Offshore Hydromechanics Module 1

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3. Potential Flows part 1







Introduction

Overview

| | Tutorial | | | | Lecture | | | | Online Assignments | |
|------|----------|----------------|---------------|----------------------------|---------|----------------|--------------|-----------------------------------|--------------------|----------------------------|
| Week | date | time | location | topic | date | time | location | topic | deadline | topic |
| 2 | | | | | 11-Sep | 8:45- 10:30 | 3mE-CZ B | Intro, Hydrostatics, Stability | | |
| 3 | | | | | 18-Sep | 8:45- 10:30 | DW-Room 2 | Hydrostatics, Stability | | |
| 4 | 23-Sep | 8:45- 10:30 | TN- TZ4.25 | Hydrostatics, Stability | 25-Sep | 8:45- 10:30 | 3mE-CZ B | Potential Flows | 27-Sep | Hydrostatics, Stability |
| 5 | | | | | 02-Oct | 8:45- 10:30 | 3mE-CZ B | Potential Flows | | |
| 6 | 07-Oct | 8:45- 10:30 | TN- TZ4.25 | Potential Flows | 09-Oct | 8:45- 10:30 | 3mE-CZ B | Real Flows | 11-Oct | Potential Flows |
| 7 | 14-Oct | 8:45- 10:30 | TN- TZ4.25 | Real Flows | 16-Oct | 8:45- 10:30 | 3mE-CZ B | Real Flows, Waves | 18-Oct | Real Flows |
| 8 | | | | | 23-Oct | 8:45- 10:30 | 3mE-CZ B | Waves | 25-Oct | Waves |
| Exam | 30-Oct | 9:00- 12:00 | TN- TZ4.25 | Exam | | | | | | |

Introduction

E-Assessment

- Grade counted as follows: exam 80%, bonus assignments 20%
 - If it improves your final grade...
 - Only bonus assignments count
- E-Assessment Potential Flows:
 - Formative Exercises (set of 5, 4 tries, minimum 3/5 score)
 - Bonus Assignment



Introduction

Topics of Module 1

- Problems of interest
- Hydrostatics
- Floating stability
- Constant potential flows
- Constant real flows
- Waves

Chapter 1 Chapter 2 Chapter 2 **Chapter 3** Chapter 4 Chapter 5



Learning Objectives

Chapter 3

- Understand the basic principles behind potential flow
- To schematically model flows applying basic potential flow elements and the superposition principle
- To perform basic flow computations applying potential flow theory



Basic assumptions (Euler flow, potential flow)

- Homogeneous properties are evenly spread over fluid
- Continuous no bubbles, holes, particles, shocks etc
- Incompressible $\rho = constant$
- Non-viscous $\mu = 0$

• Without the latter 2 assumptions you end up with the Navier-Stokes eqs.



Basic assumptions

- Assumptions:
 - Are restrictive: they limit applicability of calculations
 - Are (often) necessary: to obtain a solution within a reasonable amount of effort
 - Discrepancies often addressed in a semi-empirical manner:
 - Very simplified models or coefficients based on experimental data



Continuity (Conservation of mass)

- Physical principle:
 - Mass can be neither created nor destroyed





Continuity

Net mass flow out of control volume

= Time rate of decrease of mass within control volume





Continuity

TUDelft

Net mass flow out of control volume

Time rate of decrease of mass within control volume



Continuity

Net mass flow out of control volume

= Time rate of decrease of mass within control volume



Net mass flow out of CV:

 $\frac{dm_x}{dt} = \frac{\partial\rho u}{\partial x} \cdot dx dy dz$ $\frac{dm_y}{dt} = \frac{\partial\rho v}{\partial y} \cdot dx dy dz$ $\frac{dm_z}{dt} = \frac{\partial\rho w}{\partial z} \cdot dx dy dz$

Time rate of mass decrease within CV:

$$-\frac{\partial \rho}{\partial t} \cdot dx dy dz$$

Fluid Mechanics Laws Continuity Net mass flow out of control volume Time rate of decrease of mass within control volume dydx $v + \frac{\partial v}{\partial y} dy$ v dz \geq $\frac{\partial \rho}{\partial t} \cdot dx dy dz + \frac{\partial \rho u}{\partial x} \cdot dx dy dz + \frac{\partial \rho v}{\partial y} \cdot dx dy dz + \frac{\partial \rho w}{\partial z} \cdot dx dy dz = 0$ X $\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} + \frac{\partial \rho w}{\partial z} = 0$



Continuity

Net mass flow out of control volume

= Time rate of decrease of mass within control volume



$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} + \frac{\partial \rho w}{\partial z} = 0$$
$$\frac{\partial \rho}{\partial t} + \nabla \cdot \left(\rho \vec{V}\right) = 0$$

$$\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$$



Continuity

Net mass flow out of control volume = Time rate of decrease of mass within control volume



Incompressible flow:

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} + \frac{\partial \rho w}{\partial z} = 0$$
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$
$$\nabla \cdot \vec{V} = 0$$

$$\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$$



Conservation of momentum

- Apply Newton's second law for:
 - Incompressible fluid \rightarrow constant density
 - Inviscid fluid \rightarrow no tangential stresses in fluid
- Then the conservation of momentum yields the 'Euler Equations'
- (Linear) Momentum:

$$\vec{F} = m\vec{a} = m\frac{d\vec{V}}{dt} = \frac{d}{dt}(m\vec{V})$$



Con. of momentum

Net momentum flux out of control volume = Time rate of decrease of momentum within control volume

> + Sum of forces on control volume





Con. of momentum

Z

TUDelft

Net momentum flux out of control volume

Time rate of decrease of momentum within control volume = Sum of forces on control volume

Momentum flux:

$$\frac{d}{dt} \left(m \vec{V} \right) \rightarrow \frac{dm}{dt} \vec{V} = \rho v dx dz \cdot \vec{V}$$

Inlet momentum flux:

$$\rho v dx dz \cdot \vec{V} = \rho v \vec{V} \cdot dx dz$$

Outlet momentum flux:

$$\left[\rho v \vec{V} + \frac{\partial}{\partial x} (\rho v \vec{V}) dy\right] dx dz$$



 ∂v

-dy

 $^{>}\gamma$

Con. of momentum

dy

dz

Z

dx

 \geq

Net momentum flux out of control volume

Time rate of decrease of momentum within control volume = Sum of forces on control volume

Inlet momentum flux:

 $\rho v \vec{V} \cdot dx dz$

Outlet momentum flux:

$$\left[\rho v \vec{V} + \frac{\partial}{\partial y} (\rho v \vec{V}) dy\right] dx dz$$

Net momentum flux (out):

$$\frac{\partial}{\partial y} (\rho v \vec{V}) dx dy dz$$



v

X

 ∂v

-dy

 $^{>} v$

Con. of momentum

dy

dz

Z

dx



Time rate of decrease of momentum in control volume

Sum of forces on control volume

Time rate of momentum in CV:

$$\frac{d}{dt}(m\vec{V}) \to \frac{\partial}{\partial t}(\rho dV\vec{V})$$

Time rate of decrease of momentum in CV:

$$-rac{d}{dt}(
hoec V)dxdydz$$

TUDelft

v

X

Con. of momentum

Net momentum flux out of control volume

Net momentum flux (out):

$$\frac{\partial}{\partial x} (\rho u \vec{V}) dx dy dz$$

$$\frac{\partial}{\partial y} (\rho v \vec{V}) dx dy dz$$

$$\frac{\partial}{\partial z} (\rho w \vec{V}) dx dy dz$$

Time rate of decrease of momentum in control volume = Sum of forces on control volume

Time rate of decrease of momentum in CV:

$$-\frac{\partial}{\partial t}(\rho \vec{V})dxdydz$$

Result:

Sum of forces

$$\left[\frac{\partial}{\partial t}(\rho \vec{V}) + \frac{\partial}{\partial x}(\rho u \vec{V}) + \frac{\partial}{\partial y}(\rho v \vec{V}) + \frac{\partial}{\partial z}(\rho w \vec{V})\right] dx dy dz = \sum F$$



Con. of momentum

Net momentum flux out of control volume

Time rate of decrease of momentum in control volume = Sum of forces on control volume

Further reduction is possible:

$$\begin{aligned} \frac{\partial}{\partial t}(\rho \vec{V}) + \frac{\partial}{\partial x}(\rho u \vec{V}) + \frac{\partial}{\partial y}(\rho v \vec{V}) + \frac{\partial}{\partial z}(\rho w \vec{V}) \end{bmatrix} dx dy dz &= \sum F \\ \begin{bmatrix} \vec{V} \left(\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{V}) \right) + \rho \left(\frac{\partial \vec{V}}{\partial t} + u \frac{\partial \vec{V}}{\partial x} + v \frac{\partial \vec{V}}{\partial y} + w \frac{\partial \vec{V}}{\partial z} \right) \end{bmatrix} dx dy dz &= \sum F \\ \text{Conservation of mass!} \end{aligned}$$

$$p\left(\frac{\partial \vec{V}}{\partial t} + u\frac{\partial \vec{V}}{\partial x} + v\frac{\partial \vec{V}}{\partial y} + w\frac{\partial \vec{V}}{\partial z}\right)dxdydz = \sum F$$



Con. of momentum

Net momentum flux out of control volume

Time rate of decrease of momentum in control volume

= Sum of forces on control volume

$$\rho\left(\frac{\partial \vec{V}}{\partial t} + u\frac{\partial \vec{V}}{\partial x} + v\frac{\partial \vec{V}}{\partial y} + w\frac{\partial \vec{V}}{\partial z}\right)dxdydz = \sum F$$

Can be written as:

$$D\frac{D\vec{V}}{Dt}dxdydz = \sum F$$

Using the 'substantial derivative':

The total derivative of a particle that moves with the fluid through the control volume:

$$\frac{D\vec{V}}{Dt} = \frac{\partial\vec{V}}{\partial t} + u\frac{\partial\vec{V}}{\partial x} + v\frac{\partial\vec{V}}{\partial y} + w\frac{\partial\vec{V}}{\partial z}$$



Con. of momentum

Net momentum flux out of control volume

Time rate of decrease of momentum in control volume

Sum of forces on control volume

Gravity forces:



Con. of momentum

Net momentum flux out of control volume

Time rate of decrease of momentum in control volume

Sum of forces on control volume

Gravity forces:

 $d\vec{F}_{grav} = \rho \vec{g} dx dy dz$

Surface forces (neglecting viscous stresses):

 $dF_{surf} = -\vec{\nabla}pdxdydz$

Conservation of momentum:

$$\rho \frac{D\vec{V}}{Dt} dx dy dz = \rho \vec{g} dx dy dz - \vec{\nabla} p dx dy dz$$



Con. of momentum

Net momentum flux out of control volume

Time rate of decrease of momentum in control volume

Sum of forces on control volume

Gravity forces:

 $d\vec{F}_{grav} = \rho \vec{g} dx dy dz$

Surface forces (neglecting viscous stresses):

 $dF_{surf} = -\vec{\nabla}pdxdydz$

Conservation of momentum:

$$\rho \frac{D\vec{V}}{Dt} = \rho \vec{g} - \vec{\nabla} p$$



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Con. of momentum

Net momentum flux out of control volume

Time rate of decrease of momentum in control volume

Sum of forces on control volume

Gravity forces:

 $d\vec{F}_{grav} = \rho \vec{g} dx dy dz$

Surface forces (neglecting viscous stresses):

 $dF_{surf} = -\vec{\nabla}pdxdydz$

Conservation of momentum: $\rho \frac{D \vec{V}}{D t} = \rho \vec{g} - \vec{\nabla} p$ Euler Equation for inviscid flow



Deformation and rotation (2D)

- Stresses within fluid will deform the cube considered before
- Explanation in book (p. 3-4 and 3-5) very shady/shaky
- We will consider a 2D slice of the cube



Deformation and rotation (2D)



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Deformation and rotation (2D)





Deformation and rotation (2D)





Deformation and rotation (2D)

 Define angular velocity (or rotation) about z-axis as:

$$\omega_z = \frac{1}{2} \left(\frac{d\alpha}{dt} - \frac{d\beta}{dt} \right)$$

$$\omega_{z} = \frac{1}{2} \left(\frac{\frac{\partial v}{\partial x} dt}{dt} - \frac{\frac{\partial u}{\partial y} dt}{dt} \right) = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

$$d\alpha = \lim_{dt \to 0} \left[\tan^{-1} \frac{\frac{\partial v}{\partial x} dx dt}{dx + \frac{\partial u}{\partial x} dx dt} \right] = \frac{\partial v}{\partial x} dt \qquad d\beta = \lim_{dt \to 0} \left[\tan^{-1} \frac{\frac{\partial u}{\partial y} dy dt}{dy + \frac{\partial v}{\partial y} dy dt} \right] = \frac{\partial u}{\partial y} dt$$



Rotation in 3D and vorticity

• Rotation in 3D

$$\omega_x = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \qquad \qquad \omega_y = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) \qquad \qquad \omega_z = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

• Rotation equals the 'curl' of the velocity vector: $\vec{\omega} = \frac{1}{2}\vec{\nabla} \times \vec{V}$

• Vorticity of a fluid is defined as twice the rotation:

$$\vec{\zeta} = 2\vec{\omega} = \vec{\nabla} \times \vec{V}$$

$$\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$$



Summarizing:

• Conservation of mass (continuity):

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \left(\rho \vec{V} \right) = 0$$

Incompressible flow:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \qquad \nabla \cdot \vec{V} = 0$$

• Conservation of momentum (inviscid flow):

$$\rho \frac{D\vec{V}}{Dt} = \rho \vec{g} - \vec{\nabla} p$$

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• Rotation of a fluid element:

$$\omega_{x} = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) \qquad \qquad \omega_{z} = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) \omega_{y} = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right)$$

Vorticity:

 $\vec{\zeta} = 2\vec{\omega} = \vec{\nabla} \times \vec{V}$

Velocity Potential

- Assumptions
 - Homogeneous
 - Continuous
 - Incompressible
 - Non-viscous (inviscid)
- Extra assumption:
 - Irrotational flow \rightarrow

$$\vec{\zeta} = 2\vec{\omega} = \vec{\nabla} \times \vec{V} = 0$$



Velocity Potential

• Theorem in vector calculus:

In case the curl of a vector is zero, then the vector must be the gradient of a *scalar* function

$$\vec{\zeta} = 2\vec{\omega} = \vec{\nabla} \times \vec{V} = 0$$

• Thus:

$$\vec{V} = \nabla \Phi$$

- \bullet where $\Phi\,$ is a scalar function
- Φ is known as the Velocity Potential



Velocity Potential

• The velocity potential is a function of time and position: $\Phi(x, y, z, t)$

• The spatial derivatives of the velocity potential equal the velocity components at a time and position:

$$\frac{\partial \Phi}{\partial x} = u$$
 $\frac{\partial \Phi}{\partial y} = v$ $\frac{\partial \Phi}{\partial z} = w$

• Potential lines are defined as:

 $\Phi(x, y, z, t) = constant$


Fluid Mechanics Laws

Velocity Potential

• In 2D polar coordinates:

 $\Phi(r,\theta,t)$

$$v_r = \frac{\partial \Phi}{\partial r}$$
$$v_{\theta} = \frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta}$$



Fluid Mechanics Laws Velocity Potential

• Continuity equation for incompressible flow:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

• Velocity components:

$$u = \frac{\partial \Phi}{\partial x}$$
 $v = \frac{\partial \Phi}{\partial y}$ $w = \frac{\partial \Phi}{\partial z}$

• Continuity equation for potential flow:

$$\frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} + \frac{\partial^2 \Phi}{\partial z^2} = 0$$

$$\nabla^2 \Phi = 0$$
 Laplace equation



Fluid Mechanics Laws Velocity Potential

• Irrotational flow (in 2D):

$$u = \frac{\partial \Phi}{\partial x} \quad \text{thus:} \qquad \frac{\partial u}{\partial y} = \frac{\partial}{\partial y} \frac{\partial \Phi}{\partial x} = \frac{\partial^2 \Phi}{\partial y \partial x}$$
$$v = \frac{\partial \Phi}{\partial y} \quad \text{thus:} \qquad \frac{\partial v}{\partial x} = \frac{\partial}{\partial x} \frac{\partial \Phi}{\partial y} = \frac{\partial^2 \Phi}{\partial x \partial y}$$
$$\frac{\partial^2 \Phi}{\partial y \partial x} = \frac{\partial^2 \Phi}{\partial x \partial y} \quad \text{thus:} \qquad \omega_z = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) = 0$$



Fluid Mechanics Laws Velocity Potential

• Irrotational flow (in 3D):

$$\frac{\partial v}{\partial x} = \frac{\partial u}{\partial y}$$
 in the (x,y) plane

$$\frac{\partial w}{\partial y} = \frac{\partial v}{\partial z}$$
 in the (y,z) plane

$$\frac{\partial u}{\partial z} = \frac{\partial w}{\partial x}$$
 in the (x,z) plane

$$\omega_{x} = \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right)$$

$$\omega_{y} = \frac{1}{2} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right)$$

$$\omega_z = \frac{1}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$



• Recall the Euler Equations (sheet 29):

$$\rho \frac{D\vec{V}}{Dt} = \rho \vec{g} - \vec{\nabla} p$$



• Recall the Euler Equations (sheet 29):

$$\rho \frac{D\vec{V}}{Dt} = \rho \vec{g} - \vec{\nabla} p$$

• Note that:

$$\frac{D\vec{V}}{Dt} = \frac{\partial\vec{V}}{\partial t} + (\vec{V}\cdot\nabla)\vec{V} \qquad \qquad (\vec{V}\cdot\nabla)\vec{V} = \nabla\left(\frac{1}{2}V^2\right) + \vec{\zeta}\times\vec{V}$$



• Recall the Euler Equations (sheet 29):

$$\rho \frac{D\vec{V}}{Dt} = \rho \vec{g} - \vec{\nabla} p$$

• Note that:

$$\frac{D\vec{V}}{Dt} = \frac{\partial\vec{V}}{\partial t} + (\vec{V}\cdot\nabla)\vec{V} \qquad \qquad (\vec{V}\cdot\nabla)\vec{V} = \nabla\left(\frac{1}{2}V^2\right) + \vec{\zeta}\times\vec{V}$$

• Then:

$$\rho\left(\frac{\partial \vec{V}}{\partial t} + \nabla\left(\frac{1}{2}V^2\right) + \vec{\zeta} \times \vec{V}\right) = \rho \vec{g} - \vec{\nabla}p$$



• Recall the Euler Equations (sheet 29):

$$\rho \frac{D\vec{V}}{Dt} = \rho \vec{g} - \vec{\nabla} p$$

• Note that:

$$\frac{D\vec{V}}{Dt} = \frac{\partial\vec{V}}{\partial t} + (\vec{V}\cdot\nabla)\vec{V} \qquad \qquad (\vec{V}\cdot\nabla)\vec{V} = \nabla\left(\frac{1}{2}V^2\right) + \vec{\zeta}\times\vec{V}$$

• Then:

$$\frac{\partial \vec{V}}{\partial t} + \nabla \left(\frac{1}{2}V^2\right) + \vec{\zeta} \times \vec{V} - \vec{g} + \vec{\nabla}\frac{p}{\rho} = 0$$



• Dot with small displacement along streamline $d\mathbf{r} = (dx, dy, dz)$:

$$\left[\frac{\partial \vec{V}}{\partial t} + \nabla \left(\frac{1}{2}V^2\right) + \vec{\zeta} \times \vec{V} - \vec{g} + \nabla \frac{p}{\rho}\right] \cdot d\vec{r} = 0$$

• Then 'work done' by fluid along *dr*:

$$\frac{\partial \vec{V}}{\partial t} \cdot d\vec{r} + d\left(\frac{1}{2}V^2\right) + \vec{\zeta} \times \vec{V} \cdot d\vec{r} - gdz + \frac{dp}{\rho} = 0$$

• This can be integrated along any two points along a streamline, however: $\vec{\zeta} \times \vec{V} \cdot d\vec{r}$ is a difficult to evaluate term



• Possibilities to deal with $\vec{\zeta} \times \vec{V} \cdot d\vec{r}$:

- \vec{V} is zero; no flow only hydrostatics
- $\vec{\zeta}$ is zero; irrotational flow
- $d\vec{r}$ is perpendicular to $\vec{\zeta} \times \vec{V}$; very rare solution
- $d\vec{r}$ is parallel to $\vec{\zeta} \times \vec{V}$; integrate along *streamline*



- Possibilities to deal with $\vec{\zeta} \times \vec{V} \cdot d\vec{r}$:
 - \vec{V} is zero; no flow only hydrostatics
 - $\vec{\zeta}$ is zero; irrotational flow
 - $d\vec{r}$ is perpendicular to $\vec{\zeta} \times \vec{V}$; very rare solution
 - $d\vec{r}$ is parallel to $\vec{\zeta} \times \vec{V}$; integrate along streamline



• Possibilities to deal with $\vec{\zeta} \times \vec{V} \cdot d\vec{r}$:

- \vec{V} is zero; no flow only hydrostatics
- $\vec{\zeta}$ is zero; irrotational flow \rightarrow POTENTIAL FLOW
- $d\vec{r}$ is perpendicular to $\vec{\zeta} \times \vec{V}$; very rare solution
- $d\vec{r}$ is parallel to $\vec{\zeta} \times \vec{V}$; integrate along streamline



• Potential flow: $\vec{V} = \nabla \Phi$

$$\frac{\partial \vec{V}}{\partial t} \cdot d\vec{r} + d\left(\frac{1}{2}V^2\right) - gdz + \frac{dp}{\rho} = 0$$

$$\frac{\partial \nabla \Phi}{\partial t} \cdot d\vec{r} + d\frac{1}{2} (\nabla \Phi)^2 - gdz + \frac{dp}{\rho} = 0$$

$$d\frac{\partial\Phi}{\partial t} + d\frac{1}{2}(\nabla\Phi)^2 - gdz + \frac{dp}{\rho} = 0$$



• Potential flow:
$$\vec{V} = \nabla \Phi$$

$$d\frac{\partial\Phi}{\partial t} + d\frac{1}{2}(\nabla\Phi)^2 - gdz + \frac{dp}{\rho} = 0$$

• Finally simple integration yields (between any two points):

$$\int_{1}^{2} d\frac{\partial\Phi}{\partial t} + \int_{1}^{2} d\left(\frac{1}{2}V^{2}\right) - \int_{1}^{2} gdz + \int_{1}^{2} \frac{dp}{\rho} = 0$$

$$\frac{\partial \Phi}{\partial t_2} - \frac{\partial \Phi}{\partial t_1} + \frac{1}{2}(V_2^2 - V_1^2) - g(z_2 - z_1) + \frac{p_2 - p_1}{\rho} = 0$$



• Potential flow:
$$\vec{V} = \nabla \Phi$$

$$d\frac{\partial\Phi}{\partial t} + d\frac{1}{2}(\nabla\Phi)^2 - gdz + \frac{dp}{\rho} = 0$$

• Finally simple integration yields (between any two points):

$$\frac{\partial \Phi}{\partial t_2} - \frac{\partial \Phi}{\partial t_1} + \frac{1}{2}(V_2^2 - V_1^2) - g(z_2 - z_1) + \frac{p_2 - p_1}{\rho} = 0$$

$$\frac{\partial \Phi}{\partial t} + \frac{1}{2} \left(\nabla \Phi \right)^2 - gz + \frac{p}{\rho} = constant \qquad \text{Bernoulli equation}$$



Fluid Mechanics Laws

Steady and Unsteady Flow

• Steady flow: at any point in flow the velocity is independent of time

$$\frac{d\vec{V}}{dt} = 0 \qquad \qquad \frac{\partial\Phi}{\partial t} + \frac{1}{2}(\nabla\Phi)^2 - gz + \frac{p}{\rho} = constant$$

- Unsteady flow: any other flow
 - E.g. waves
 - Motions of floating objects in a flow
 - etc.



Stream lines (2D)

- Definition:
 - A line that follows the flow (as if you would have injected dye into the flow)
- Stream line: curve tangent to flow velocity vectors at a time instant:









Stream function (2D)



Rate of flow through ds:

$$d\Psi = -(\vec{V}\cdot\vec{n})ds$$

 $\vec{V} = \begin{bmatrix} u \\ v \end{bmatrix}$



 $ds = \sqrt{dx^2 + dy^2}$









Stream function (2D)

Definition stream funtion:

$$d\Psi = udy - vdx$$





Stream funtion (2D)

• $\Psi\,$ is the (2D) stream function, with:

$$\frac{d\Psi}{dy} = u \qquad \qquad \frac{d\Psi}{dx} = -\nu$$

- Difference of Ψ between neighboring stream lines: rate of flow between streamlines



Potential flow properties

Summary

- Orthogonality: $\frac{d\Psi}{dy} = \frac{d\Phi}{dx} = u$ $\frac{d\Psi}{dx} = -\frac{d\Phi}{dy} = -v$
- Impervious boundaries equals streamline: $\frac{d\Phi}{dn} = 0$ $\Psi = constant$
- Conditions far away from disturbance:

$$R \to \infty \Rightarrow \Phi \to \Phi_{\infty} \land \Psi \to \Psi_{\infty}$$

- Steady and unsteady flow: $\frac{d\vec{V}}{dt} = 0$, $\frac{d\Phi}{dt} = 0$
- Uniform flow (s coordinate along streamline):

$$\frac{d\vec{V}}{ds} = 0$$



Introduction

- Using the previous we can define 'flow elements'
- Building blocks that respect the assumptions of potential flow:
 - Homogeneous
 - Continuous
 - Inviscid
 - Incompressible
 - Irrotational
- We can add these elements up to construct realistic flow patterns
- Modeling of submerged bodies by matching streamlines to body outline
- Using the velocity potential, stream function and Bernoulli equation to find velocities, pressures and eventually fluid forces on bodies



Uniform flow





Source and sink flow





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Source and sink flow

$$\Phi = +\frac{Q}{2\pi} \cdot \ln r$$
$$\Psi = +\frac{Q}{2\pi} \cdot \theta$$

$$v_r = \frac{\partial \Phi}{\partial r} = \frac{1}{r} \cdot \frac{\partial \Psi}{\partial \theta} = \frac{Q}{2\pi r}$$
$$v_\theta = \frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta} = -\frac{\partial \Psi}{\partial r} = 0$$





Circulation or vortex elements

$$\Phi = +\frac{\Gamma}{2\pi} \cdot \theta$$
$$\Psi = +\frac{\Gamma}{2\pi} \cdot \ln r$$

$$v_r = \frac{\partial \Phi}{\partial r} = \frac{1}{r} \cdot \frac{\partial \Psi}{\partial \theta} = 0$$
$$v_\theta = \frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta} = -\frac{\partial \Psi}{\partial r} = \frac{\Gamma}{2\pi r}$$





Circulation or vortex elements

$$\Phi = +\frac{\Gamma}{2\pi} \cdot \theta \qquad \Psi = +\frac{\Gamma}{2\pi} \cdot \ln r$$
$$v_r = \frac{\partial \Phi}{\partial r} = \frac{1}{r} \cdot \frac{\partial \Psi}{\partial \theta} = 0$$
$$v_\theta = \frac{1}{r} \cdot \frac{\partial \Phi}{\partial \theta} = -\frac{\partial \Psi}{\partial r} = \frac{\Gamma}{2\pi r}$$

Circulation strenght constant:

$$\Gamma = \oint v_{\theta} \cdot ds = 2\pi r \cdot v_{\theta} = constant$$

Therefore: no rotation, origin singular point: velocity infinite



Methodology (source in positive uniform flow)

 The resulting velocity fields, potential fields or stream function fields may be simply superposed to find the combined flow patterns







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(Using stream function values)



Sink in negative uniform flow

• Besides graphically this works also with formulas:





Separated source and sink

$$\Psi_{source} = +\frac{Q}{2\pi} \cdot \theta_1 = +\frac{Q}{2\pi} \cdot \arctan\frac{y}{x_1}$$
$$\Psi_{sink} = -\frac{Q}{2\pi} \cdot \theta_2 = -\frac{Q}{2\pi} \cdot \arctan\frac{y}{x_2}$$

$$\Psi = \frac{Q}{2\pi} \cdot \arctan\frac{2ys}{x^2 + y^2 - s^2}$$





Separated source and sink in uniform flow



$$\Psi = \frac{Q}{2\pi} \cdot \arctan\frac{2ys}{x^2 + y^2 - s^2} + U_{\infty}y$$


Separated source and sink in uniform flow



Streamline resembles fixed boundary (Rankine oval)

The flow outside this streamline resembles flow around solid boundary with this shape Shape can be changed by using more source-sinks along x-axis with different strenghts



Separated source and sink in uniform flow



This approach can be extended to form ship forms in 2D or 3D:

Rankine ship forms

Useful for simple flow computations



Doublet or dipole

When distance 2s becomes zero a new basic flow element is produced:

Doublet or dipole producing flow in positive x-direction

$$\Psi = \lim_{s \to 0} \left[\frac{Q}{2\pi} \cdot \arctan\left(\frac{2ys}{x^2 + y^2 - s^2}\right) \right]$$
$$\Psi = \lim_{s \to 0} \left[\frac{Q}{\pi} s \cdot \left(\frac{y}{x^2 + y^2 - s^2}\right) \right]$$

Note: in book errors w.r.t. to doublet and its orientation!





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Set constant:
$$\mu = \frac{Q}{\pi} s$$



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$$\Psi = \lim_{s \to 0} \left[\frac{Q}{\pi} s \cdot \left(\frac{y}{x^2 + y^2 - s^2}\right) \right]$$
Disappears when: $s \to 0$ Set constant: $\mu = \frac{Q}{\pi} s$



Doublet or dipole

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$$\Psi = \lim_{s \to 0} \left[\frac{Q}{2\pi} \cdot \arctan\left(\frac{2ys}{x^2 + y^2 - s^2}\right) \right]$$

$$\Psi = \mu \cdot \frac{y}{x^2 + y^2} = \mu \cdot \frac{\sin\theta}{r}$$

$$\Phi = -\mu \cdot \frac{x}{x^2 + y^2} = -\mu \cdot \frac{\cos\theta}{r}$$



Doublet in a uniform flow



Doublet pointing in positive x-direction, uniform flow in negative xdirection:





Doublet in a uniform flow

$$\Phi = -\mu \cdot \frac{x}{x^2 + y^2} - U_{\infty} x$$
$$\Phi = -\mu \cdot \frac{\cos\theta}{r} - U_{\infty} r \cos\theta$$

$$\Psi = \mu \cdot \frac{y}{x^2 + y^2} - U_{\infty} y$$

$$\Psi = \mu \cdot \frac{\sin\theta}{r} - U_{\infty} r \sin\theta$$

Set $\Psi = 0$ then:

True when:

$$\Psi = y \left[\frac{\mu}{x^2 + y^2} - U_{\infty} \right] = 0 \qquad \qquad y = 0$$
$$\frac{\mu}{x^2 + y^2} - U_{\infty} = 0 \implies x^2 + y^2 = \frac{\mu}{U_{\infty}}$$



Doublet in a uniform flow: flow around a circle

• The radius of the circle:

$$R = \sqrt{\frac{\mu}{U_{\alpha}}}$$

• Doublet strength needed for radius R:

$$\mu = U_{\infty}R^2$$

• This yields the following:

$$\Phi = -\frac{U_{\infty}R^{2}\cos\theta}{r} - U_{\infty}r\cos\theta = RU_{\infty}\left[\frac{R}{r} - \frac{r}{R}\right]\cos\theta$$
$$\Psi = \frac{U_{\infty}R^{2}\sin\theta}{r} - U_{\infty}r\sin\theta = RU_{\infty}\left[\frac{R}{r} - \frac{r}{R}\right]\sin\theta$$



$$\Phi = -\mu \cdot \frac{\cos \theta}{r} - U_{\infty} r \cos \theta$$

<u>___</u>

$$\Psi = \mu \cdot \frac{\sin\theta}{r} - U_{\infty} r \sin\theta$$

Doublet in a uniform flow: flow around a circle





Doublet in a uniform flow: flow around a circle



TUDelft

Doublet in a uniform flow: flow around a circle



TUDelft

Evaluate velocities on cylinder wall

• Generally, velocity on cylinder wall:

 $\Psi = \mu \cdot \frac{\sin\theta}{r} - U_{\infty} r \sin\theta$

$$v_{\theta}(r=R) = -\left[\frac{\partial\Psi}{\partial r}\right]_{r=R} = -\frac{\partial}{\partial r}\left[\frac{U_{\infty}R^{2}\sin\theta}{r} - U_{\infty}r\sin\theta\right] = \dots = -2U_{\infty}\sin\theta$$



Evaluate pressures on cylinder wall

• Use the Bernoulli equation:

$$\frac{1}{2}\rho U_{\infty}^{2} + 0 = p + \frac{1}{2}\rho v_{\theta}^{2}$$

$$v_{\theta} = -2U_{\infty}\sin\theta$$
Pressure at stagnation points:
$$v = 0$$
Pressure at cylinder boundary:
$$v_{r} = 0$$

$$v_{r} = 0$$

Assuming constant elevation

• Result:
$$p = \frac{1}{2}\rho U_{\infty}^2 [1 - 4\sin^2\theta]$$



Evaluate pressures on cylinder wall

• Velocity profile:

$$v_{\theta} = -2U_{\infty}\sin\theta$$

• Pressure profile:

$$p = \frac{1}{2}\rho U_{\infty}^2 [1 - 4\sin^2\theta]$$





Evaluate pressures on cylinder wall

• Velocity profile:

$$v_{\theta} = -2U_{\infty}\sin\theta$$





Pipeline near seabed

• How to calculate the flow around a pipeline near the seabed?





Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:





 y_{\uparrow}

 y_0

 y_0

Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
 - undisturbed
 - cylinder
 - mirrored cylinder
- Result is zero normal flow on seabed



 U_{∞}

Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
 - undisturbed
 - cylinder
 - mirrored cylinder
- Result is zero normal flow on seabed

• Is flow exactly right?





 y_{\uparrow}

 y_0

 y_0

Pipeline near seabed

- Mirror flow in seabed!
- Superpose flows:
 - undisturbed
 - cylinder
 - mirrored cylinder
- Result is zero normal flow on seabed

 Is flow exactly right? NO: interaction cylinders not modeled!



 U_{∞}

- Add circulation (or vortex flow element)
- Resulting velocity field:



- Add circulation (or vortex flow element)
- Resulting velocity field:





- Add circulation (or vortex flow element)
- Resulting velocity field:





- Add circulation (or vortex flow element)
- Resulting velocity field:





- Now integration of pressure yields a net force perpendicular to the undisturbed flow direction: the **lift** force
- However: still no net force in the flow direction: no drag





Sources images

All images are from the book Offshore Hydromechanics by Journée and Massie.



