

Demonstrations system identification lecture 1

LinearStep.mdl

2nd order system: $1/(0.25s^2 + 0.33s + 1)$

Goal: System response with and without noise

- excluding noise
- including noise (random generator, variance = 0.001)

Conclusions:

1. System dynamics can not easily be recognized from step response
2. Additional noise makes it even more difficult to recognize the step response

AverageMultipleSteps.m

2nd order system: $1/(0.25s^2 + 0.33s + 1)$

Goal: Removal of noise by averaging of a number of realizations

Program call: AverageMultipleSteps(NrSteps)

Conclusion:

1. With a larger number of repetitions the noise can be removed. It decreases the perturbation on the step response.
2. Very many repetitions are needed for complete annihilation of the noise.

LinearWhiteNoise.mdl

2nd order system: $1/(0.25s^2 + 0.33s + 1)$

Goal: Demonstrate the effect of a stochastic input signal

Remark: Input signal is filtered by low-pass filter (Butterworth) with cut-off frequency of 30 Hz (3rd order), because the sample frequency of the simulation is 100 Hz. Filter settings are found by

`[A,B]=butter(3,30,'s')`

in which 's' results in a continuous filter, 3 is the order of the filter, and 30 is the desired filter frequency.

Simulation results in $u(t)$ and $y(t)$, which can be used to demonstrate further data processing.

Cumulative distribution function ('Verdelingsfunctie')

`Yu = normcdf(Xu,mean(u),std(u))`

in which $Xu = -5:0.1:5$ (values of $u(t)$ for which the cumulative distribution function is calculated).

Probability distribution function ('Verdelingsdichtheidsfunctie')

`Pu = normpdf(Xu,mean(u),std(u))`

in which $Xu = -5:0.1:5$ (values of $u(t)$ for which the probability distribution function is calculated).

demonstration of results:

- `plot(Xu,Pu,'b',Xu,Yu,'r')`

or:

- `hist(u,Xu)`
`plot(Xu,Pu*90,'b')`

Disttool

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Demonstration of cumulative distribution function and probability distribution function

Normplot

Normplot(u)

Demonstration how precise a normal distribution is achieved.

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