

Dynamic Translinear Circuits

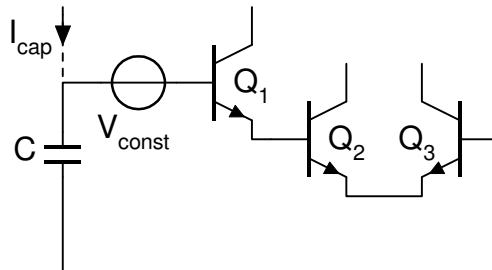
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Dynamic translinear elements

- **The capacitor**
- The bipolar transistor
- The diode
- The MOS transistor in weak inversion (NB: body effect)
 - SOI, SOA
 - Bulk-driven
 - Triode region
- Voltage-translinear principle: MOSTs in strong inversion; quadratic relation between drain current and gate-source voltage

Generalized DTL principle



$$I_{cap} = CU_T \left(\frac{\dot{I}_{C1}}{I_{C1}} + \frac{\dot{I}_{C2}}{I_{C2}} - \frac{\dot{I}_{C3}}{I_{C3}} \right)$$

$$I_{cap} = CU_T \sum_i \pm \frac{\dot{I}_{Ci}}{I_{Ci}}$$

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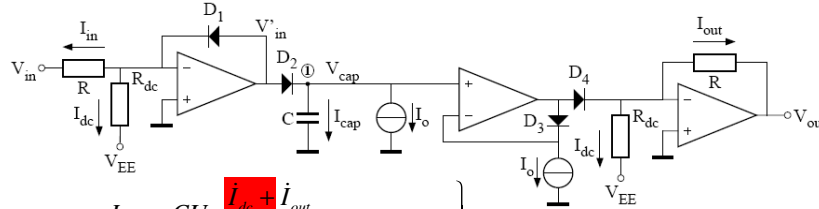
DTL analysis

Input: detailed circuit diagram

- Derivation of TL (collector-current) relations; KCLs (incl. capacitance currents)
- Obtain expressions for the capacitance currents
- Solve the system of equations

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DTL analysis (II), example



$$I_{cap} = CU_T \frac{\dot{I}_{dc} + \dot{I}_{out}}{I_{dc} + I_{out}}$$

$$(I_{dc} + I_{in})I_o = (I_o + I_{cap})(I_{dc} + I_{out})$$

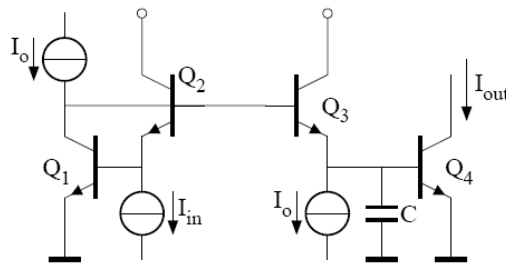
$$CU_T \dot{I}_{out} + I_o I_{out} = I_o I_{in}$$

$$\frac{CU_T}{I_o} \dot{I}_{out} + I_{out} = I_{in}$$

$$H(s) = \frac{1}{1 + s\tau}; \quad \tau = \frac{CU_T}{I_o}$$

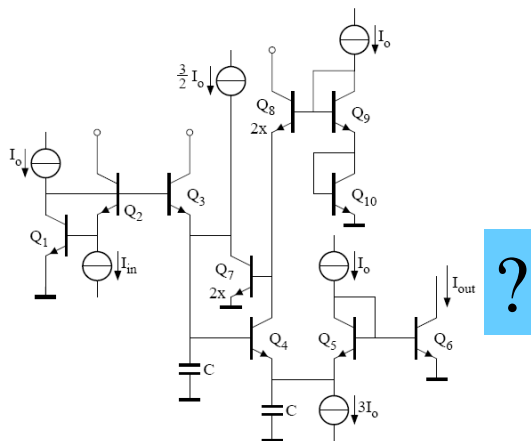
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DTL analysis (III), example (II)



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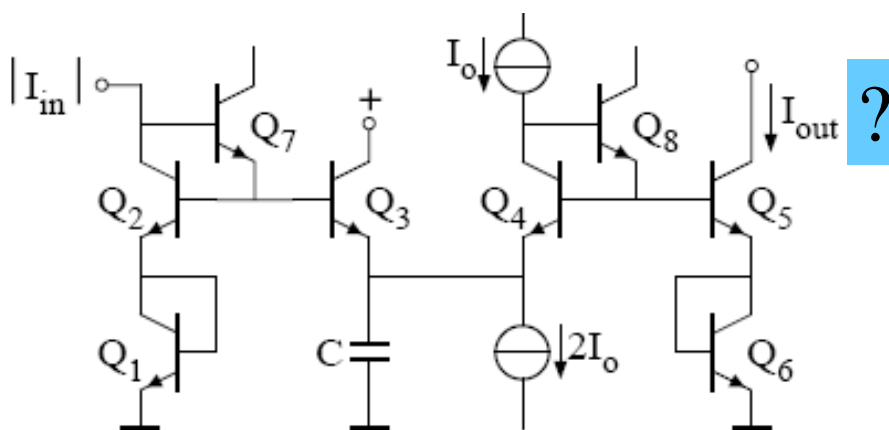
DTL analysis (IV), example (III)



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DTL analysis (V), example (IV)



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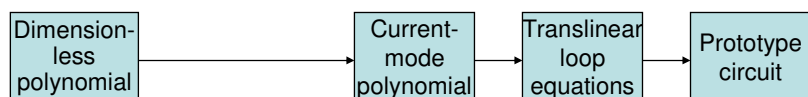
DTL synthesis

1. Add dimensions (current and time)
 - We now have a current-mode differential equation
2. Define capacitance currents
 - We now have a current-mode polynomial without derivatives
3. Do the TL composition, i.e., map the polynomial onto equations that comprise products of currents only
 - Research is still going on; often heuristically found solutions
4. Compose the circuit at signal level
 - We now have a circuit topology that comprises transistors (and/or diodes), capacitances, and current sources
5. Do the biasing, i.e., replace the ideal bias sources by realistic ones

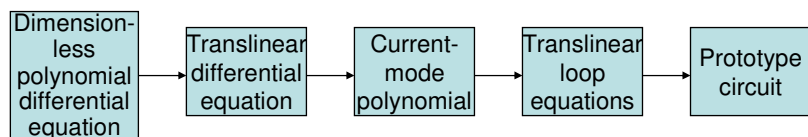
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Synthesis procedure



Static translinear circuits



Dynamic translinear circuits

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