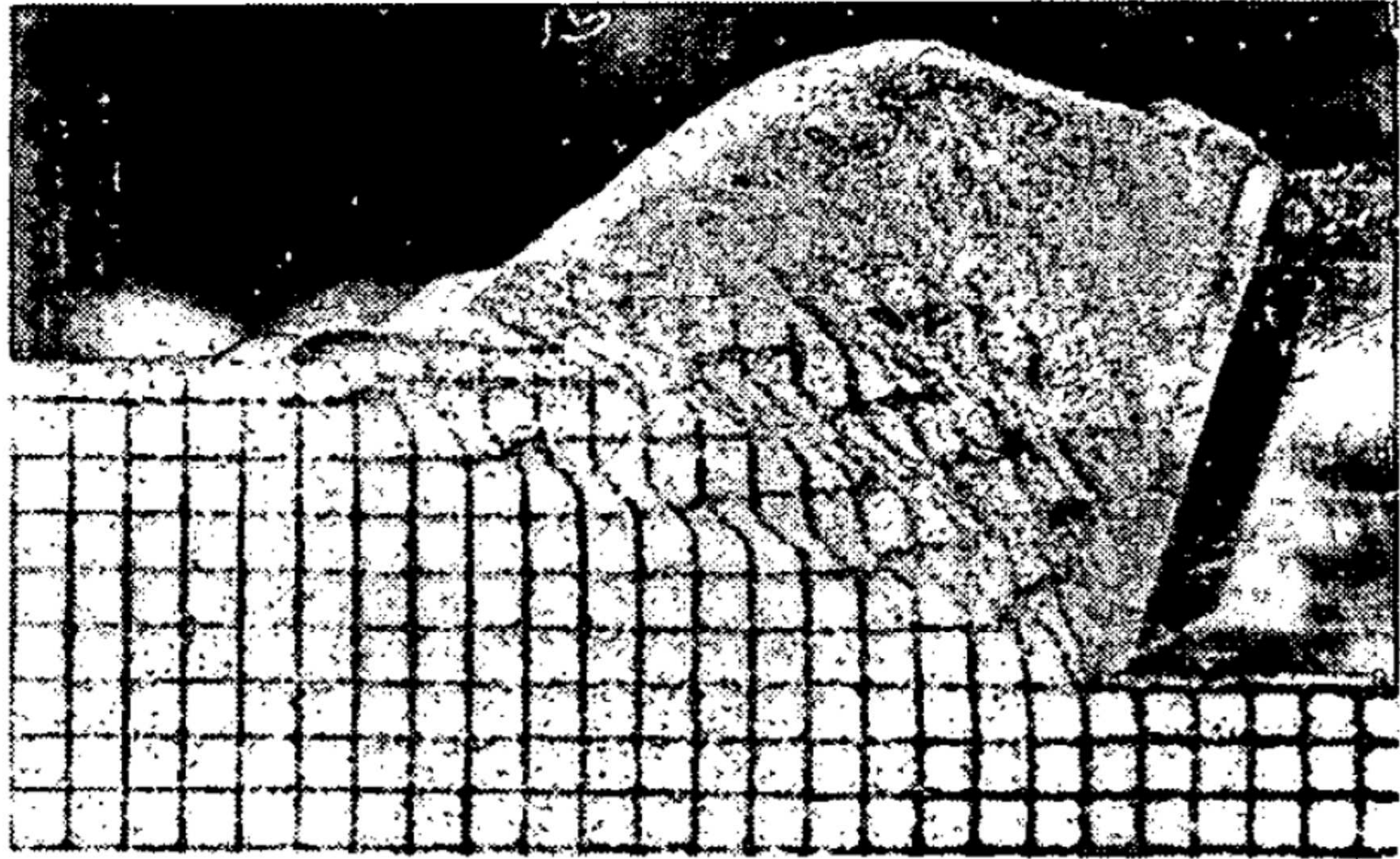
(b) Cutting angle $\alpha = 45^\circ$.

Hatamura Chijiwa Dry Sand 60 deg.



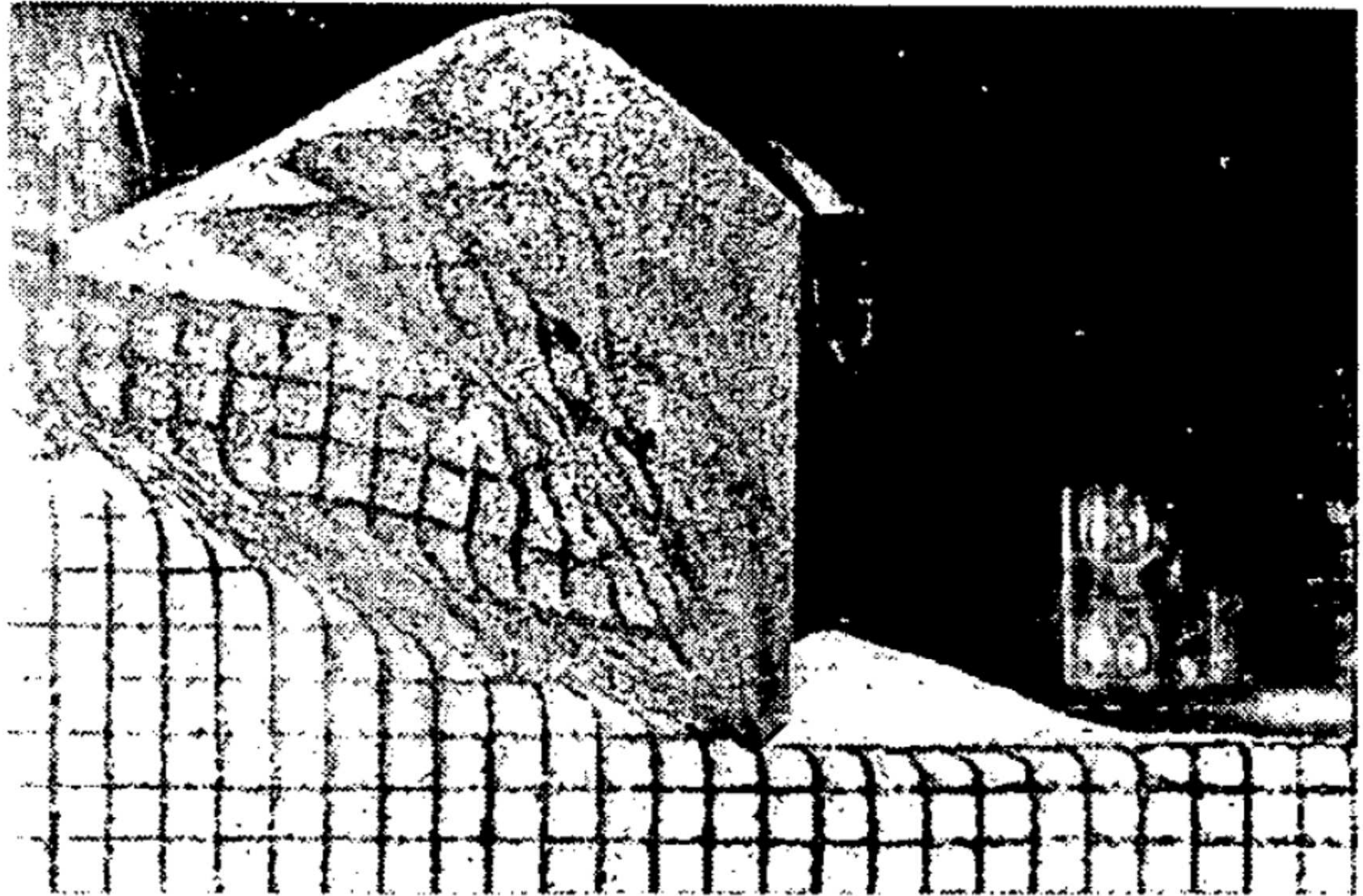
(c) Cutting angle $\alpha = 60^\circ$

Hatamura Chijiwa Dry Sand 75 deg.



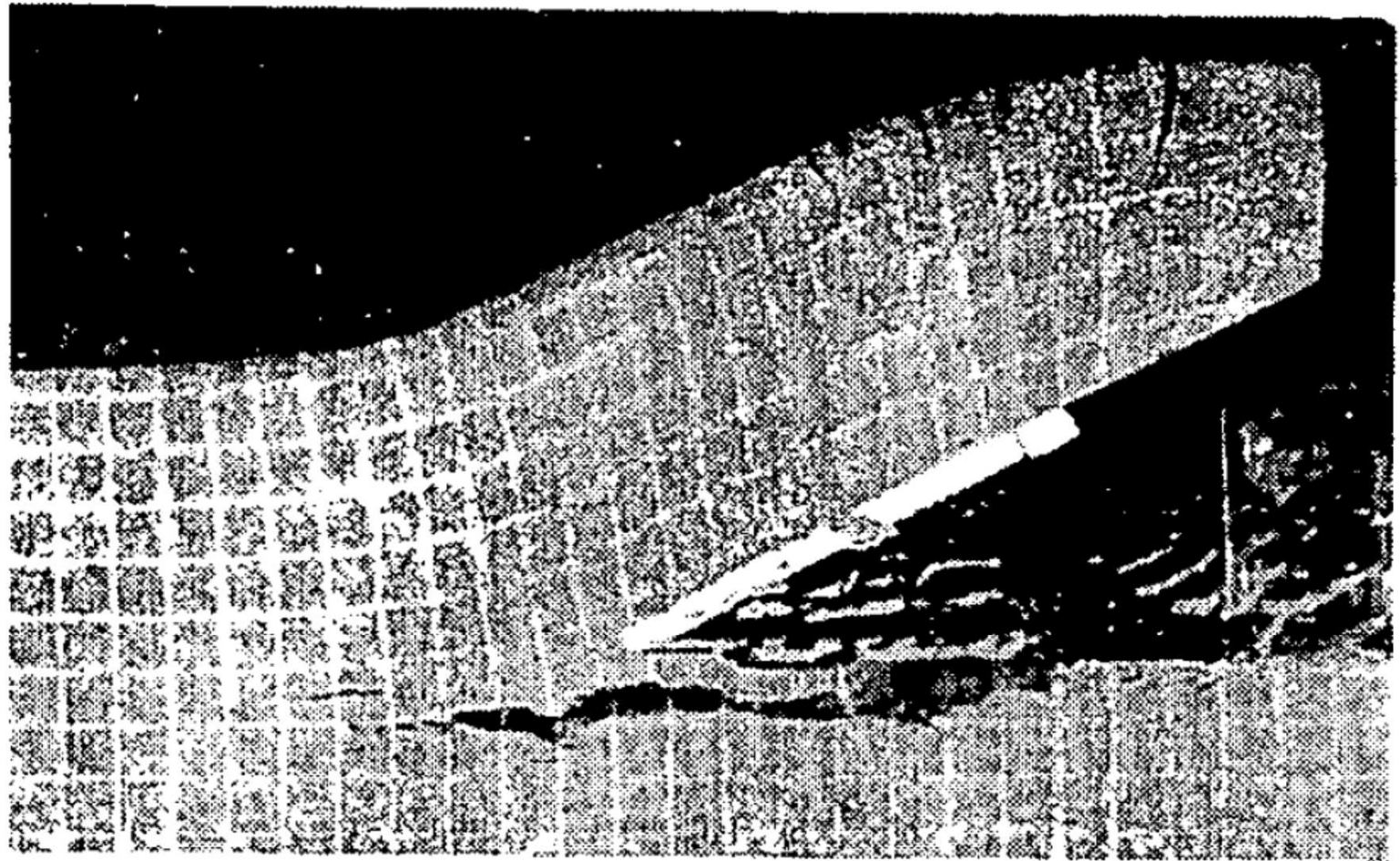
(d) Cutting angle $\alpha = 75^\circ$

Hatamura Chijiwa Dry Sand 90 deg.



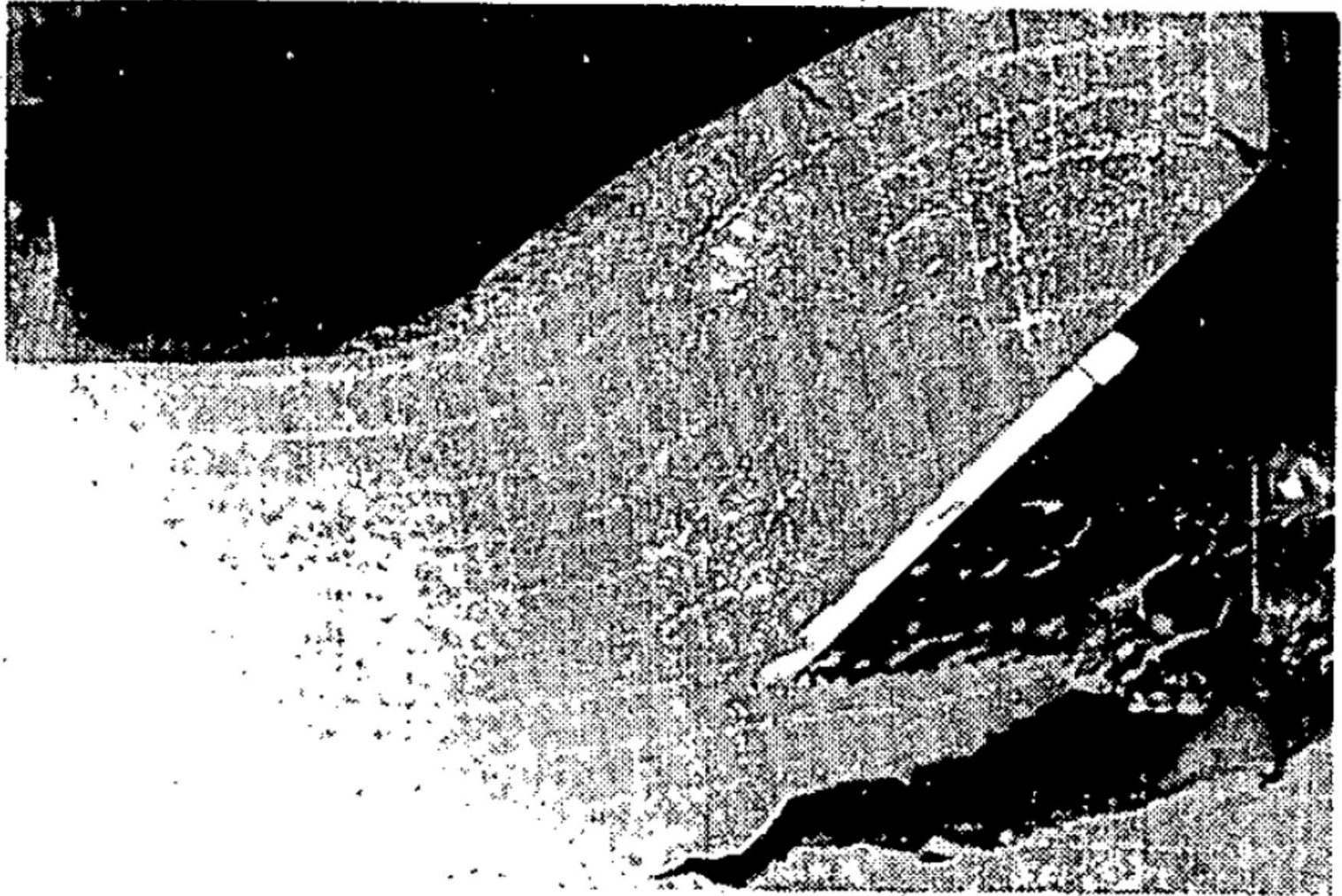
(e) Cutting angle $\alpha = 90^\circ$

Hatamura Chijiwa Plastic Loam 30 deg.



(a) Cutting angle $\alpha = 30^\circ$

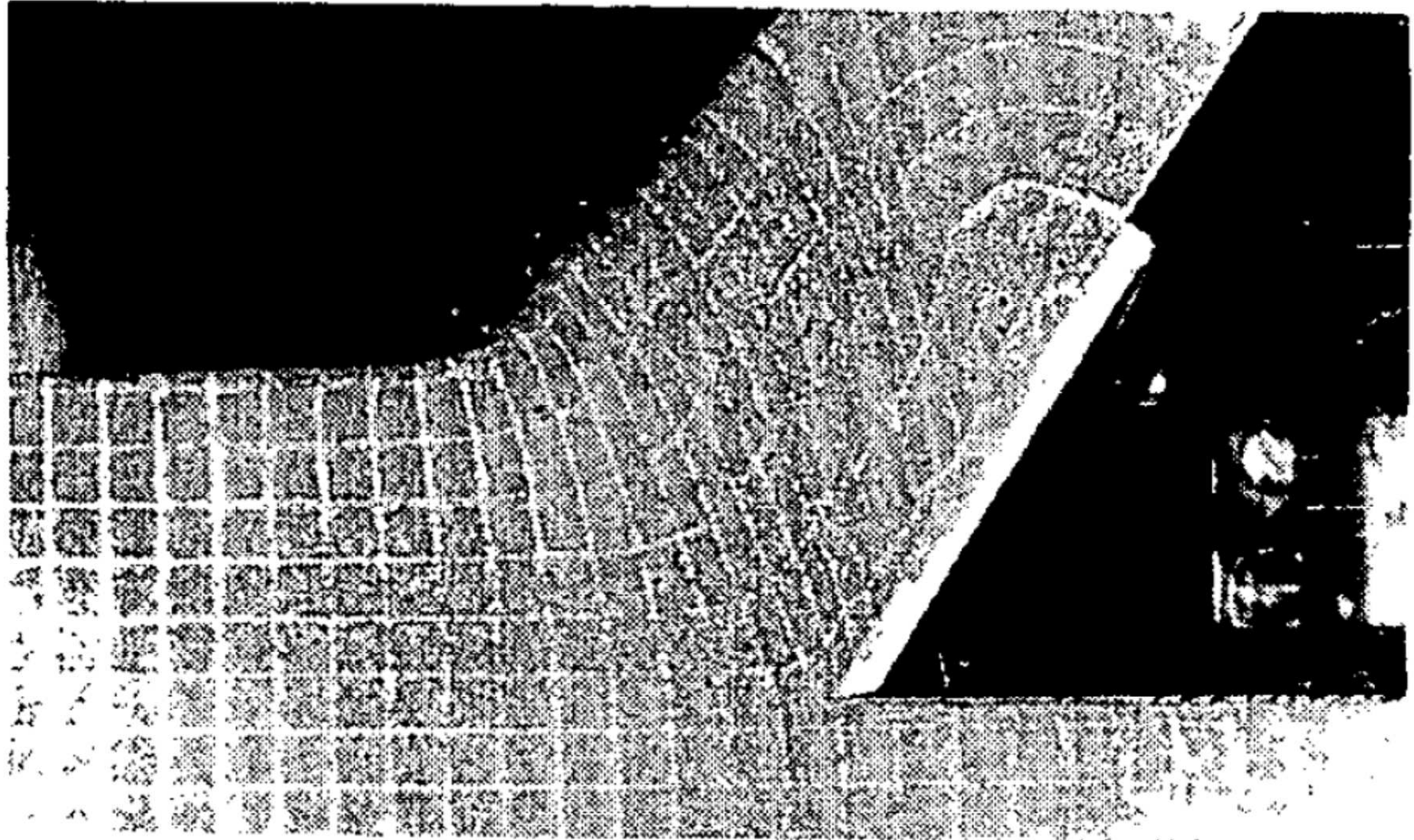
Hatamura Chijiwa Plastic Loam 45 deg.



(b) Cutting angle $\alpha = 45^\circ$

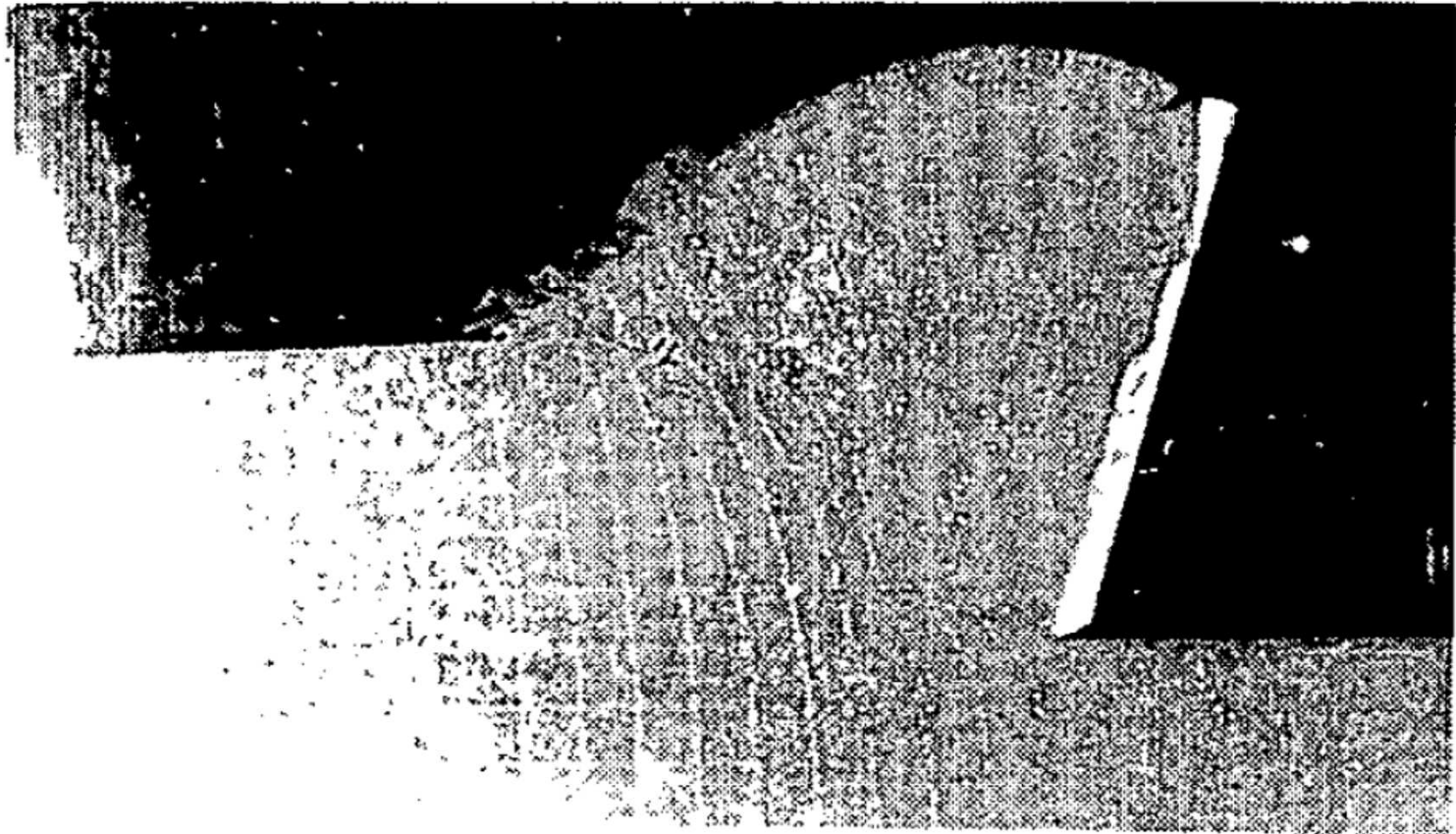
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Hatamura Chijiwa Plastic Loam 60 deg.



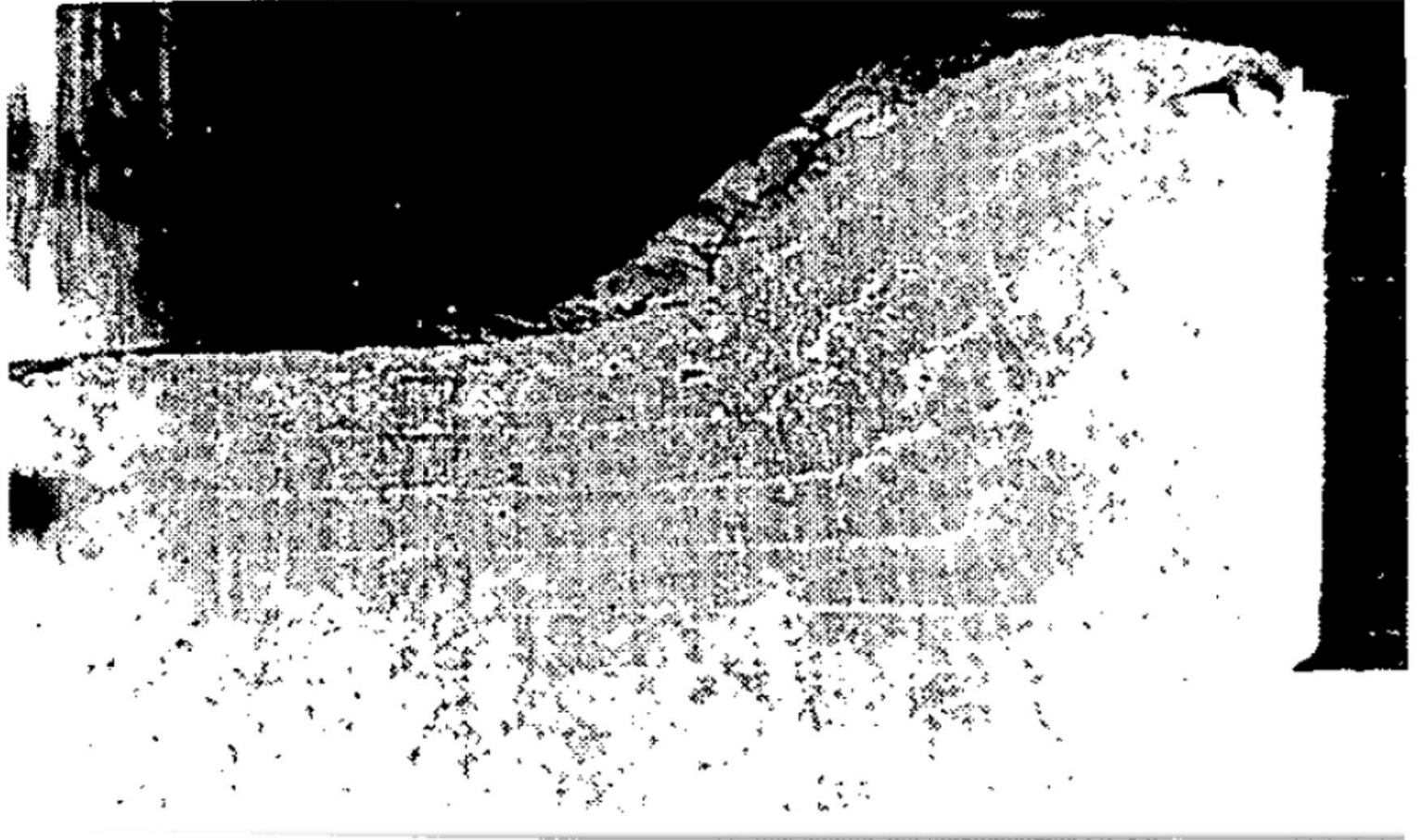
(c) Cutting angle $\alpha = 60^\circ$

Hatamura Chijiwa Plastic Loam 75 deg.



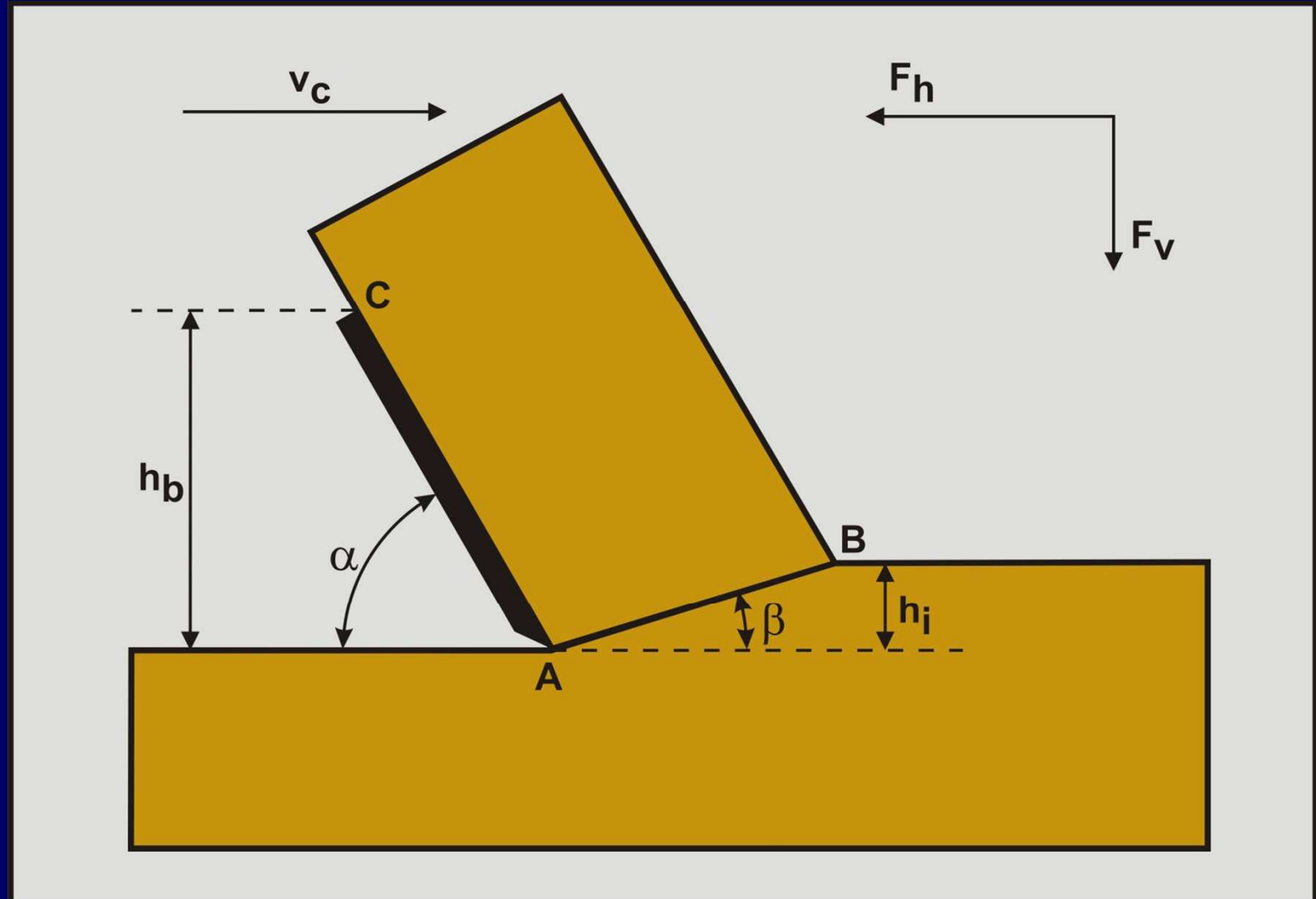
(d) Cutting angle $\alpha = 75^\circ$

Hatamura Chijiwa Plastic Loam 90 deg.

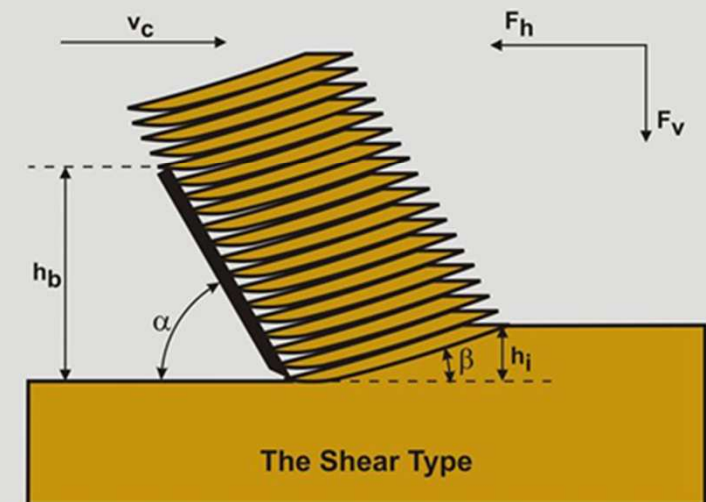
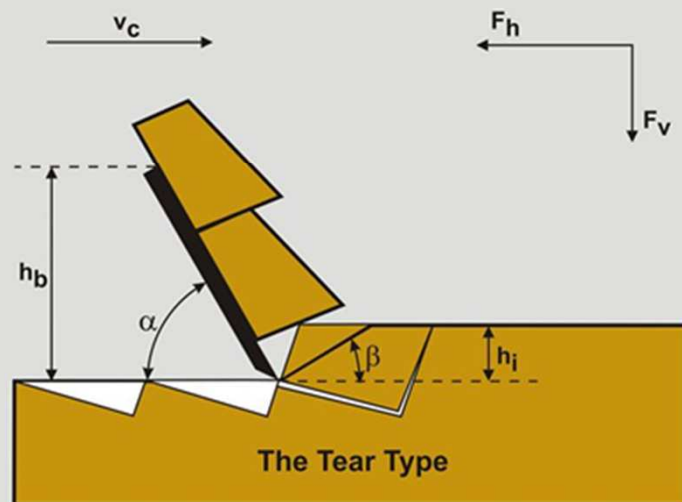
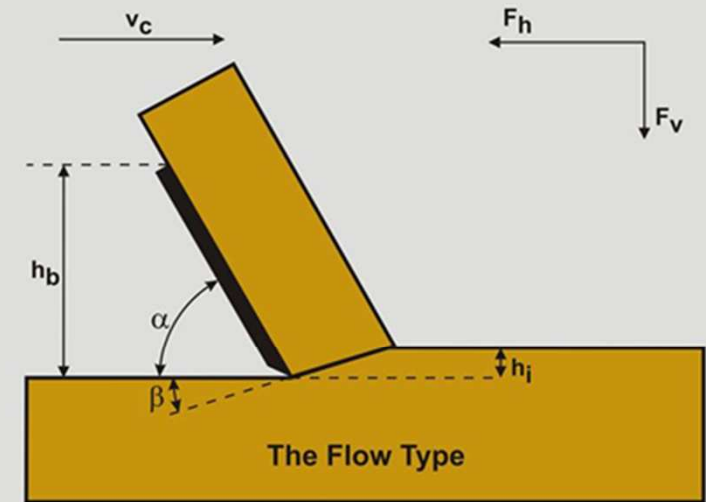
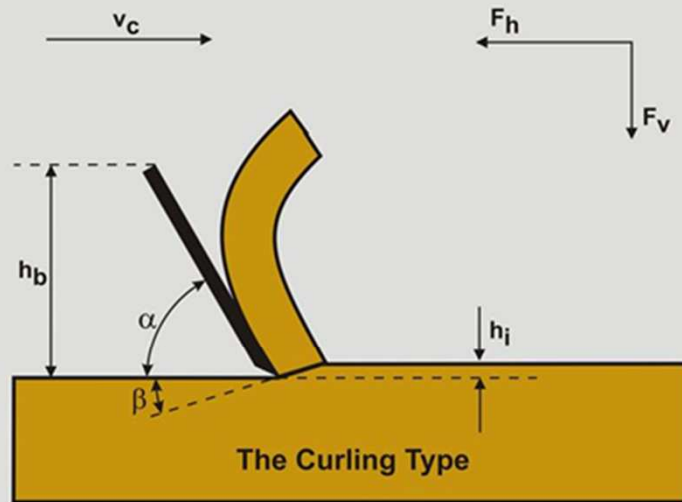


(e) Cutting angle $\alpha = 90^\circ$

Definitions



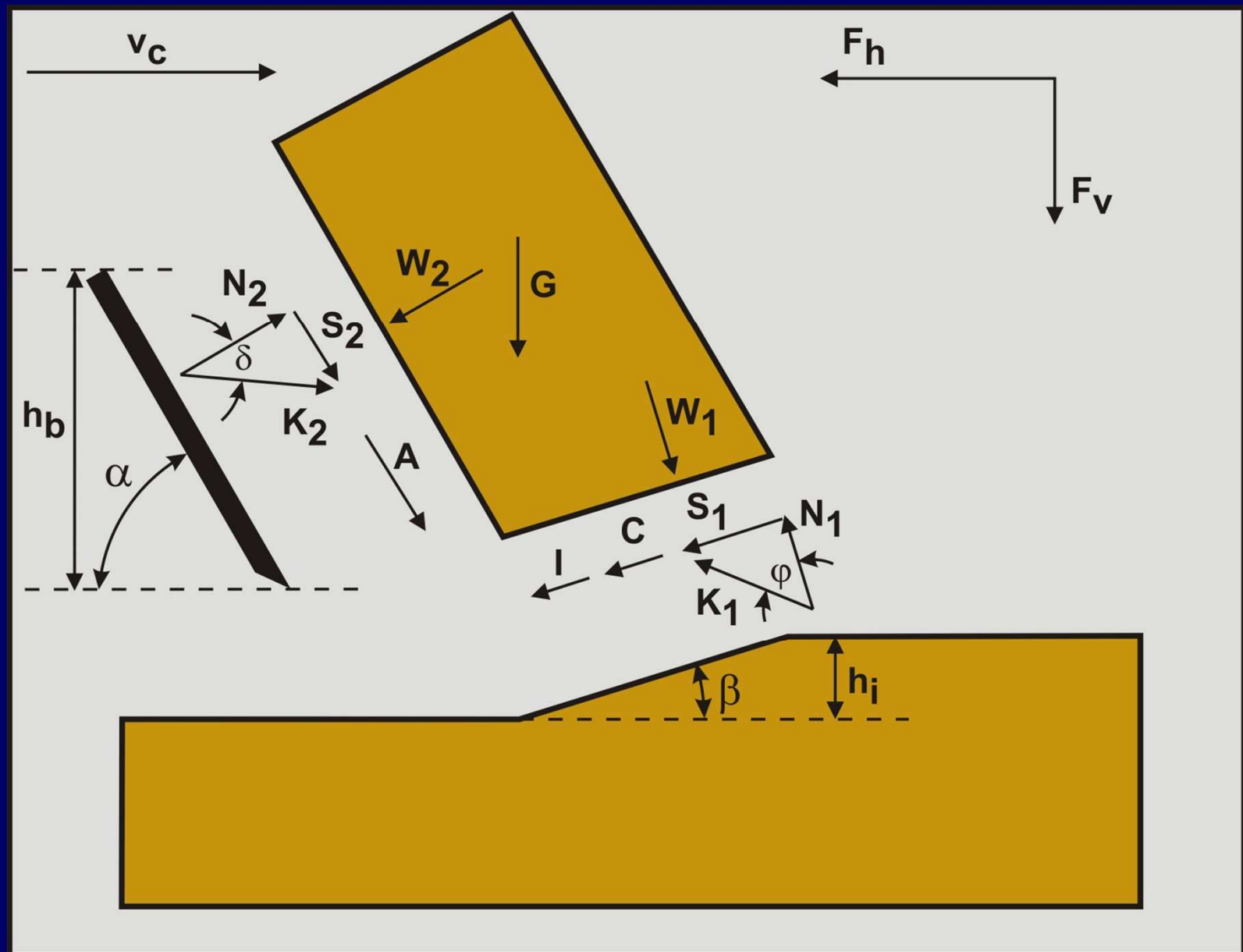
Cutting Mechanisms





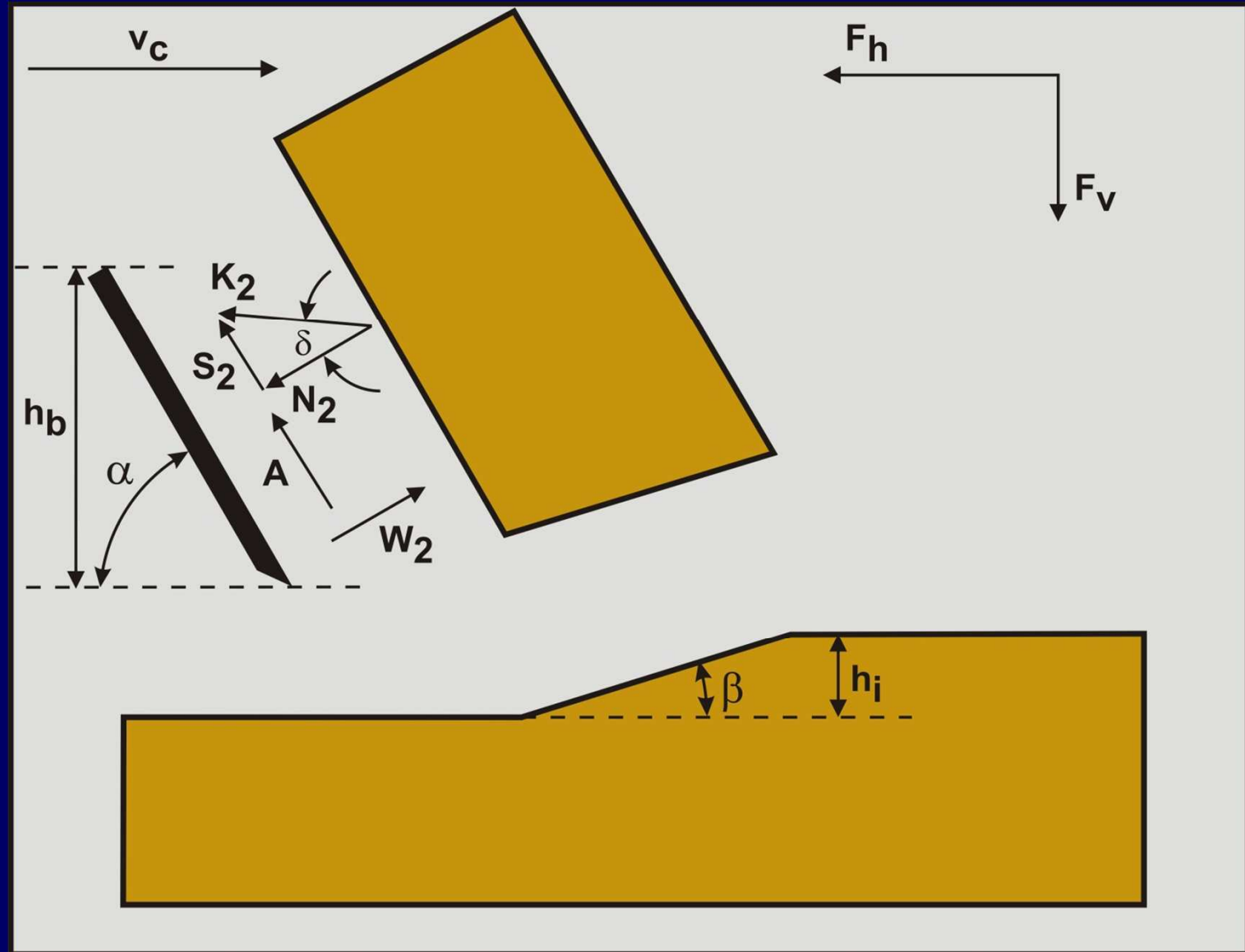
Cutting Forces

Forces on the Layer Cut

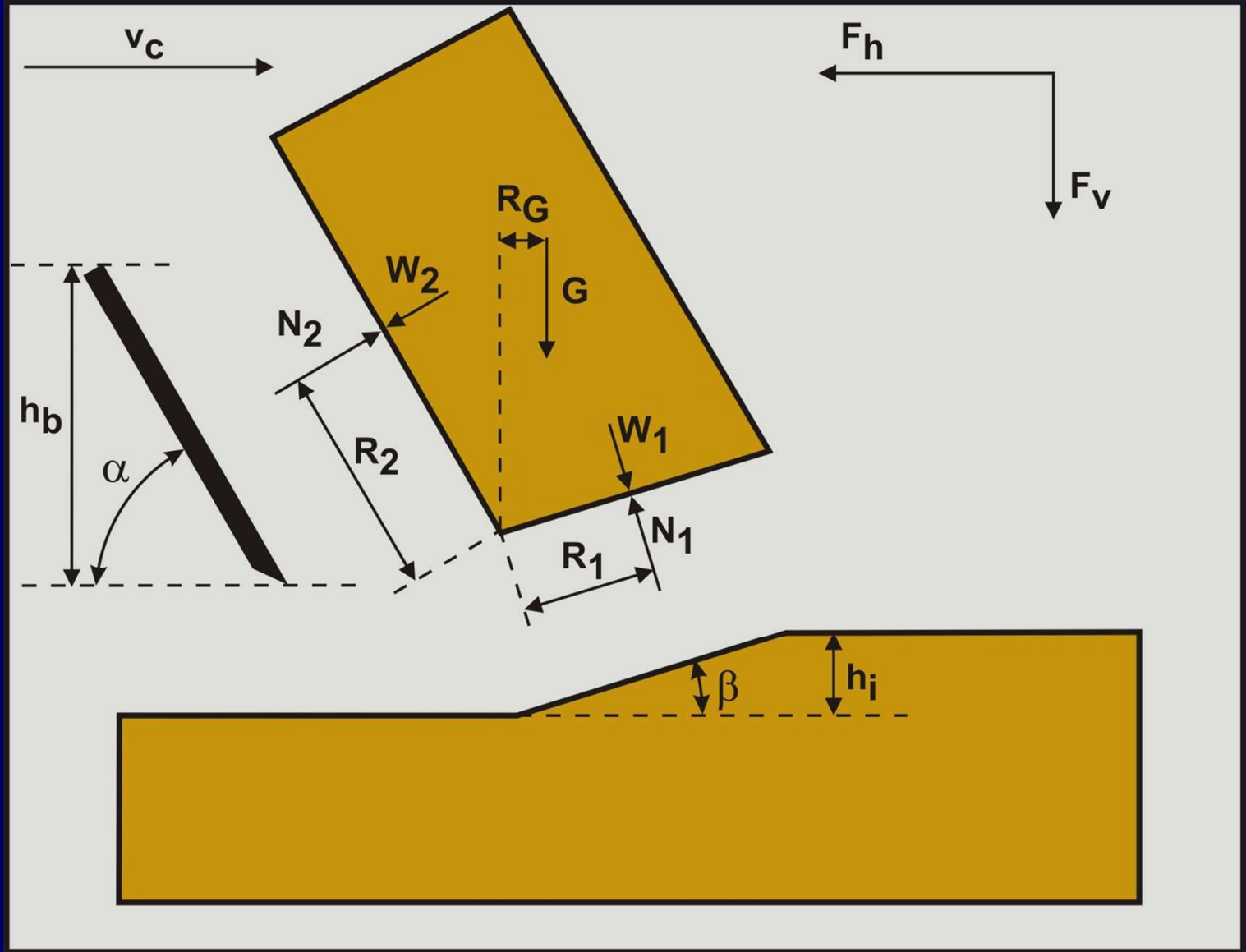


Faculty of 3mE - Dredging Engineering

Forces on the Blade



Moments



Resulting Equations

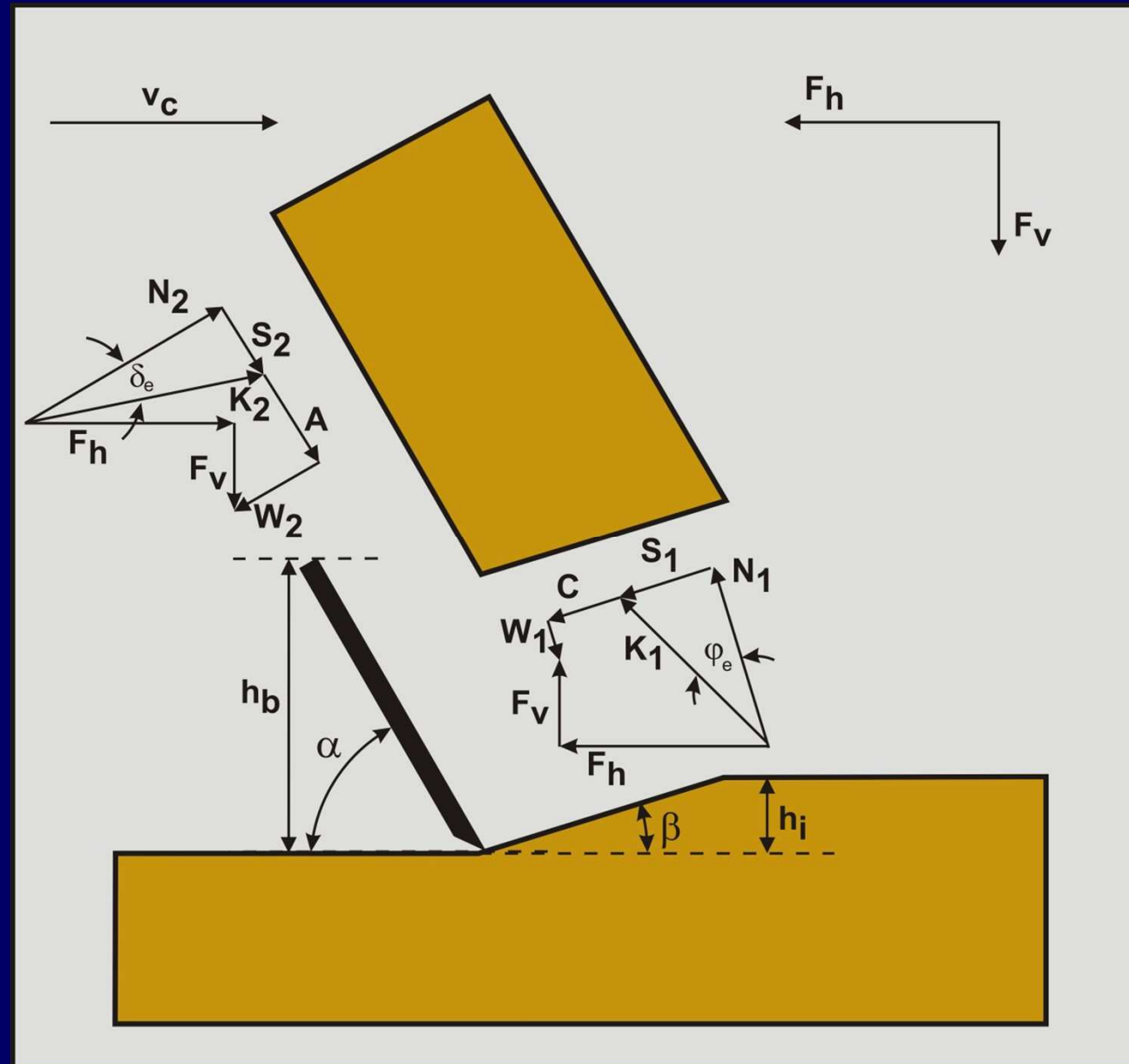
$$K_2 = \frac{W_2 \cdot \sin(\alpha + \beta + \varphi) + W_1 \cdot \sin(\varphi) + G \cdot \sin(\beta + \varphi)}{\sin(\alpha + \beta + \delta + \varphi)}$$

$$\frac{+I \cdot \cos(\varphi) + C \cdot \cos(\varphi) - A \cdot \cos(\alpha + \beta + \varphi)}{\sin(\alpha + \beta + \delta + \varphi)}$$

$$F_h = -W_2 \cdot \sin(\alpha) + K_2 \cdot \sin(\alpha + \delta) + A \cdot \cos(\alpha)$$

$$F_v = -W_2 \cdot \cos(\alpha) + K_2 \cdot \cos(\alpha + \delta) - A \cdot \sin(\alpha)$$

Vector Diagram



Faculty of 3mE - Dredging Engineering

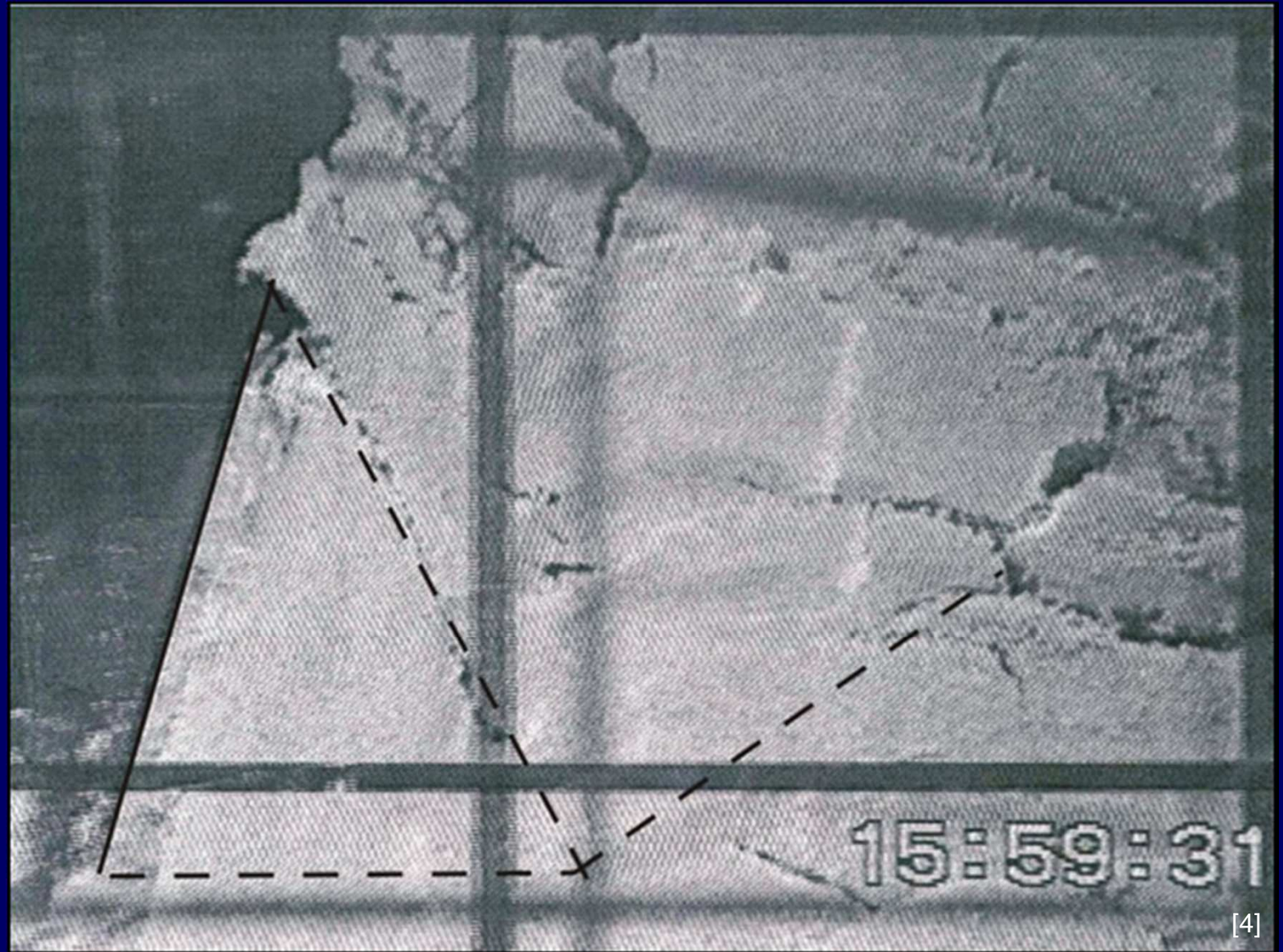
Which Terms in Which Soil

| | Gravity | Inertia | Pore Pressure | Cohesion | Adhesion | Friction |
|------------------|---------|---------|---------------|----------|----------|----------|
| Dry sand | | | | | | |
| Saturated sand | | | | | | |
| Clay | | | | | | |
| Atmospheric rock | | | | | | |
| Hyperbaric rock | | | | | | |



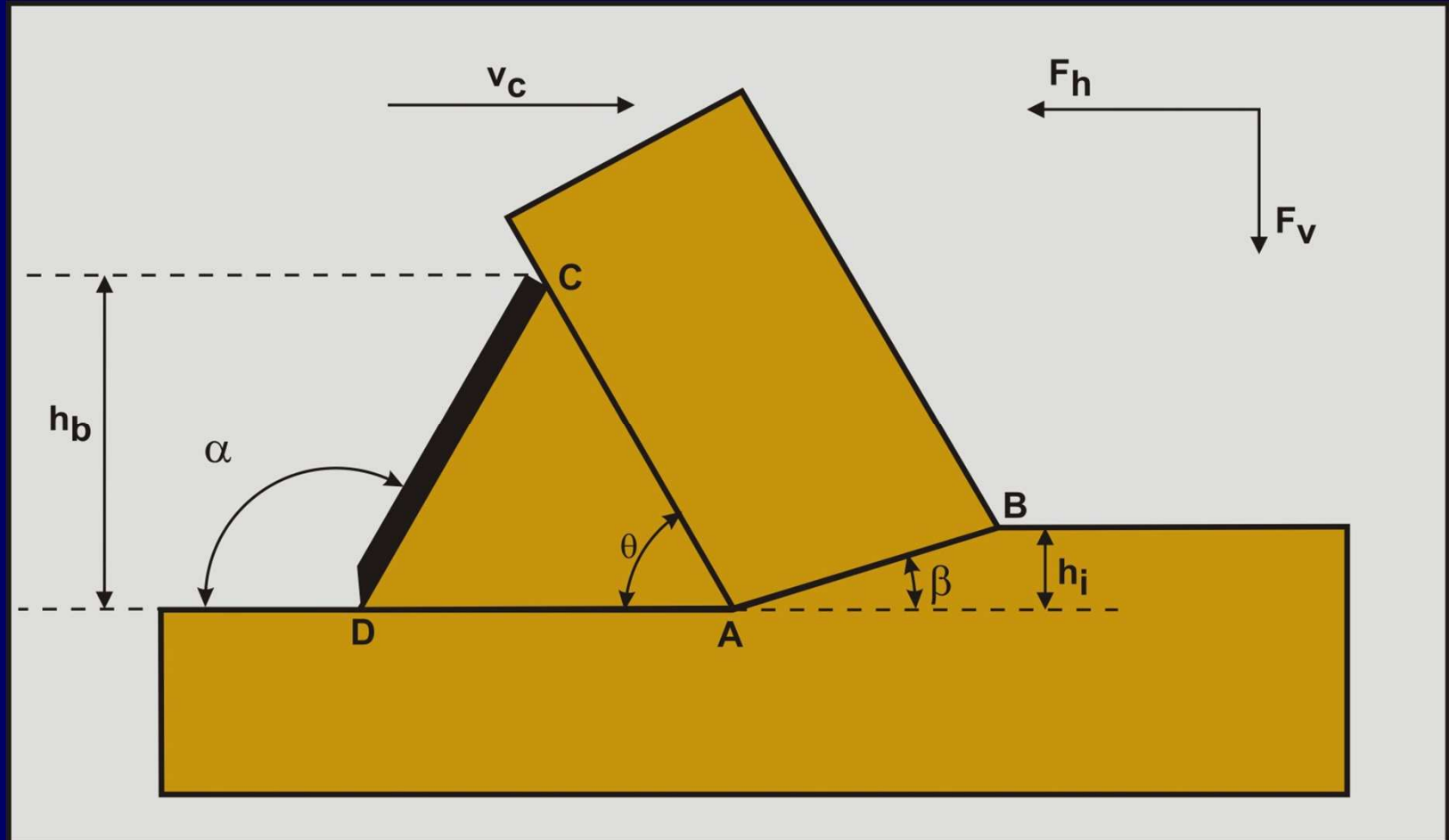
Cutting Forces with Wedge

A Wedge in Dry Sand

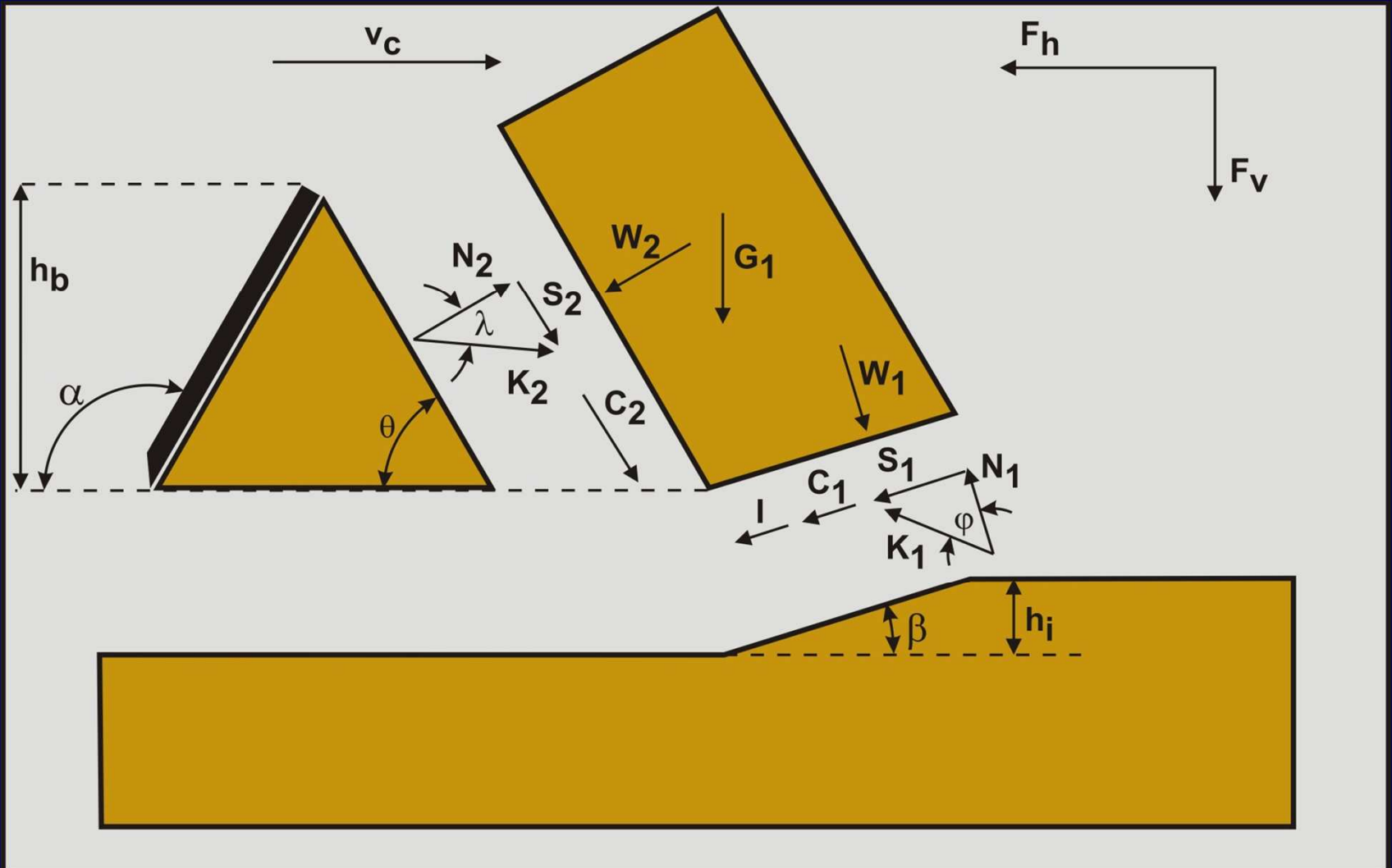


Faculty of 3mE - Dredging Engineering

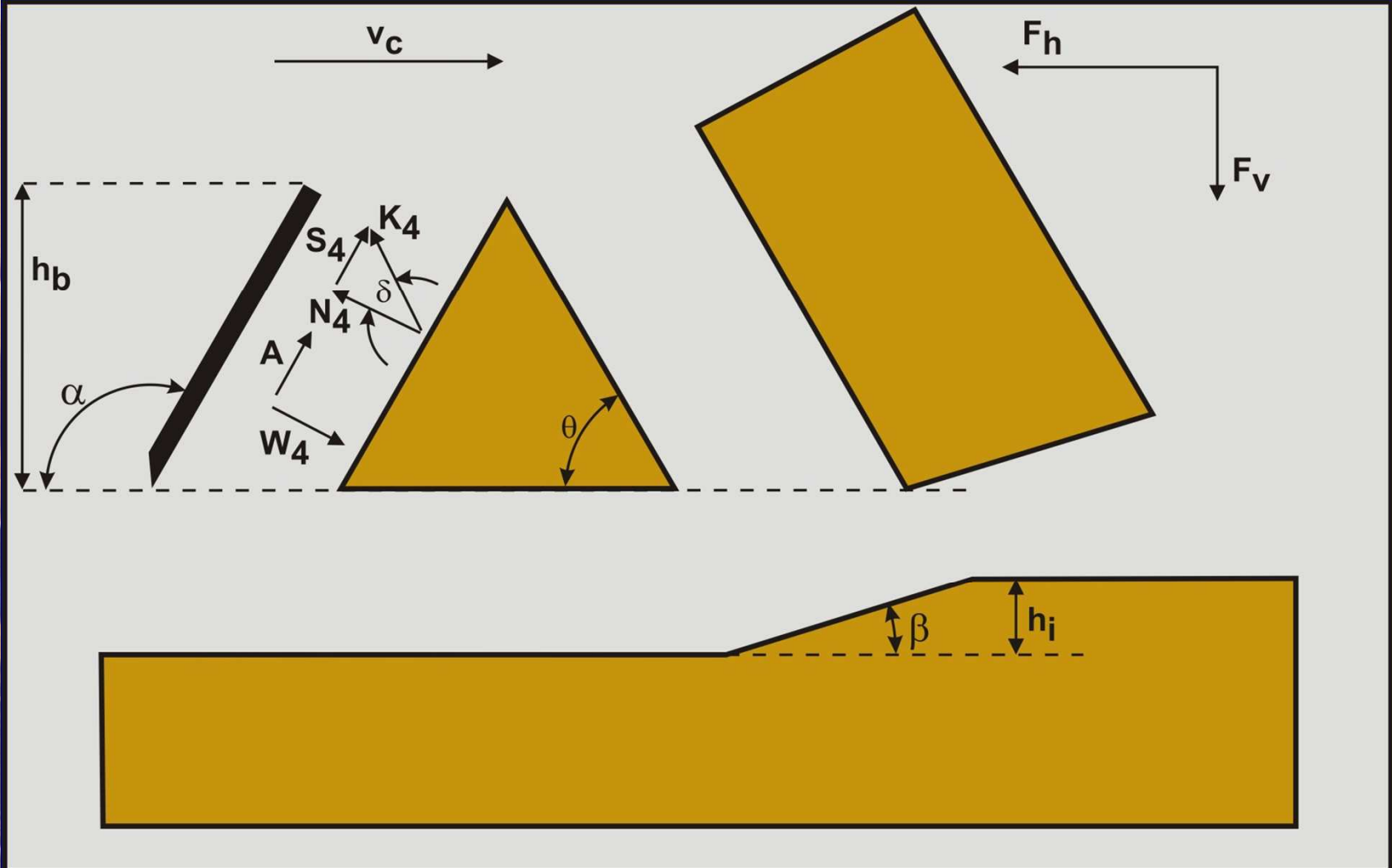
Wedge Definitions



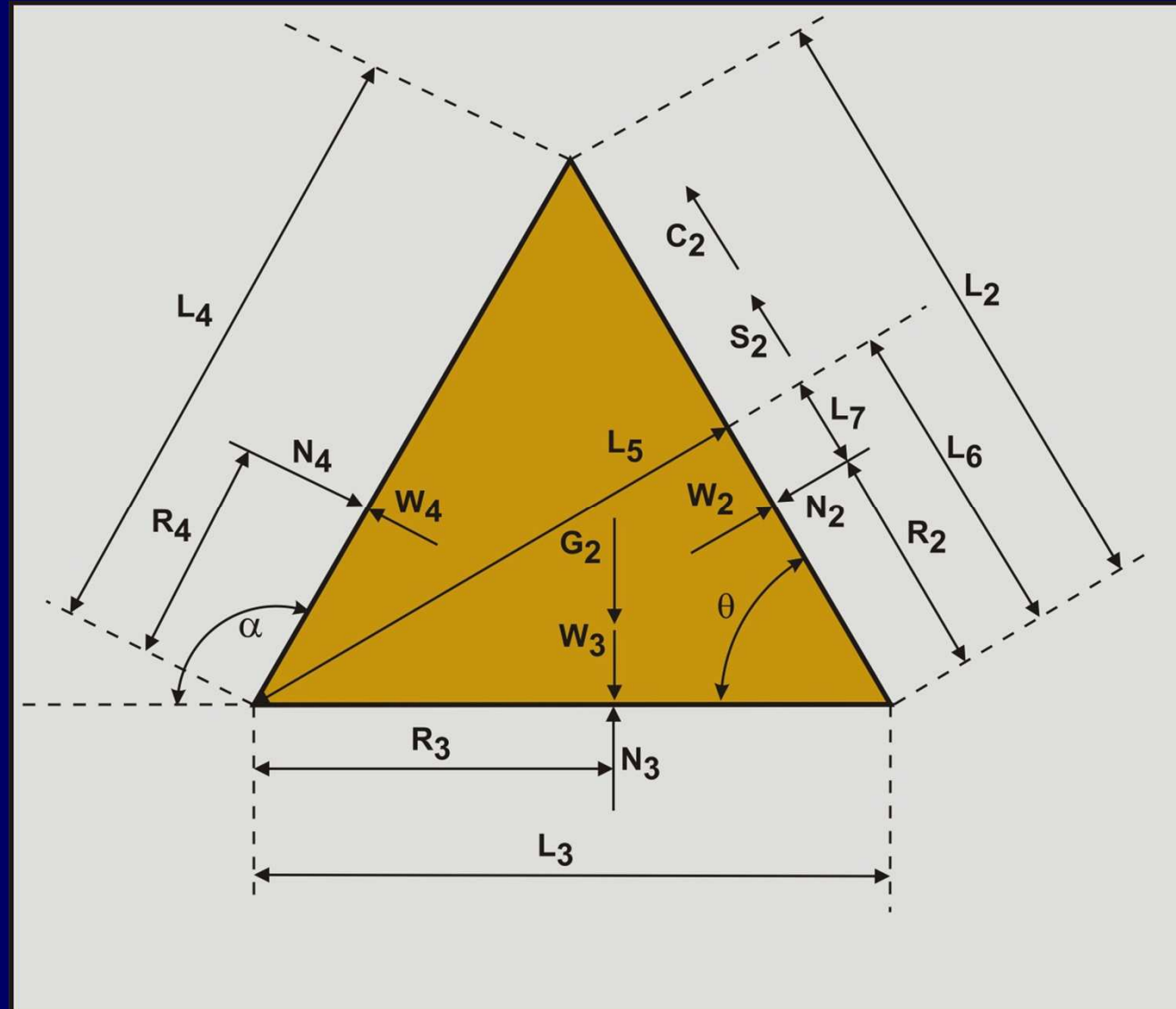
Forces on Layer Cut



Forces on the Blade



Moments on the Wedge

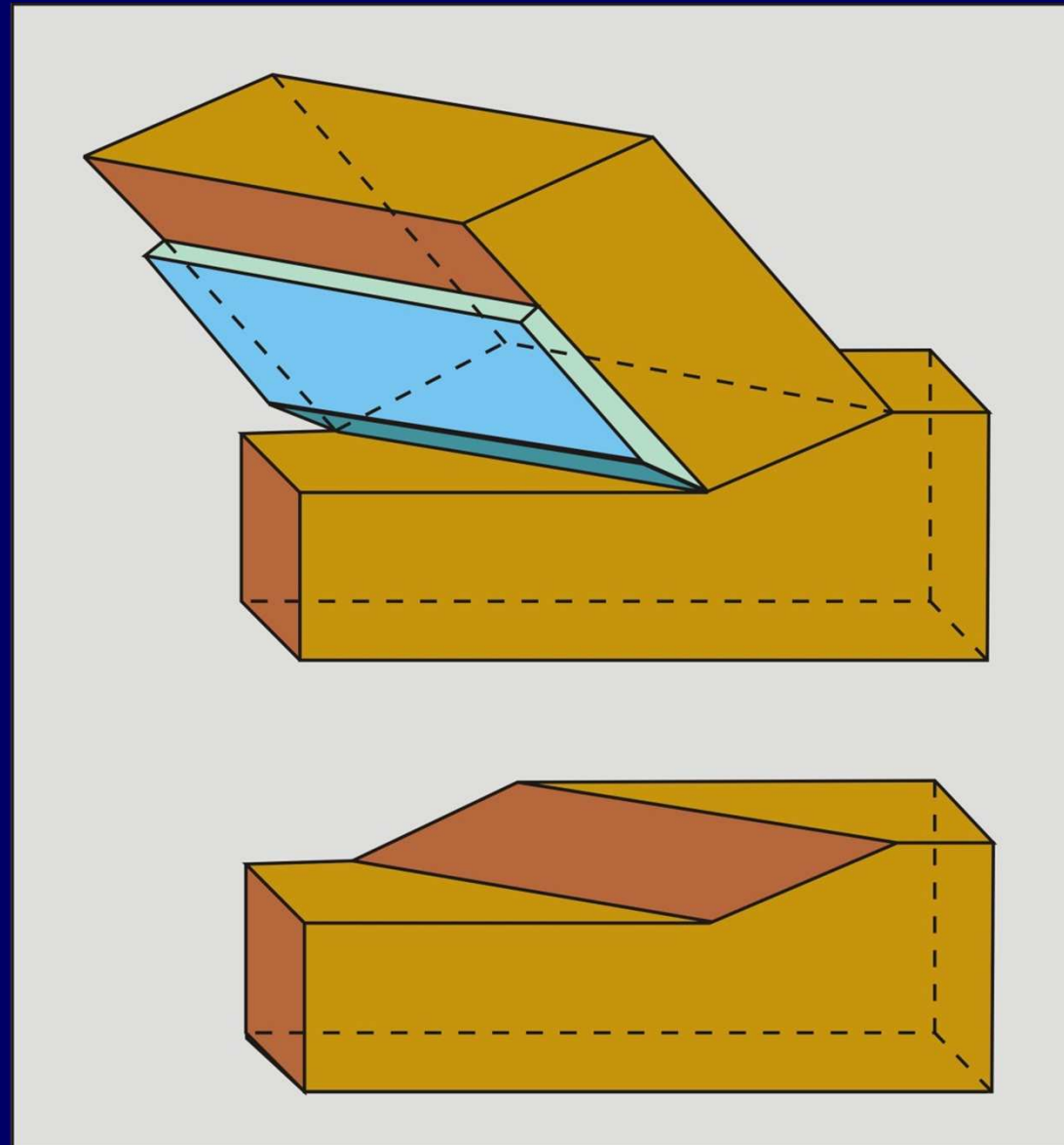


Faculty of 3mE - Dredging Engineering

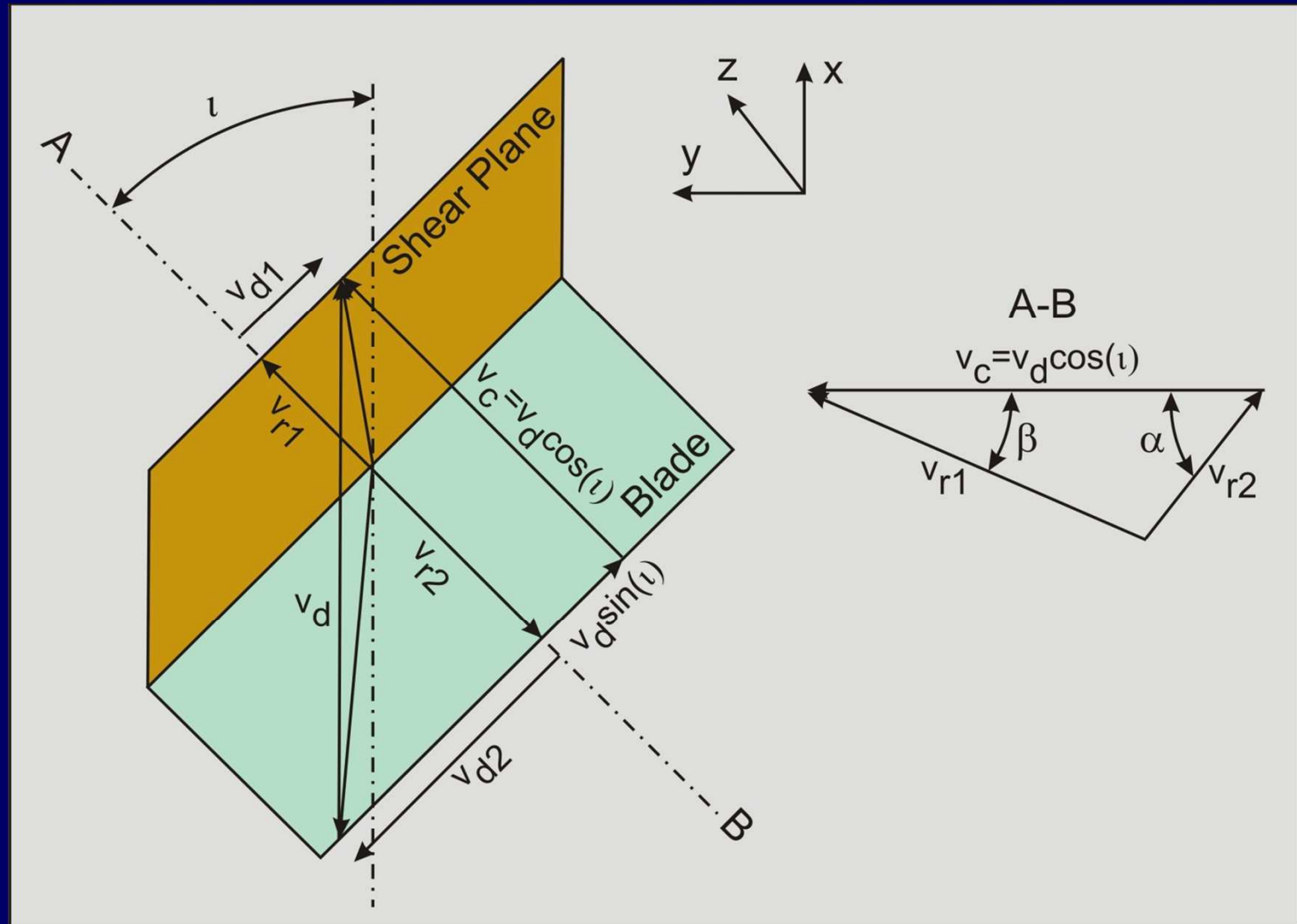


Snow Plough Effect

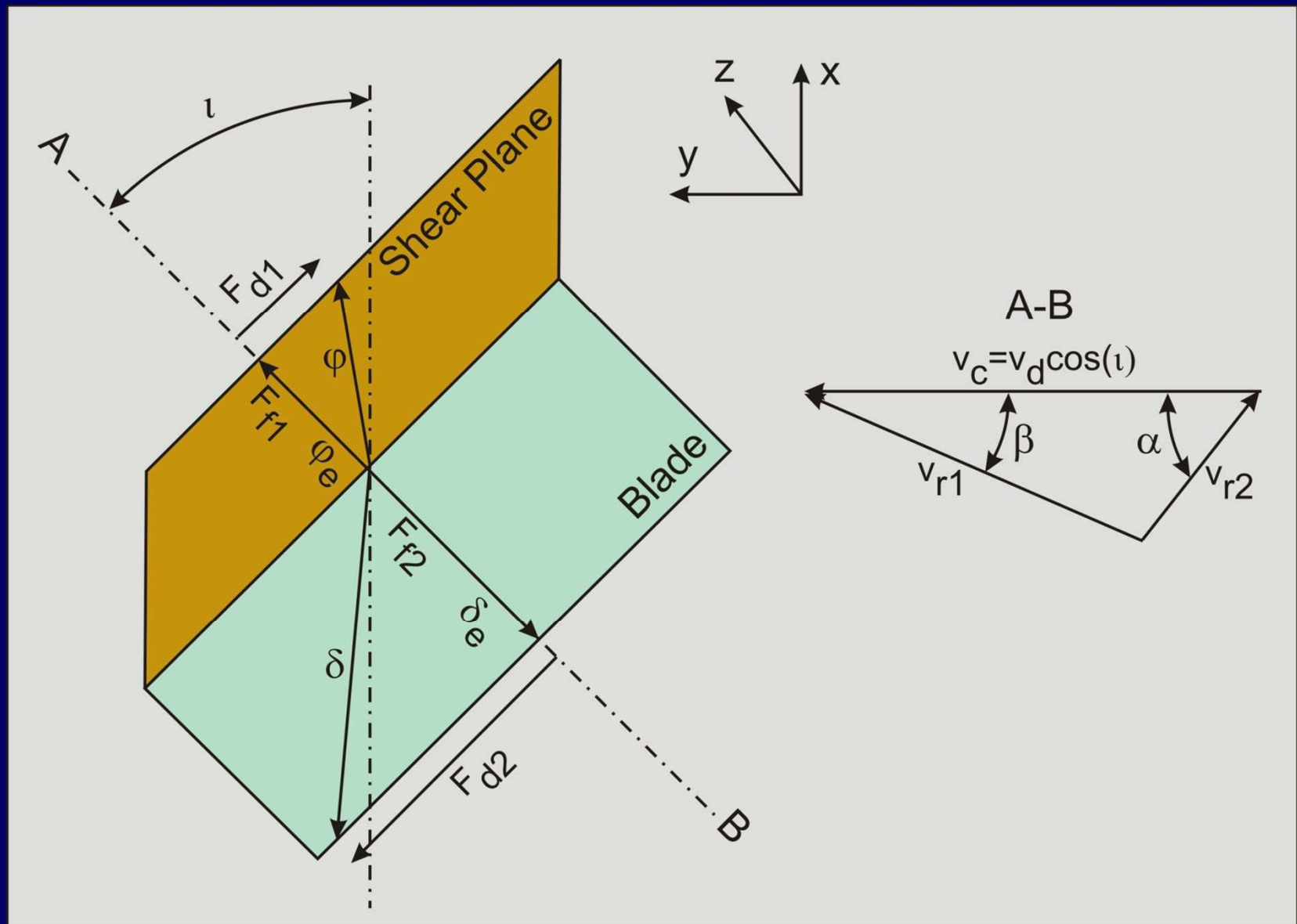
Snow Plough Effect



Snow Plough Velocities



Snow Plough Forces



Effective Friction & Shear Stress

$$\tan(\varphi_e) = \tan(\varphi) \cdot \cos\left(\operatorname{atan}\left(\frac{v_{d1}}{v_{r1}}\right)\right)$$

$$\tan(\delta_e) = \tan(\delta) \cdot \cos\left(\operatorname{atan}\left(\frac{v_{d2}}{v_{r2}}\right)\right)$$

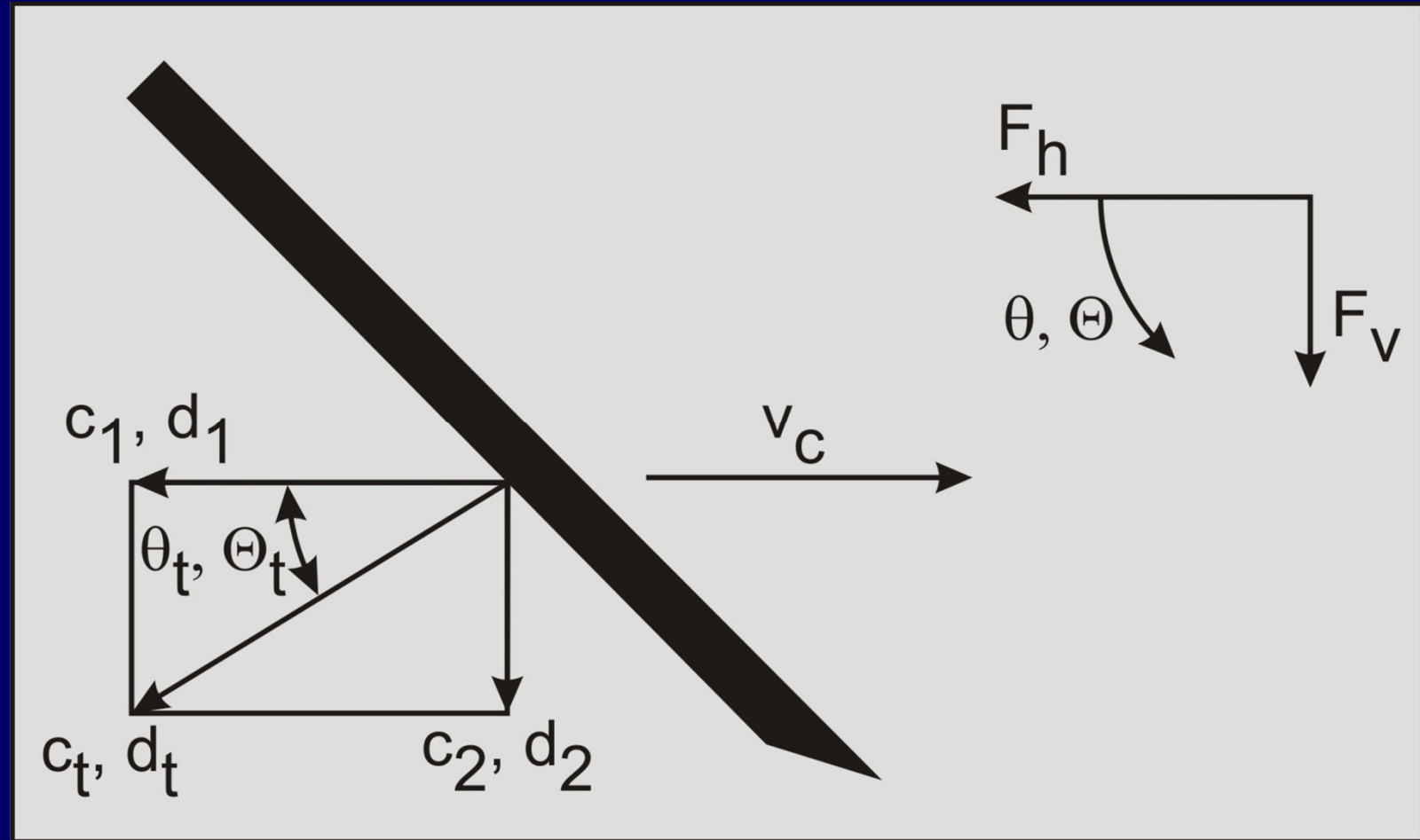
$$c_e = c \cdot \cos\left(\operatorname{atan}\left(\frac{v_{d1}}{v_{r1}}\right)\right)$$

$$a_e = a \cdot \cos\left(\operatorname{atan}\left(\frac{v_{d2}}{v_{r2}}\right)\right)$$

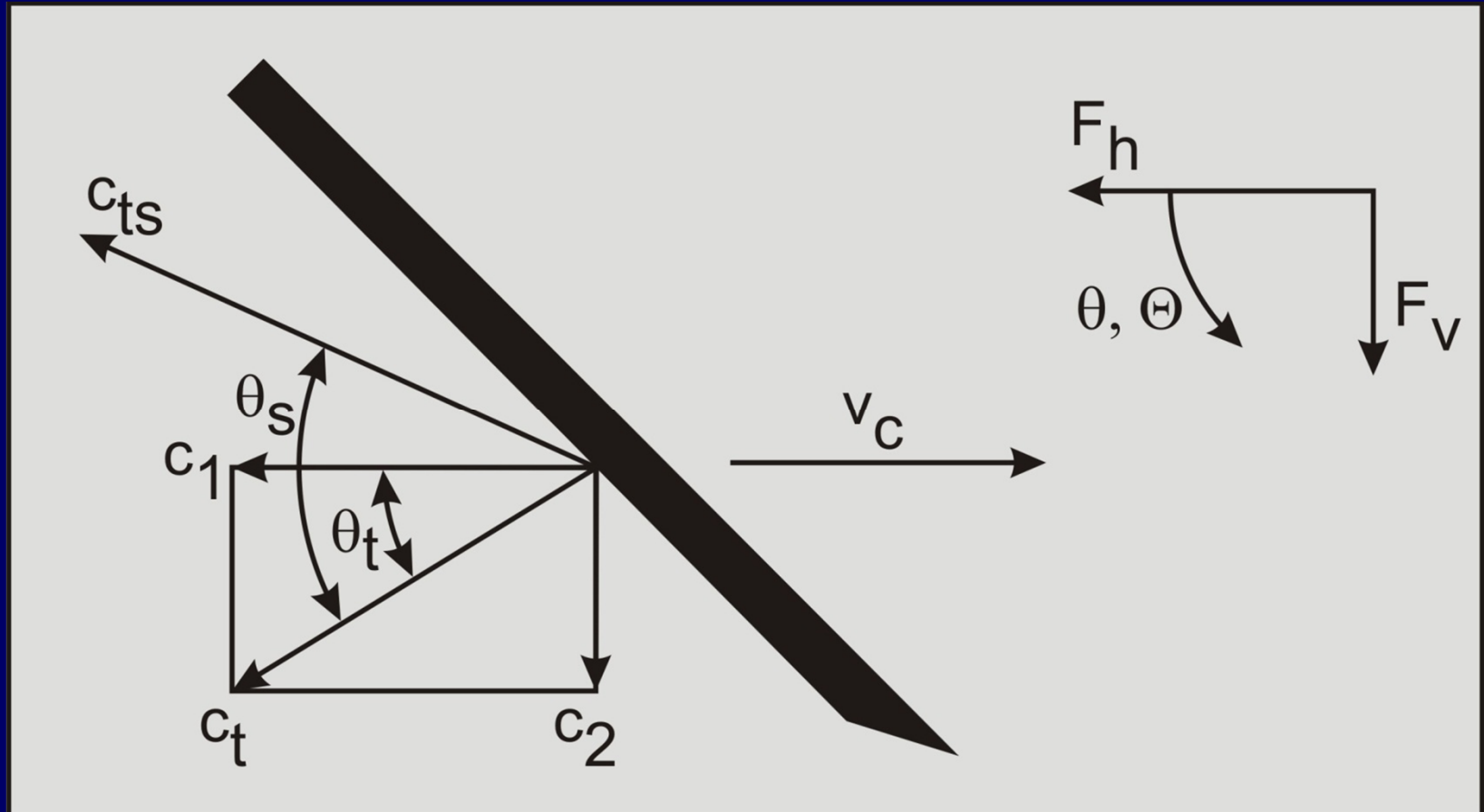


Wear and 3D Effects

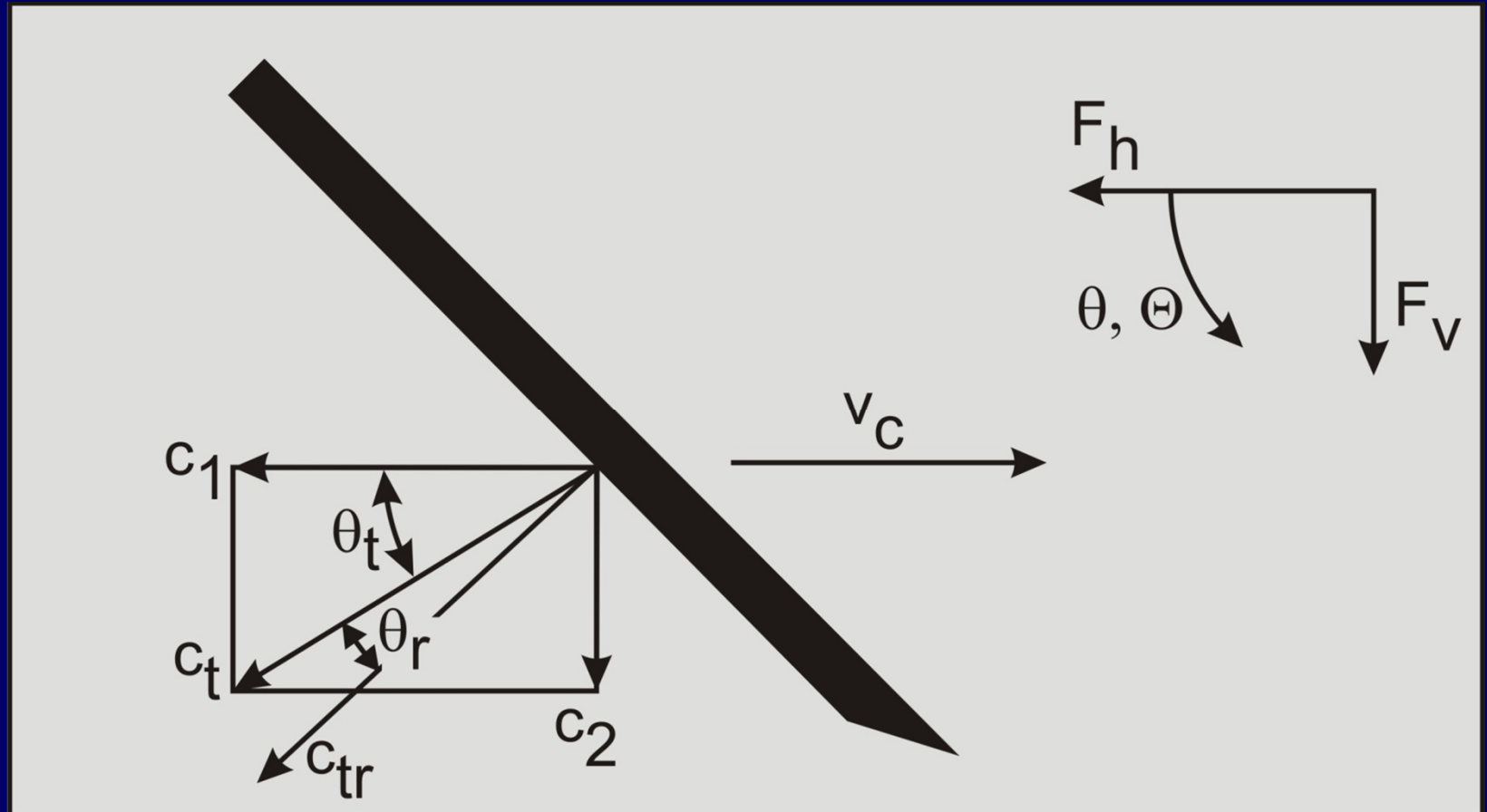
Forces on the Blade



Wear



3D Effects





Questions?

Sources images

1. A model cutter head, source: Delft University of Technology.
2. Off shore platform, source: Castrol (Switzerland) AG
3. Off shore platform, source: <http://www.wireropetraining.com>
4. Diagram of the failure pattern with Rake angle 120, source: TUDelft/S.A.Miedema