

Traffic Flow Theory and Simulation

V.L. Knoop

Lecture 6
Traffic Analysis: Characteristics

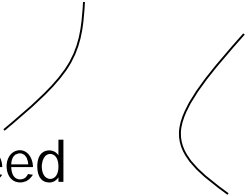



Traffic analyses - characteristics

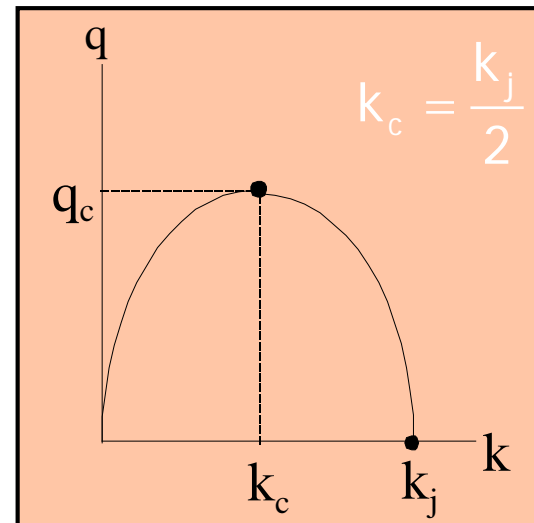
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Recap of shockwave theory

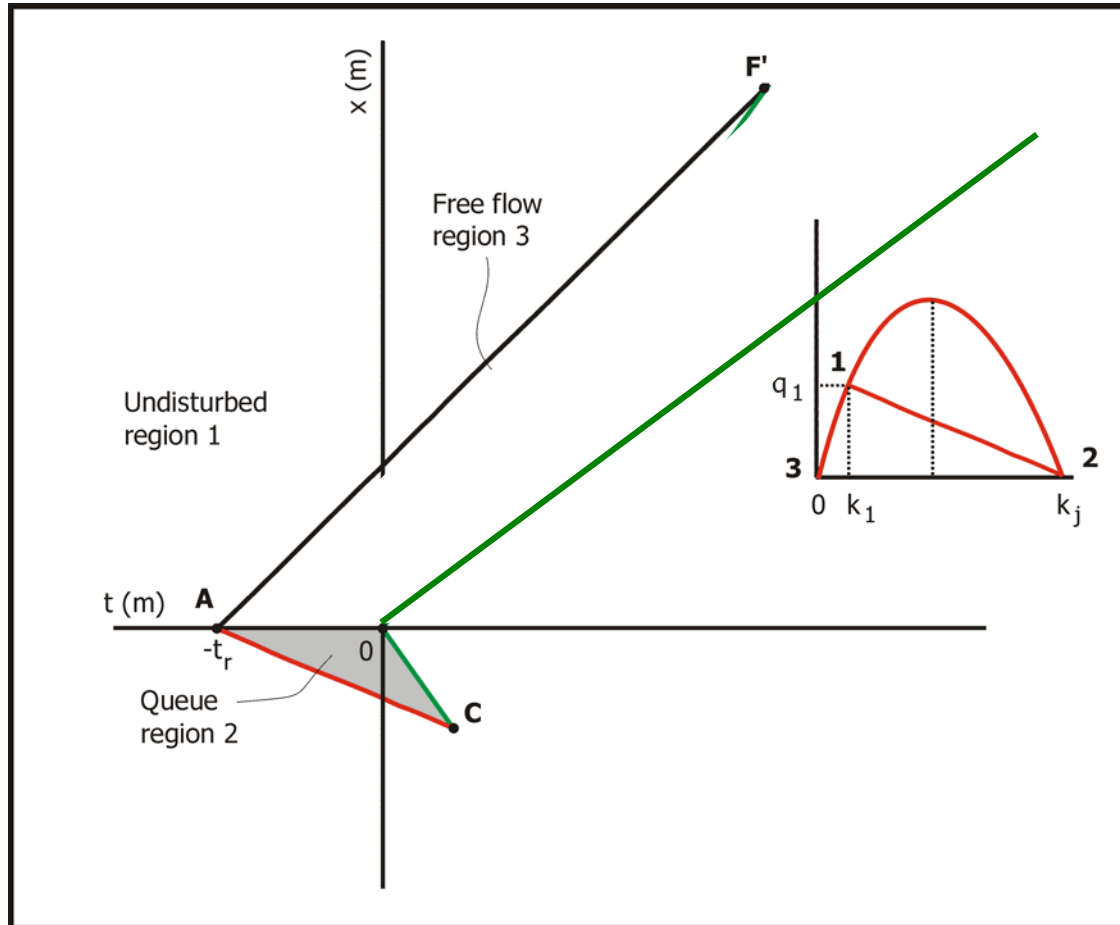
- Queuing at signalized intersection
- Upstream traffic demand equals q_1 (region 1)
- Initial conditions are free-flow (k_1, q_1) for all x until $t = -t_r$
- Assume Greenshields simplified fundamental diagram

Free speed 

Jam density 

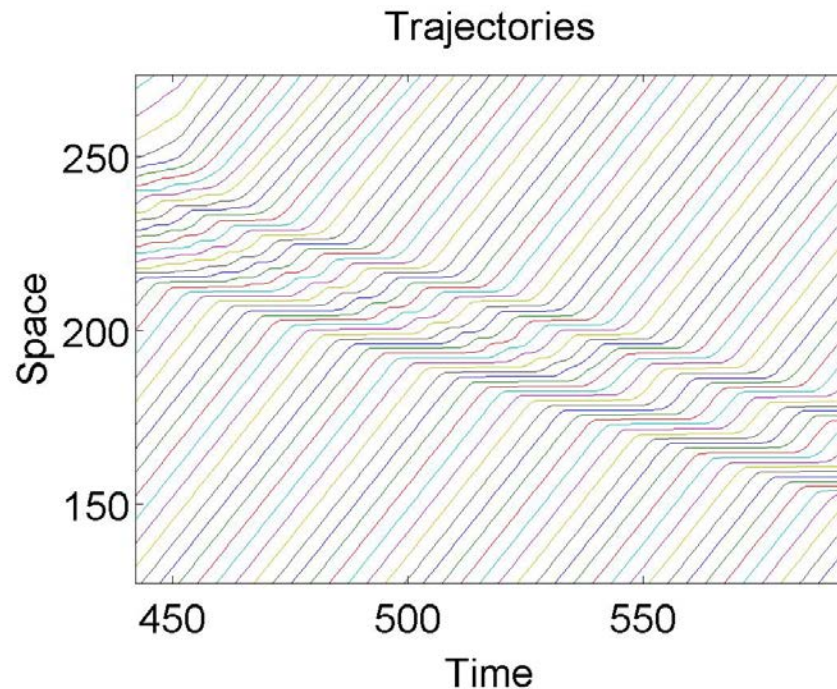


Queuing at signalized intersection (2)



Characteristics?

- Characteristic: line in x-t plane with constant properties



Method of Characteristics (MoC)

- Approach to solve traffic evolution analytically
 - Construct *characteristics / characteristic curves*: lines in the xt -plane with constant density (and speed, and flow)
 - Conditions known at boundaries, so we know them along the characteristics as well
 - Enough characteristics \Rightarrow determine the traffic state everywhere

Method of characteristics - recipe

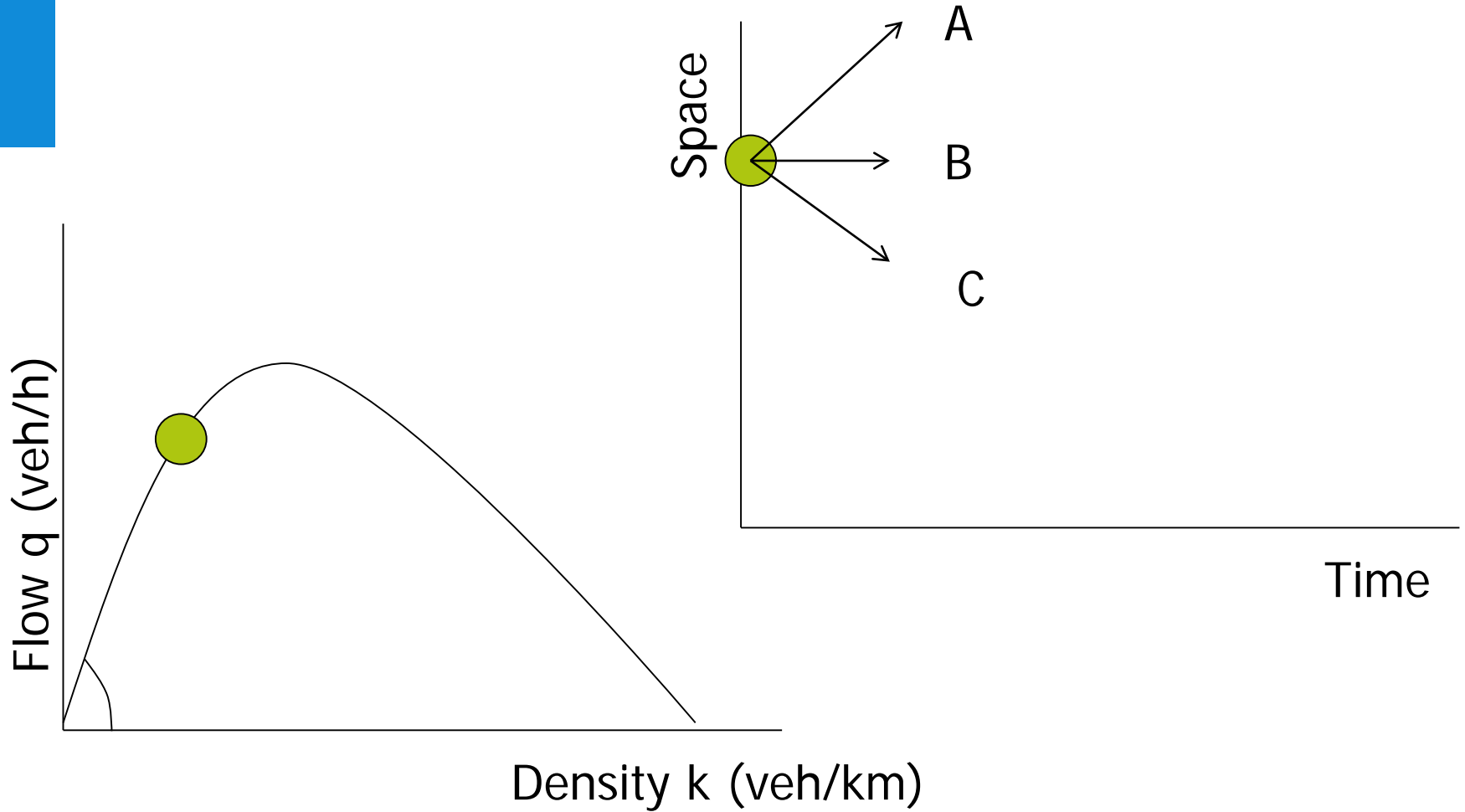
Characteristics are lines in the (x,t) -plane:

1. Slope of characteristic depends on the condition
 2. Density is **constant** along characteristics
 3. Combine 2+3: characteristics are straight lines from boundary
- Intersection of characteristics: shockwave!
(use shockwave analysis to solve problem)

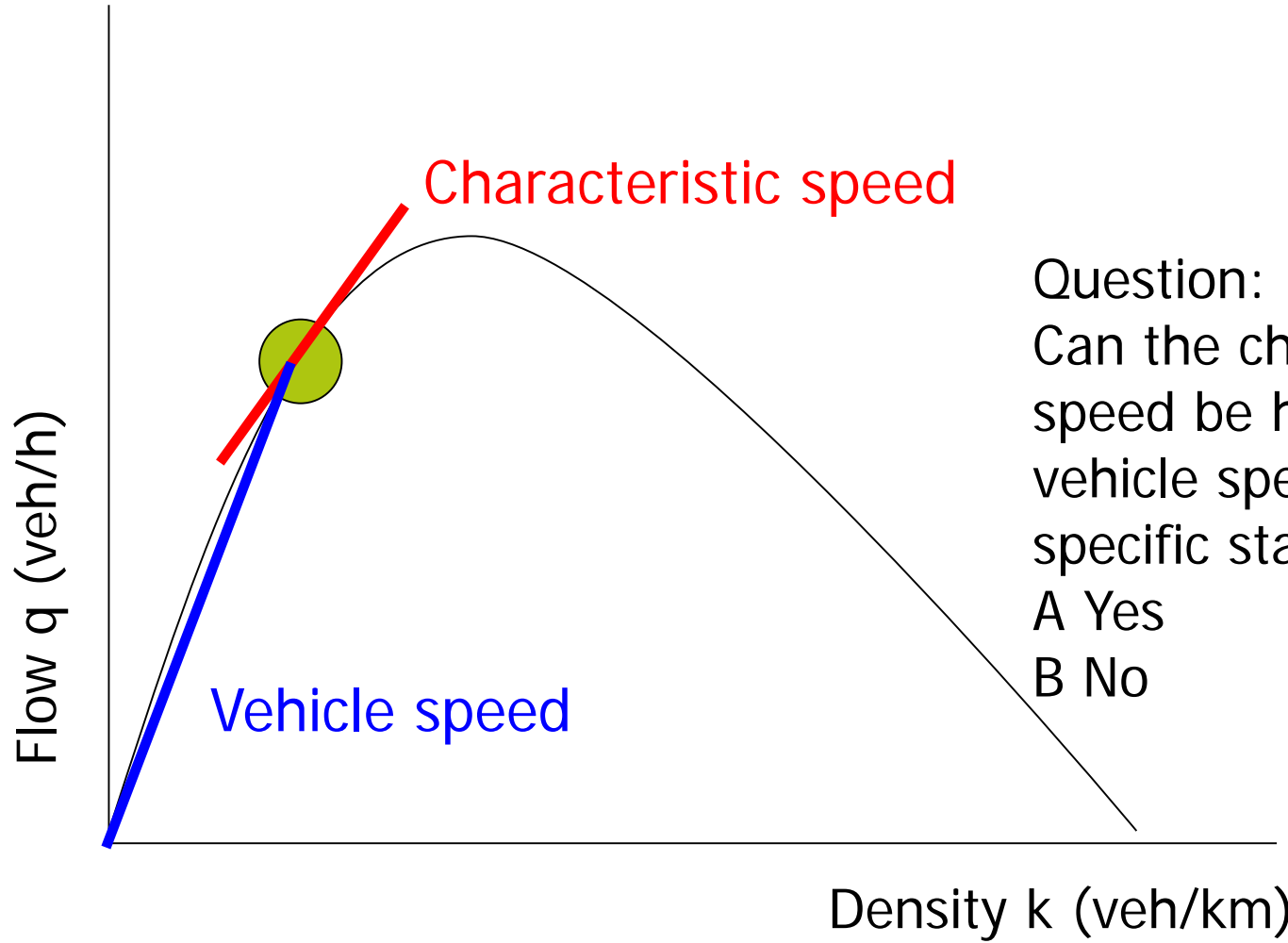
Speed of characteristic

- In principle a shockwave with two sides (almost) the same condition

Question: where does the condition go?



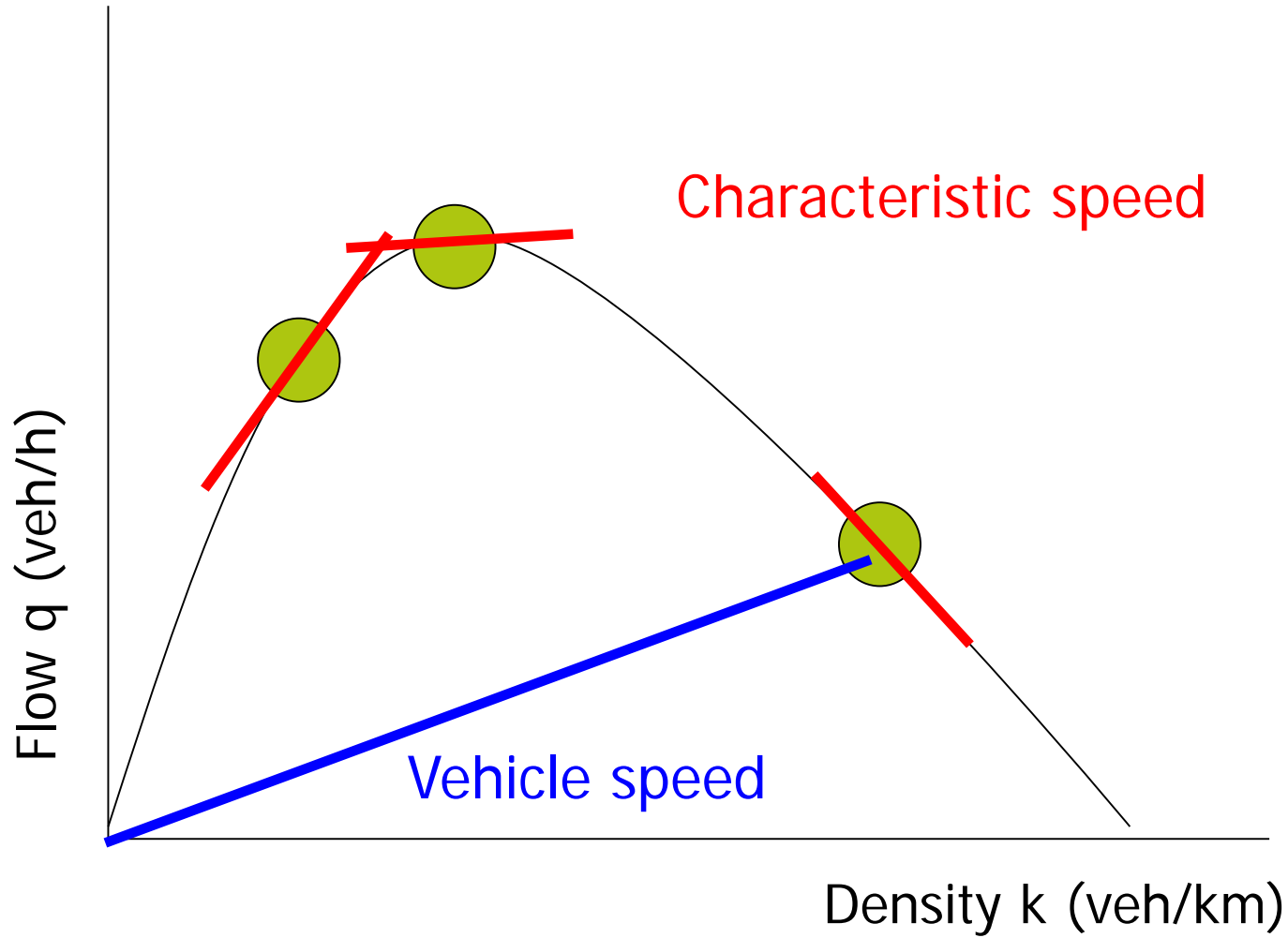
Two speeds



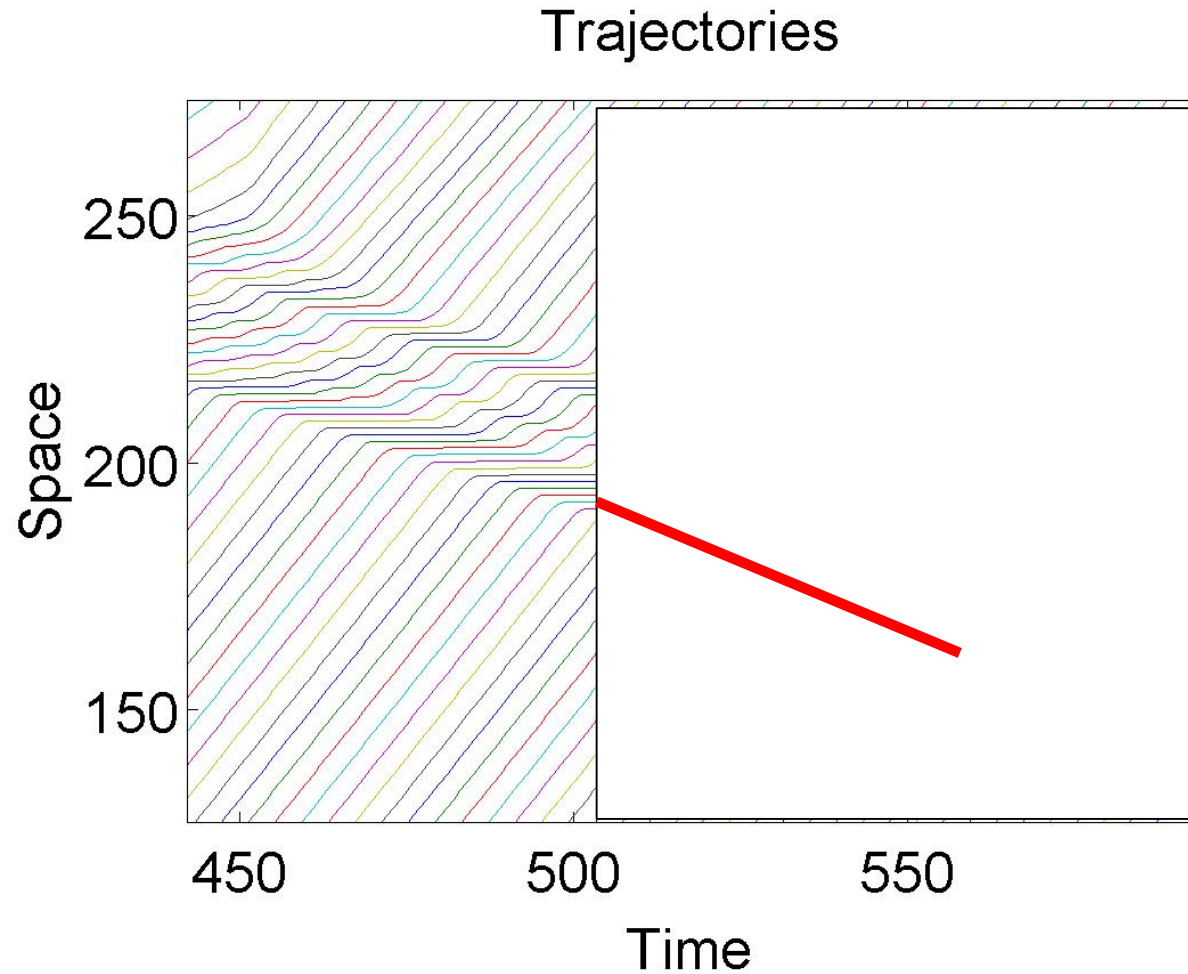
Question:
Can the characteristic speed be higher than the vehicle speed for a specific state?

- A Yes
- B No

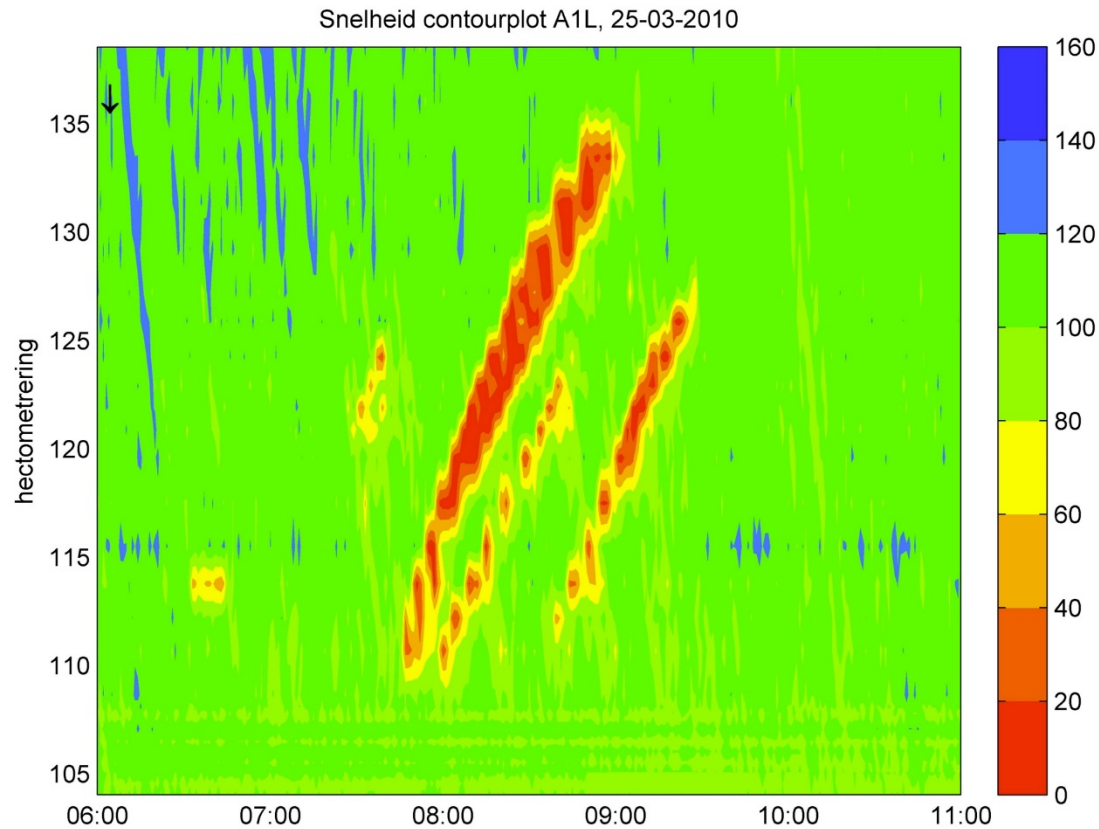
Two speeds



Use: forward or backward analysis



Real-life example

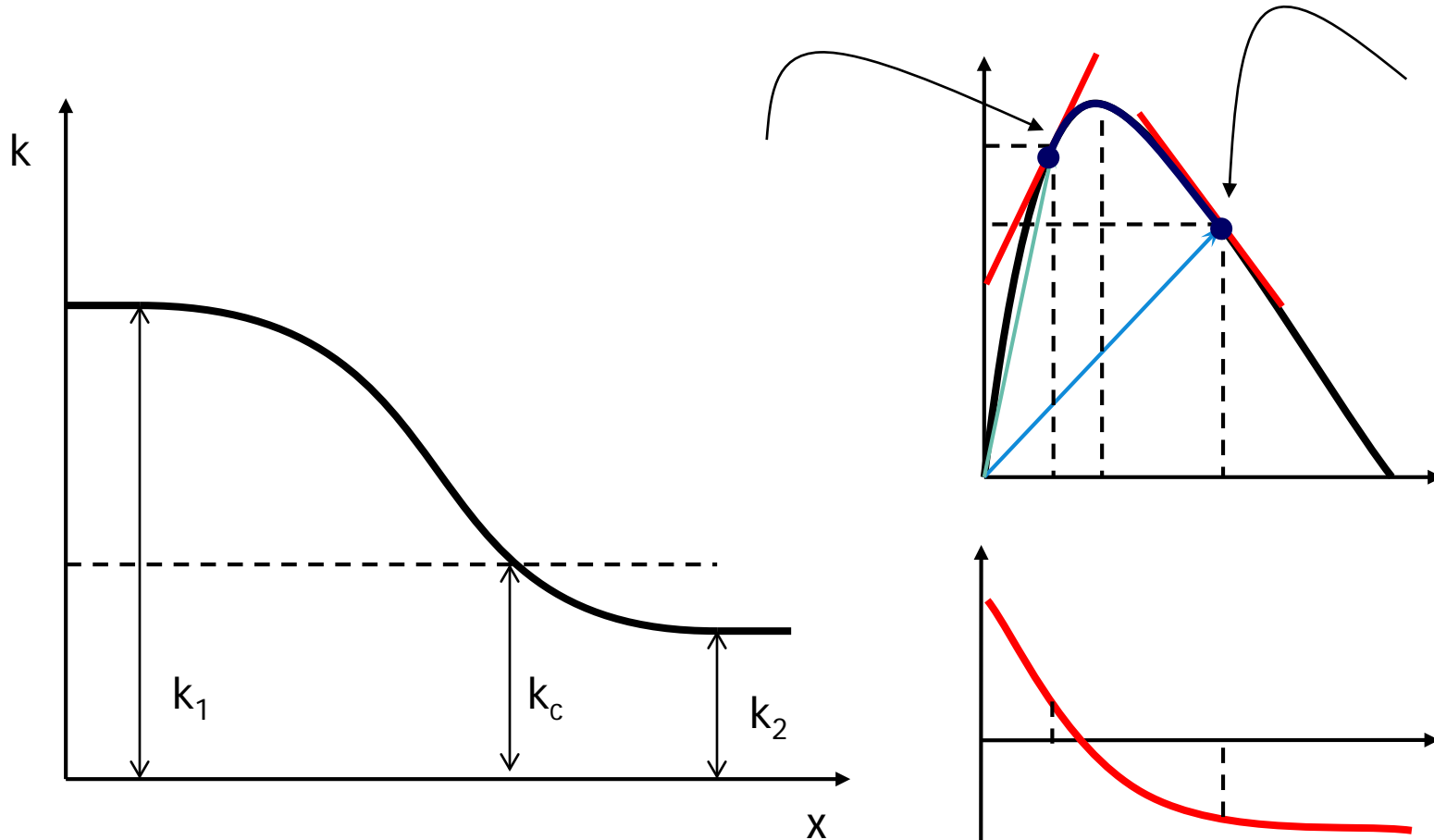


Acceleration fans and the formation of shockwaves

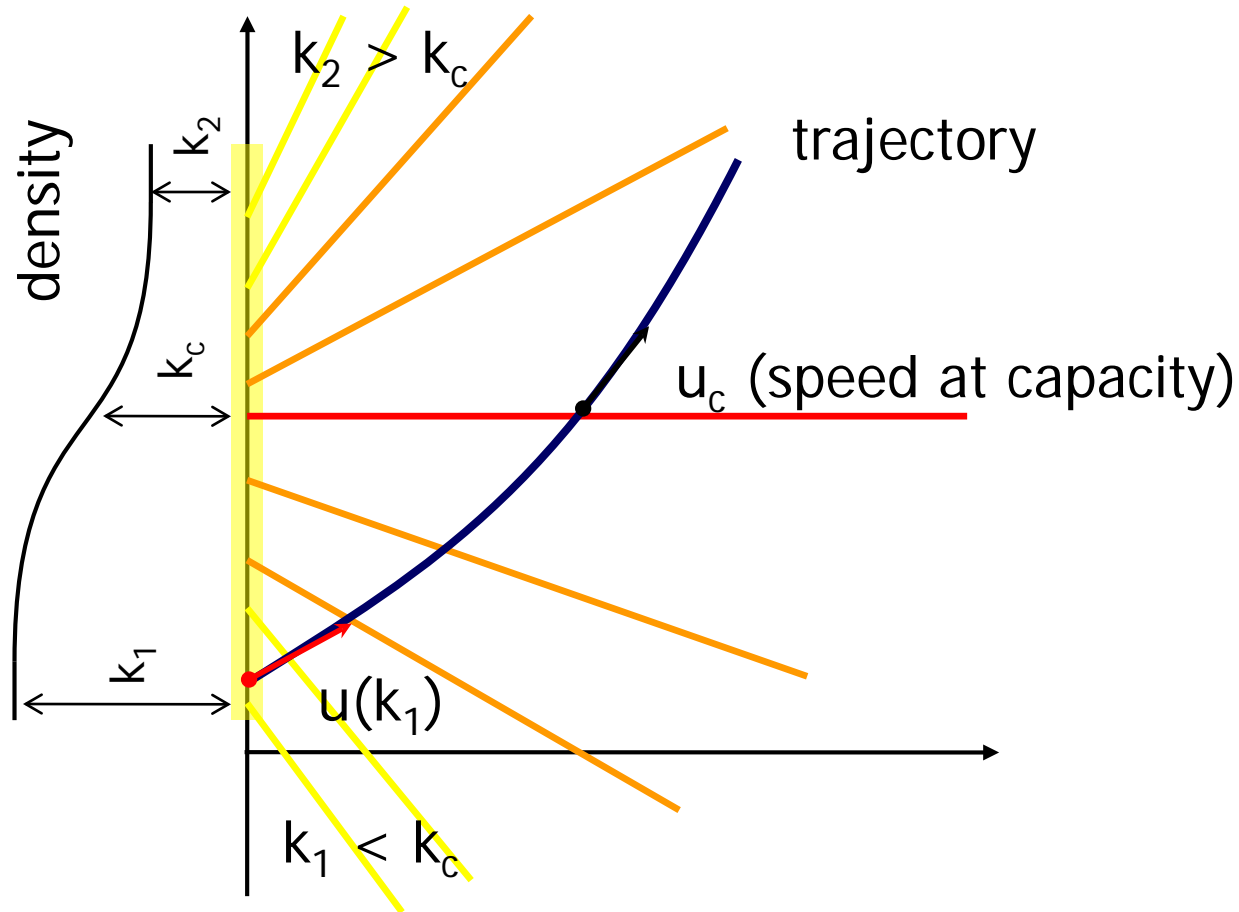
APPLICATIONS OF MOC

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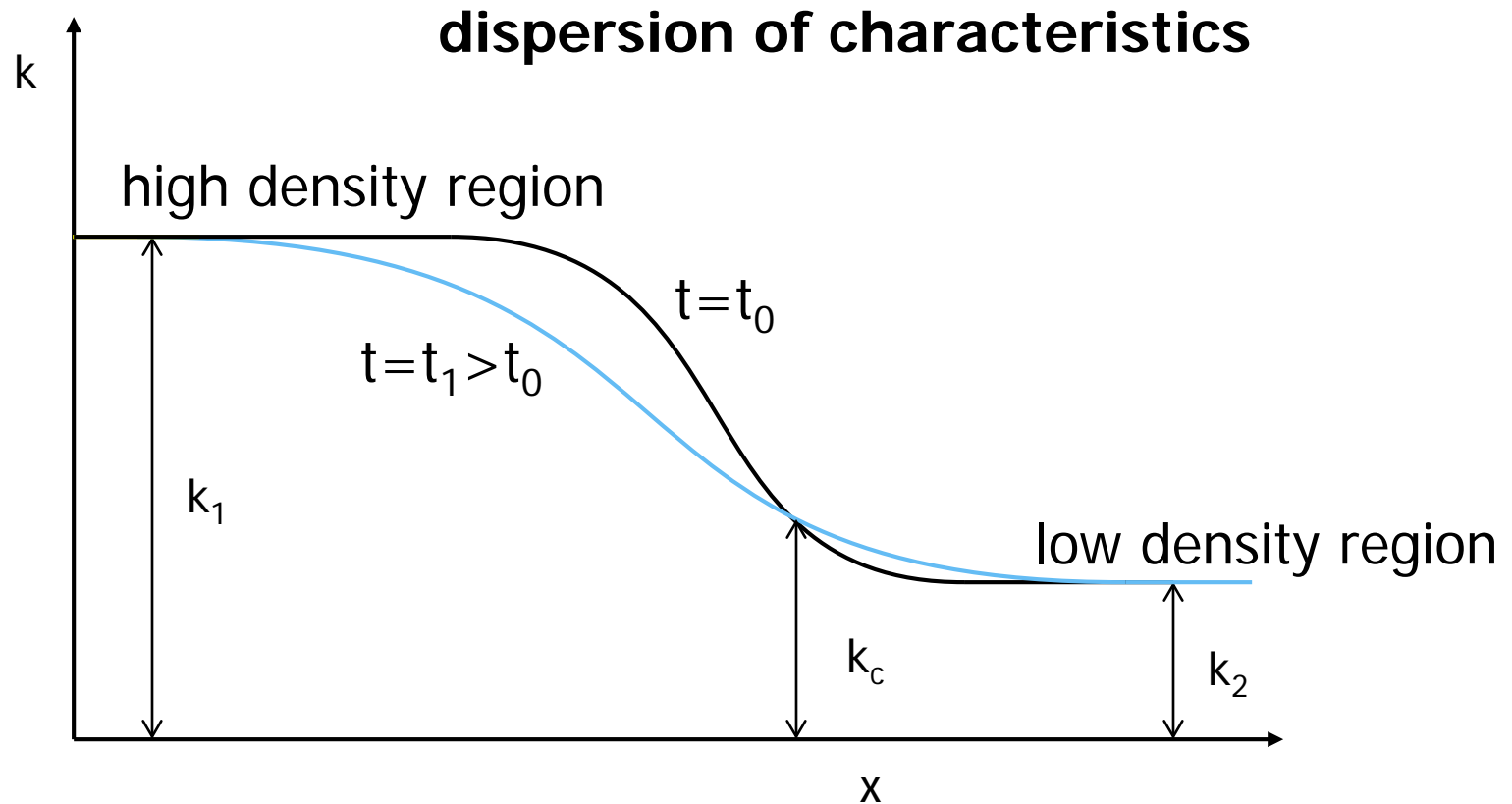
Application – acceleration fans




Application – acceleration fans (2)

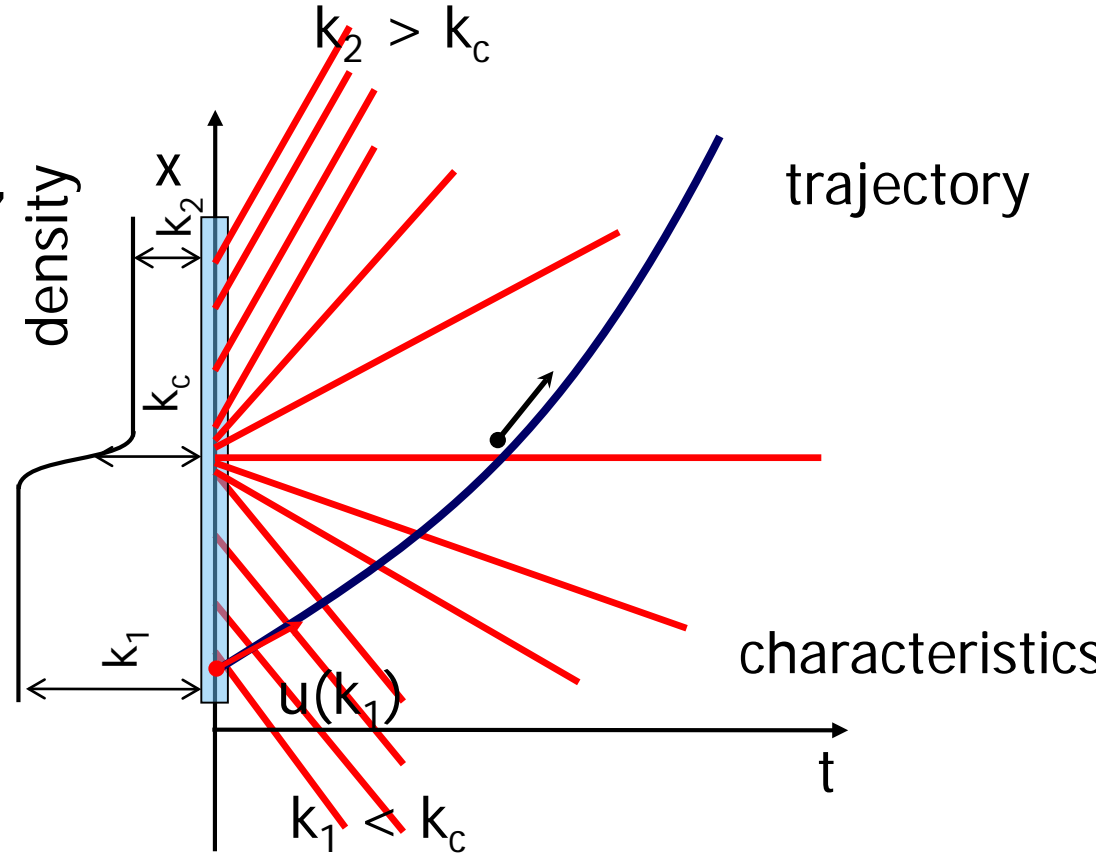
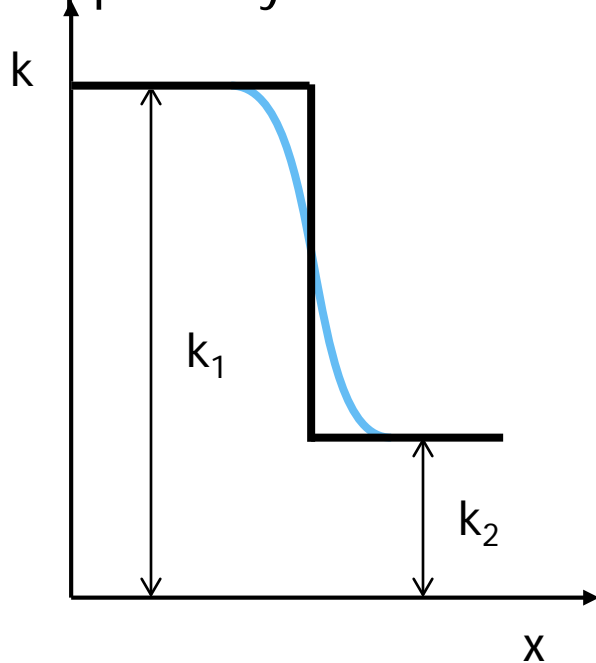


Application – acceleration fans (3)



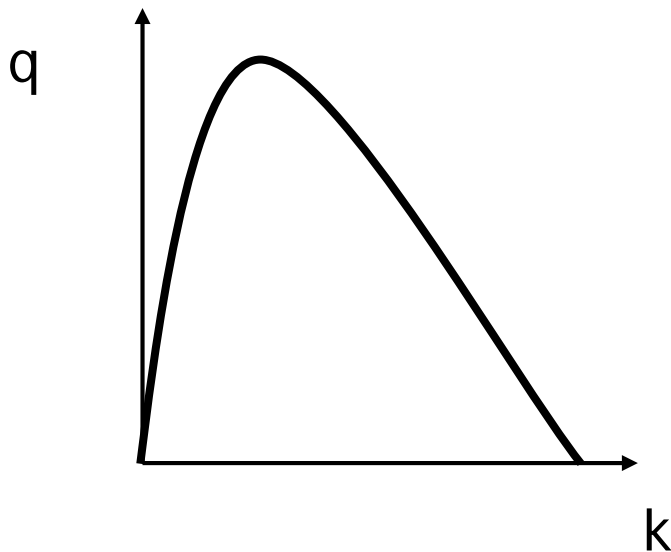
Application – acceleration fan (4)

- Consider shock 
- Approx. by 'smooth shock'



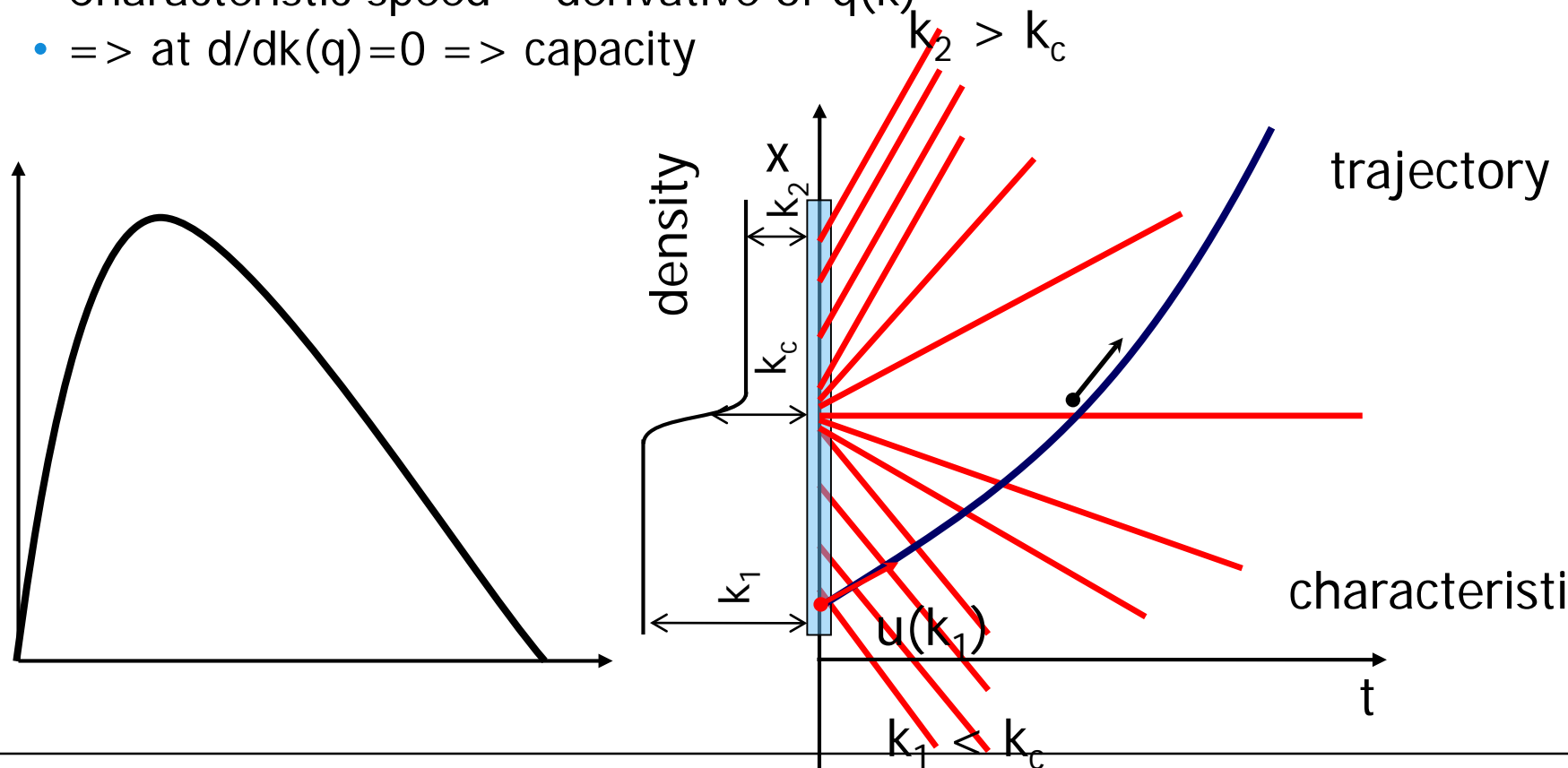
Question

- There is a queue upstream of a traffic light
- The traffic light turns green
- **What is the traffic state at the stop line**
- Use this fundamental diagram:

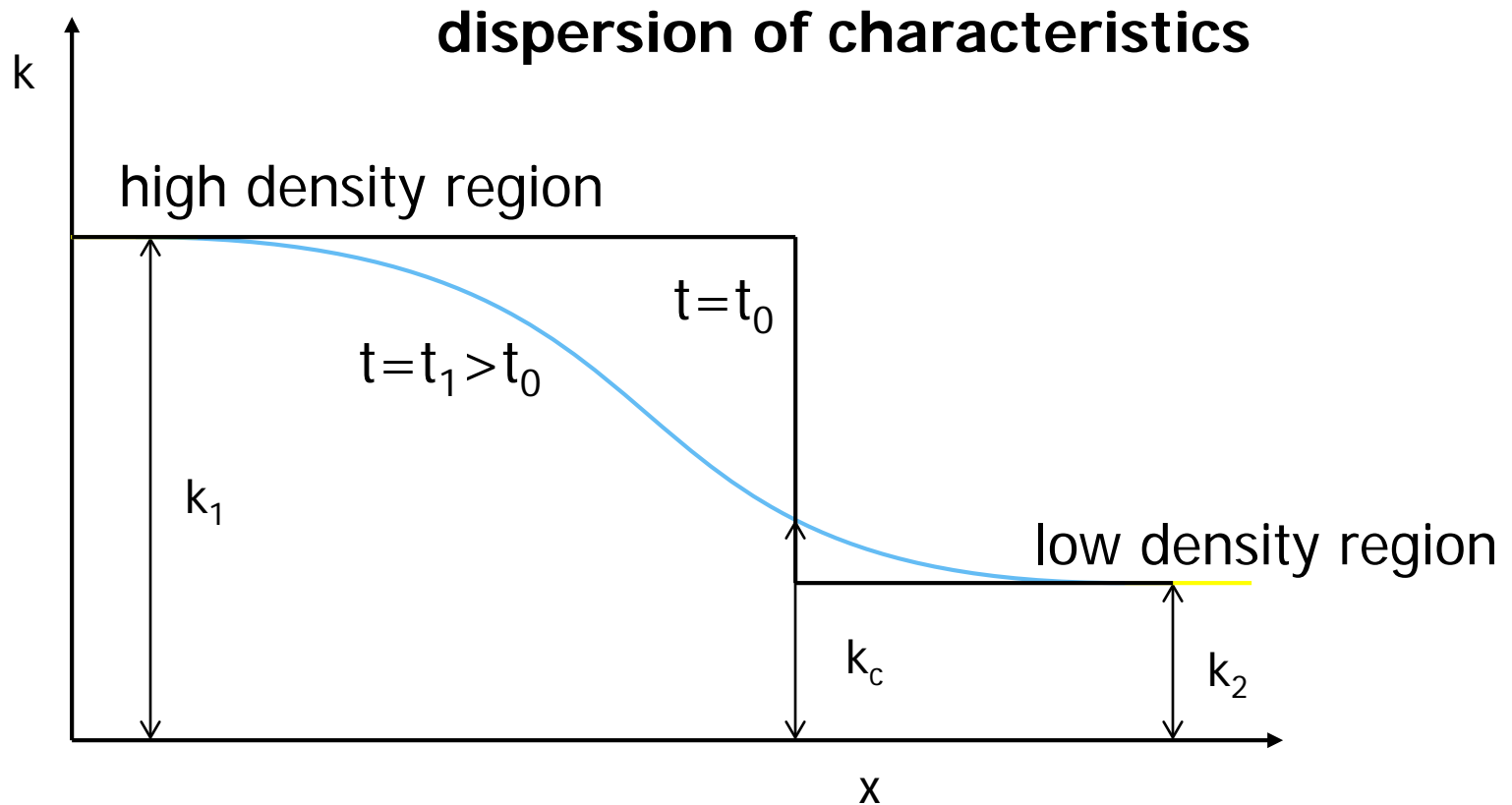


- A. Undercritical
- B. Overcritical
- C. Critical = Capacity

- At $t=0$ "all" densities at stop line
- So \Rightarrow which density has a characteristic speed of 0
- Characteristic speed = derivative of $q(k)$
- \Rightarrow at $d/dk(q)=0 \Rightarrow$ capacity



Application – acceleration fan (5)

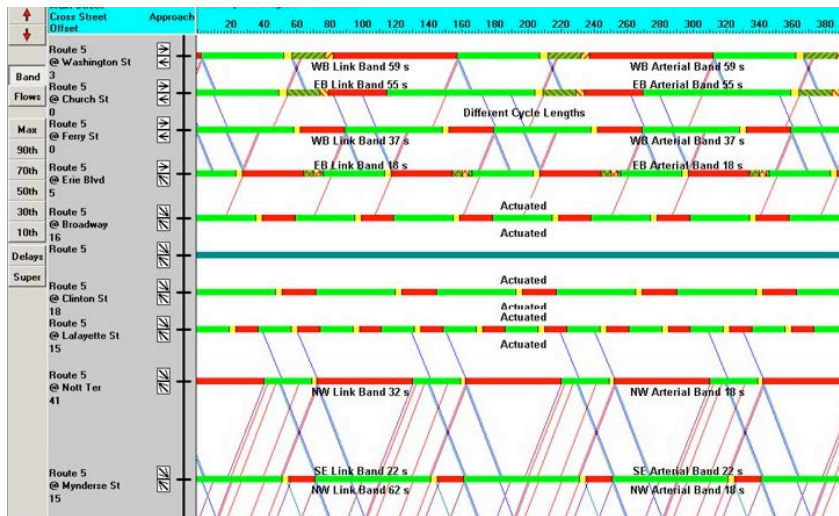


Link to practice – green wave

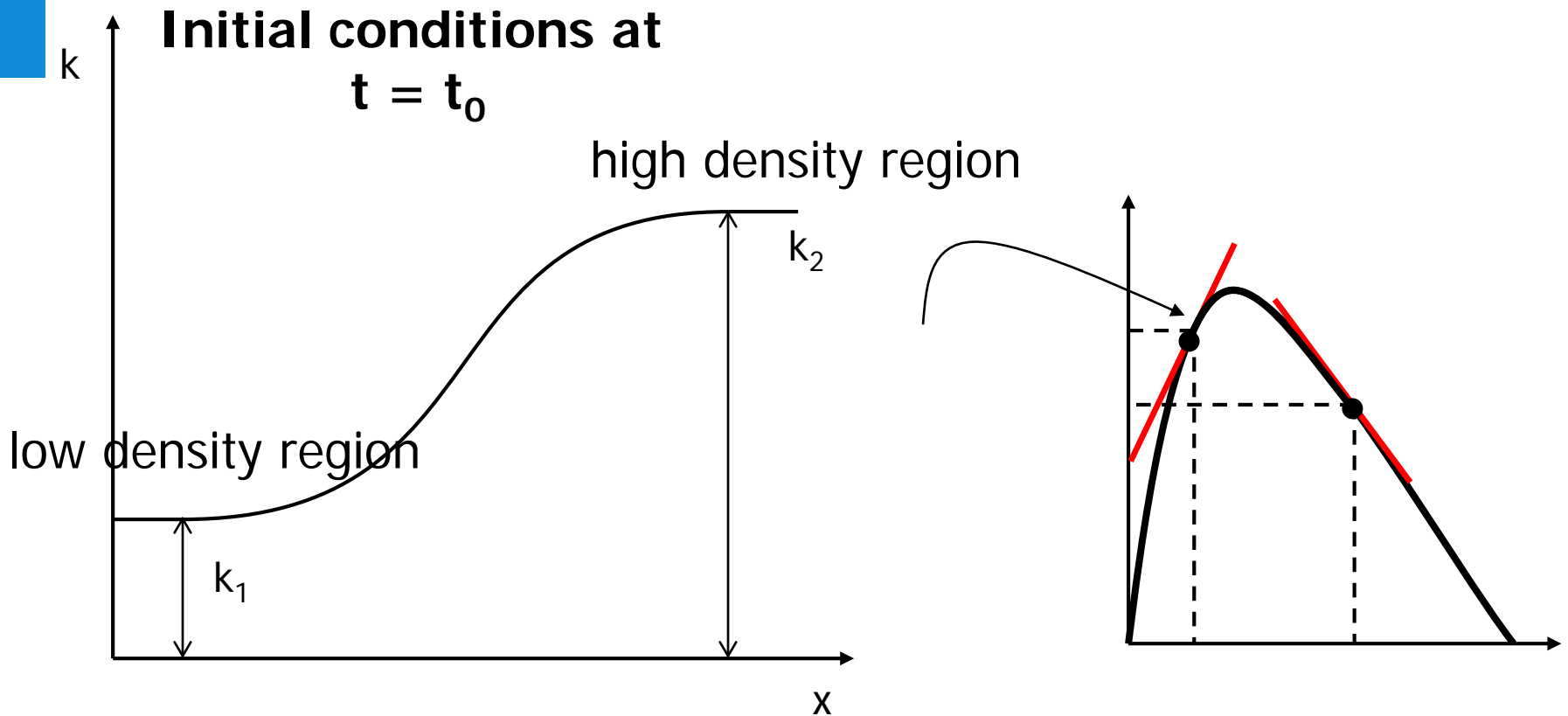
- After a red traffic light, keep the platoon of vehicles together and give them green throughout a section
- Avoid platoon dispersion
- Advise speed



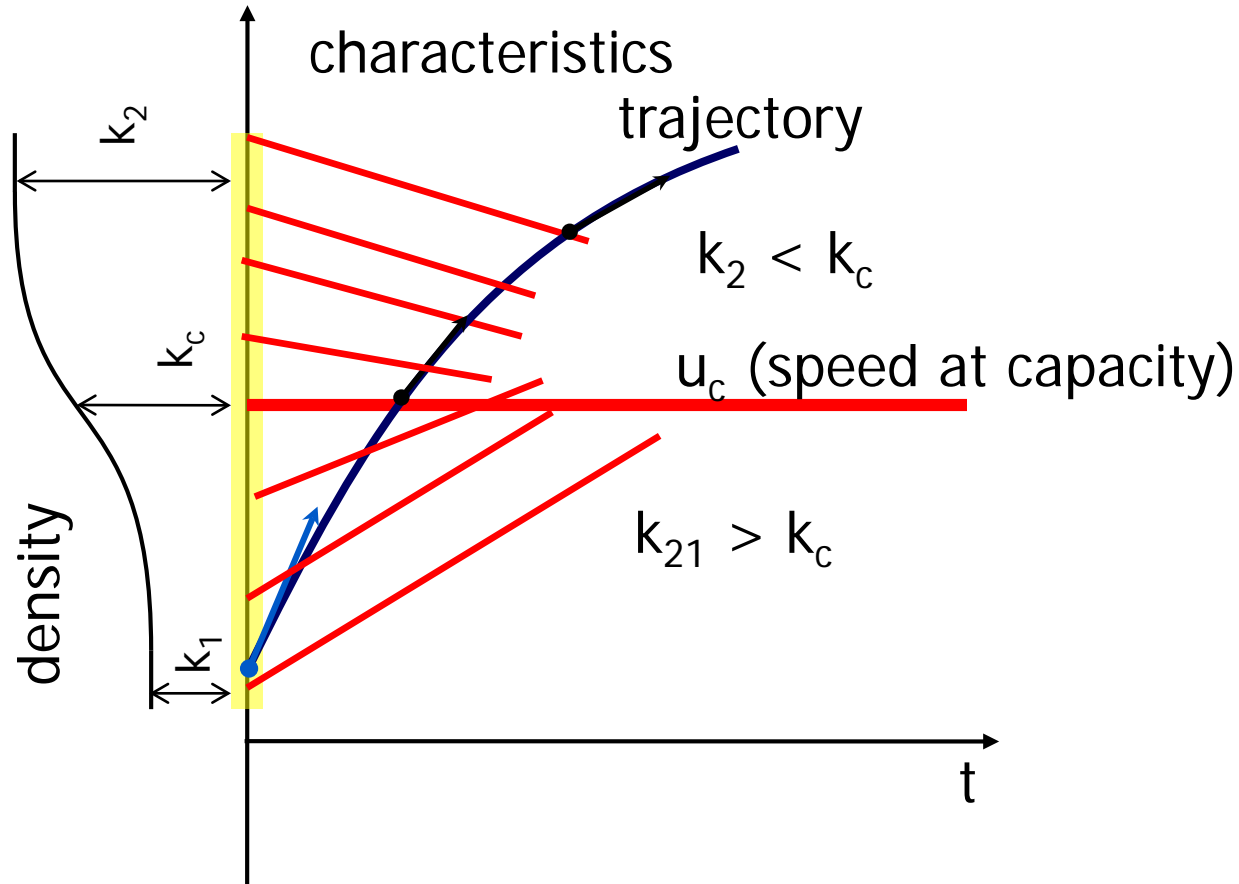
Groene golf by rijkswaterstaat



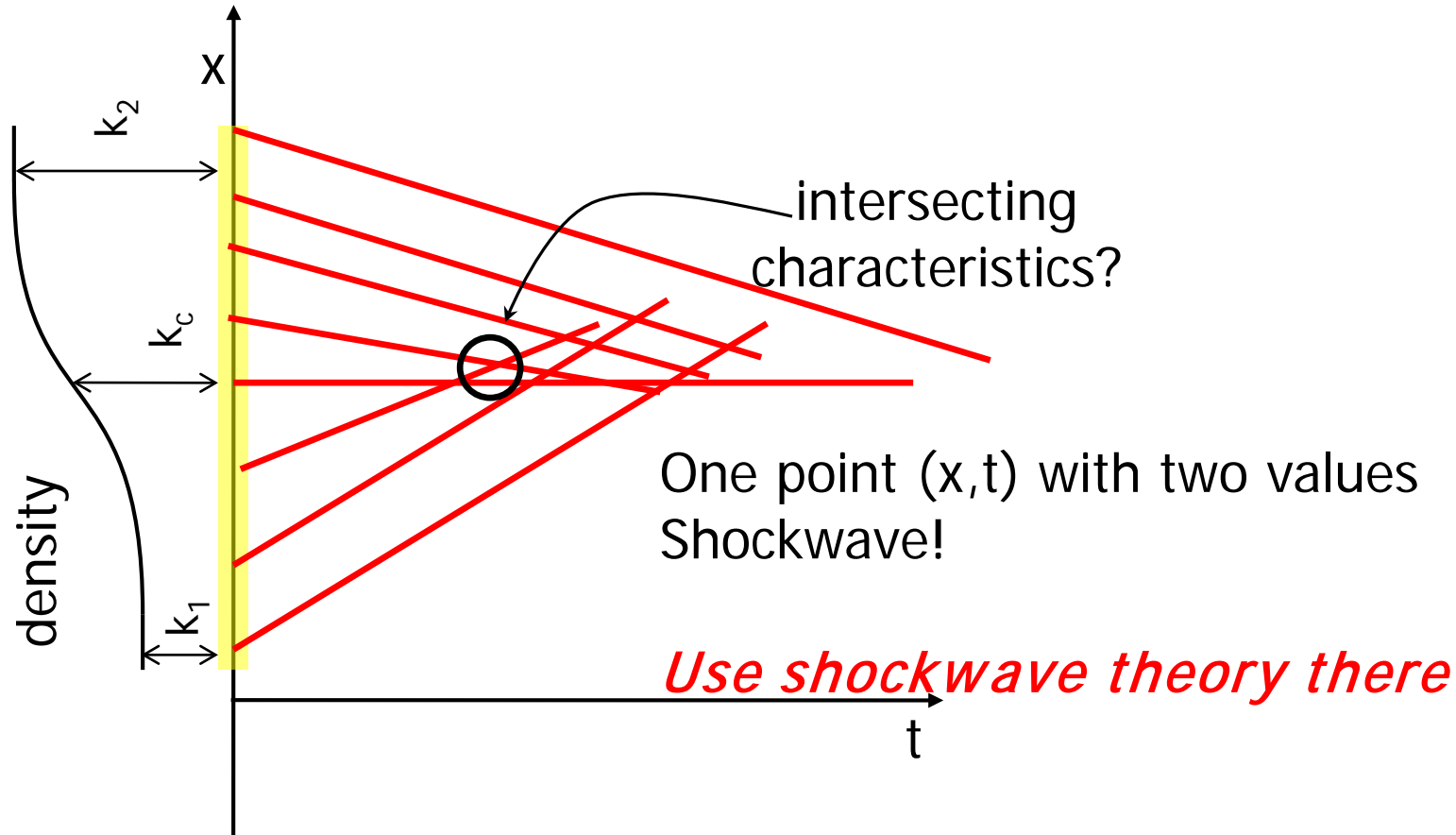
Application – deceleration fans



Application – deceleration fans (2)

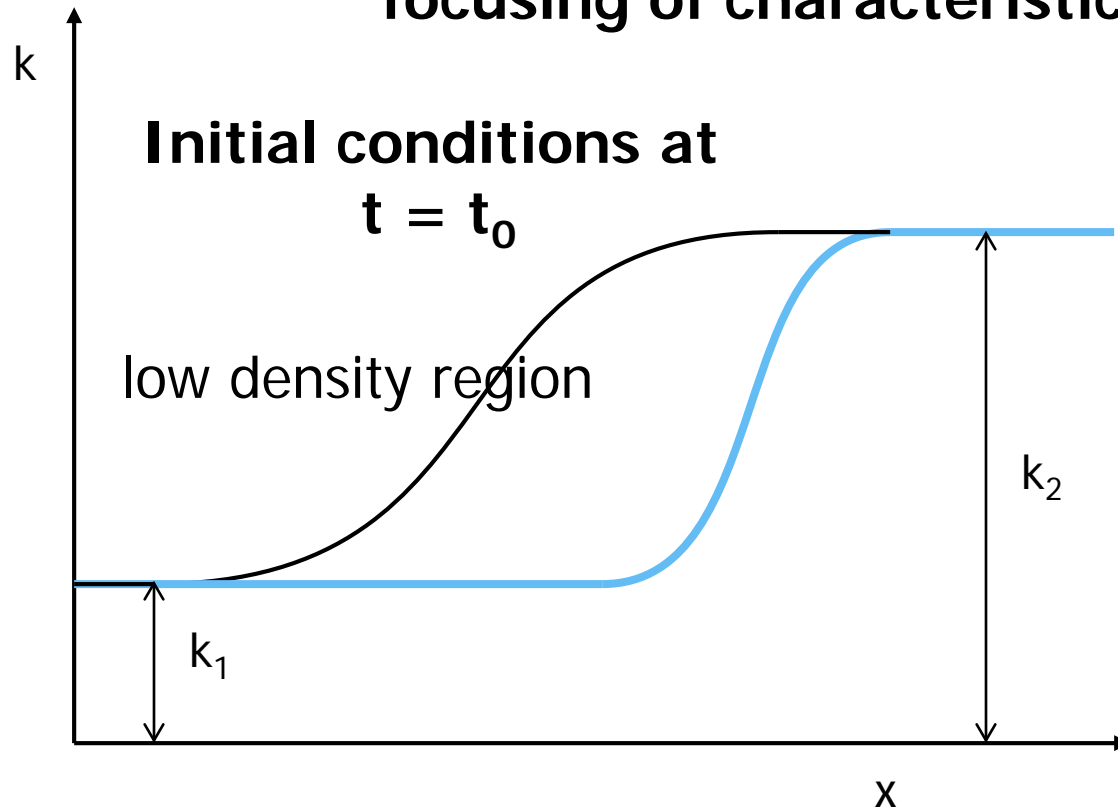


Formation of shocks



Formation of shocks (2)

focusing of characteristics



In practice:


- Problem?




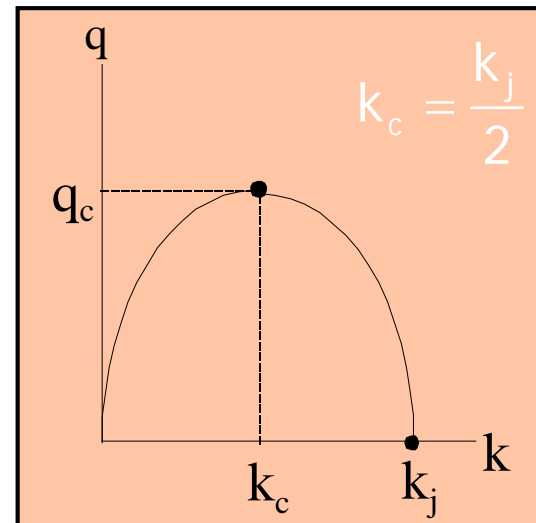
[Photo by Wikipedia](#)

Application of kinematic wave model

- Queuing at signalized intersection
- Upstream traffic demand equals q_1 (region 1)
- Initial conditions are free-flow (k_1, q_1) for all x until $t = -t_r$
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Free speed 

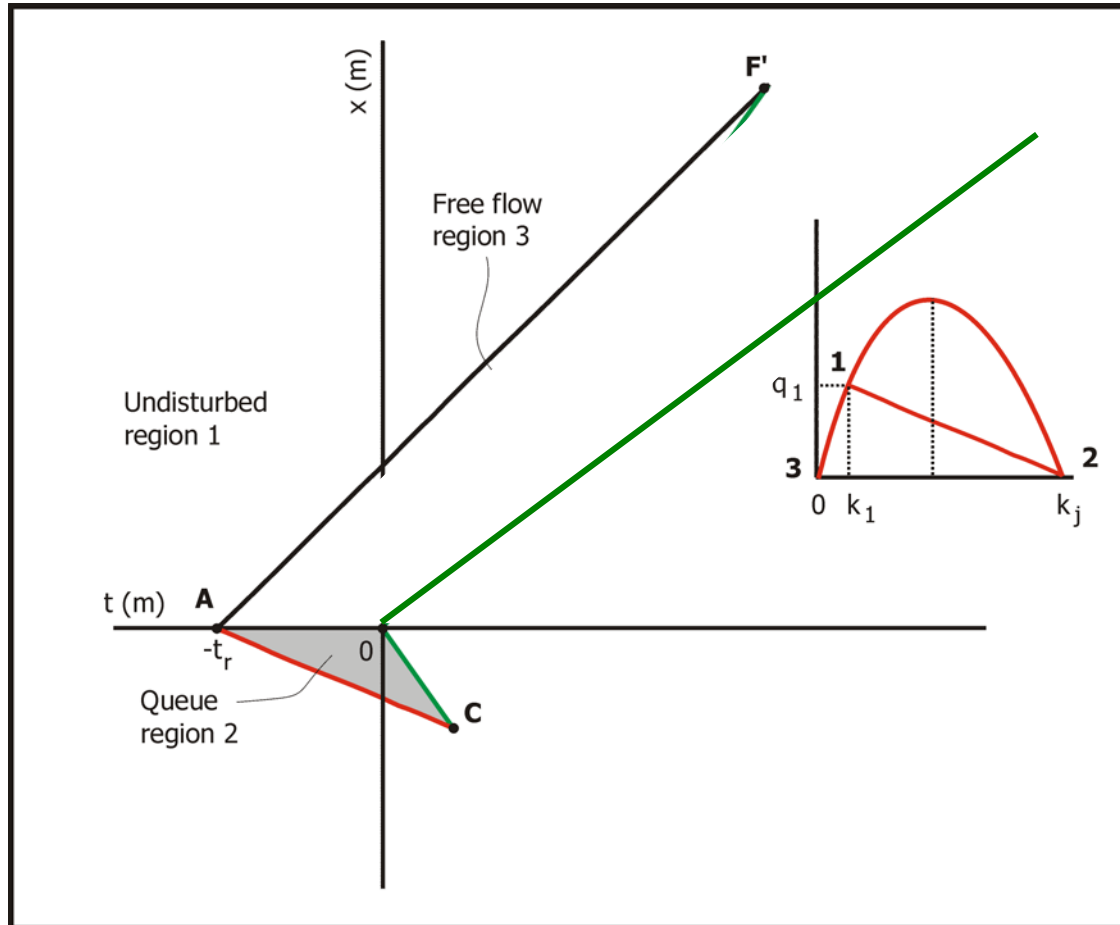
Jam density 



Queuing at signalized intersection

- Assume that at $t = -t_r$ a traffic light changes from green to red
 - As a result, a queue will start to build up starting at the stop-line at $x = 0$ (region 2)
 - Speed at which queue moves upstream can be determined using shockwave analysis
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- Downstream of stopping line, free flow conditions (region 3)
 - Two other shockwaves between:
 - Region 1 and 2
 - Region 1 and 3

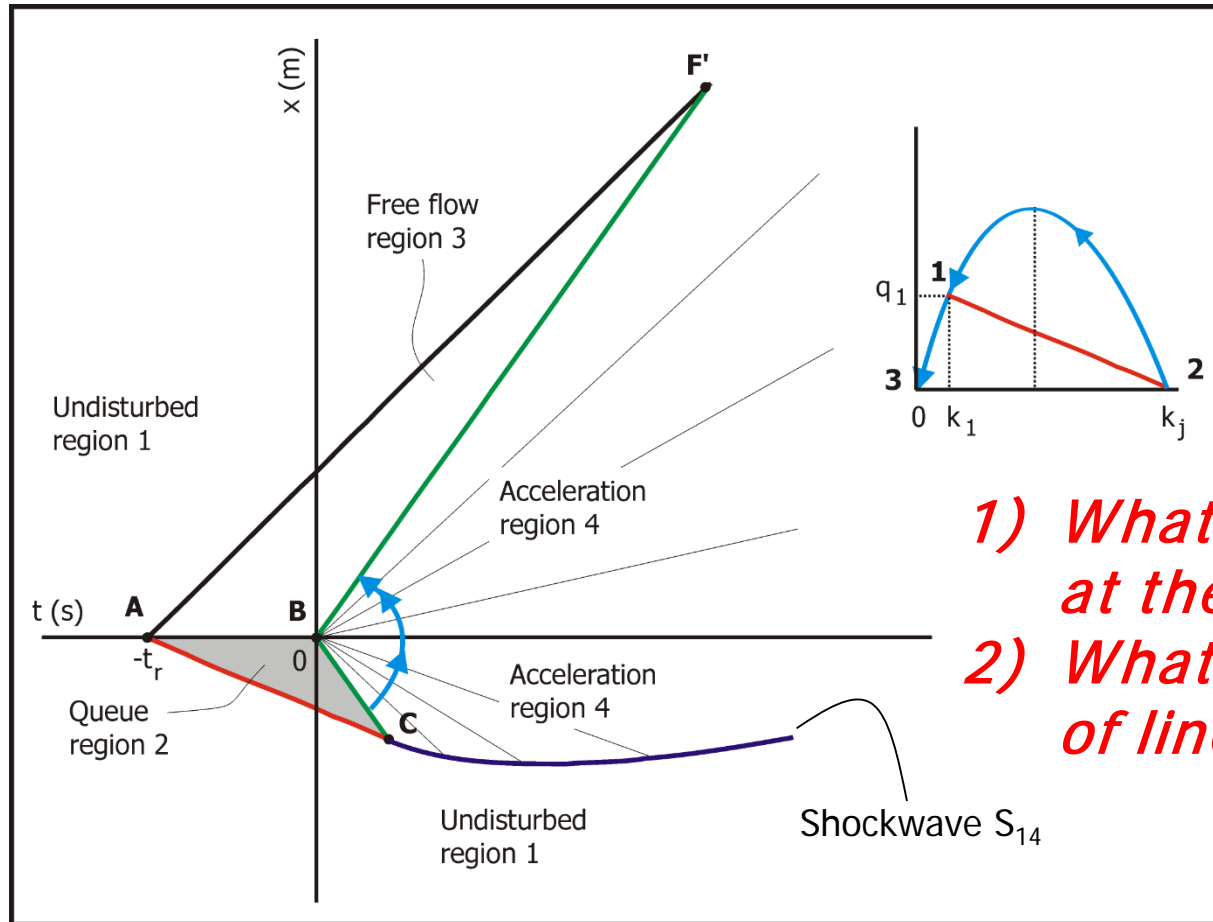
Queuing at signalized intersection (2)



Queuing at signalized intersection (3)

- At $t = 0$ red-phase ends. What will happen?
- Shockwave theory predicts that vehicles will drive away from the queue at capacity flow
- What will the kinematic wave model predict?
- Approximate shock at stop-line $x=0$ by ‘smooth shock’ yields description of acceleration fan

Queuing at signalized intersection (4)



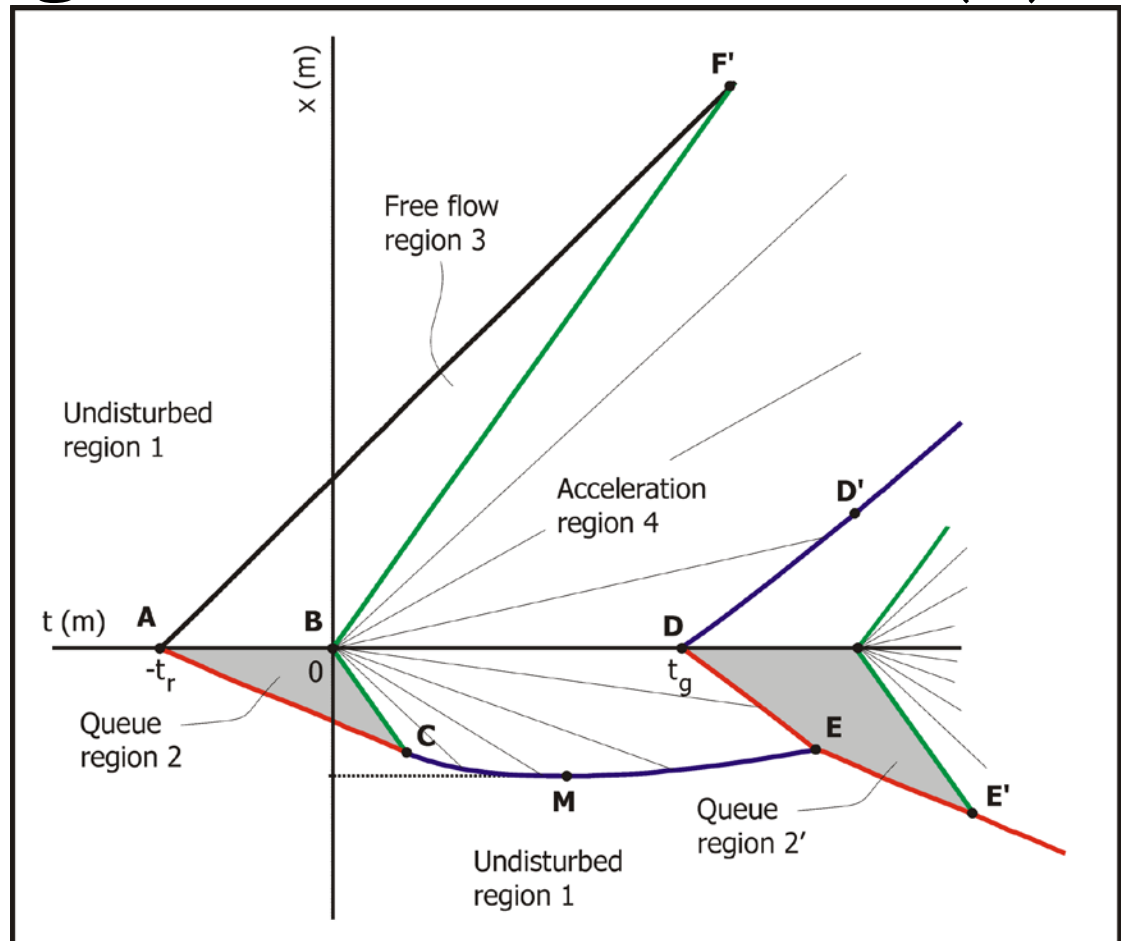
- 1) *What is the flow at the stop-line?*
- 2) *What is the slope of line B-C*

Queuing at signalized intersection (5)

- How to determine dynamics of shock S_{14} ?
- Consider any point (x,t) in the acceleration region 4
- This point lies on the characteristic emanating from the origin $(0,0)$ thus having slope
- For Greenshields function we have
- Which enables us to determine the density at (x,t) , and thus shockwave speed:
- Can be solved analytically (use Maple?) (see reader)

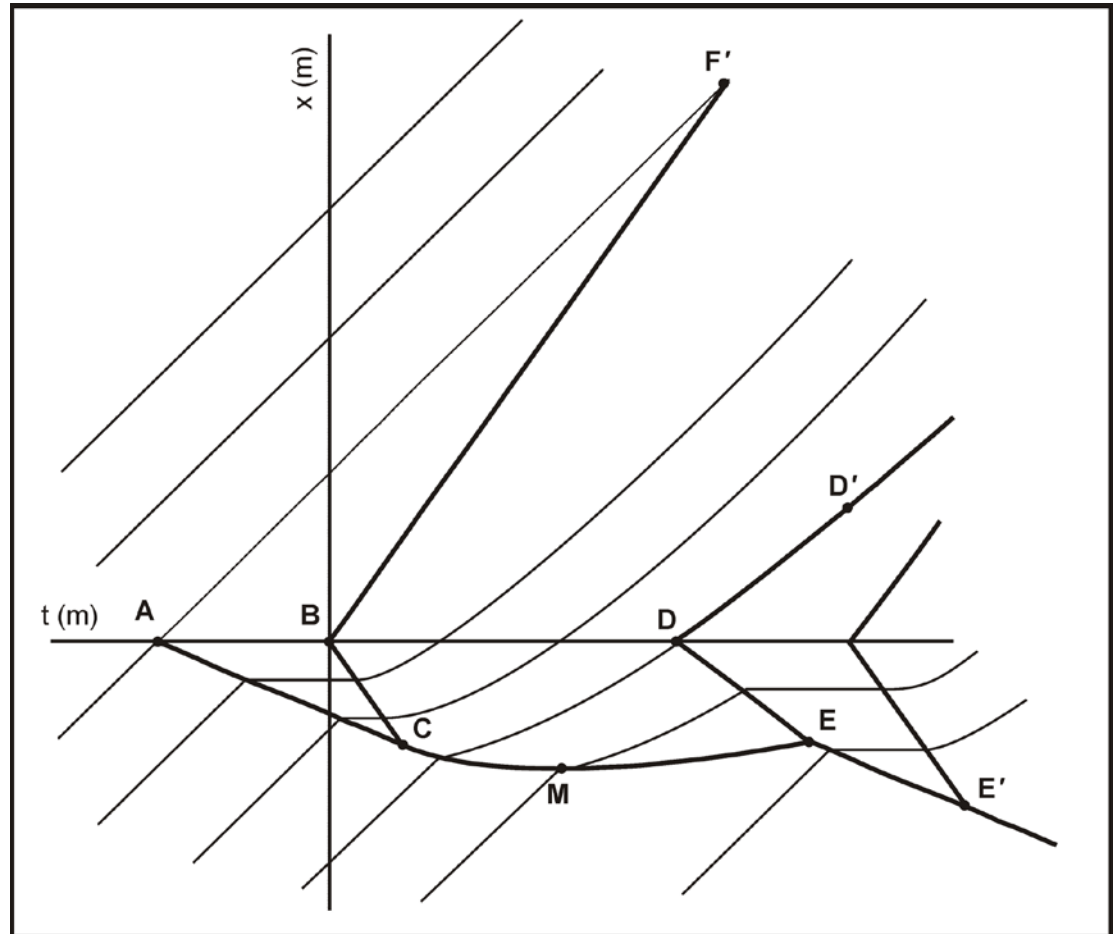
Queuing at signalized intersection (8)

- Assuming that red-phase occurs again during the acceleration phase
- Congestion region increases (queue grows as time goes by)



Queuing at signalized intersection (9)

- Example trajectories for signalized intersection



Queuing at signalized intersection (6)

- Thus for region 1:
- And for region 2:
- The speed of the shock S_{14} is thus

Queuing at signalized intersection (7)

- Shockwave trajectory $x_{CE}(t)$ starts at (x_C, t_C) and its slope is given by $dx_{CE}/dt = \omega_{14}$
- The shock S_{14} can thus be determined by solving the ODE

subject to

- Can be solved analytically (use Maple?) (see reader)

Queuing at signalized intersection (8)

- How to determine point C?
- Point C represents the intersection of the shockwave S_{12} and the 'slowest' characteristic emanating from $x = 0$ (acceleration fan)
- This is the shockwave traveling at speed

- Point (x_C, t_C) is found easily (see reader)

Numerical solution approaches

Godunov scheme

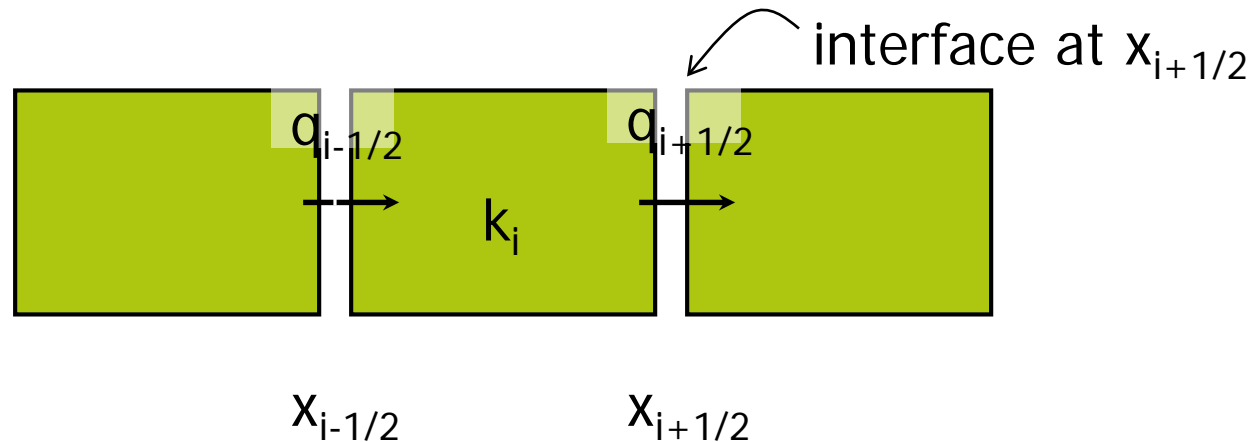
24-3-2014

Why numerical solutions are needed

- Analytical solution to kinematic wave model is exact
- Only applicable in relatively simple situations, e.g. with respect to upstream traffic demand, off-ramps and on-ramps, etc.
- What to do when demand on main-road and on-ramps is changing dynamically? Use numerical approximations!
- Practical applications, e.g. use for network simulation (e.g. DSMART by Frank Zuurbier)

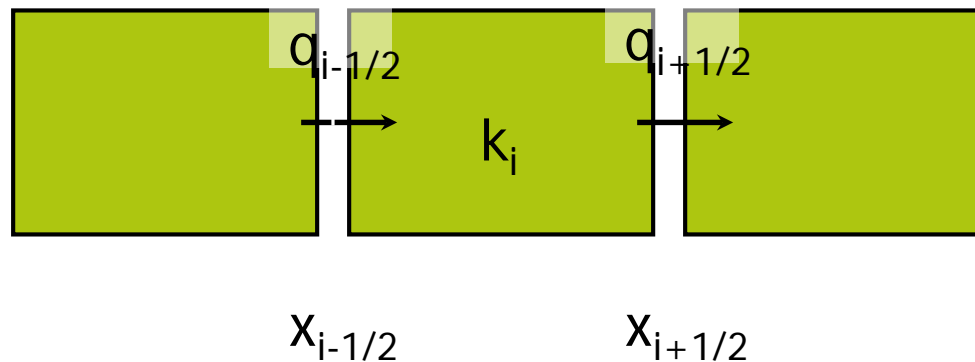
Basic principles

- Various approaches exist to solve kinematic wave model
- Simplest:
 - Divide roadway into cells i , length dx
 - Divide time into steps with length dt



Assumptions

- Cells are homogeneous
- Within a time step (dt) , traffic flow is stationary
- Question: express $k_{i+1,j} = f(k_i, j, q_{i-1/2}, q_{i+1/2}, dt, dx)$



Basic principles (2)

- For the slides: this is the answer...

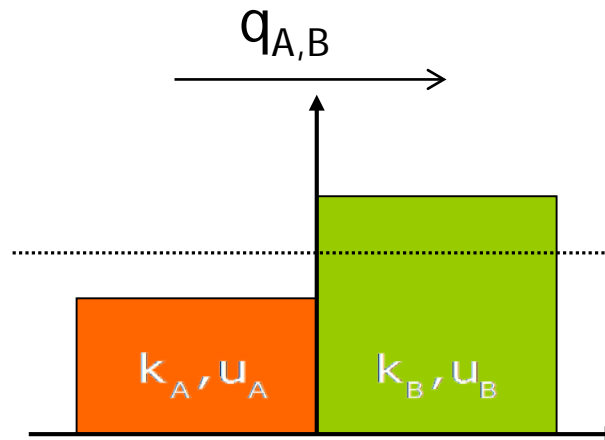
$$k_{i,j+1} = k_{i,j} + \frac{dt}{dx} (q_{i+1/2,j} - q_{i-1/2,j})$$

- But how to get to:

- free-flow conditions:

What if congested?

- What determines the flow from A to B?
 - A – state in cell A
 - B – state in cell B
 - C - capacity



Traffic Light by OCAL

Combining: Godunov scheme (3)

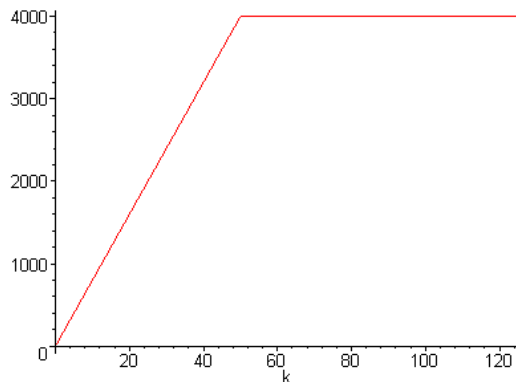
- *Demand* of region A and *supply* of region B

$$D_L := \begin{cases} q_A & k < k_c \\ c & k > k_c \end{cases} \quad S_B := \begin{cases} c & k < k_c \\ q_B & k > k_c \end{cases}$$

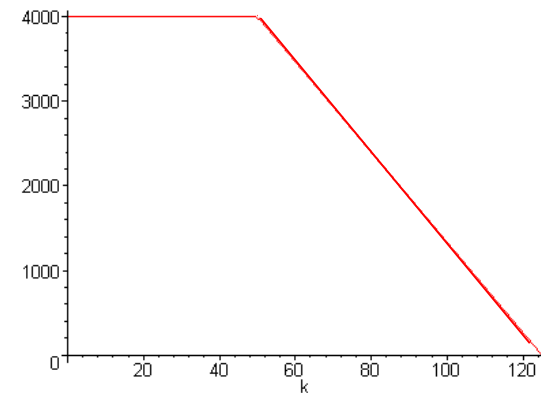
- D_L = maximum number of vehicles that can flow out region L (bounded by the capacity of the road)
- S_R = maximum number of vehicles that can flow into region R (bounded by road capacity and the space becoming available during one time-step)
- Actual flow at $x=0$: $\min(D_L, S_R)$

Godunov graphically

- Flow based on Demand & Supply
- => fundamental diagram



Supply



Network: do this for all cells & times

- For all cells i , determine the cell demands for period j

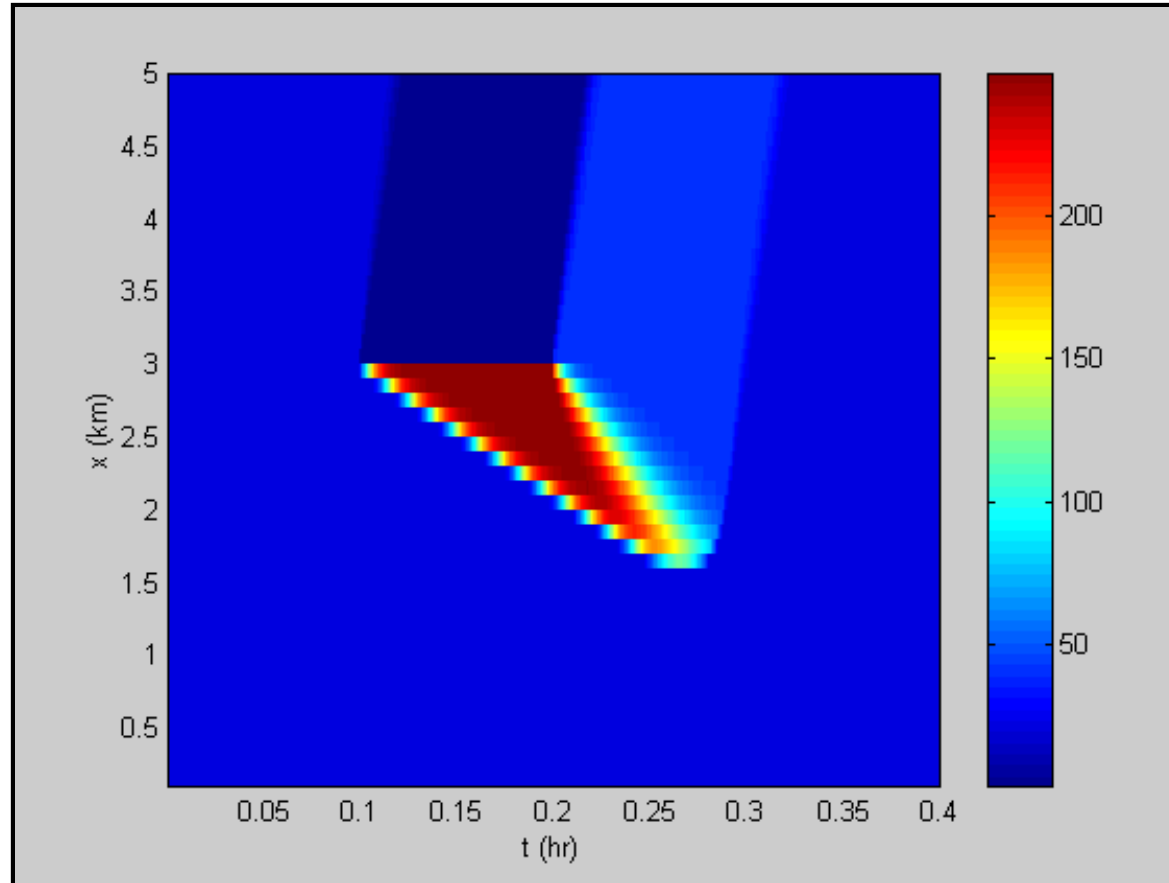
and the cell supplies for period j

- The numerical flow between cell i and $i+1$ for period j becomes

Resulting traffic operations

- Movie

Example application Godunov



Summary – and learning goals

- Studied :
 - characteristics
 - Cell transmission model
- You can:
 - Follow traffic characteristics
 - Make traffic predictions
 - Method of characteristics
 - + Shock wave theory when needed
 - Cell transmission model
(equations, interpretation of results)