## Offshore

Hydromechanics Module 1

Dr. ir. Pepijn de Jong

3. Potential Flows part 1

## Introduction

## Overview

|  | Tutorial |  |  |  | Lecture |  |  |  | Online Assignments |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Week | date | time | location | topic | date | time | location | topic | deadline | topic |
| 2 |  |  |  |  | 11-Sep | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $3 \mathrm{mE}-\mathrm{CZ}$ B | Intro, Hydrostatics, Stability |  |  |
| 3 |  |  |  |  | 18-Sep | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $\begin{gathered} \text { DW-Room } \\ 2 \end{gathered}$ | Hydrostatics, Stability |  |  |
| 4 | 23-Sep | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $\begin{gathered} \text { TN- } \\ \text { TZ4. } 25 \end{gathered}$ | Hydrostatics, Stability | 25-Sep | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $3 \mathrm{mE}-\mathrm{CZ}$ B | Potential Flows | 27-Sep | Hydrostatics, Stability |
| 5 |  |  |  |  | 02-Oct | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $3 \mathrm{mE}-\mathrm{CZ}$ B | Potential Flows |  |  |
| 6 | 07-Oct | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $\begin{gathered} \text { TN- } \\ \text { TZ4. } 25 \end{gathered}$ | Potential Flows | 09-Oct | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $3 \mathrm{mE}-\mathrm{CZ} \mathrm{B}$ | Real Flows | 11-Oct | Potential Flows |
| 7 | 14-Oct | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $\begin{gathered} \text { TN- } \\ \text { TZ4.25 } \end{gathered}$ | Real Flows | 16-Oct | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $3 \mathrm{mE}-\mathrm{CZ}$ B | Real Flows, Waves | 18-Oct | Real Flows |
| 8 |  |  |  |  | 23-Oct | $\begin{aligned} & 8: 45- \\ & 10: 30 \end{aligned}$ | $3 \mathrm{mE}-\mathrm{CZ}$ B | Waves | 25-Oct | Waves |
| Exam | 30-Oct | $\begin{aligned} & 9: 00- \\ & \text { 12:00 } \end{aligned}$ | $\begin{gathered} \text { TN- } \\ \text { TZ4. } 25 \end{gathered}$ | Exam |  |  |  |  |  |  |

TUDelft

## Introduction

## E-Assessment

- Grade counted as follows: exam 80\%, bonus assignments 20\%
- If it improves your final grade...
- Only bonus assignments count
- E-Assessment Potential Flows:
- Formative Exercises (set of 5, 4 tries, minimum 3/5 score)
- Bonus Assignment


## Introduction

## Topics of Module 1

- Problems of interest
- Hydrostatics
- Floating stability
- Constant potential flows
- Constant real flows
- Waves

Chapter 1
Chapter 2
Chapter 2
Chapter 3
Chapter 4
Chapter 5

## Learning Objectives

## Chapter 3

- Understand the basic principles behind potential flow
- To schematically model flows applying basic potential flow elements and the superposition principle
- To perform basic flow computations applying potential flow theory


## Fluid Mechanics Laws

## Basic assumptions (Euler flow, potential flow)

- Homogeneous
- Continuous
- Incompressible
- Non-viscous
properties are evenly spread over fluid no bubbles, holes, particles, shocks etc
$\rho=$ constant
$\mu=0$
- Without the latter 2 assumptions you end up with the Navier-Stokes eqs.


## Fluid Mechanics Laws

## Basic assumptions

- Assumptions:
- Are restrictive: they limit applicability of calculations
- Are (often) necessary: to obtain a solution within a reasonable amount of effort
- Discrepancies often addressed in a semi-empirical manner:
- Very simplified models or coefficients based on experimental data


## Fluid Mechanics Laws

## Continuity (Conservation of mass)

- Physical principle:
- Mass can be neither created nor destroyed



## Fluid Mechanics Laws

## Continuity

## Net mass flow out of control volume

 =Time rate of decrease of mass within control volume


## Fluid Mechanics Laws

## Continuity

## Net mass flow out of control volume

 =Time rate of decrease of mass within control volume


## Fluid Mechanics Laws

## Continuity

Net mass flow out of control volume =
Time rate of decrease of mass within control volume

Net mass flow out of CV:

$$
\begin{aligned}
\frac{d m_{x}}{d t} & =\frac{\partial \rho u}{\partial x} \cdot d x d y d z \\
\frac{d m_{y}}{d t} & =\frac{\partial \rho v}{\partial y} \cdot d x d y d z \\
\frac{d m_{z}}{d t} & =\frac{\partial \rho w}{\partial z} \cdot d x d y d z
\end{aligned}
$$

Time rate of mass decrease within CV:

$$
-\frac{\partial \rho}{\partial t} \cdot d x d y d z
$$

## Fluid Mechanics Laws

## Continuity

## Net mass flow out of control volume

 =Time rate of decrease of mass within control volume
(

## Fluid Mechanics Laws

## Continuity

## Net mass flow out of control volume

 =Time rate of decrease of mass within control volume

$$
\begin{gathered}
\frac{\partial \rho}{\partial t}+\frac{\partial \rho u}{\partial x}+\frac{\partial \rho v}{\partial y}+\frac{\partial \rho w}{\partial z}=0 \\
\frac{\partial \rho}{\partial t}+\nabla \cdot(\rho \vec{V})=0
\end{gathered}
$$

$$
\vec{\nabla}=\left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)
$$

## Fluid Mechanics Laws

## Continuity

## Net mass flow out of control volume

 =Time rate of decrease of mass within control volume

Incompressible flow:

$$
\begin{gathered}
\frac{\partial \rho}{\partial t}+\frac{\partial \rho u}{\partial x}+\frac{\partial \rho v}{\partial y}+\frac{\partial \rho w}{\partial z}=0 \\
\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}+\frac{\partial w}{\partial z}=0 \\
\nabla \cdot \vec{V}=0
\end{gathered}
$$

$$
\vec{\nabla}=\left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)
$$

## Fluid Mechanics Laws

## Conservation of momentum

- Apply Newton's second law for:
- Incompressible fluid $\rightarrow$ constant density
- Inviscid fluid $\rightarrow$ no tangential stresses in fluid
- Then the conservation of momentum yields the 'Euler Equations'
- (Linear) Momentum:

$$
\vec{F}=m \vec{a}=m \frac{d \vec{V}}{d t}=\frac{d}{d t}(m \vec{V})
$$

## Fluid Mechanics Laws

## Con. of momentum



## Fluid Mechanics Laws

## Con. of momentum

Net momentum flux out of control volume
Time rate of decrease of momentum within control volume
Sum of forces on control volume

Momentum flux:

$$
\frac{d}{d t}(m \vec{V}) \rightarrow \frac{d m}{d t} \vec{V}=\rho v d x d z \cdot \vec{V}
$$

Inlet momentum flux:

$$
\rho v d x d z \cdot \vec{V}=\rho v \vec{V} \cdot d x d z
$$

Outlet momentum flux:

$$
\left[\rho v \vec{V}+\frac{\partial}{\partial x}(\rho v \vec{V}) d y\right] d x d z
$$

## Fluid Mechanics Laws

## Con. of momentum



Net momentum flux out of control volume
Time rate of decrease of momentum within control volume
Sum of forces on control volume

Inlet momentum flux:

$$
\rho v \vec{V} \cdot d x d z
$$

Outlet momentum flux:

$$
\left[\rho v \vec{V}+\frac{\partial}{\partial y}(\rho v \vec{V}) d y\right] d x d z
$$

Net momentum flux (out):

$$
\frac{\partial}{\partial y}(\rho v \vec{V}) d x d y d z
$$

## Fluid Mechanics Laws

## Con. of momentum



Net momentum flux out of control volume
Time rate of decrease of momentum in control volume

Sum of forces on control volume

Time rate of momentum in CV:

$$
\frac{d}{d t}(m \vec{V}) \rightarrow \frac{\partial}{\partial t}(\rho d V \vec{V})
$$

Time rate of decrease of momentum in CV:

$$
-\frac{d}{d t}(\rho \vec{V}) d x d y d z
$$

## Fluid Mechanics Laws

## Con. of momentum

Net momentum flux (out):

$$
\begin{gathered}
\frac{\partial}{\partial x}(\rho u \vec{V}) d x d y d z \\
\frac{\partial}{\partial y}(\rho v \vec{V}) d x d y d z \\
\frac{\partial}{\partial z}(\rho w \vec{V}) d x d y d z
\end{gathered}
$$

Net momentum flux out of control volume
Time rate of decrease of momentum in control volume =
Sum of forces on control volume

Time rate of decrease of momentum in CV :

$$
-\frac{\partial}{\partial t}(\rho \vec{V}) d x d y d z
$$

Result:
Sum of forces

$$
\left[\frac{\partial}{\partial t}(\rho \vec{V})+\frac{\partial}{\partial x}(\rho u \vec{V})+\frac{\partial}{\partial y}(\rho v \vec{V})+\frac{\partial}{\partial z}(\rho w \vec{V})\right] d x d y d z=\sum F
$$

## Fluid Mechanics Laws

## Con. of momentum

Net momentum flux out of control volume
Time rate of decrease of momentum in control volume =
Sum of forces on control volume

Further reduction is possible:

$$
\begin{aligned}
& {\left[\frac{\partial}{\partial t}(\rho \vec{V})+\frac{\partial}{\partial x}(\rho u \vec{V})+\frac{\partial}{\partial y}(\rho v \vec{V})+\frac{\partial}{\partial z}(\rho w \vec{V})\right] d x d y d z=\sum F} \\
& {\left[\vec{V}\left(\frac{\partial \vec{r}}{\partial t}+\vec{\nabla}+(\rho \vec{V})\right)+\rho\left(\frac{\partial \vec{V}}{\partial t}+u \frac{\partial \vec{V}}{\partial x}+v \frac{\partial \vec{V}}{\partial y}+w \frac{\partial \vec{V}}{\partial z}\right)\right] d x d y d z=\sum F} \\
& \text { Conservation of mass! }
\end{aligned}
$$

$$
\rho\left(\frac{\partial \vec{V}}{\partial t}+u \frac{\partial \vec{V}}{\partial x}+v \frac{\partial \vec{V}}{\partial y}+w \frac{\partial \vec{V}}{\partial z}\right) d x d y d z=\sum F
$$

## Fluid Mechanics Laws

## Con. of momentum

Net momentum flux out of control volume
Time rate of decrease of momentum in control volume =
Sum of forces on control volume

$$
\rho\left(\frac{\partial \vec{V}}{\partial t}+u \frac{\partial \vec{V}}{\partial x}+v \frac{\partial \vec{V}}{\partial y}+w \frac{\partial \vec{V}}{\partial z}\right) d x d y d z=\sum F
$$

Can be written as:

$$
\rho \frac{D \vec{V}}{D t} d x d y d z=\sum F
$$

Using the 'substantial derivative':
The total derivative of a particle that moves with the fluid through the control volume:

$$
\frac{D \vec{V}}{D t}=\frac{\partial \vec{V}}{\partial t}+u \frac{\partial \vec{V}}{\partial x}+v \frac{\partial \vec{V}}{\partial y}+w \frac{\partial \vec{V}}{\partial z}
$$

## Fluid Mechanics Laws

## Con. of momentum

Net momentum flux out of control volume
Time rate of decrease of momentum in control volume
Sum of forces on control volume

Gravity forces:

$$
\begin{array}{r}
d \vec{F}_{g r a v}=\rho \vec{g} d x d y d z \\
\vec{g}=[0,0,-g]
\end{array}
$$

Surface forces (neglecting viscous stresses):

$$
\begin{aligned}
& d F_{x s u r f}=\frac{-\partial p}{\partial x} d x d y d z \\
& d F_{y s u r f}=\frac{-\partial p}{\partial y} d y d x d z \\
& d F_{\text {zsurf }}=\frac{-\partial p}{\partial z} d z d x d y
\end{aligned}
$$



## Fluid Mechanics Laws

## Con. of momentum

Gravity forces:

Net momentum flux out of control volume
Time rate of decrease of momentum in control volume
=
Sum of forces on control volume

$$
d \vec{F}_{g r a v}=\rho \vec{g} d x d y d z
$$

Surface forces (neglecting viscous stresses):

$$
d F_{\text {surf }}=-\vec{\nabla} p d x d y d z
$$

Conservation of momentum:

$$
\rho \frac{D \vec{V}}{D t} d x d y d z=\rho \vec{g} d x d y d z-\vec{\nabla} p d x d y d z
$$

## Fluid Mechanics Laws

## Con. of momentum

Gravity forces:

Net momentum flux out of control volume
Time rate of decrease of momentum in control volume =
Sum of forces on control volume

$$
d \vec{F}_{g r a v}=\rho \vec{g} d x d y d z
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Surface forces (neglecting viscous stresses):

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d F_{\text {surf }}=-\vec{\nabla} p d x d y d z
$$

Conservation of momentum:

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

## Fluid Mechanics Laws

## Con. of momentum

Gravity forces:
Net momentum flux out of control volume
Time rate of decrease of momentum in control volume
=
Sum of forces on control volume

$$
d \vec{F}_{g r a v}=\rho \vec{g} d x d y d z
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Surface forces (neglecting viscous stresses):

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d F_{\text {surf }}=-\vec{\nabla} p d x d y d z
$$

Conservation of momentum:

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

Euler Equation for inviscid flow

## Fluid Mechanics Laws

## Deformation and rotation (2D)

- Stresses within fluid will deform the cube considered before
- Explanation in book (p. 3-4 and 3-5) very shady/shaky
- We will consider a 2D slice of the cube


## Fluid Mechanics Laws

Deformation and rotation (2D)


## Fluid Mechanics Laws

## Deformation and rotation (2D)

- Define angular velocity (or rotation) about z-axis as:

$$
\omega_{z}=\frac{1}{2}\left(\frac{d \alpha}{d t}-\frac{d \beta}{d t}\right)
$$

$$
d y+\frac{\partial v}{\partial y} d y d t
$$

- Define deformation velocity (or dilatation) as:

$$
\frac{1}{2}\left(\frac{d \alpha}{d t}+\frac{d \beta}{d t}\right)
$$



## Fluid Mechanics Laws

## Deformation and rotation (2D)

- Define angular velocity (or rotation) about z-axis as:

$$
\omega_{z}=\frac{1}{2}\left(\frac{d \alpha}{d t}-\frac{d \beta}{d t}\right)
$$

$$
\begin{array}{ll}
d \alpha=\lim _{d t \rightarrow 0}\left[\tan ^{-1} \frac{\frac{\partial v}{\partial x} d x d t}{d x+\frac{\partial u}{\partial x} d x d t}\right] & d y+\frac{\partial v}{\partial y} d y d t \\
d \beta=\lim _{d t \rightarrow 0}\left[\tan ^{-1} \frac{\frac{\partial u}{\partial y} d y d t}{d y+\frac{\partial v}{\partial y} d y d t}\right] & d \alpha
\end{array}
$$

## Fluid Mechanics Laws

## Deformation and rotation (2D)

- Define angular velocity (or rotation) about z-axis as:

$$
\omega_{z}=\frac{1}{2}\left(\frac{d \alpha}{d t}-\frac{d \beta}{d t}\right)
$$

$$
\omega_{z}=\frac{1}{2}\left(\frac{\frac{\partial v}{\partial x} d t}{d t}-\frac{\frac{\partial u}{\partial y} d t}{d t}\right)=\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)
$$

$$
d \alpha=\lim _{d t \rightarrow 0}\left[\tan ^{-1} \frac{\frac{\partial v}{\partial x} d x d t}{d x+\frac{\partial u}{\partial x} d x d t}\right]=\frac{\partial v}{\partial x} d t \quad d \beta=\lim _{d t \rightarrow 0}\left[\operatorname{tgh}^{-1} \frac{\frac{\partial u}{\partial y} d y d t}{d y+\frac{\partial v}{\partial y} d y d t}\right]=\frac{\partial u}{\partial y} d t
$$

## Fluid Mechanics Laws

## Rotation in 3D and vorticity

- Rotation in 3D

$$
\omega_{x}=\frac{1}{2}\left(\frac{\partial w}{\partial y}-\frac{\partial v}{\partial z}\right) \quad \omega_{y}=\frac{1}{2}\left(\frac{\partial u}{\partial z}-\frac{\partial w}{\partial x}\right) \quad \omega_{z}=\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)
$$

- Rotation equals the 'curl' of the velocity vector:

$$
\vec{\omega}=\frac{1}{2} \vec{\nabla} \times \vec{V}
$$

- Vorticity of a fluid is defined as twice the rotation:

$$
\vec{\zeta}=2 \vec{\omega}=\vec{\nabla} \times \vec{V}
$$

$$
\vec{\nabla}=\left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)
$$

## Fluid Mechanics Laws

## Summarizing:

- Conservation of mass (continuity):

$$
\frac{\partial \rho}{\partial t}+\nabla \cdot(\rho \vec{V})=0
$$

Incompressible flow:

$$
\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}+\frac{\partial w}{\partial z}=0 \quad \nabla \cdot \vec{V}=0
$$

- Conservation of momentum (inviscid flow):

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

- Rotation of a fluid element:

$$
\begin{gathered}
\omega_{x}=\frac{1}{2}\left(\frac{\partial w}{\partial y}-\frac{\partial v}{\partial z}\right) \quad \omega_{z}=\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right) \\
\omega_{y}=\frac{1}{2}\left(\frac{\partial u}{\partial z}-\frac{\partial w}{\partial x}\right)
\end{gathered}
$$

## Fluid Mechanics Laws

## Velocity Potential

- Assumptions
- Homogeneous
- Continuous
- Incompressible
- Non-viscous (inviscid)
- Extra assumption:
- Irrotational flow $\rightarrow$

$$
\vec{\zeta}=2 \vec{\omega}=\vec{\nabla} \times \vec{V}=0
$$

## Fluid Mechanics Laws

## Velocity Potential

- Theorem in vector calculus:

In case the curl of a vector is zero, then the vector must be the gradient of a scalar function

$$
\vec{\zeta}=2 \vec{\omega}=\vec{V} \times \vec{V}=0
$$

- Thus:

$$
\vec{V}=\nabla \Phi
$$

- where $\Phi$ is a scalar function
- $\Phi$ is known as the Velocity Potential


## Fluid Mechanics Laws

## Velocity Potential

- The velocity potential is a function of time and position:

$$
\Phi(x, y, z, t)
$$

- The spatial derivatives of the velocity potential equal the velocity components at a time and position:

$$
\frac{\partial \Phi}{\partial x}=u \quad \frac{\partial \Phi}{\partial y}=v \quad \frac{\partial \Phi}{\partial z}=w
$$

- Potential lines are defined as:

$$
\Phi(x, y, z, t)=\text { constant }
$$

## Fluid Mechanics Laws

## Velocity Potential

- In 2D polar coordinates:

$$
\begin{aligned}
& \Phi(r, \theta, t) \\
& v_{r}=\frac{\partial \Phi}{\partial r} \\
& v_{\theta}=\frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta}
\end{aligned}
$$

## Fluid Mechanics Laws

## Velocity Potential

- Continuity equation for incompressible flow:

$$
\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}+\frac{\partial w}{\partial z}=0
$$

- Velocity components:

$$
u=\frac{\partial \Phi}{\partial x} \quad v=\frac{\partial \Phi}{\partial y} \quad w=\frac{\partial \Phi}{\partial z}
$$

- Continuity equation for potential flow:

$$
\frac{\partial^{2} \Phi}{\partial x^{2}}+\frac{\partial^{2} \Phi}{\partial y^{2}}+\frac{\partial^{2} \Phi}{\partial z^{2}}=0
$$

$$
\nabla^{2} \Phi=0 \quad \text { Laplace equation }
$$

## Fluid Mechanics Laws

## Velocity Potential

- Irrotational flow (in 2D):

$$
\begin{array}{lll}
u=\frac{\partial \Phi}{\partial x} & \text { thus: } & \frac{\partial u}{\partial y}=\frac{\partial}{\partial y} \frac{\partial \Phi}{\partial x}=\frac{\partial^{2} \Phi}{\partial y \partial x} \\
v=\frac{\partial \Phi}{\partial y} & \text { thus: } & \frac{\partial v}{\partial x}=\frac{\partial}{\partial x} \frac{\partial \Phi}{\partial y}=\frac{\partial^{2} \Phi}{\partial x \partial y} \\
\frac{\partial^{2} \Phi}{\partial y \partial x}=\frac{\partial^{2} \Phi}{\partial x \partial y} & \text { thus: } \quad \omega_{z}=\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)=0
\end{array}
$$

## Fluid Mechanics Laws

## Velocity Potential

- Irrotational flow (in 3D):

$$
\begin{aligned}
& \frac{\partial v}{\partial x}=\frac{\partial u}{\partial y} \text { in the }(x, y) \text { plane } \\
& \frac{\partial w}{\partial y}=\frac{\partial v}{\partial z} \text { in the }(\mathrm{y}, \mathrm{z}) \text { plane } \\
& \frac{\partial u}{\partial z}=\frac{\partial w}{\partial x} \text { in the }(\mathrm{x}, \mathrm{z}) \text { plane }
\end{aligned}
$$

$$
\omega_{x}=\frac{1}{2}\left(\frac{\partial w}{\partial y}-\frac{\partial v}{\partial z}\right)
$$

$$
\omega_{y}=\frac{1}{2}\left(\frac{\partial u}{\partial z}-\frac{\partial w}{\partial x}\right)
$$

$$
\omega_{z}=\frac{1}{2}\left(\frac{\partial v}{\partial x}-\frac{\partial u}{\partial y}\right)
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Recall the Euler Equations (sheet 29):

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Recall the Euler Equations (sheet 29):

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

- Note that:

$$
\frac{D \vec{V}}{D t}=\frac{\partial \vec{V}}{\partial t}+(\vec{V} \cdot \nabla) \vec{V} \quad(\vec{V} \cdot \nabla) \vec{V}=\nabla\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V}
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Recall the Euler Equations (sheet 29):

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

- Note that:

$$
\frac{D \vec{V}}{D t}=\frac{\partial \vec{V}}{\partial t}+(\vec{V} \cdot \nabla) \vec{V} \quad(\vec{V} \cdot \nabla) \vec{V}=\nabla\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V}
$$

- Then:

$$
\rho\left(\frac{\partial \vec{V}}{\partial t}+\nabla\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V}\right)=\rho \vec{g}-\vec{\nabla} p
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Recall the Euler Equations (sheet 29):

$$
\rho \frac{D \vec{V}}{D t}=\rho \vec{g}-\vec{\nabla} p
$$

- Note that:

$$
\frac{D \vec{V}}{D t}=\frac{\partial \vec{V}}{\partial t}+(\vec{V} \cdot \nabla) \vec{V} \quad(\vec{V} \cdot \nabla) \vec{V}=\nabla\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V}
$$

- Then:

$$
\frac{\partial \vec{V}}{\partial t}+\nabla\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V}-\vec{g}+\vec{\nabla} \frac{p}{\rho}=0
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Dot with small displacement along streamline $d r=(d x, d y, d z)$ :

$$
\left[\frac{\partial \vec{V}}{\partial t}+\nabla\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V}-\vec{g}+\nabla \frac{p}{\rho}\right] \cdot d \vec{r}=0
$$

- Then 'work done' by fluid along $d r$ :

$$
\frac{\partial \vec{V}}{\partial t} \cdot d \vec{r}+d\left(\frac{1}{2} V^{2}\right)+\vec{\zeta} \times \vec{V} \cdot d \vec{r}-g d z+\frac{d p}{\rho}=0
$$

- This can be integrated along any two points along a streamline, however:

$$
\vec{\zeta} \times \vec{V} \cdot d \vec{r} \quad \text { is a difficult to evaluate term }
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Possibilities to deal with $\vec{\zeta} \times \vec{V} \cdot d \vec{r}$ :
- $\vec{V}$ is zero; no flow only hydrostatics
- $\vec{\zeta}$ is zero; irrotational flow
- $d \vec{r}$ is perpendicular to $\vec{\zeta} \times \vec{V}$; very rare solution
- $d \vec{r}$ is parallel to $\vec{\zeta} \times \vec{V}$; integrate along streamline


## Fluid Mechanics Laws

## Bernoulli Equation

- Possibilities to deal with $\vec{\zeta} \times \vec{V} \cdot d \vec{r}$ :
- $\vec{V}$ is zero; no flow only hydrostatics
- $\vec{\zeta}$ is zero; irrotational flow
- $d \vec{r}$ is perpendicular to $\vec{\zeta} \times \vec{V}$; very rare solution
$\cdot d \vec{r}$ is parallel to $\vec{\zeta} \times \vec{V}$; integrate along streamline


## Fluid Mechanics Laws

## Bernoulli Equation

- Possibilities to deal with $\vec{\zeta} \times \vec{V} \cdot d \vec{r}$ :
- $\vec{V}$ is zero; no flow only hydrostatics
- $\vec{\zeta}$ is zero; irrotational flow $\rightarrow$ POTENTIAL FLOW
- $d \vec{r}$ is perpendicular to $\vec{\zeta} \times \vec{V}$; very rare solution
$\cdot d \vec{r}$ is parallel to $\vec{\zeta} \times \vec{V}$; integrate along streamline


## Fluid Mechanics Laws

## Bernoulli Equation

- Potential flow: $\vec{V}=\nabla \Phi$

$$
\begin{aligned}
& \frac{\partial \vec{V}}{\partial t} \cdot d \vec{r}+d\left(\frac{1}{2} V^{2}\right)-g d z+\frac{d p}{\rho}=0 \\
& \frac{\partial \nabla \Phi}{\partial t} \cdot d \vec{r}+d \frac{1}{2}(\nabla \Phi)^{2}-g d z+\frac{d p}{\rho}=0 \\
& d \frac{\partial \Phi}{\partial t}+d \frac{1}{2}(\nabla \Phi)^{2}-g d z+\frac{d p}{\rho}=0
\end{aligned}
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Potential flow: $\vec{V}=\nabla \Phi$

$$
d \frac{\partial \Phi}{\partial t}+d \frac{1}{2}(\nabla \Phi)^{2}-g d z+\frac{d p}{\rho}=0
$$

- Finally simple integration yields (between any two points):

$$
\begin{aligned}
& \int_{1}^{2} d \frac{\partial \Phi}{\partial t}+\int_{1}^{2} d\left(\frac{1}{2} V^{2}\right)-\int_{1}^{2} g d z+\int_{1}^{2} \frac{d p}{\rho}=0 \\
& \frac{\partial \Phi}{\partial t_{2}}-\frac{\partial \Phi}{\partial t_{1}}+\frac{1}{2}\left(V_{2}^{2}-V_{1}^{2}\right)-g\left(z_{2}-z_{1}\right)+\frac{p_{2}-p_{1}}{\rho}=0
\end{aligned}
$$

## Fluid Mechanics Laws

## Bernoulli Equation

- Potential flow: $\vec{V}=\nabla \Phi$

$$
d \frac{\partial \Phi}{\partial t}+d \frac{1}{2}(\nabla \Phi)^{2}-g d z+\frac{d p}{\rho}=0
$$

- Finally simple integration yields (between any two points):

$$
\frac{\partial \Phi}{\partial t_{2}}-\frac{\partial \Phi}{\partial t_{1}}+\frac{1}{2}\left(V_{2}^{2}-V_{1}^{2}\right)-g\left(z_{2}-z_{1}\right)+\frac{p_{2}-p_{1}}{\rho}=0
$$

$$
\frac{\partial \Phi}{\partial t}+\frac{1}{2}(\nabla \Phi)^{2}-g z+\frac{p}{\rho}=\text { constant } \quad \text { Bernoulli equation }
$$

## Fluid Mechanics Laws

## Steady and Unsteady Flow

- Steady flow: at any point in flow the velocity is independent of time

$$
\frac{d \vec{V}}{d t}=0 \quad \frac{\partial \Phi}{\partial t}+\frac{1}{2}(\nabla / \Phi)^{2}-g z+\frac{p}{\rho}=\text { constant }
$$

- Unsteady flow: any other flow
- E.g. waves
- Motions of floating objects in a flow
- etc.


## Potential Flow

## Stream lines (2D)

- Definition:
- A line that follows the flow (as if you would have injected dye into the flow)
- Stream line: curve tangent to flow velocity vectors at a time instant:



## Potential Flow

## Stream function (2D)



## Potential Flow

## Stream function (2D)



Rate of flow through ds:

$$
d \Psi=-(\vec{V} \cdot \vec{n}) d s
$$

And:

$$
\begin{aligned}
& \vec{V}=\left[\begin{array}{l}
u \\
v
\end{array}\right] \\
& \vec{n}=\frac{1}{\sqrt{d x^{2}+d y^{2}}}\left[\begin{array}{c}
-d y \\
d x
\end{array}\right] \\
& d s=\sqrt{d x^{2}+d y^{2}}
\end{aligned}
$$

## Potential Flow

## Stream function (2D)



Rate of flow through ds:

$$
\begin{gathered}
d \Psi=-\left[\begin{array}{l}
u \\
v
\end{array}\right] \cdot\left[\begin{array}{c}
-d y \\
d x
\end{array}\right] \\
d \Psi=u d y-v d x
\end{gathered}
$$

## Potential Flow <br> $$
d \Psi=u d y-v d x
$$

## Stream function (2D)



Flow in y-direction:

$$
\begin{aligned}
& d \Psi=-v d x \\
& \frac{d \Psi}{d x}=-v
\end{aligned}
$$

Flow in x-direction:

$$
\begin{aligned}
& d \Psi=u d y \\
& \frac{d \Psi}{d y}=\mathrm{u}
\end{aligned}
$$

$\Psi$ is the stream function
Its value is constant on streamline:

$$
d \Psi=u d y-v d x=0
$$

## Potential Flow

## Stream function (2D)



Definition stream funtion:

$$
d \Psi=u d y-v d x
$$

$$
\frac{d \Psi}{d x}=-v \quad \frac{d \Psi}{d y}=u
$$

Hence:

$$
\begin{aligned}
\Delta \Psi_{A \rightarrow B} & =\int_{A}^{B}-(\vec{V} \cdot \vec{n}) d s \\
& =\int_{A}^{B}(u d y-v d x) \\
& =\int_{A}^{B} d \Psi \\
& =\Psi(B)-\Psi(A)
\end{aligned}
$$

## Potential Flow

## Stream funtion (2D)

- $\Psi$ is the (2D) stream function, with:

$$
\frac{d \Psi}{d y}=u \quad \frac{d \Psi}{d x}=-v
$$

- Difference of $\Psi$ between neighboring stream lines: rate of flow between streamlines


## Potential flow properties

## Summary

- Orthogonality: $\frac{d \Psi}{d y}=\frac{d \Phi}{d x}=u \quad \frac{d \Psi}{d x}=-\frac{d \Phi}{d y}=-v$
- Impervious boundaries equals streamline:

$$
\frac{d \Phi}{d n}=0
$$

$$
\Psi=\text { constant }
$$

- Conditions far away from disturbance:

$$
R \rightarrow \infty \Rightarrow \Phi \rightarrow \Phi_{\infty} \wedge \Psi \rightarrow \Psi_{\infty}
$$

- Steady and unsteady flow:

$$
\frac{d \vec{V}}{d t}=0, \quad \frac{d \Phi}{d t}=0
$$

- Uniform flow (s coordinate along streamline):

$$
\frac{d \vec{V}}{d s}=0
$$

## Potential flow elements

## Introduction

- Using the previous we can define 'flow elements'
- Building blocks that respect the assumptions of potential flow:
- Homogeneous
- Continuous
- Inviscid
- Incompressible
- Irrotational
- We can add these elements up to construct realistic flow patterns
- Modeling of submerged bodies by matching streamlines to body outline
- Using the velocity potential, stream function and Bernoulli equation to find velocities, pressures and eventually fluid forces on bodies


## Potential flow elements

## Uniform flow



$$
\begin{gathered}
\Phi=U \cdot x \\
\Psi=U \cdot y \\
u=\frac{d \Phi}{d x}=\frac{d \Psi}{d y}=U
\end{gathered}
$$



$$
\Phi=-U \cdot x
$$

$$
\Psi=-U \cdot y
$$

$$
u=\frac{d \Phi}{d x}=\frac{d \Psi}{d y}=-U
$$

## Potential flow elements

## Source and sink flow




$$
\begin{gathered}
\Phi=+\frac{Q}{2 \pi} \cdot \ln r=+\frac{Q}{2 \pi} \cdot \ln \sqrt{x^{2}+y^{2}} \\
\Psi=+\frac{Q}{2 \pi} \cdot \theta=+\frac{Q}{2 \pi} \cdot \arctan \frac{y}{x}
\end{gathered}
$$

$$
\begin{gathered}
\Phi=-\frac{Q}{2 \pi} \cdot \ln r=-\frac{Q}{2 \pi} \cdot \ln \sqrt{x^{2}+y^{2}} \\
\Psi=-\frac{Q}{2 \pi} \cdot \theta=-\frac{Q}{2 \pi} \cdot \arctan \frac{y}{x}
\end{gathered}
$$

## Potential flow elements

## Source and sink flow

$$
\begin{aligned}
& \Phi=+\frac{Q}{2 \pi} \cdot \ln r \\
& \Psi=+\frac{Q}{2 \pi} \cdot \theta \\
& v_{r}=\frac{\partial \Phi}{\partial r}=\frac{1}{r} \cdot \frac{\partial \Psi}{\partial \theta}=\frac{Q}{2 \pi r} \\
& v_{\theta}=\frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta}=-\frac{\partial \Psi}{\partial r}=0
\end{aligned}
$$



## Potential flow elements

## Circulation or vortex elements

$$
\begin{aligned}
\Phi & =+\frac{\Gamma}{2 \pi} \cdot \theta \\
\Psi & =+\frac{\Gamma}{2 \pi} \cdot \ln r \\
v_{r} & =\frac{\partial \Phi}{\partial r}=\frac{1}{r} \cdot \frac{\partial \Psi}{\partial \theta}=0 \\
v_{\theta} & =\frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta}=-\frac{\partial \Psi}{\partial r}=\frac{\Gamma}{2 \pi r}
\end{aligned}
$$

## Potential flow elements

## Circulation or vortex elements

$$
\begin{aligned}
& \Phi=+\frac{\Gamma}{2 \pi} \cdot \theta \quad \Psi=+\frac{\Gamma}{2 \pi} \cdot \ln r \\
& v_{r}=\frac{\partial \Phi}{\partial r}=\frac{1}{r} \cdot \frac{\partial \Psi}{\partial \theta}=0 \\
& v_{\theta}=\frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta}=-\frac{\partial \Psi}{\partial r}=\frac{\Gamma}{2 \pi r}
\end{aligned}
$$

Circulation strenght constant:

$$
\Gamma=\oint v_{\theta} \cdot d s=2 \pi r \cdot v_{\theta}=\text { constant }
$$

Therefore: no rotation, origin singular point: velocity infinite

## Superposition of potential flow elements

Methodology (source in positive uniform flow)

- The resulting velocity fields, potential fields or stream function fields may be simply superposed to find the combined flow patterns
(Using stream function values)



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D

## Superposition of potential flow elements

## Methodology (source in positive uniform flow)

- The resulting velocity fields, potential fields or stream function fields may be simply superposed to find the combined flow patterns
(Using stream function values)



## Superposition of potential flow elements

## Sink in negative uniform flow

- Besides graphically this works also with formulas:

$$
\begin{aligned}
& \Psi=-\frac{Q}{2 \pi} \cdot \arctan \frac{y}{x}-U_{\infty} \cdot y \\
& \Phi=-\frac{Q}{2 \pi} \cdot \ln \sqrt{x^{2}+y^{2}}-U_{\infty} \cdot x \\
& \text { For instance: } \\
& \text { Find location stagnation } \\
& \text { point (Blackboard...) }
\end{aligned}
$$

## Superposition of potential flow elements

## Separated source and sink

$$
\begin{gathered}
\Psi_{\text {source }}=+\frac{Q}{2 \pi} \cdot \theta_{1}=+\frac{Q}{2 \pi} \cdot \arctan \frac{y}{x_{1}} \\
\Psi_{\text {sink }}=-\frac{Q}{2 \pi} \cdot \theta_{2}=-\frac{Q}{2 \pi} \cdot \arctan \frac{y}{x_{2}} \\
\Psi=\frac{Q}{2 \pi} \cdot \arctan \frac{2 y s}{x^{2}+y^{2}-s^{2}}
\end{gathered}
$$



## Superposition of potential flow elements

Separated source and sink in uniform flow


$$
\Psi=\frac{Q}{2 \pi} \cdot \arctan \frac{2 y s}{x^{2}+y^{2}-s^{2}}+U_{\infty} y
$$

## Superposition of potential flow elements

## Separated source and sink in uniform flow



Streamline resembles fixed boundary (Rankine oval) The flow outside this streamline resembles flow around solid boundary with this shape Shape can be changed by using more source-sinks along $x$-axis with different strenghts

## Superposition of potential flow elements

## Separated source and sink in uniform flow



This approach can be extended to form ship forms in 2D or 3D:

Rankine ship forms
Useful for simple flow computations

## Superposition of potential flow elements

## Doublet or dipole

When distance 2 s becomes zero a new basic flow element is produced:

Doublet or dipole producing flow in positive $x$-direction

$$
\begin{aligned}
& \Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{2 \pi} \cdot \arctan \left(\frac{2 y s}{x^{2}+y^{2}-s^{2}}\right)\right] \\
& \Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{\pi} s \cdot\left(\frac{y}{x^{2}+y^{2}-s^{2}}\right)\right]
\end{aligned}
$$

Note: in book errors w.r.t. to doublet and its orientation!

## Superposition of potential flow elements

## Doublet or dipole

When distance 2 s becomes zero a new basic flow element is produced:

Doublet or dipole producing flow in positive x-direction

$$
\begin{aligned}
& \Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{2 \pi} \cdot \arctan \left(\frac{2 y s}{x^{2}+y^{2}-s^{2}}\right)\right] \\
& \Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{\pi} s \cdot\left(\frac{y}{x^{2}+y^{2}-s^{2}}\right)\right]
\end{aligned}
$$

$$
\text { Set constant: } \quad \mu=\frac{Q}{\pi} s
$$

## Superposition of potential flow elements

## Doublet or dipole

When distance $2 s$ becomes zero a new basic flow element is produced:

Doublet or dipole producing flow in positive x -direction

$$
\Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{2 \pi} \cdot \arctan \left(\frac{2 y s}{x^{2}+y^{2}-s^{2}}\right)\right]
$$

$$
\Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{\pi} s \cdot\left(\frac{y}{x^{2}+y^{2}-s^{2}}\right)\right]
$$

$$
\text { Set constant: } \quad \mu=\frac{Q}{\pi} s
$$

## Superposition of potential flow elements

## Doublet or dipole

When distance 2 s becomes zero a new basic flow element is produced:

Doublet or dipole producing flow in positive $x$-direction

$$
\begin{aligned}
& \Psi=\lim _{s \rightarrow 0}\left[\frac{Q}{2 \pi} \cdot \arctan \left(\frac{2 y s}{x^{2}+y^{2}-s^{2}}\right)\right] \\
& \Psi=\mu \cdot \frac{y}{x^{2}+y^{2}}=\mu \cdot \frac{\sin \theta}{r} \\
& \Phi=-\mu \cdot \frac{x}{x^{2}+y^{2}}=-\mu \cdot \frac{\cos \theta}{r}
\end{aligned}
$$

## Superposition of potential flow elements

## Doublet in a uniform flow

$$
\begin{array}{ll}
\Phi=-\mu \cdot \frac{x}{x^{2}+y^{2}}-U_{\infty} x & \Psi=\mu \cdot \frac{y}{x^{2}+y^{2}}-U_{\infty} y \\
\Phi=-\mu \cdot \frac{\cos \theta}{r}-U_{\infty} r \cos \theta & \Psi=\mu \cdot \frac{\sin \theta}{r}-U_{\infty} r \sin \theta \\
\text { Wrong in book! }
\end{array}
$$

Doublet pointing in positive x-direction, uniform flow in negative $x$ direction:


## Superposition of potential flow elements

Doublet in a uniform flow

$$
\begin{aligned}
& \Phi=-\mu \cdot \frac{x}{x^{2}+y^{2}}-U_{\infty} x \\
& \Phi=-\mu \cdot \frac{\cos \theta}{r}-U_{\infty} r \cos \theta
\end{aligned}
$$

$$
\begin{aligned}
& \Psi=\mu \cdot \frac{y}{x^{2}+y^{2}}-U_{\infty} y \\
& \Psi=\mu \cdot \frac{\sin \theta}{r}-U_{\infty} r \sin \theta
\end{aligned}
$$

Set $\Psi=0$ then:

$$
\Psi=y\left[\frac{\mu}{x^{2}+y^{2}}-U_{\infty}\right]=0
$$

True when:

$$
\begin{aligned}
& y=0 \\
& \frac{\mu}{x^{2}+y^{2}}-U_{\infty}=0 \rightarrow x^{2}+y^{2}=\frac{\mu}{U_{\infty}}
\end{aligned}
$$

## Superposition of potential flow elements

Doublet in a uniform flow: flow around a circle

- The radius of the circle:

$$
R=\sqrt{\frac{\mu}{U_{\infty}}}
$$

- Doublet strength needed for radius R :

$$
\begin{aligned}
& \Phi=-\mu \cdot \frac{\cos \theta}{r}-U_{\infty} r \cos \theta \\
& \Psi=\mu \cdot \frac{\sin \theta}{r}-U_{\infty} r \sin \theta
\end{aligned}
$$

$$
\mu=U_{\infty} R^{2}
$$

- This yields the following:

$$
\begin{aligned}
& \Phi=-\frac{U_{\infty} R^{2} \cos \theta}{r}-U_{\infty} r \cos \theta=R U_{\infty}\left[\frac{R}{r}-\frac{r}{R}\right] \cos \theta \\
& \Psi=\frac{U_{\infty} R^{2} \sin \theta}{r}-U_{\infty} r \sin \theta=R U_{\infty}\left[\frac{R}{r}-\frac{r}{R}\right] \sin \theta
\end{aligned}
$$

## Superposition of potential flow elements

Doublet in a uniform flow: flow around a circle

$$
\Phi=-R U_{\infty}\left[\frac{R}{r}-\frac{r}{R}\right] \cos \theta
$$

$$
\Phi=-U_{\infty} R^{2} \cdot \frac{x}{x^{2}+y^{2}}-U_{\infty} x
$$

$u=\frac{d \Phi}{d x}=U_{\infty} R^{2} \frac{x^{2}-y^{2}}{\left(x^{2}+y^{2}\right)^{2}}-U_{\infty}$


## Superposition of potential flow elements

## Doublet in a uniform flow: flow around a circle

$$
\Phi=-R U_{\infty}\left[\frac{R}{r}-\frac{r}{R}\right] \cos \theta
$$

$$
\Phi=-U_{\infty} R^{2} \cdot \frac{x}{x^{2}+y^{2}}-U_{\infty} x
$$

$$
u=\frac{d \Phi}{d x}=U_{\infty} R^{2} \frac{x^{2}-y^{2}}{\left(x^{2}+y^{2}\right)^{2}}-U_{\infty}
$$



$$
\begin{gathered}
x= \pm R, \quad y=0 \\
u=\frac{d \Phi}{d x}=U_{\infty} R^{2} \frac{R^{2}-0^{2}}{\left(R^{2}+0^{2}\right)^{2}}-U_{\infty}=U_{\infty} R^{2} \frac{R^{2}}{R^{4}}-U_{\infty}=0
\end{gathered}
$$

Stagnation points!

## Superposition of potential flow elements

## Doublet in a uniform flow: flow around a circle

$$
\Phi=-R U_{\infty}\left[\frac{R}{r}-\frac{r}{R}\right] \cos \theta
$$

$$
\Phi=-U_{\infty} R^{2} \cdot \frac{x}{x^{2}+y^{2}}-U_{\infty} x
$$

$$
u=\frac{d \Phi}{d x}=U_{\infty} R^{2} \frac{x^{2}-y^{2}}{\left(x^{2}+y^{2}\right)^{2}}-U_{\infty}
$$



$$
\begin{aligned}
& x=0, \quad y= \pm R \\
& u=\frac{d \Phi}{d x}=U_{\infty} R^{2} \frac{0^{2}-R^{2}}{\left(0^{2}+R^{2}\right)^{2}}-U_{\infty}=-U_{\infty} R^{2} \frac{R^{2}}{R^{4}}-U_{\infty}=-2 U_{\infty}
\end{aligned}
$$

## Superposition of potential flow elements

## Evaluate velocities on cylinder wall

- Generally, velocity on cylinder wall:

$$
\Psi=\mu \cdot \frac{\sin \theta}{r}-U_{\infty} r \sin \theta
$$

$$
v_{\theta}(r=R)=-\left[\frac{\partial \Psi}{\partial r}\right]_{r=R}=-\frac{\partial}{\partial r}\left[\frac{U_{\infty} R^{2} \sin \theta}{r}-U_{\infty} r \sin \theta\right]=\ldots=-2 U_{\infty} \sin \theta
$$

## Superposition of potential flow elements

## Evaluate pressures on cylinder wall

- Use the Bernoulli equation:

$$
\frac{1}{2} \rho U_{\infty}^{2}+0=p+\frac{1}{2} \rho v_{\theta}^{2}
$$

$$
v_{\theta}=-2 U_{\infty} \sin \theta
$$

Pressure at stagnation points:

$$
v=0
$$

Pressure at cylinder boundary:

$$
v_{r}=0
$$

Assuming constant elevation

- Result:

$$
p=\frac{1}{2} \rho U_{\infty}^{2}\left[1-4 \sin ^{2} \theta\right]
$$

## Superposition of potential flow elements

Evaluate pressures on cylinder wall

- Velocity profile:

$$
v_{\theta}=-2 U_{\infty} \sin \theta
$$

- Pressure profile:

$$
p=\frac{1}{2} \rho U_{\infty}^{2}\left[1-4 \sin ^{2} \theta\right]
$$



## Superposition of potential flow elements

Evaluate pressures on cylinder wall

- Velocity profile:

$$
v_{\theta}=-2 U_{\infty} \sin \theta
$$

- Pressure profile:

$$
p=\frac{1}{2} \rho U_{\infty}^{2}\left[1-4 \sin ^{2} \theta\right]
$$

-No net resulting force!!!
-D'Alembert's Paradox


## Superposition of potential flow elements

## Pipeline near seabed

- How to calculate the flow around a pipeline near the seabed?



## Superposition of potential flow elements

Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
- undisturbed
- cylinder
- mirrored cylinder


## Superposition of potential flow elements

Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
- undisturbed
- cylinder
- mirrored cylinder
- Result is zero normal flow on seabed



## Superposition of potential flow elements

Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
- undisturbed
- cylinder
- mirrored cylinder
- Result is zero normal flow on seabed
- Is flow exactly right?



## Superposition of potential flow elements

## Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
- undisturbed
- cylinder
- mirrored cylinder
- Result is zero normal flow on seabed
- Is flow exactly right?

NO: interaction
cylinders not modeled!

## Superposition of potential flow elements

## Circulation

- Add circulation (or vortex flow element)
- Resulting velocity field:



## Superposition of potential flow elements

## Circulation

- Add circulation (or vortex flow element)
- Resulting velocity field:



## Superposition of potential flow elements

## Circulation

- Add circulation (or vortex flow element)
- Resulting velocity field:



## Superposition of potential flow elements

## Circulation

- Add circulation (or vortex flow element)
- Resulting velocity field:



## Superposition of potential flow elements

## Circulation

- Now integration of pressure yields a net force perpendicular to the undisturbed flow direction: the lift force
- However: still no net force in the flow direction: no drag



## Sources images

All images are from the book Offshore Hydromechanics by Journée and Massie.

