Dredging Processes

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5. Clay Cutting











Dredging A Way Of Life





Offshore A Way Of Life





Offshore & Dredging Engineering

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Mechanisms





Definitions





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The Flow Type





Forces on the Layer Cut





Forces on the Blade











Resulting Equations

$$K_2 = \frac{C - A \cdot \cos(\alpha + \beta)}{\sin(\alpha + \beta)}$$

$$F_h = K_2 \cdot \sin(\alpha) + A \cdot \cos(\alpha)$$

$$F_{\nu} = K_2 \cdot \cos(\alpha) - A \cdot \sin(\alpha)$$

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Strain Rate Effect







Problem Definition

How to model the strengthening of clay as a function of the strain rate

$$\tau = \tau_{y} + \tau_{0} \cdot \ln \begin{bmatrix} \cdot \\ 1 + \frac{\varepsilon}{\cdot} \\ \cdot \\ \varepsilon_{0} \end{bmatrix}$$



Energy Barriers Mitchell 1976









The Bolzman Distribution



$$\mathbf{p}(\mathbf{E}) = \frac{1}{\mathbf{R} \cdot \mathbf{T}} \cdot \exp\left[\frac{-\mathbf{E}}{\mathbf{R} \cdot \mathbf{T}}\right]$$







$$\mathbf{p}_{\mathrm{E}>\mathrm{E}_{\mathrm{a}}} = \exp\left[\frac{-\mathrm{E}_{\mathrm{a}}}{\mathrm{R}\cdot\mathrm{T}}\right]$$



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Strain Rate



$$\overset{\cdot}{\epsilon} = 2 \cdot \mathbf{X} \cdot \frac{\mathbf{k} \cdot \mathbf{T}}{\mathbf{h}} \cdot exp \left[\frac{-\mathbf{E}_{a}}{\mathbf{R} \cdot \mathbf{T}} \right] \cdot sinh \left[\frac{\tau \cdot \lambda \cdot \mathbf{N}}{2 \cdot \mathbf{S} \cdot \mathbf{R} \cdot \mathbf{T}} \right]$$



Theory Proposed





Case 1





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$$\dot{\varepsilon} = \mathbf{X} \cdot \frac{\mathbf{k} \cdot \mathbf{T}}{\mathbf{h} \cdot \mathbf{i}} \cdot \left\{ \exp\left[-\left(\frac{\mathbf{E}_{\mathbf{a}}}{\mathbf{R} \cdot \mathbf{T}} - \frac{\mathbf{\tau} \cdot \boldsymbol{\lambda} \cdot \mathbf{N}}{2 \cdot \mathbf{S} \cdot \mathbf{R} \cdot \mathbf{T}}\right) \right] - \exp\left[\frac{-\mathbf{E}_{\ell}}{\mathbf{R} \cdot \mathbf{T}}\right] \right\}$$



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Case 3



$$\dot{\varepsilon} = \mathbf{X} \cdot \frac{\mathbf{k} \cdot \mathbf{T}}{\mathbf{h} \cdot \mathbf{i}} \cdot \left\{ \exp\left[-\left(\frac{\mathbf{E}_{\mathbf{a}}}{\mathbf{R} \cdot \mathbf{T}} - \frac{\mathbf{\tau} \cdot \boldsymbol{\lambda} \cdot \mathbf{N}}{2 \cdot \mathbf{S} \cdot \mathbf{R} \cdot \mathbf{T}}\right) \right] - \exp\left[\frac{-\mathbf{E}_{\ell}}{\mathbf{R} \cdot \mathbf{T}}\right] \right\}$$





Case 4





$$\tau = (\mathbf{E}_{\mathbf{a}} - \mathbf{E}_{\ell}) \cdot \frac{2 \cdot \mathbf{S}}{\lambda \cdot \mathbf{N}} + \mathbf{R} \cdot \mathbf{T} \cdot \frac{2 \cdot \mathbf{S}}{\lambda \cdot \mathbf{N}} \cdot \ell \mathbf{n} \begin{bmatrix} \mathbf{i} \\ \mathbf{1} + \frac{\mathbf{\hat{\epsilon}}}{\mathbf{\hat{\epsilon}_0}} \end{bmatrix}$$

$$\dot{\boldsymbol{\varepsilon}_0} = \left[\frac{\mathbf{X} \cdot \mathbf{k} \cdot \mathbf{T}}{\mathbf{h} \cdot \mathbf{i}} \cdot \exp\left[\frac{-\mathbf{E}_{\ell}}{\mathbf{R} \cdot \mathbf{T}}\right]\right]$$

Mitchell 1976

 $S = a + b.\sigma_e$

$$\tau = \mathbf{a} \cdot \left\{ (\mathbf{E}_{\mathbf{a}} - \mathbf{E}_{\ell}) \cdot \frac{2}{\lambda \cdot \mathbf{N}} + \mathbf{R} \cdot \mathbf{T} \cdot \frac{2}{\lambda \cdot \mathbf{N}} \cdot \ell \mathbf{n} \left[\mathbf{1} + \frac{\dot{\varepsilon}}{\varepsilon_{0}} \right] \right\}$$
$$+ \mathbf{b} \cdot \left\{ (\mathbf{E}_{\mathbf{a}} - \mathbf{E}_{\ell}) \cdot \frac{2}{\lambda \cdot \mathbf{N}} + \mathbf{R} \cdot \mathbf{T} \cdot \frac{2}{\lambda \cdot \mathbf{N}} \cdot \ell \mathbf{n} \left[\mathbf{1} + \frac{\dot{\varepsilon}}{\varepsilon_{0}} \right] \right\} \cdot \sigma_{\mathbf{e}}$$
$$\tau = \tau_{\mathbf{c}} + \sigma_{\mathbf{e}} \cdot \mathbf{tan}(\phi)$$
$$\tau = \mathbf{a} \cdot \left\{ \mathbf{E}_{\mathbf{a}} \cdot \frac{2}{\lambda \cdot \mathbf{N}} + \mathbf{R} \cdot \mathbf{T} \cdot \frac{2}{\lambda \cdot \mathbf{N}} \cdot \ell \mathbf{n} \left[\frac{\dot{\varepsilon}}{\mathbf{B}} \right] \right\} + \mathbf{b} \cdot \left\{ \mathbf{E}_{\mathbf{a}} \cdot \frac{2}{\lambda \cdot \mathbf{N}} + \mathbf{R} \cdot \mathbf{T} \cdot \frac{2}{\lambda \cdot \mathbf{N}} \cdot \ell \mathbf{n} \left[\frac{\dot{\varepsilon}}{\mathbf{B}} \right] \right\} \cdot \sigma_{\mathbf{e}}$$



Simplifications

$$\tau = \tau_{y} + \tau_{0} \cdot \ln \begin{bmatrix} \cdot \\ 1 + \frac{\varepsilon}{\cdot} \\ \cdot \\ \varepsilon_{0} \end{bmatrix}$$

$$\frac{(d\epsilon/dt)}{(d\epsilon_0/dt)} << 1$$

$$\tau = \tau_{y} + \tau_{0} \cdot \frac{\varepsilon}{\varepsilon_{0}}$$

$(d\epsilon/dt)/(d\epsilon_0/dt) >> 1$

$$\tau = \tau_{y} + \tau_{0} \cdot \ln \left[\frac{\cdot}{\frac{\varepsilon}{\cdot}} \right]$$

 $\frac{\frac{d\varepsilon}{dt}}{\frac{d\varepsilon}{dt}} > 1$ $\tau - \tau_{y} << \tau_{y}$ $\Gamma = \int_{\tau_{y}}^{\tau_{0}} \tau_{y}$

$$\tau = \tau_{\mathbf{y}} \cdot \left[\frac{\cdot}{\varepsilon} \\ \frac{\cdot}{\varepsilon_0} \right]^{\gamma \cdot \mathbf{y}}$$

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Shear Strength vs Strain Rate





Shear Strength vs Strain Rate





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Rheological models







Conclusions

The new shear strength equation matches the measurements very well
The new shear strength equation can be simplified to match existing equations
For dredging applications the dynamic shear strength (cohesion) is about two times the static shear strength



Resulting Equations, Clay Cutting

$$\mathbf{K}_{2} = \frac{\mathbf{C} - \mathbf{A} \cdot \cos(\alpha + \beta)}{\sin(\alpha + \beta)}$$

$$\mathbf{F}_{\mathbf{h}} = \mathbf{K}_2 \cdot \sin(\alpha) + \mathbf{A} \cdot \cos(\alpha)$$

$$\mathbf{F}_{v} = \mathbf{K}_{2} \cdot \cos(\alpha) - \mathbf{A} \cdot \sin(\alpha)$$

$$\mathbf{C} = \frac{\mathbf{c} \cdot \mathbf{h}_{i} \cdot \mathbf{w}}{\sin(\beta)}$$

$$\mathbf{A} = \frac{\mathbf{a} \cdot \mathbf{h}_{\mathbf{b}} \cdot \mathbf{w}}{\sin(\alpha)}$$







$$\begin{split} \mathbf{F}_{\mathbf{h}} &= \left\{ \frac{\mathbf{c}_{\mathbf{d}} \cdot \mathbf{h}_{\mathbf{i}}}{\sin\left(\beta\right) \cdot \sin\left(\alpha + \beta\right)} + \frac{\mathbf{a} \cdot \mathbf{h}_{\mathbf{b}} \cdot \sin\left(\beta\right)}{\sin\left(\alpha\right) \cdot \sin\left(\alpha + \beta\right)} \right\} \cdot \mathbf{w} \\ \mathbf{k}_{\mathbf{a}} &= \frac{\mathbf{a} \cdot \mathbf{h}_{\mathbf{b}}}{\mathbf{c}_{\mathbf{d}} \cdot \mathbf{h}_{\mathbf{i}}} \\ \\ \mathbf{F}_{\mathbf{h}} &= \left\{ \frac{1}{\sin\left(\beta\right) \cdot \sin\left(\alpha + \beta\right)} + \frac{\mathbf{k}_{\mathbf{a}} \cdot \sin\left(\beta\right)}{\sin\left(\alpha\right) \cdot \sin\left(\alpha + \beta\right)} \right\} \cdot \mathbf{c}_{\mathbf{d}} \cdot \mathbf{h}_{\mathbf{i}} \cdot \mathbf{w} \end{split}$$





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The Shear Angle β





The Horizontal Cutting Force F_h (c=1 kPa)





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The Vertical Cutting Force F_v (c=1 kPa)



The Vertical Cutting Force F_v vs The Blade Angle lpha



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$$\mathbf{c}_{\mathbf{d}} = \mathbf{c}_{\mathbf{y}} + \mathbf{c}_{\mathbf{0}} \cdot \ln \left(\begin{array}{c} \cdot \\ \mathbf{\epsilon} \\ \mathbf{1} + \frac{\varepsilon}{\cdot} \\ \mathbf{\epsilon}_{\mathbf{0}} \end{array} \right) \approx 2 \cdot \mathbf{c}_{\mathbf{y}}$$

1

$$c_y \approx 6 \cdot SPT \implies c_d \approx 12 \cdot SPT$$

$$\mathbf{E}_{sp} = \frac{\mathbf{F}_{h} \cdot \mathbf{v}_{c}}{\mathbf{h}_{i} \cdot \mathbf{w} \cdot \mathbf{v}_{c}} \qquad \mathbf{Q} = \frac{\mathbf{P}}{\mathbf{E}_{sp}}$$

$$\mathbf{E}_{sp} = \left\{ \frac{1}{\sin(\beta) \cdot \sin(\alpha + \beta)} + \frac{\mathbf{k}_{a} \cdot \sin(\beta)}{\sin(\alpha) \cdot \sin(\alpha + \beta)} \right\} \cdot 12 \cdot SPT$$





$$\dot{\boldsymbol{\epsilon}}_{a} = 1.4 \cdot \frac{\boldsymbol{v}_{c}}{\boldsymbol{h}_{i}} \cdot \frac{sin(\beta)}{sin(\alpha + \beta)}$$

$$\tau_0 \ / \ \tau_y = 0.1428, \ \dot{\epsilon}_0 = 0.03$$







Specific Energy in Clay, 30 Degree Blade





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Production in Clay, 30 Degree Blade





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Specific Energy in Clay, 45 Degree Blade







Production in Clay, 45 Degree Blade







Specific Energy in Clay, 60 Degree Blade





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ProDuction in Clay, 60 Degree Blade





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The Tear Type





The Reduced Mohr Circle







The specific energy Esp as a function of the compressive strength of clay, for different layer thicknesses at vc=1 m/s for a 60 degree blade.

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The Curling Type











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Equilibrium of Moments

$$\left(\frac{\mathbf{A} - \mathbf{C} \cdot \cos(\alpha + \beta)}{\sin(\alpha + \beta)}\right) \cdot \frac{\lambda_1 \cdot \mathbf{h}_i}{\sin(\beta)} = \left(\frac{\mathbf{C} - \mathbf{A} \cdot \cos(\alpha + \beta)}{\sin(\alpha + \beta)}\right) \cdot \frac{\lambda_2 \cdot \mathbf{h}_b}{\sin(\alpha)}$$

$$\mathbf{A} \cdot \mathbf{x}^2 + \mathbf{B} \cdot \mathbf{x} + \mathbf{C} = 0$$

$$\mathbf{h}_b^{'} = \mathbf{x} = \frac{-\mathbf{B} - \sqrt{\mathbf{B}^2 - 4 \cdot \mathbf{A} \cdot \mathbf{C}}}{2 \cdot \mathbf{A}}$$

$$\mathbf{A} = \frac{\lambda_2 \cdot \mathbf{a} \cdot \cos(\alpha + \beta)}{\sin(\alpha) \cdot \sin(\alpha)}$$

$$\mathbf{B} = \frac{\lambda_1 \cdot \mathbf{a} - \lambda_2 \cdot \mathbf{c}}{\sin(\alpha) \cdot \sin(\beta)} \cdot \mathbf{h}_i$$

$$\mathbf{C} = -\frac{\lambda_1 \cdot \mathbf{c} \cdot \cos(\alpha + \beta)}{\sin(\beta) \cdot \sin(\beta)} \cdot \mathbf{h}_i \cdot \mathbf{h}_i$$
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Questions?

Sources images

- 1. A model cutter head, source: Delft University of Technology.
- 2. Off shore platform, source: Castrol (Switzerland) AG
- 3. Off shore platform, source: http://www.wireropetraining.com



