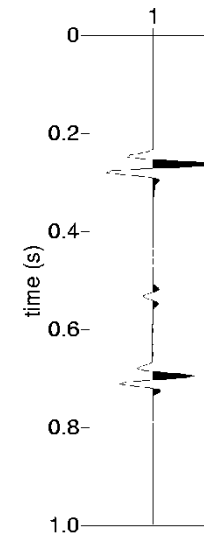
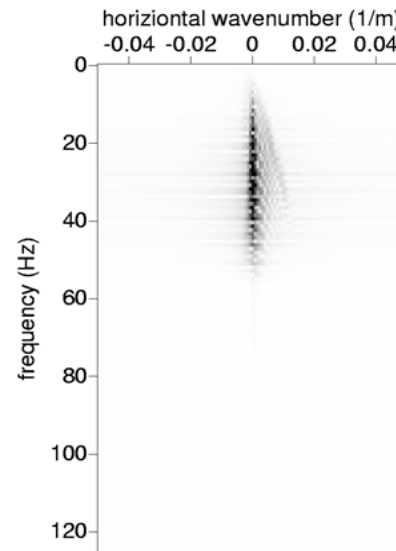
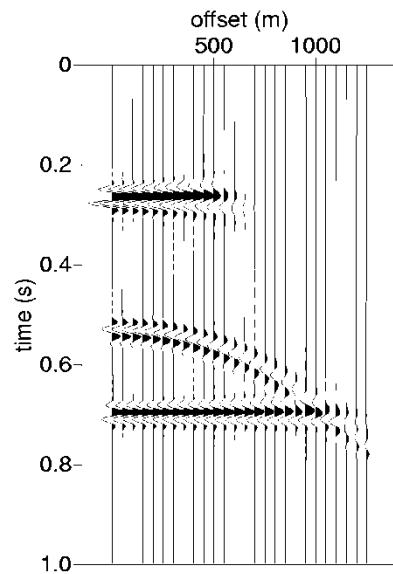
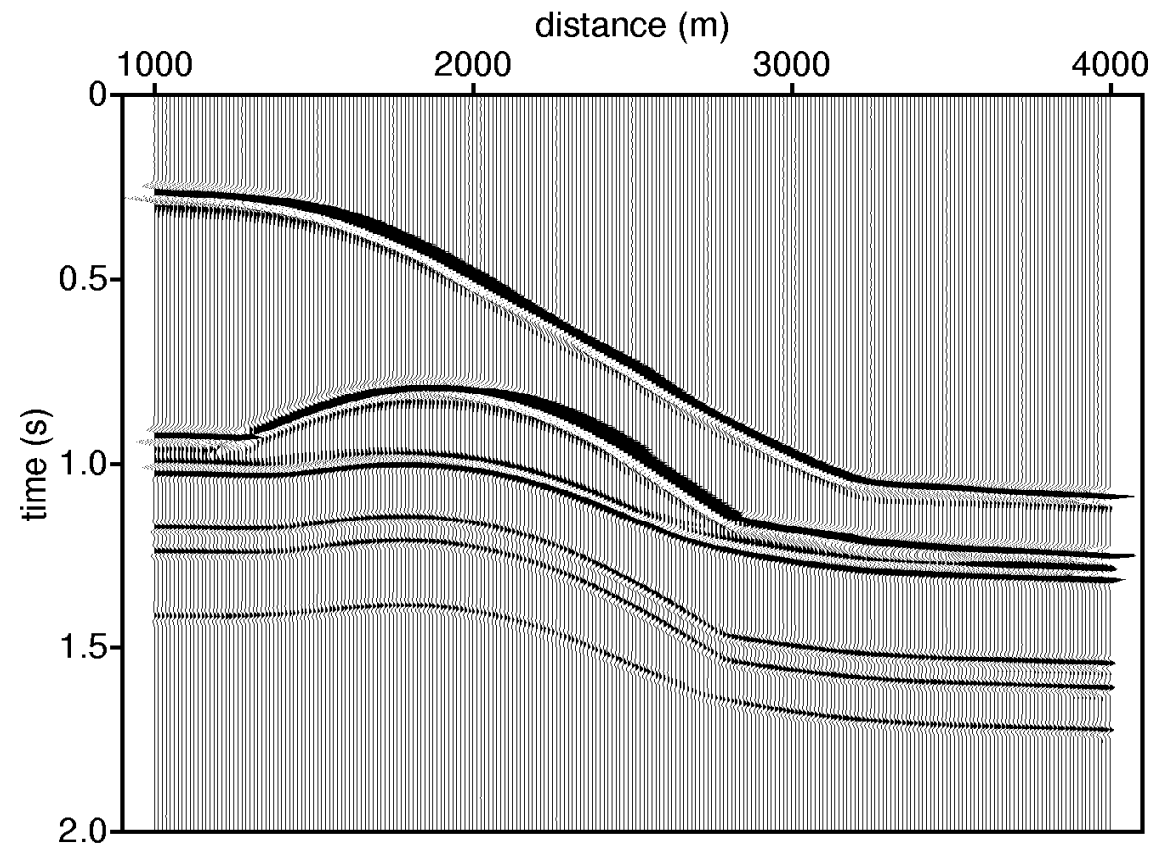


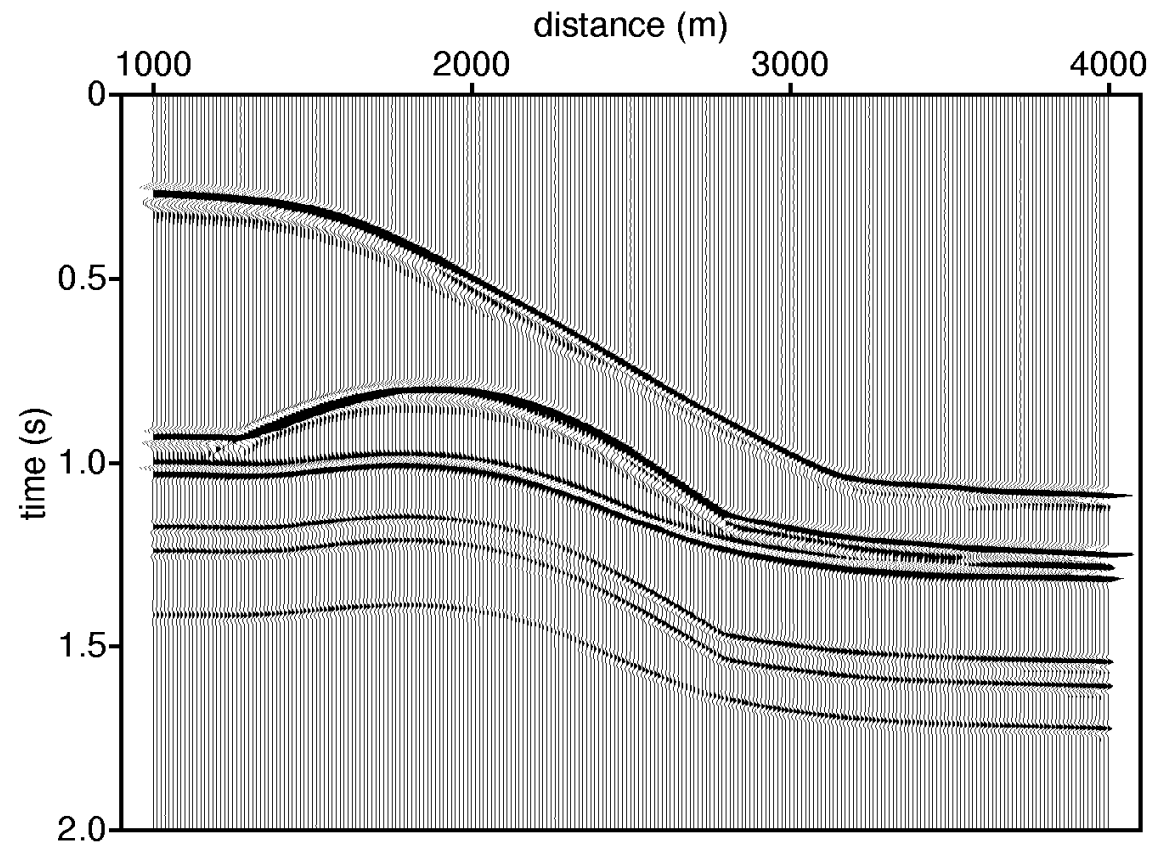
Primaries and multiple: stack



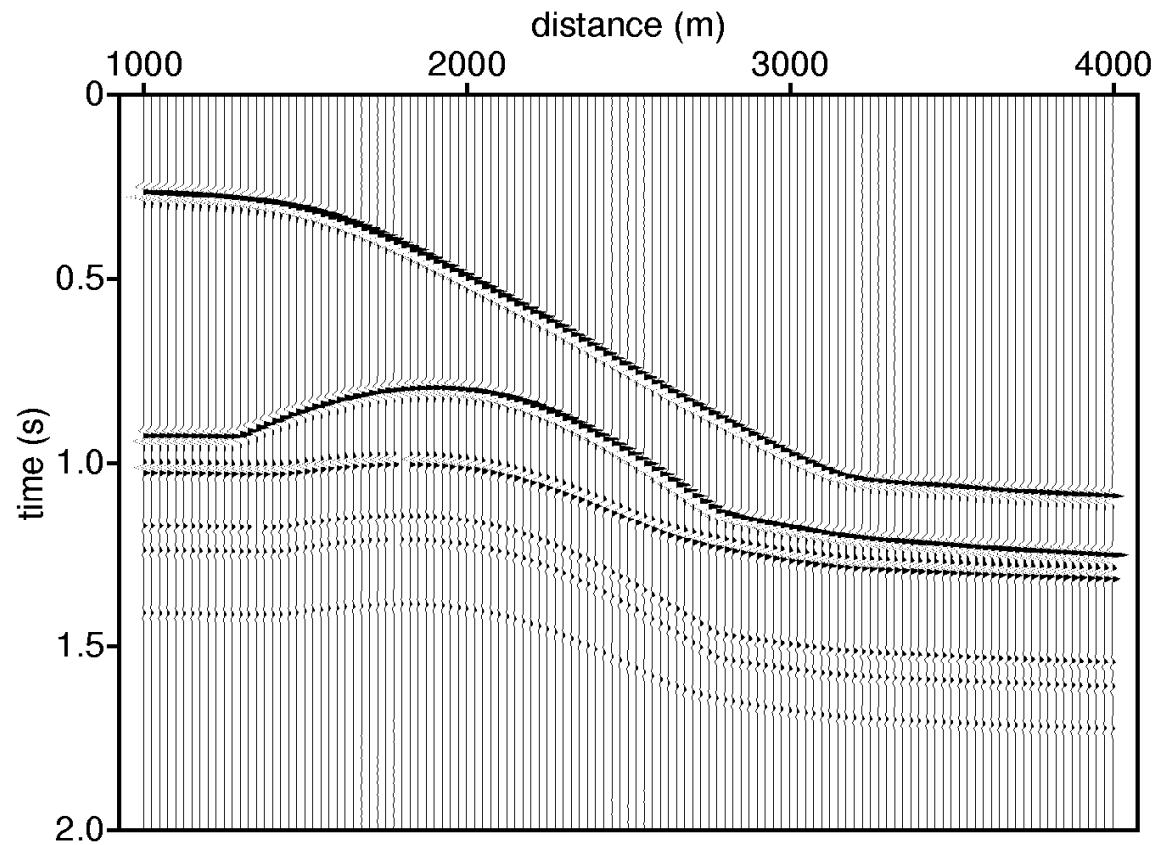
Stack



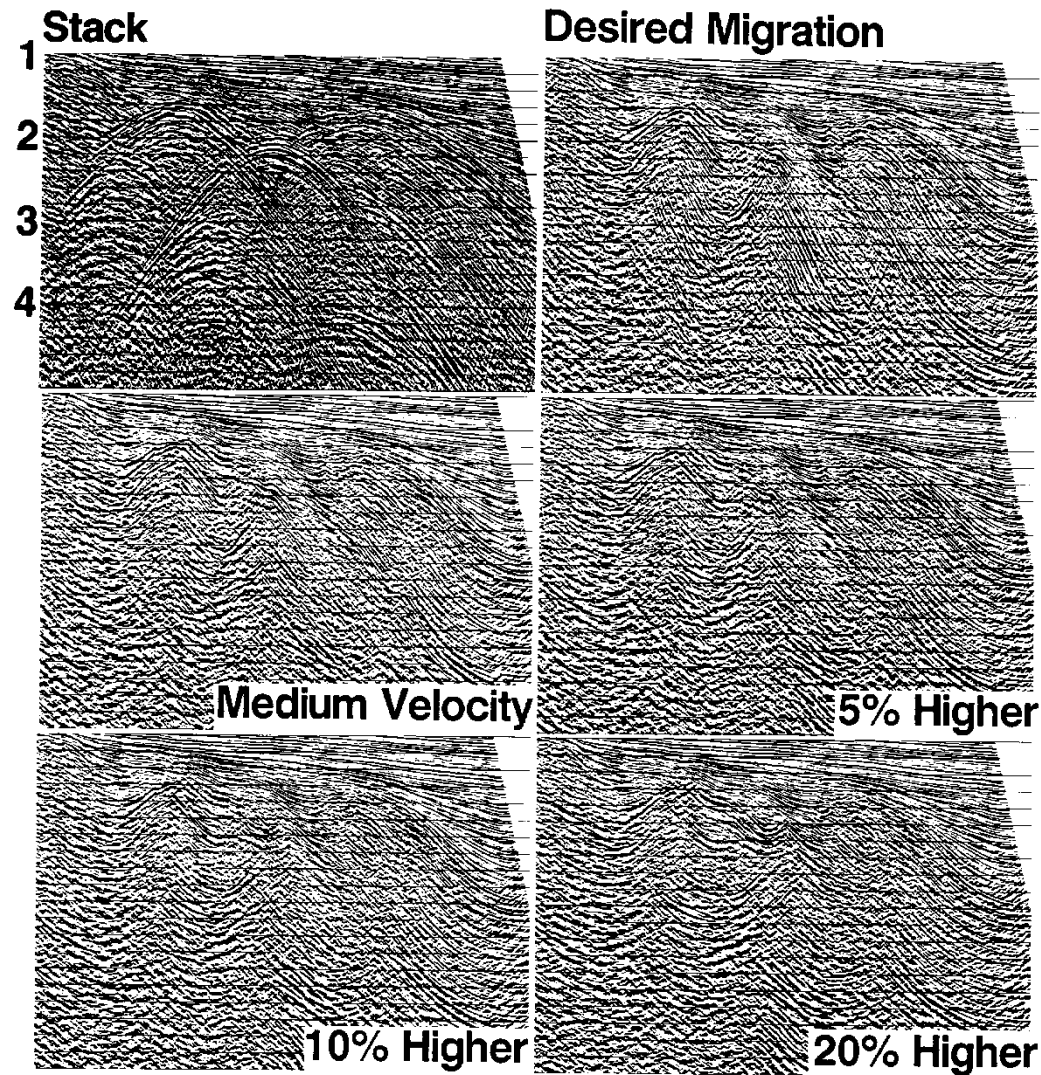
Stack: 7% wrong velocity



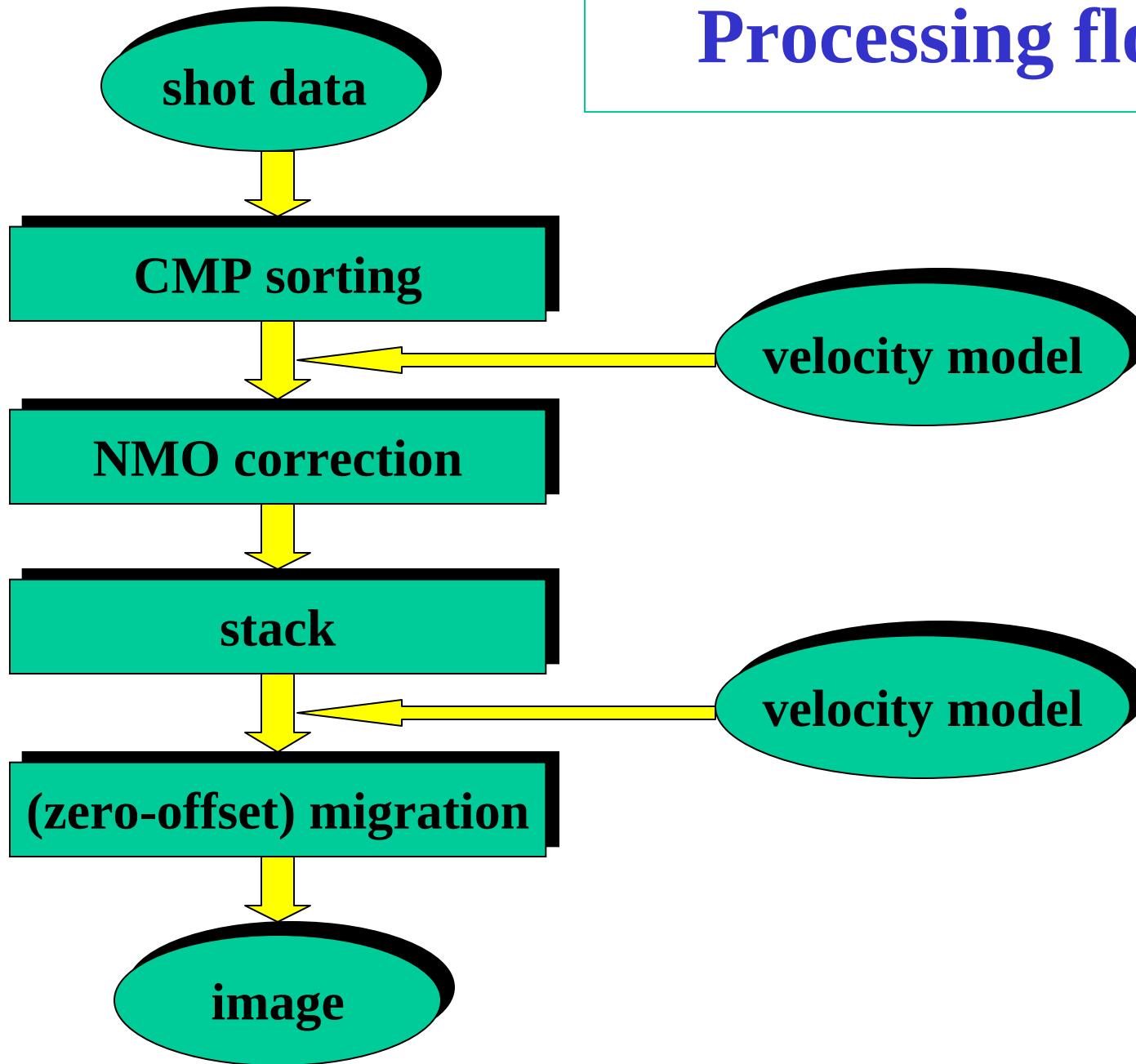
Zero-offset gather (no stacking)



Effect velocity on stack/migration



Processing flow



Migration (zero-offset)

Stacked section is assumed to be zero-offset

(as if you shot with 1 geophone, and geophone at shot position)

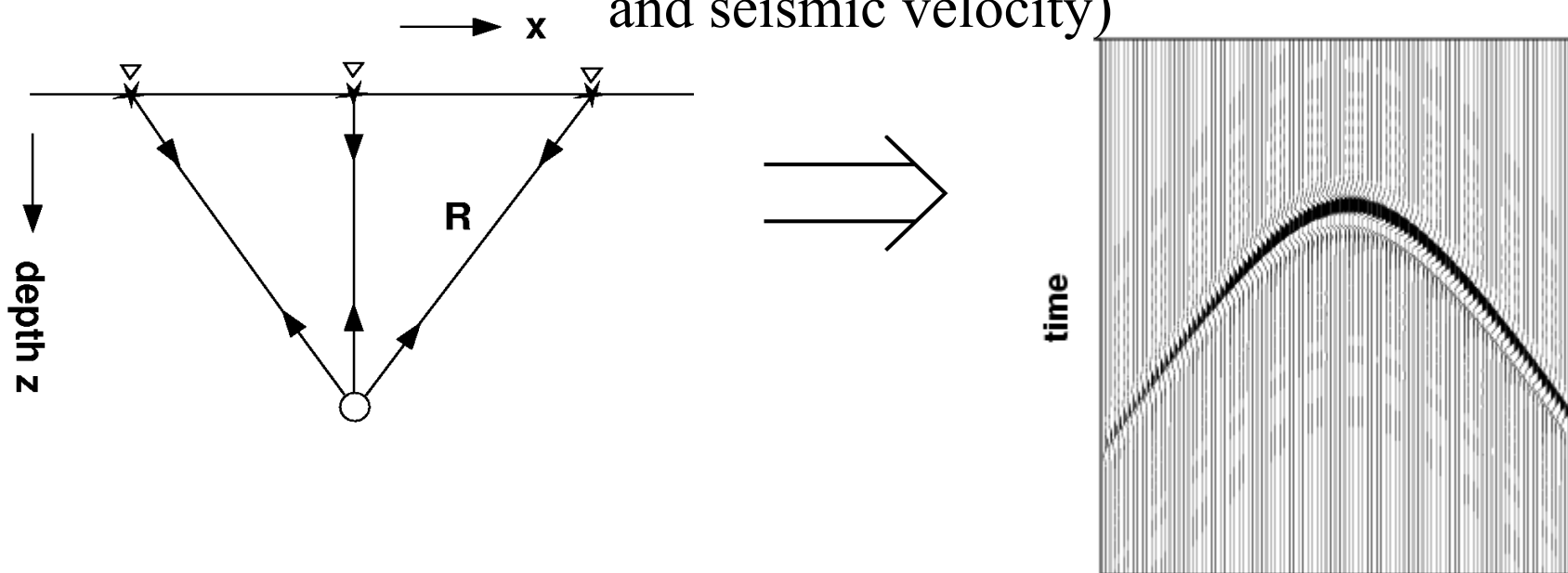
A zero-offset section:

energy is still not focussed !!!

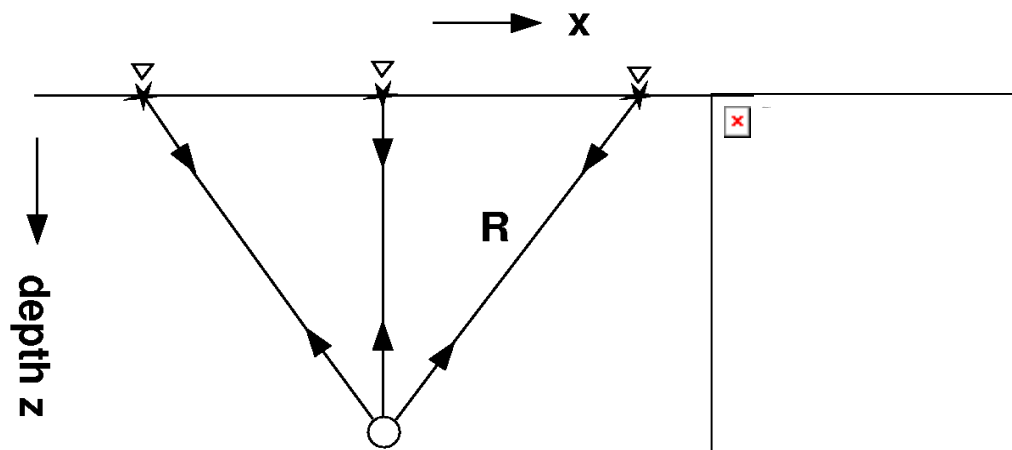
Diffractor: zero-offset

Modelling

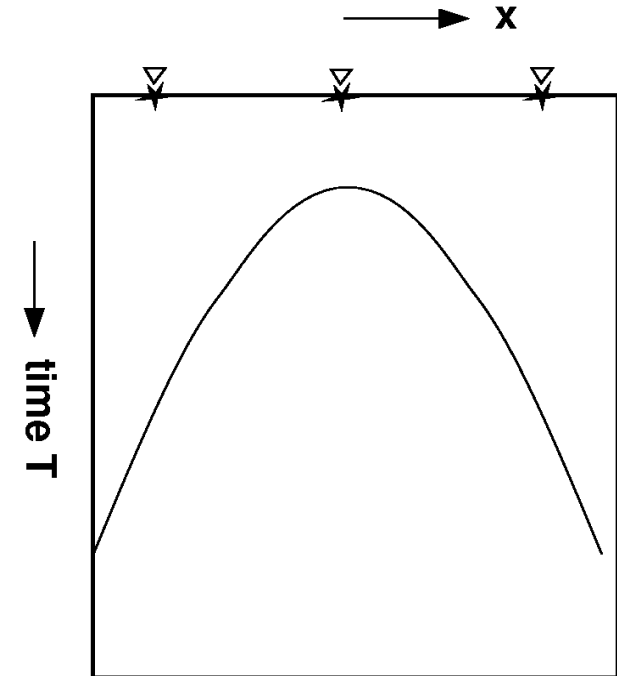
(we know the Earth:
Position of diffractor
and seismic velocity)



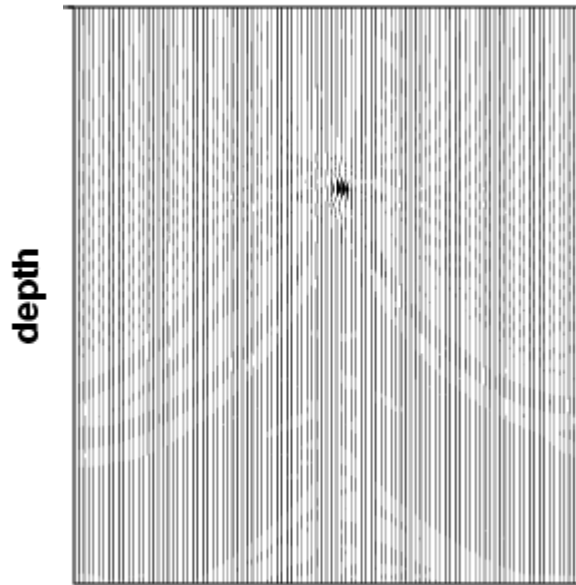
Diffractor: zero-offset



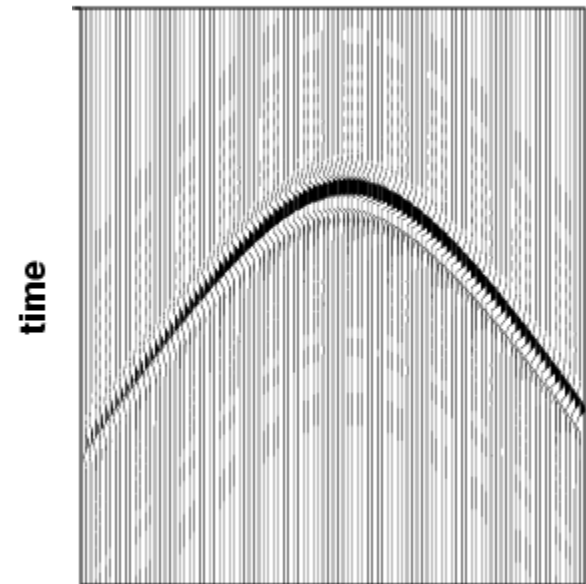
Migration
(we do NOT know
the position of
diffractor, but do
know the velocity)



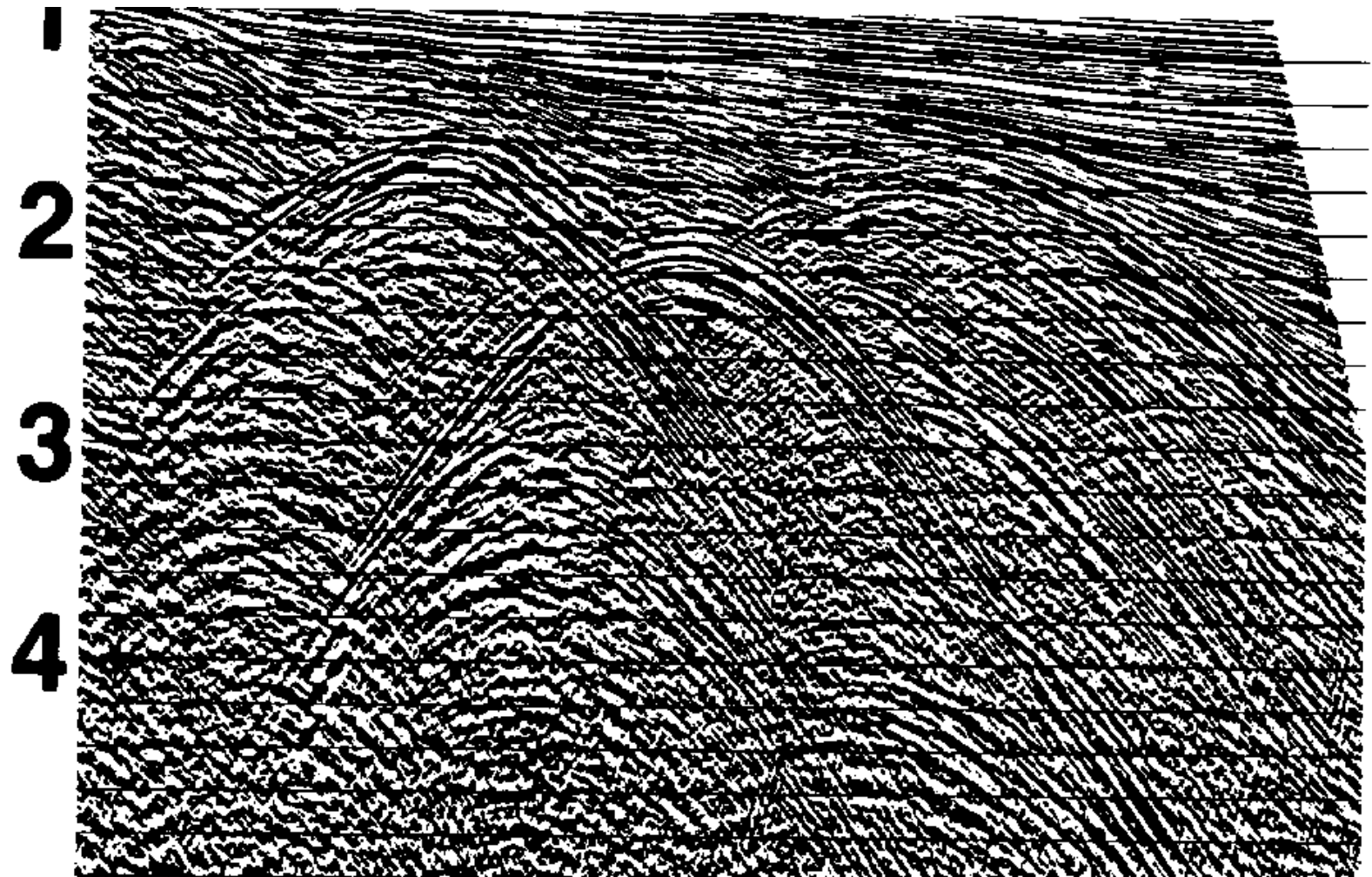
Diffractor: zero-offset



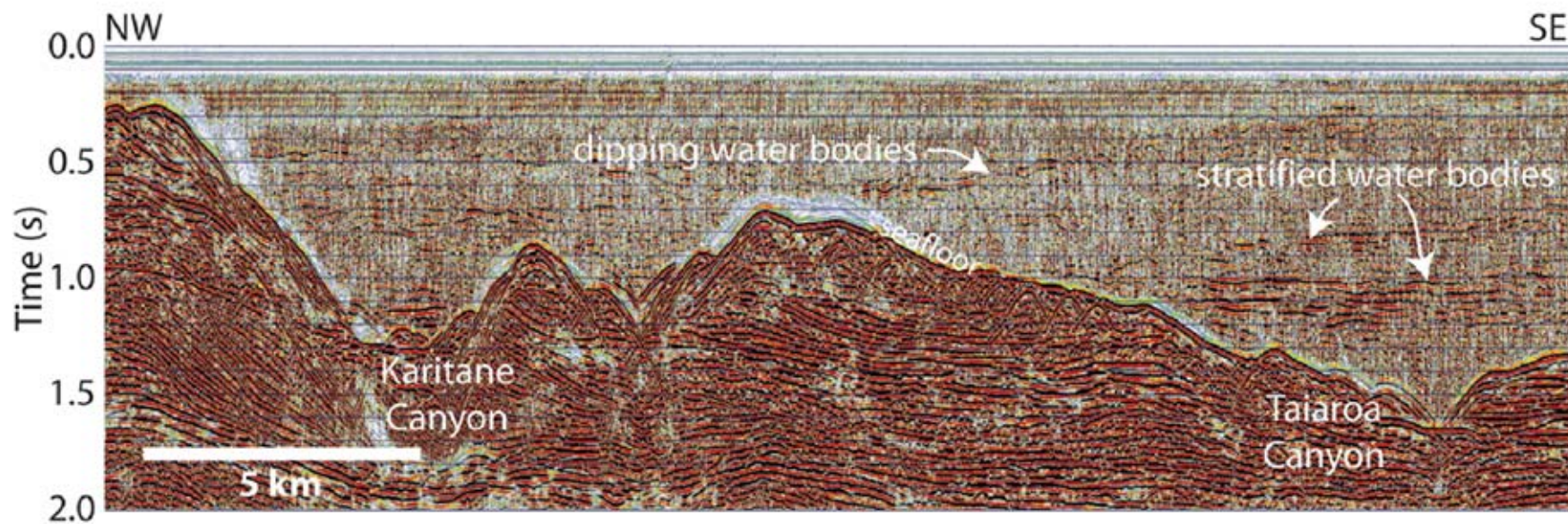
Migration
(we do NOT know
the position of
diffractor, but do
know the velocity)



Diffractor: zero-offset stack



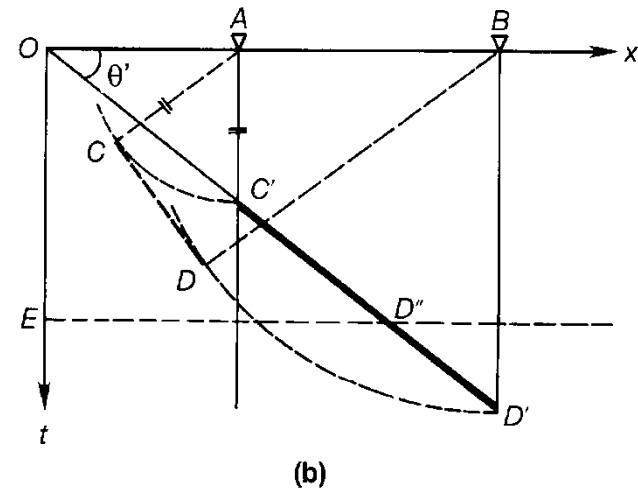
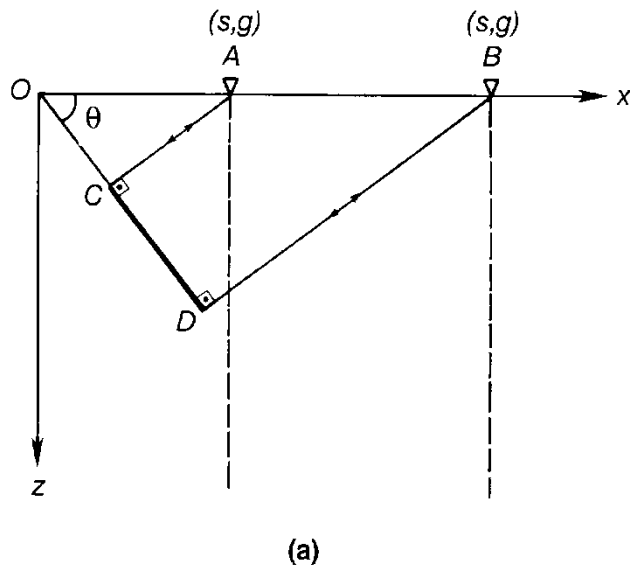
Diffraction: zero-offset stack



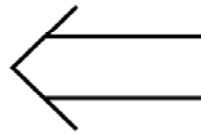
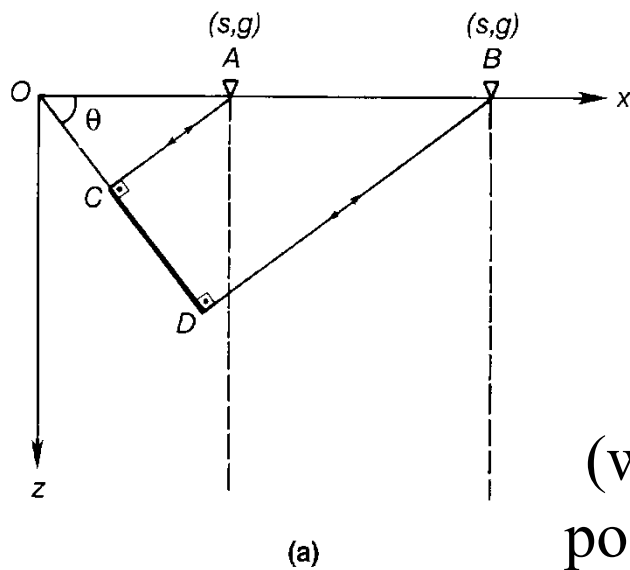
(60-fold stack)

Migration on dipping reflector

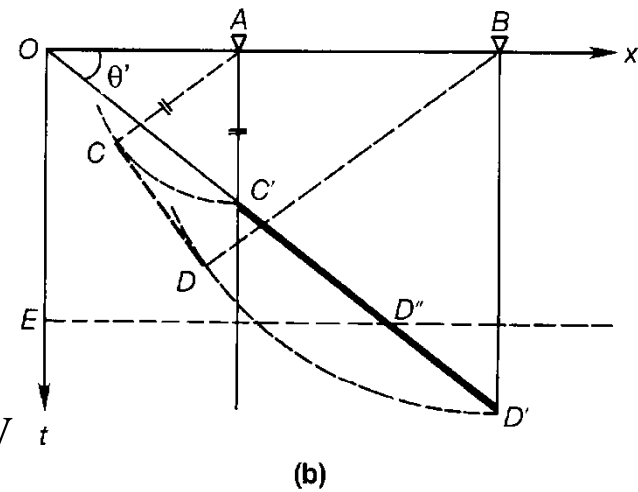
Modelling
(we know the Earth:
Position of reflector
and seismic velocity)



Migration on dipping reflector



Migration
(we do NOT know
position of reflector,
but do know
seismic velocity)



Migration on piece of dipping reflector:

- Moves piece up-dip**
- Makes dip steeper**
- Makes piece shorter**

Migration on dipping reflector

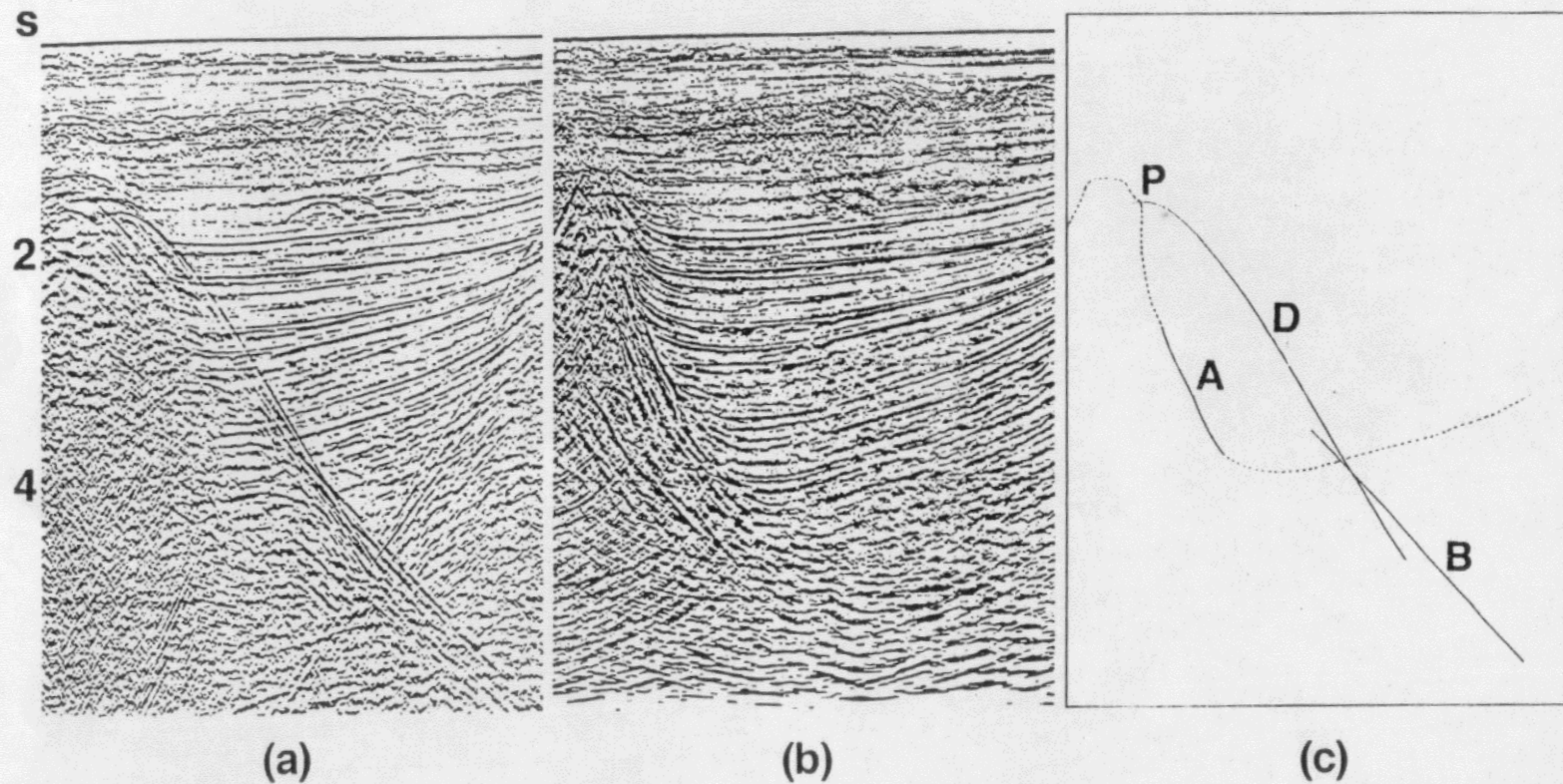
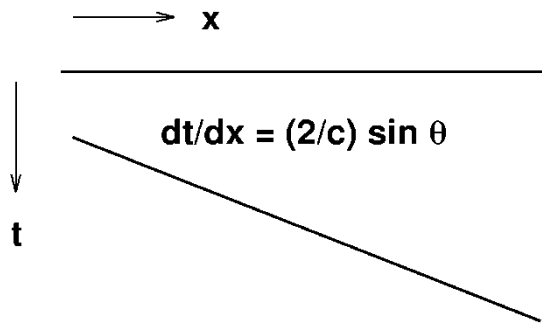


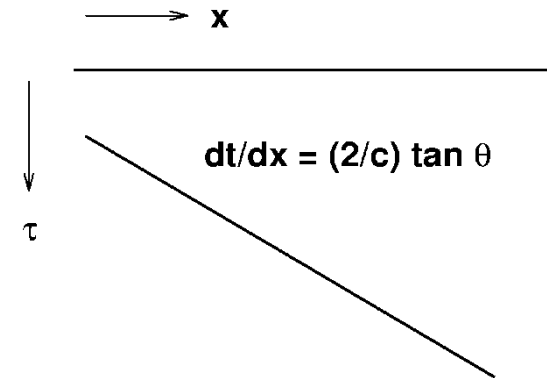
FIG. 4-1. (a) CMP stack, (b) migration, (c) sketch of a prominent diffraction *D* and a dipping event before (*B*) and after (*A*) migration. Migration moves the dipping event *B* to its assumed true subsurface position *A* and collapses the diffraction *D* to its apex *P*. The dotted line indicates the boundary of the salt dome.

Apparent dips

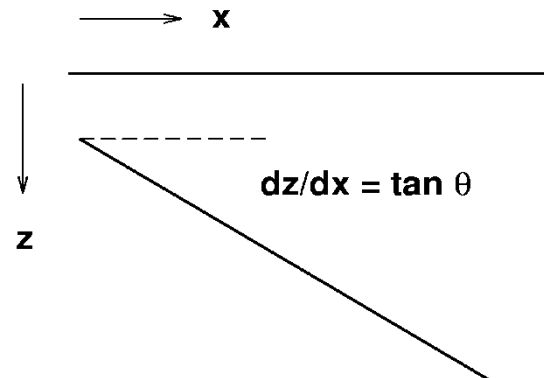
Zero-offset section:



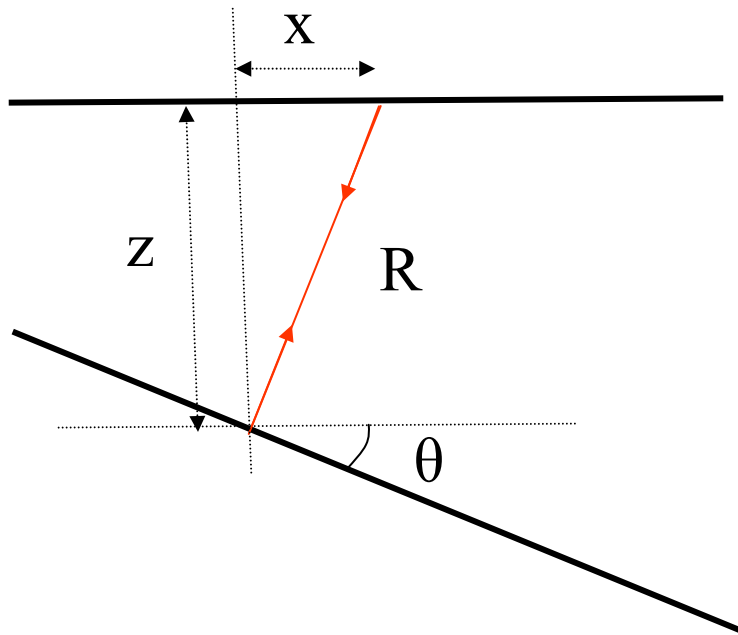
(time-) migrated section:



(depth-) migrated section = depth section:



Dip

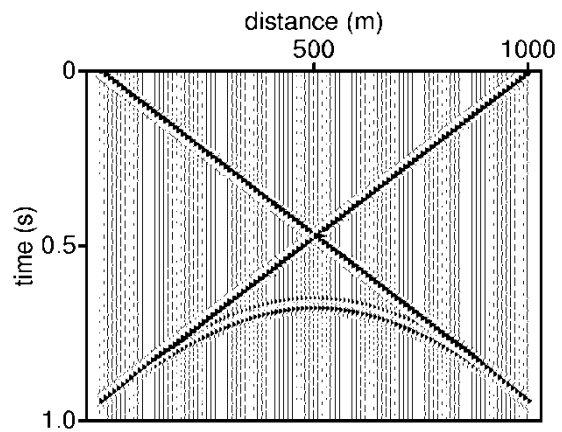


$$\begin{aligned} T &= 2 R/c = 2 \sqrt{(x^2+z^2)}/c \\ \partial T/\partial x &= (2/c)^{1/2} (x^2+z^2)^{-1/2} 2 x \\ &= (2/c) x/(x^2+z^2)^{1/2} \\ &= (2/c) x/R \end{aligned}$$

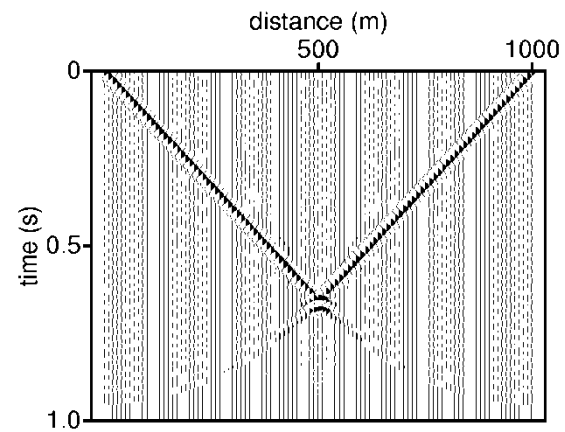
$$\sin \theta = x/R$$

$$\text{So: } \partial T/\partial x = 2/c \sin \theta$$

Double-dip

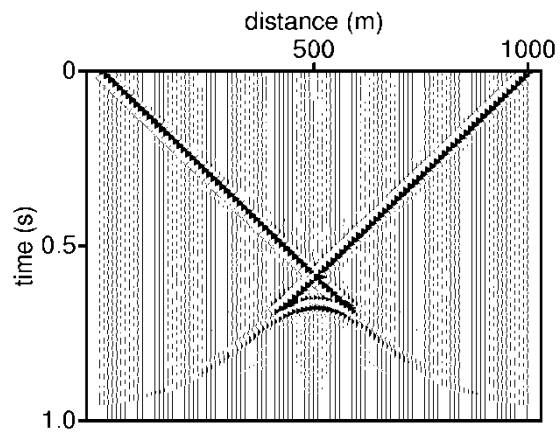


Zero-offset section:
before migration

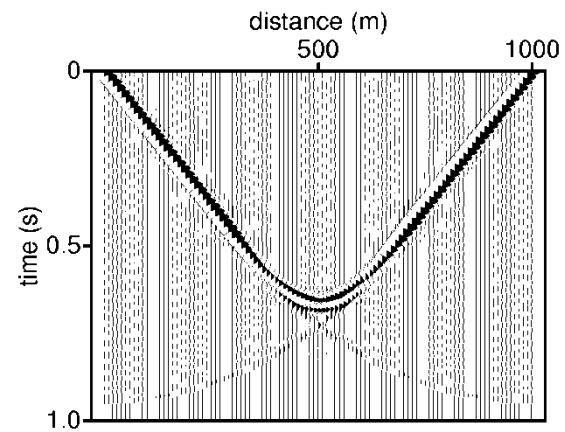


After migration

Double-dip (2)

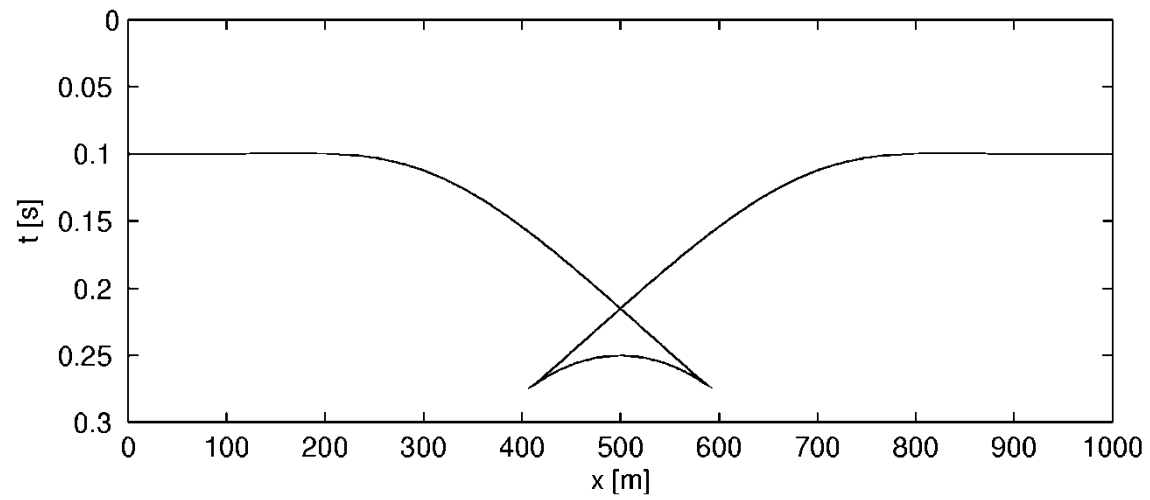
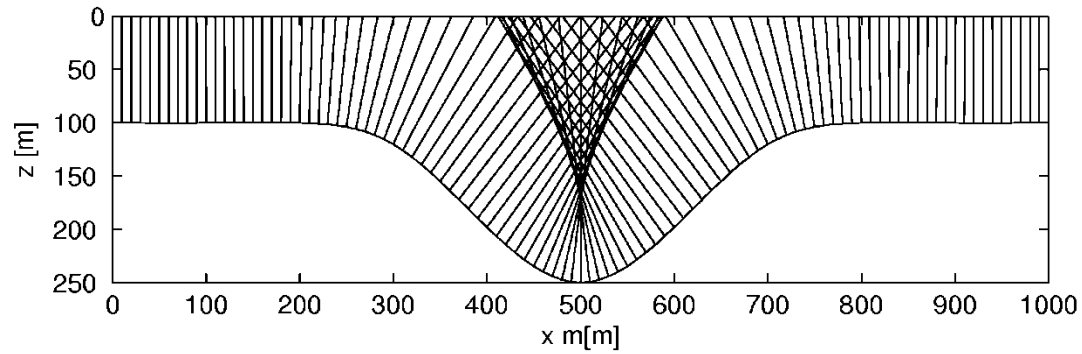


Migration with too low velocity

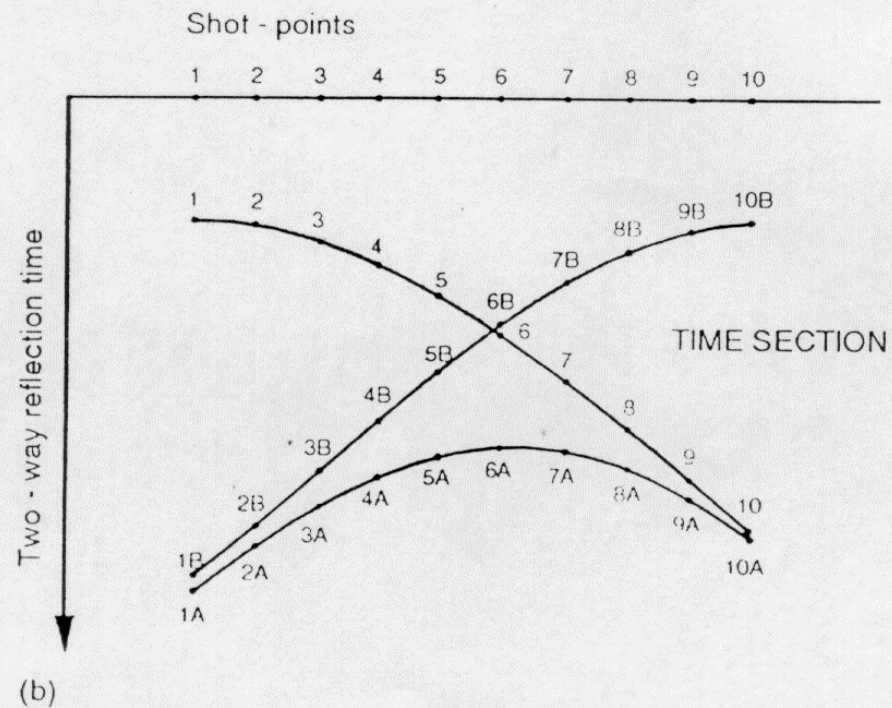
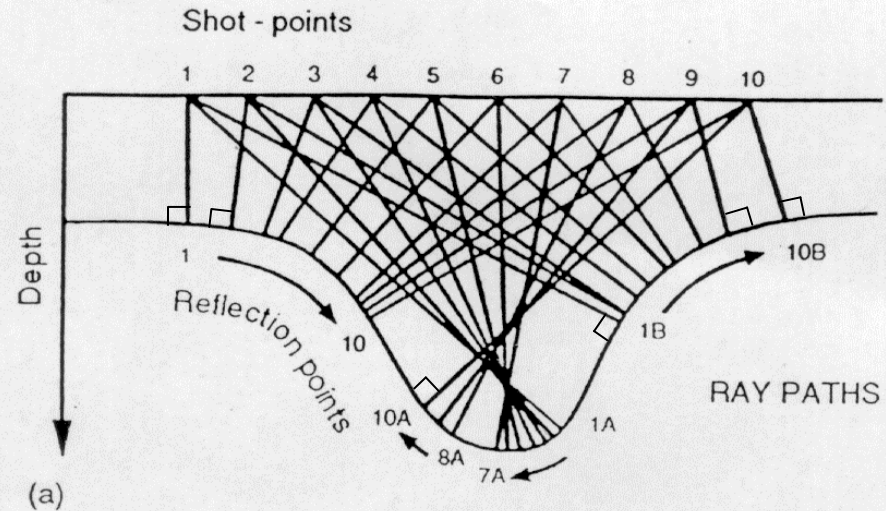


Migration with too high velocity

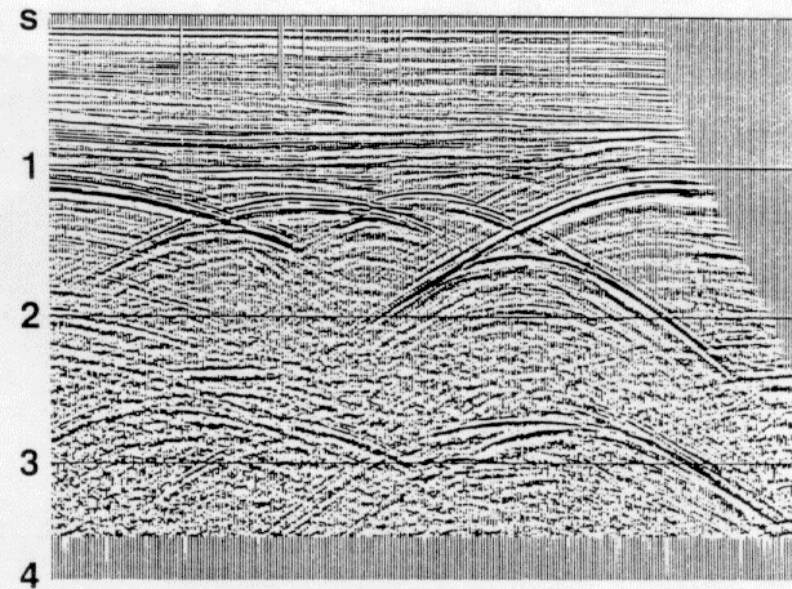
Syncline



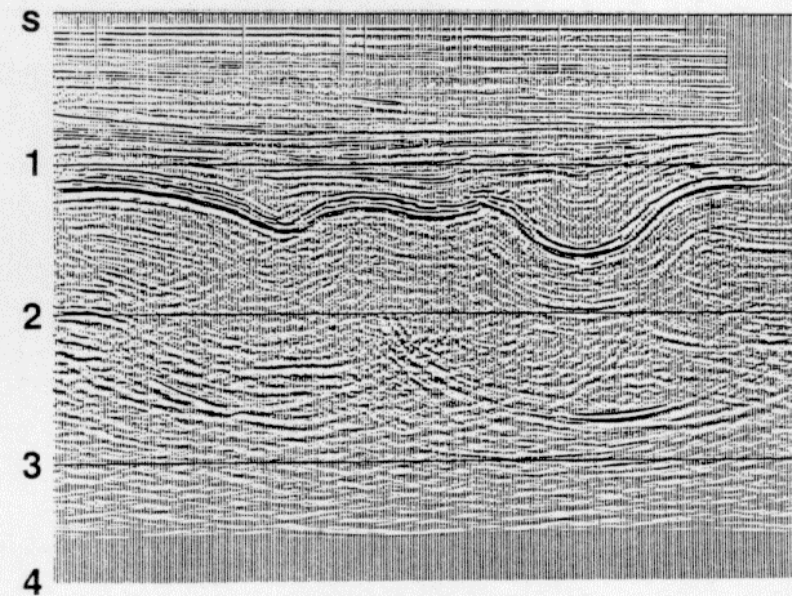
Syncline model with ray paths



Syncline: real data example



(a)

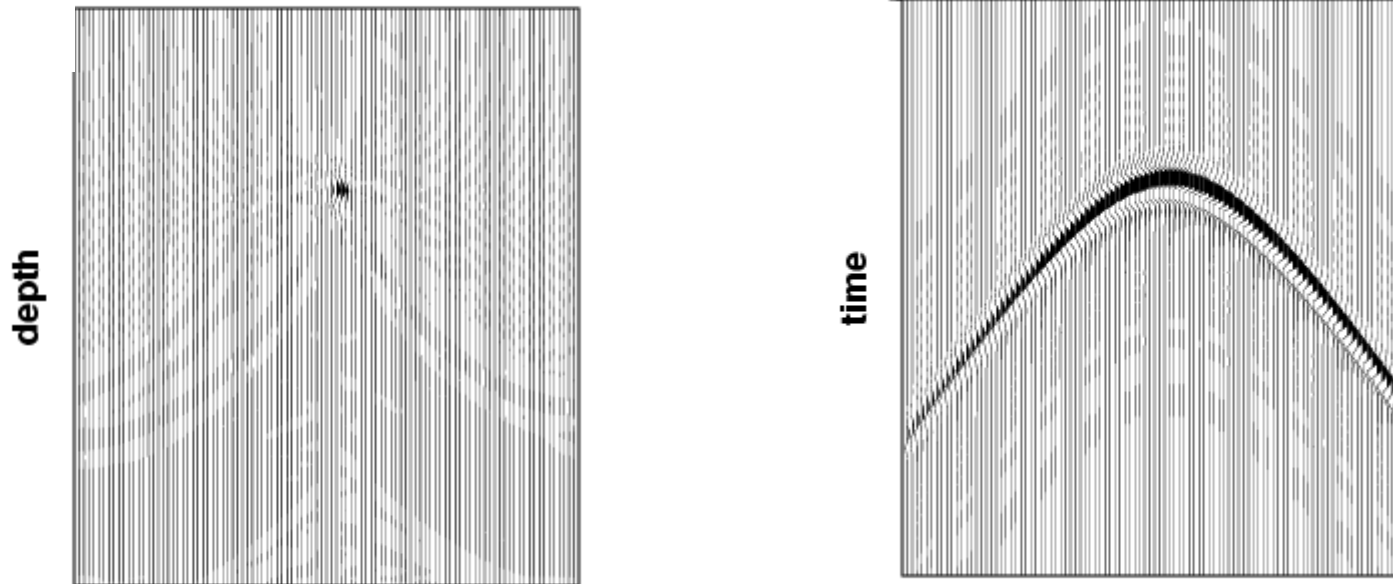


(b)

Migration:

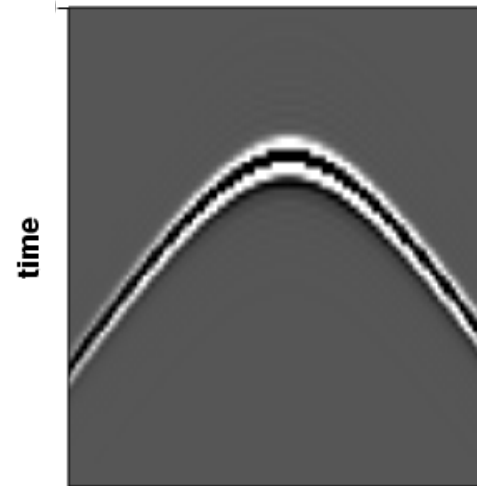
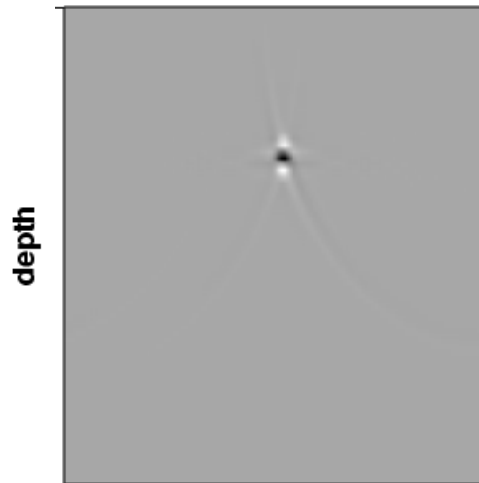
HOW ??

1 Diffractor: zero-offset



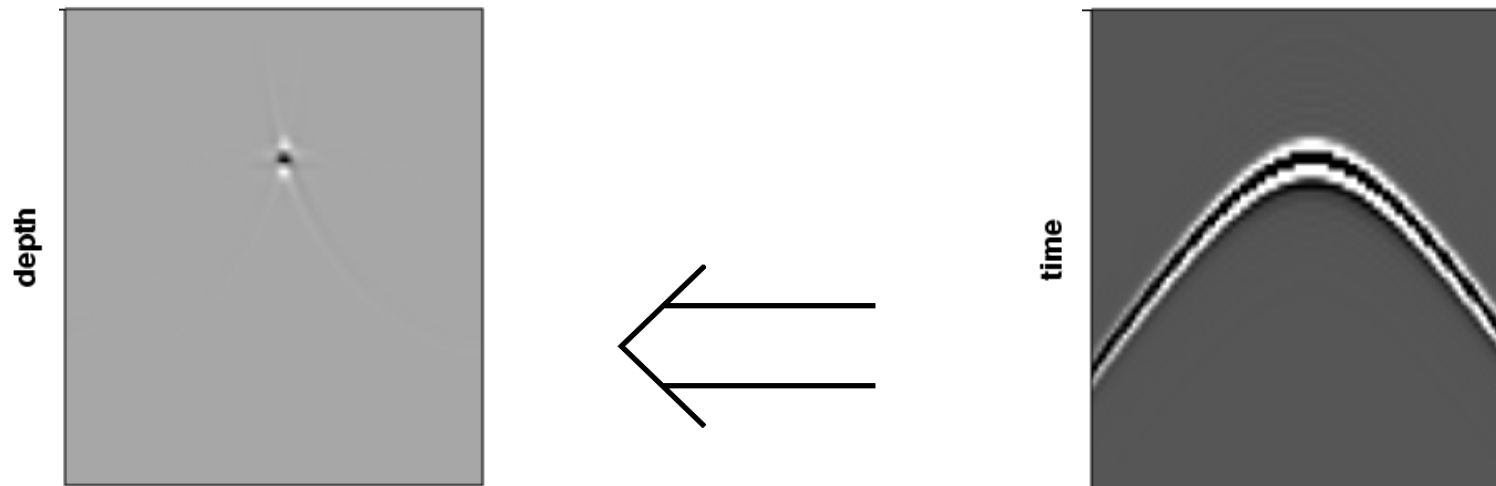
“Wiggle plot”:
Signals next to each other

1 diffractor: zero-offset



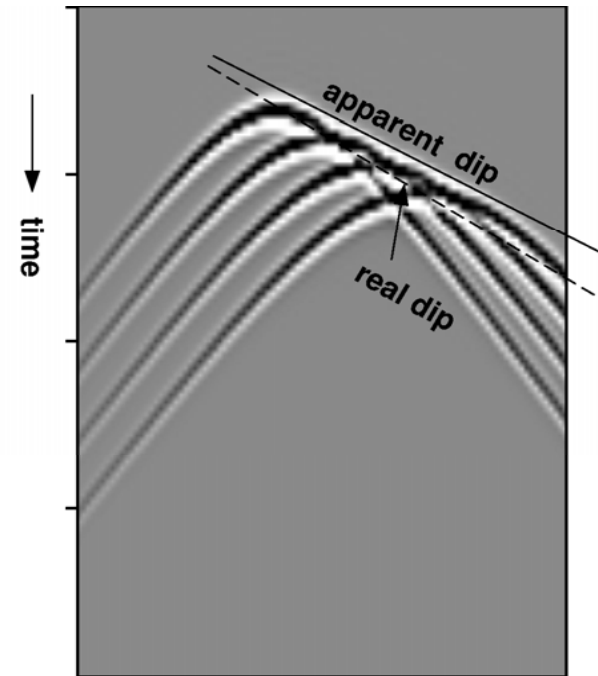
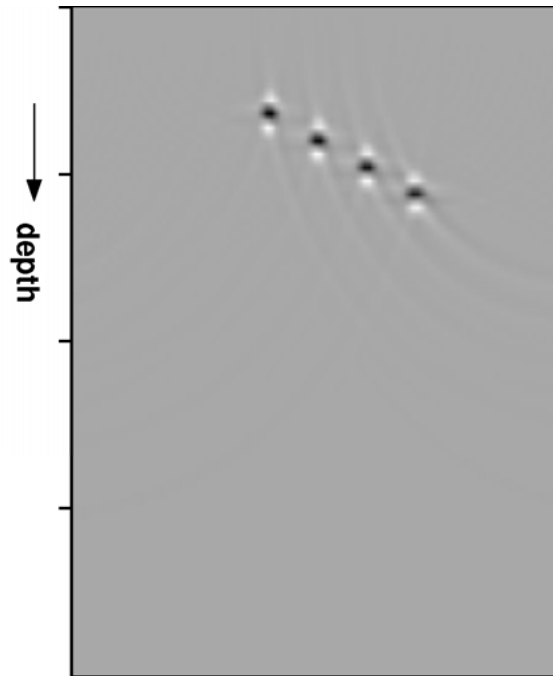
“Image plot”:
Like a photograph

1 diffractor: zero-offset

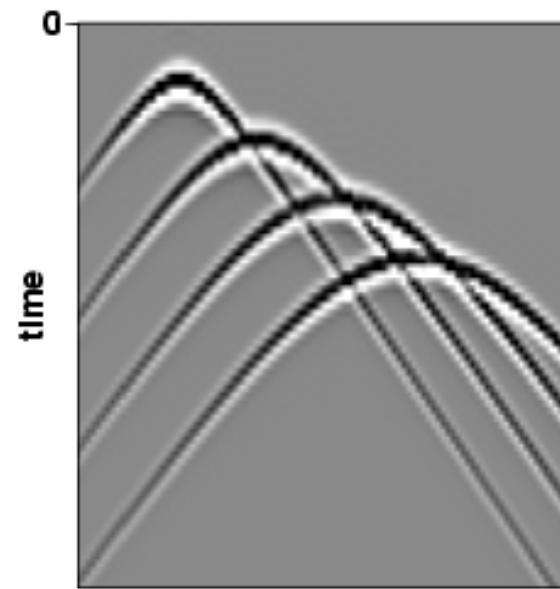
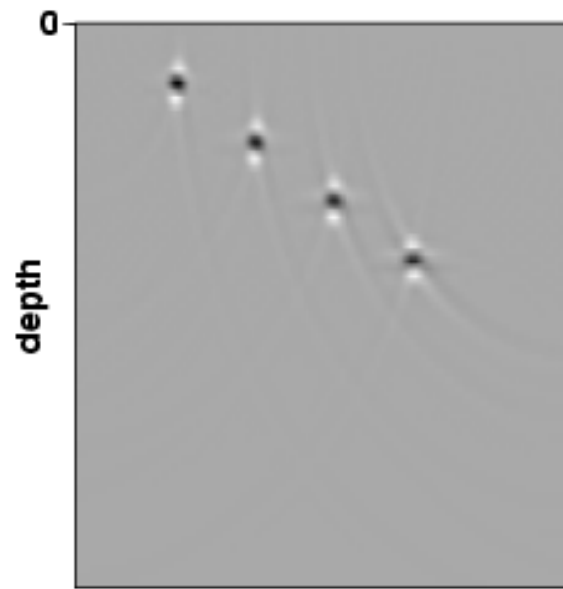


Migration:
Add along hyperbola
(we *do* know velocity)

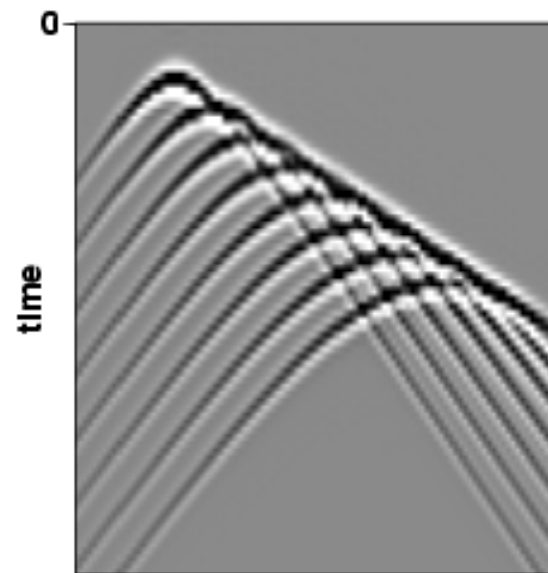
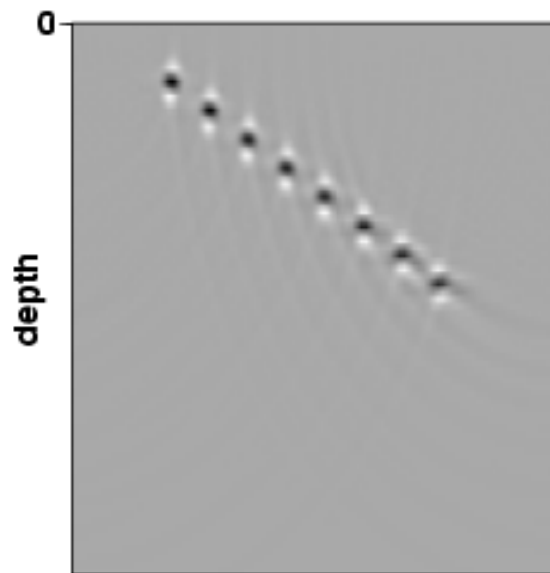
4 diffractors: zero-offset



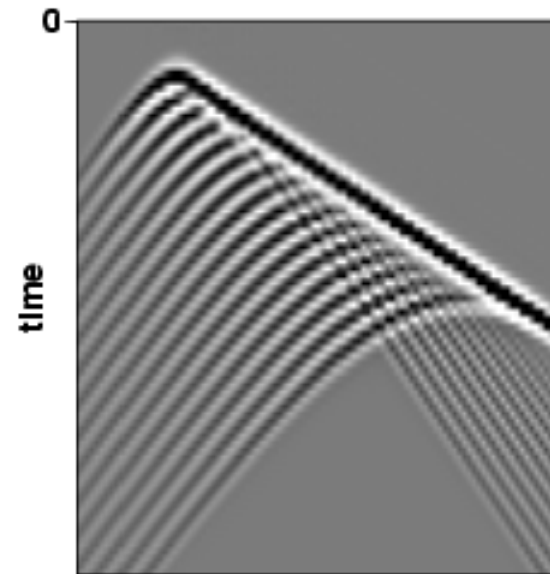
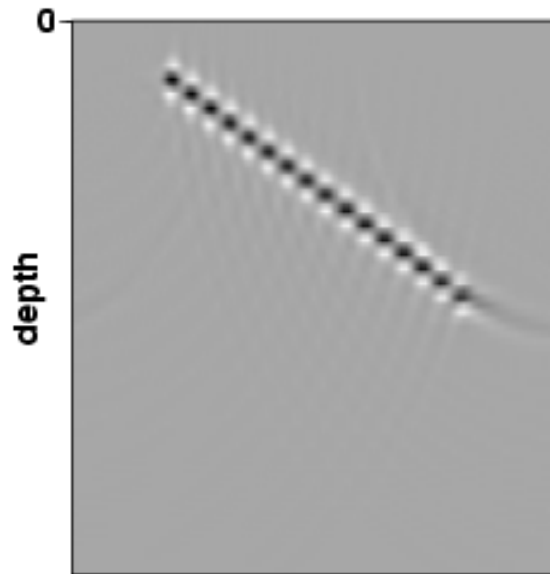
4 diffractors: zero-offset



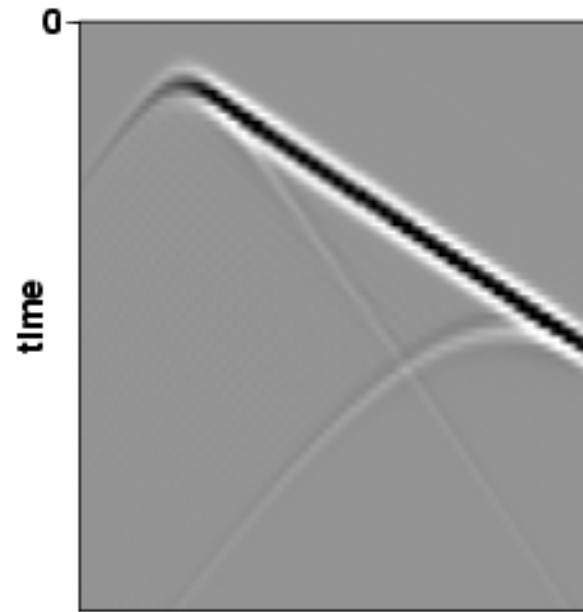
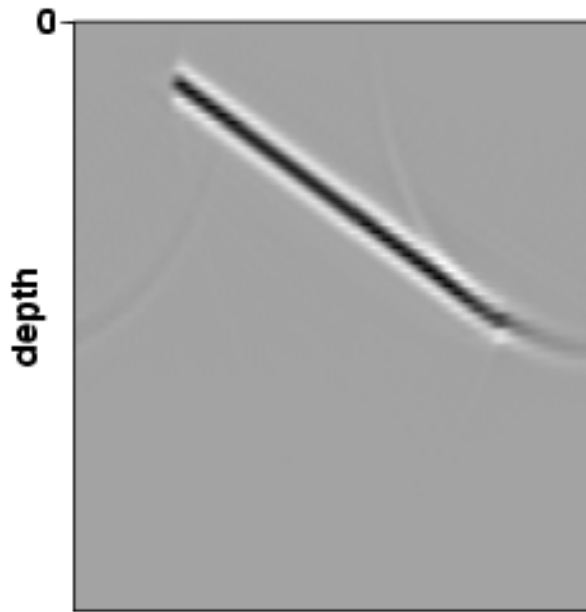
8 diffractors: zero-offset



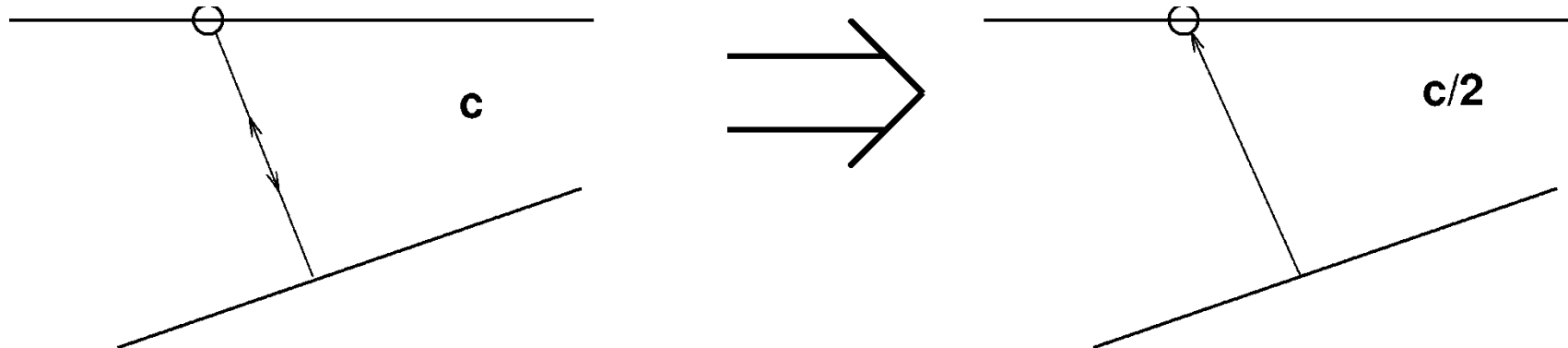
16 diffractors: zero-offset



32 diffractors: zero-offset

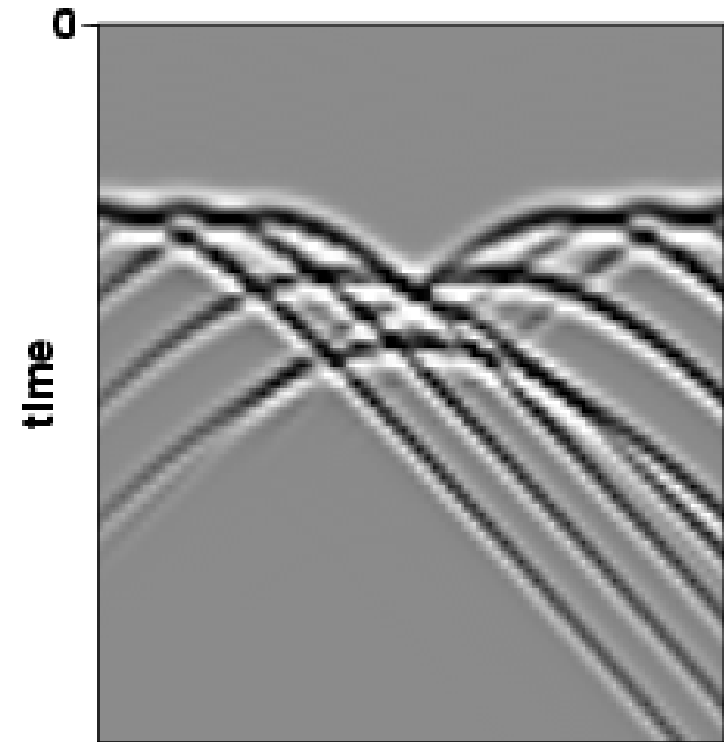
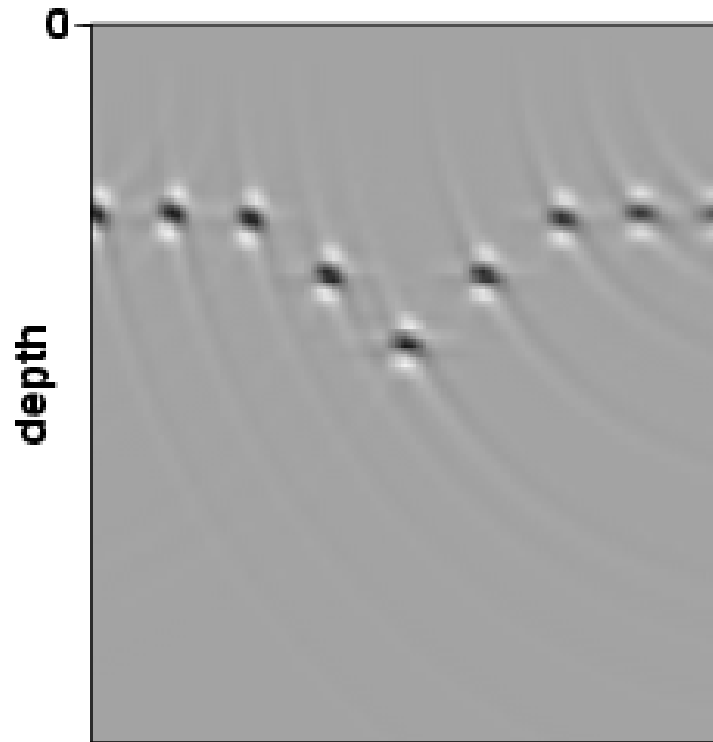


Exploding-reflector model

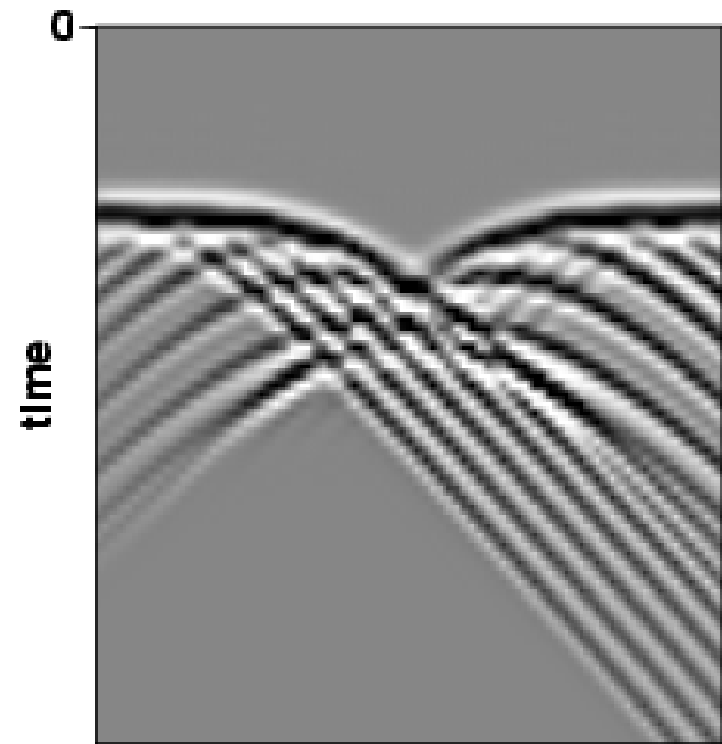
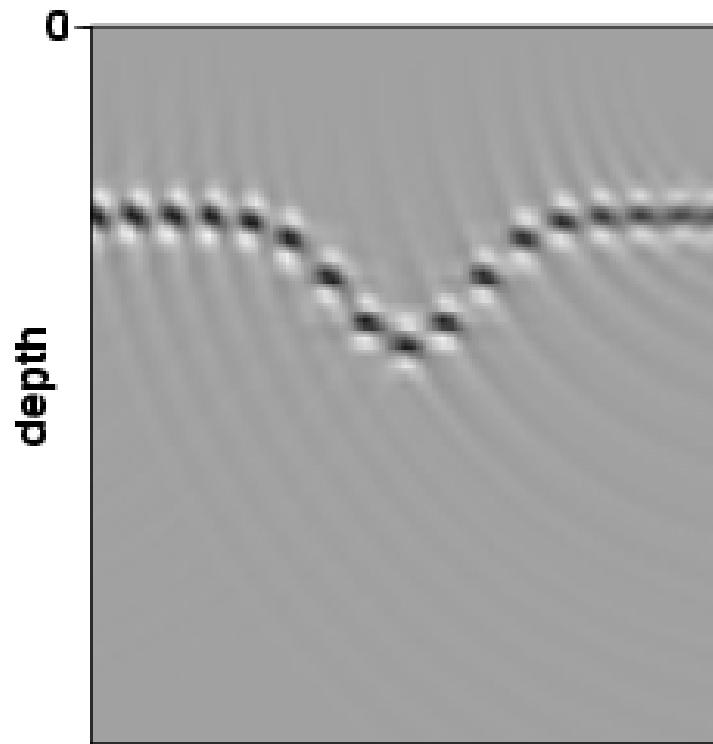


Zero-offset response can be simulated by putting sources at reflector and take half the medium velocity

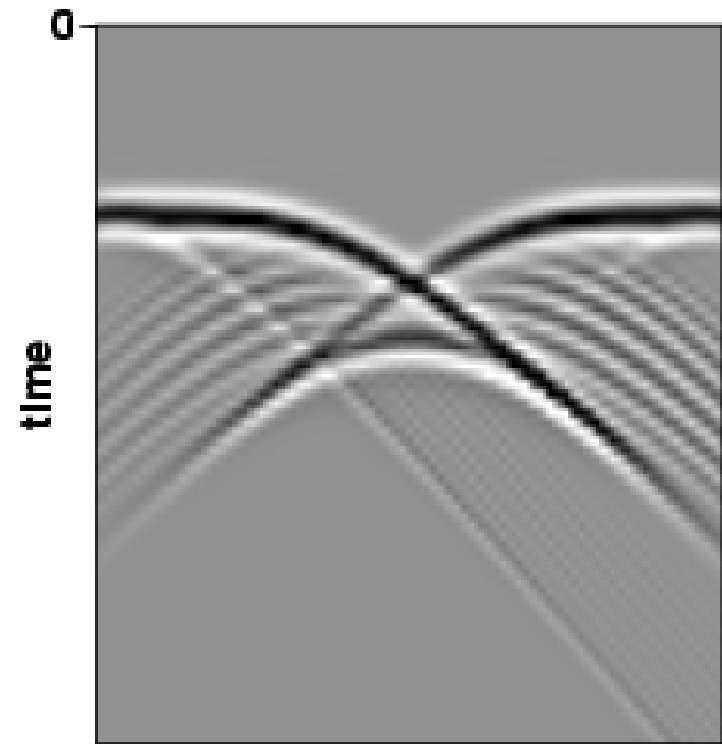
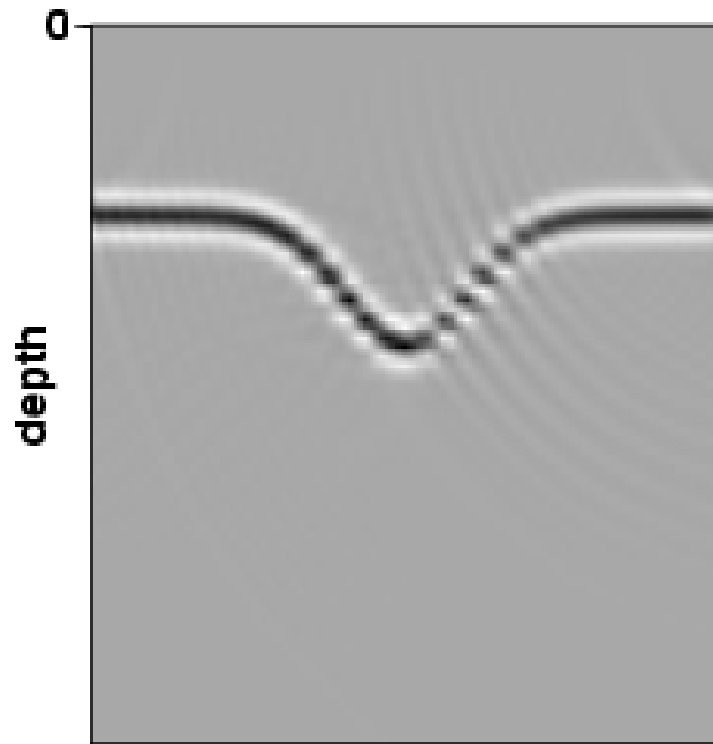
9 diffractors: zero-offset



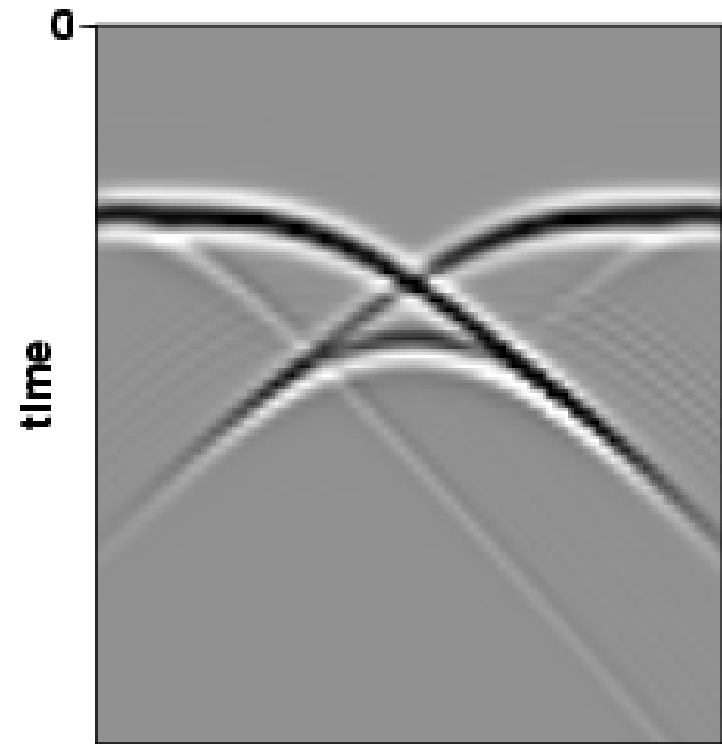
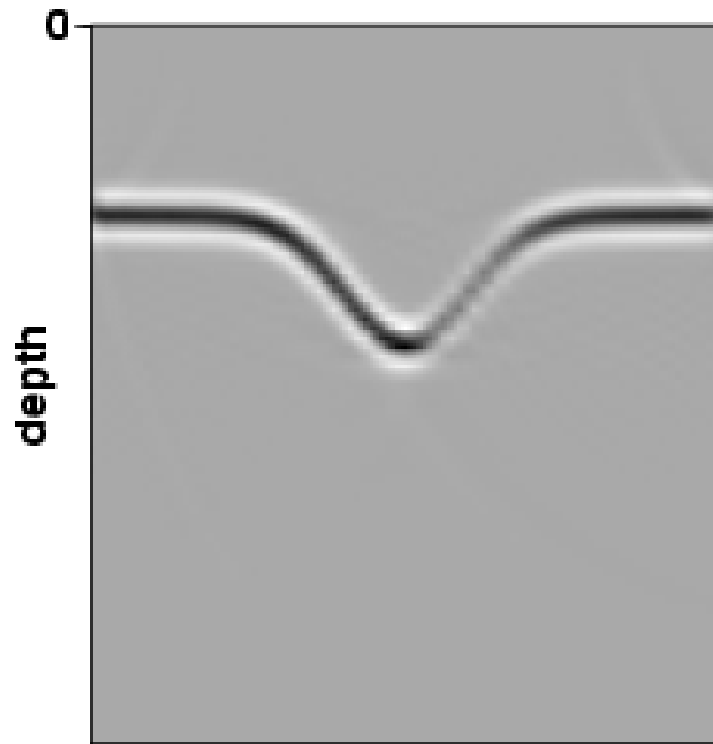
17 diffractors: zero-offset



33 diffractors: zero-offset



49 diffractors: zero-offset



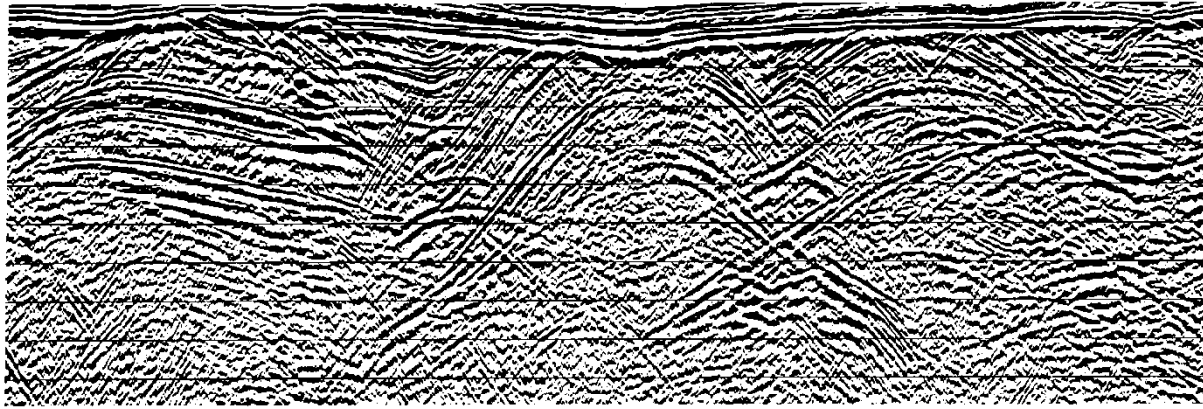
Processing

Input: Multi-offset shot records

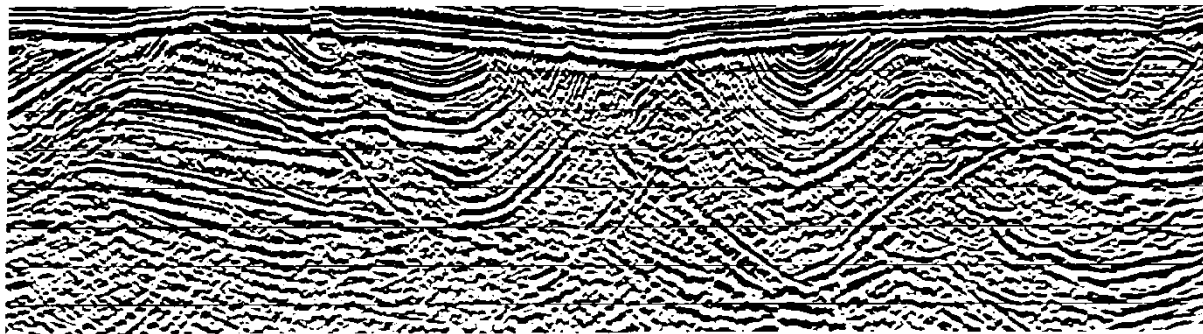
Results of processing (after migration):

1. Structural map of impedance contrasts
2. Velocity model

Effect migration



(a)



(b)

Conversion from time to depth

Migration examples so far:

output section in **time**

This is called **time migration**

Still, data needs to be converted to depth: true earth

Simplest case: horizontal layers

From root-mean-square velocities to interval velocities:

Dix' formula

Dix' formula:
from V_{RMS} to V_{INTERVAL}

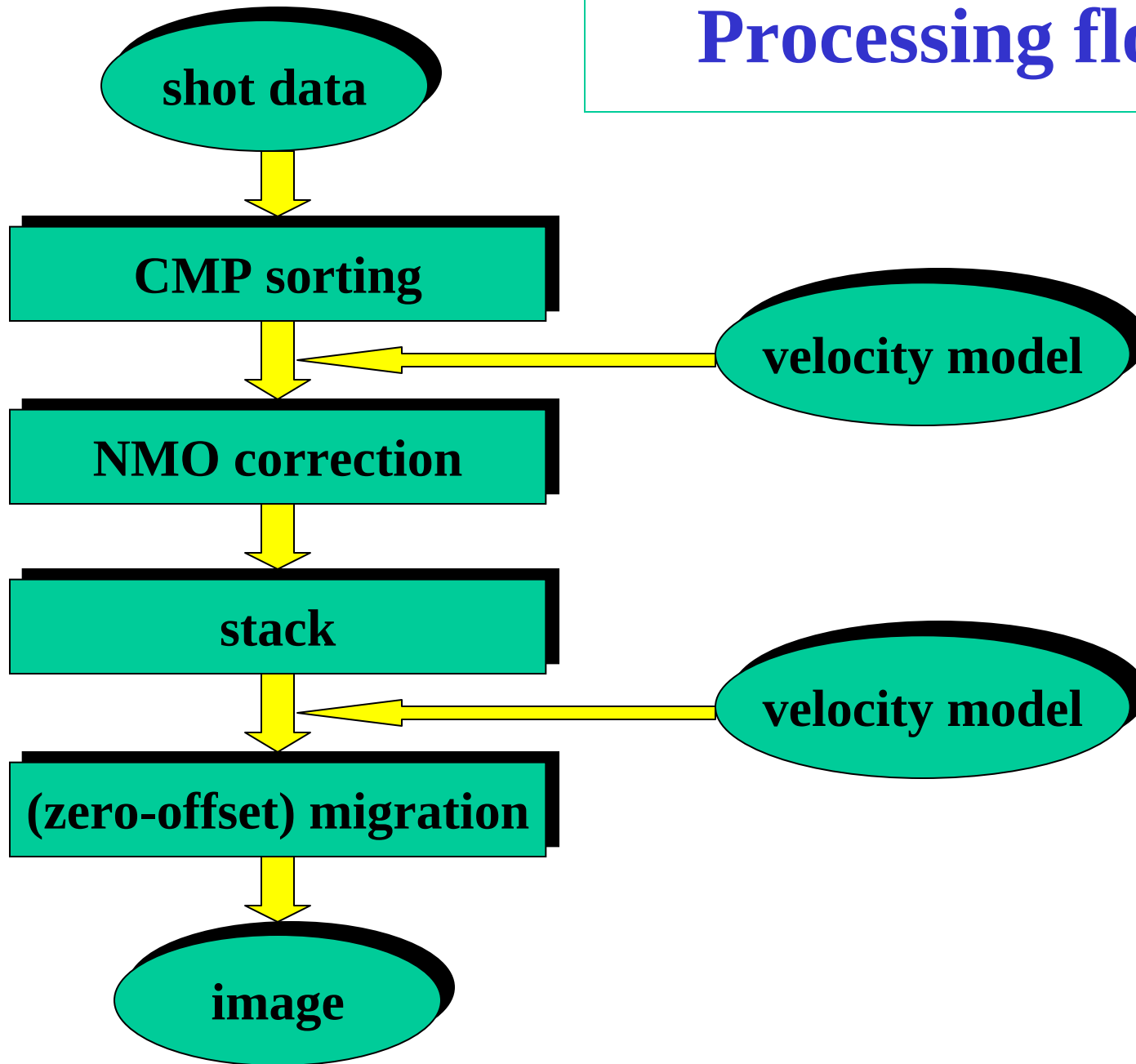
(pdf-eqs)

Conversion from time to depth via Dix' formula

Theoretically: valid for plane horizontal layers
(Theoretically: no migration necessary)

Practically: still works well for dipping reflectors and mild
lateral velocity variations, but then:
AFTER (time) migration

Processing flow



Strategy for seismic migration

Why ?

In beginning: only RMS-velocity model known: very crude
→ time migration (relatively fast/cheap)

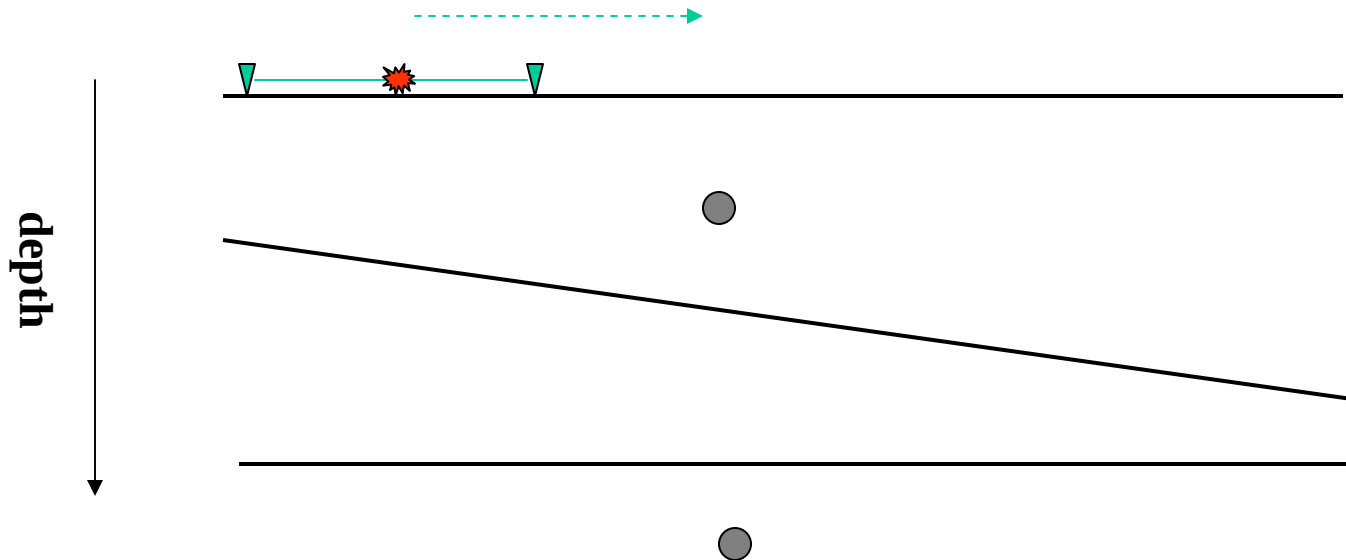
When one well available: better (interval-) velocity model
→ some depth migration possible (relatively slow/expensive)

When more wells available: good (interval-) velocity model known
→ pre-stack depth migration possible (slow/expensive !\$!)

Strategy for seismic migration

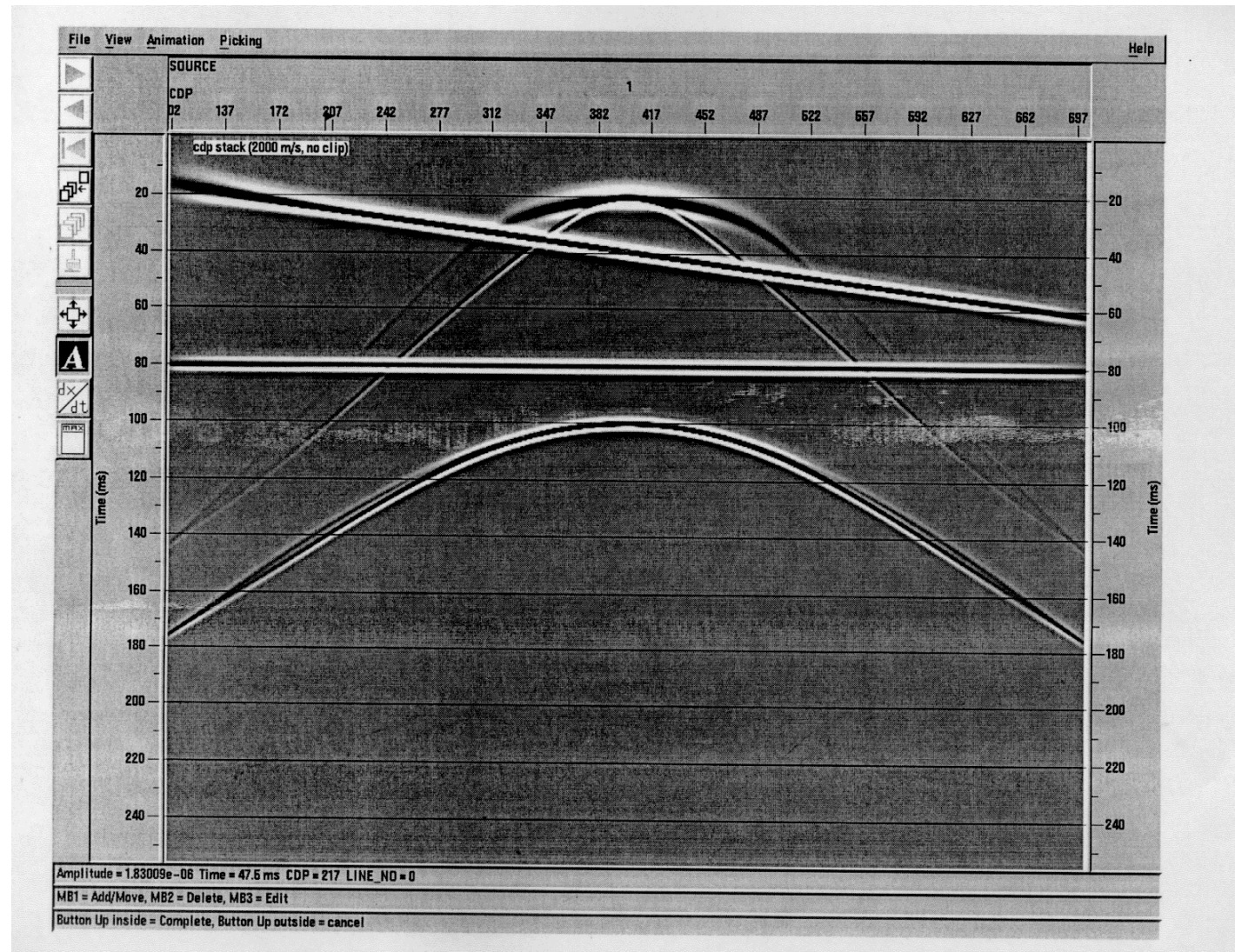
- **Simple structure: post-stack migration**
- **Complex structure: pre-stack migration**
(such as DMO)
- **Small lateral velocity variations: time migration**
- **Large lateral velocity variations: depth migration**
(no hyperbolae any more)

Complex structure: simplest case of diffractors



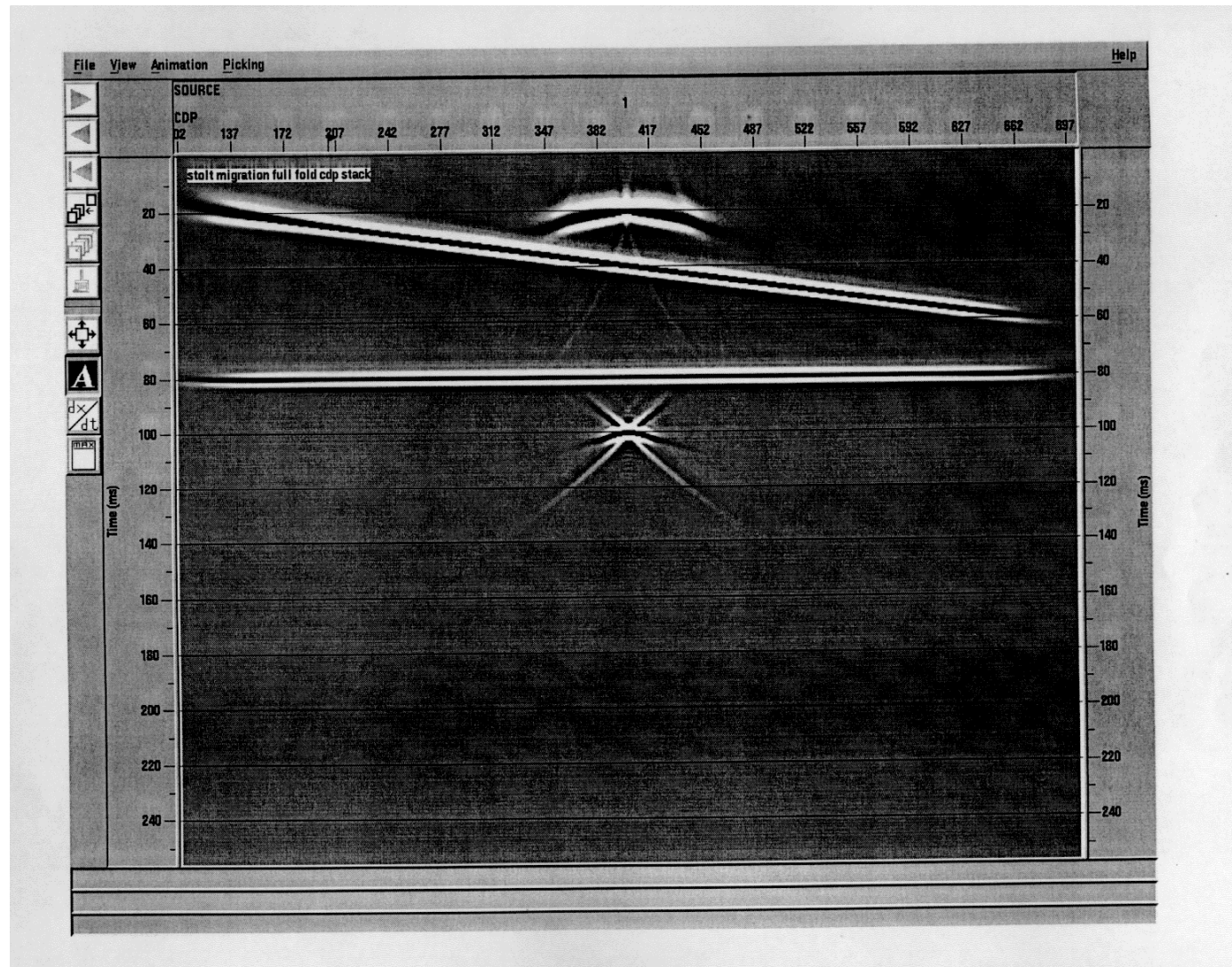
Complex structure: simplest case of diffractors

Stack with
no DMO



Complex structure: simplest case of diffractors

Migrated stack
With no DMO



Complex structure: simplest case of diffractors

Stack with
DMO



Complex structure: simplest case of diffractors

Migrated stack
With DMO



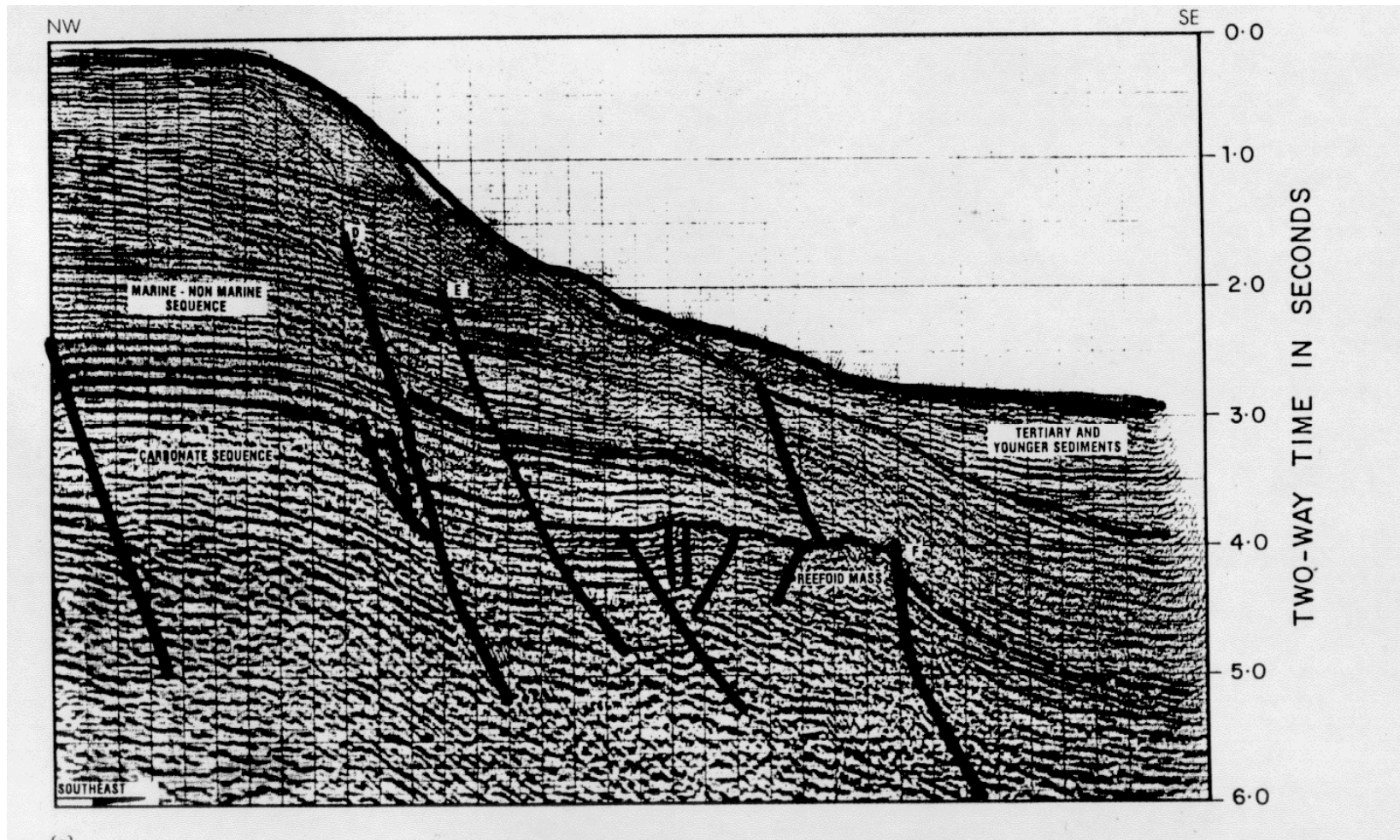
Complex structure: simplest case of diffractors

Complex case:

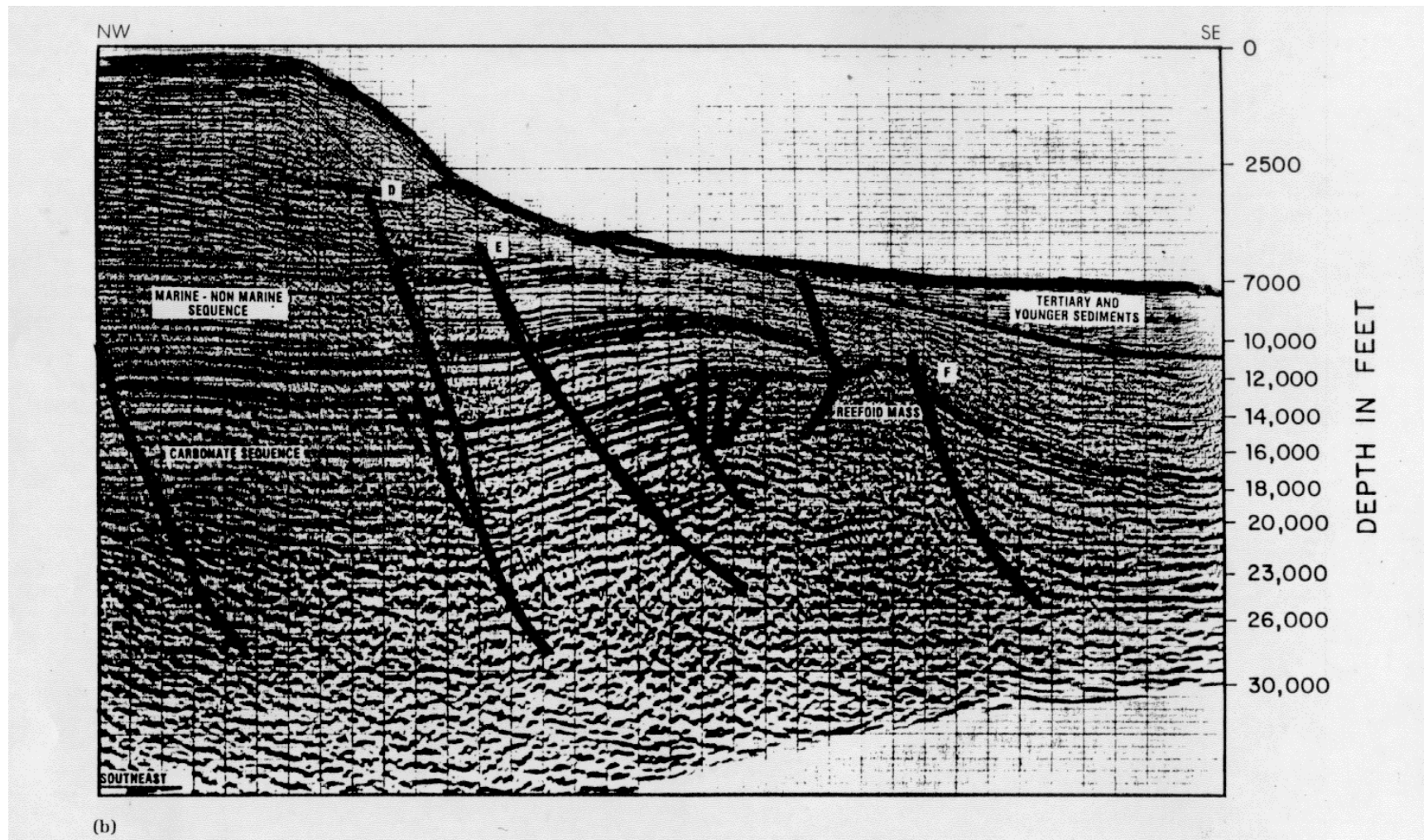
DMO = form of pre-stack time migration necessary

(only root-mean-square-velocity model necessary)

Large lateral velocity variations: time section



Large lateral velocity variations: depth section

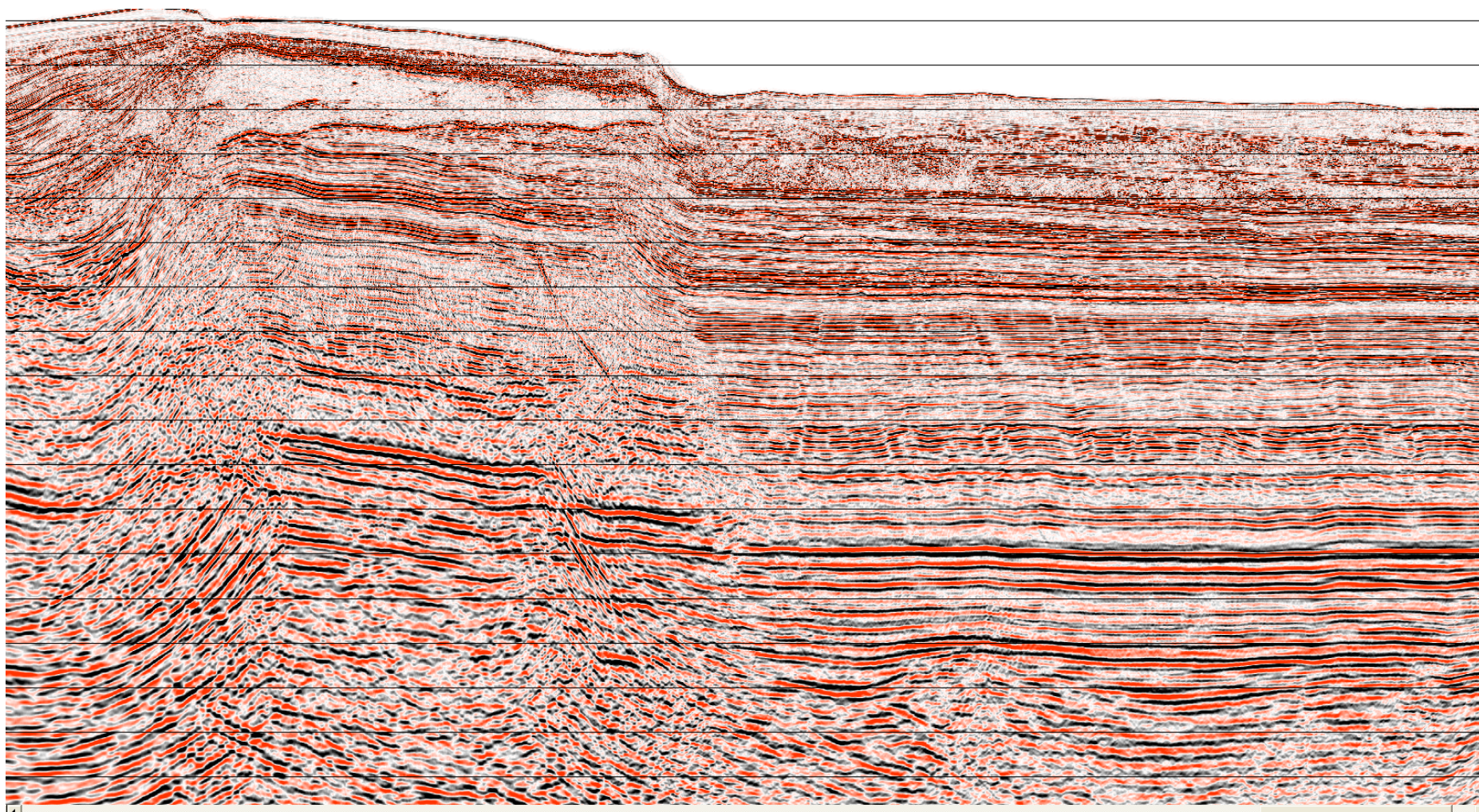


Large lateral velocity variations

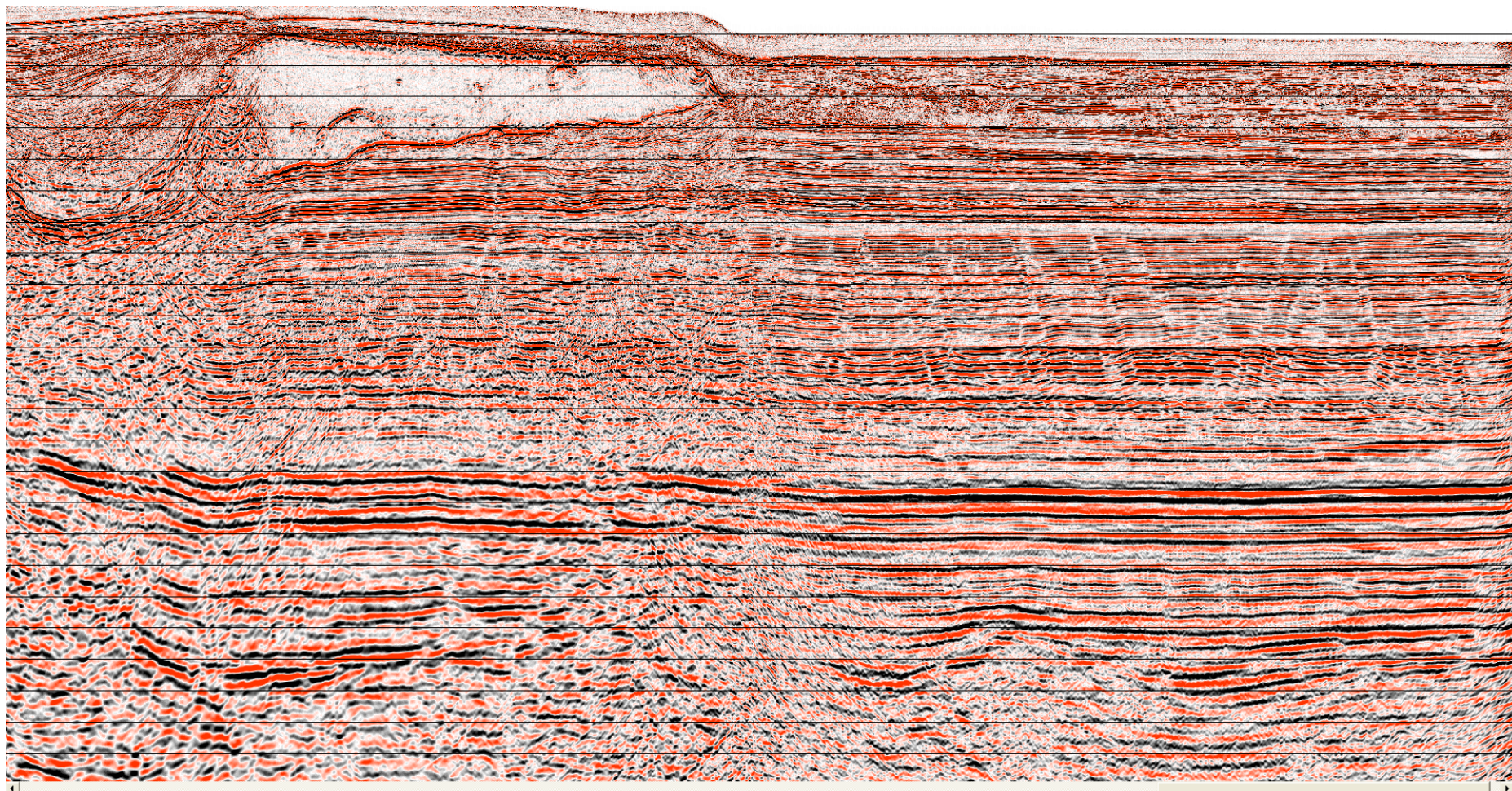
Notice **lateral shift** of faults as well

(so here time-stretching axis will not do !!!)

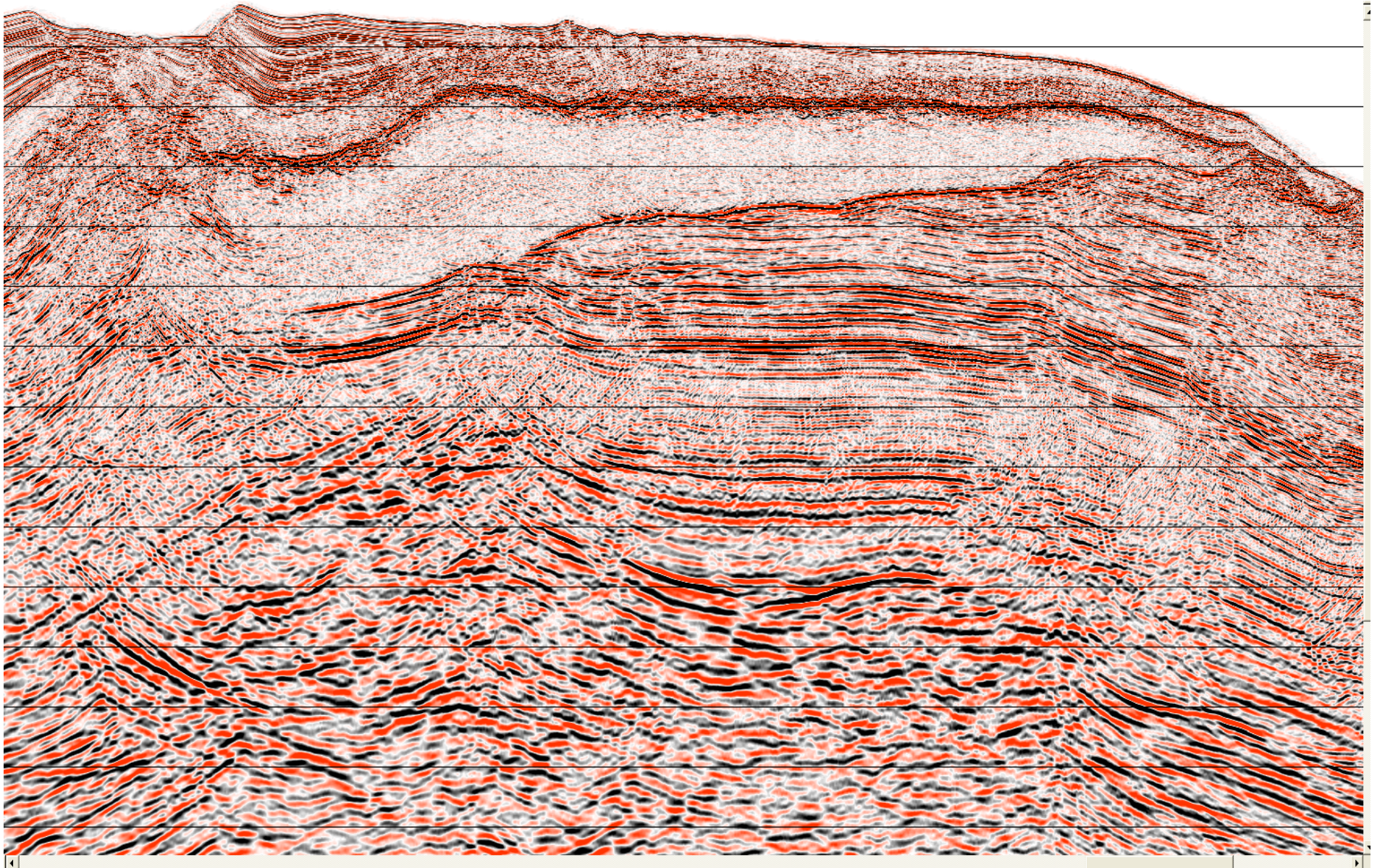
Kirchhoff Pre-stack Time Migration



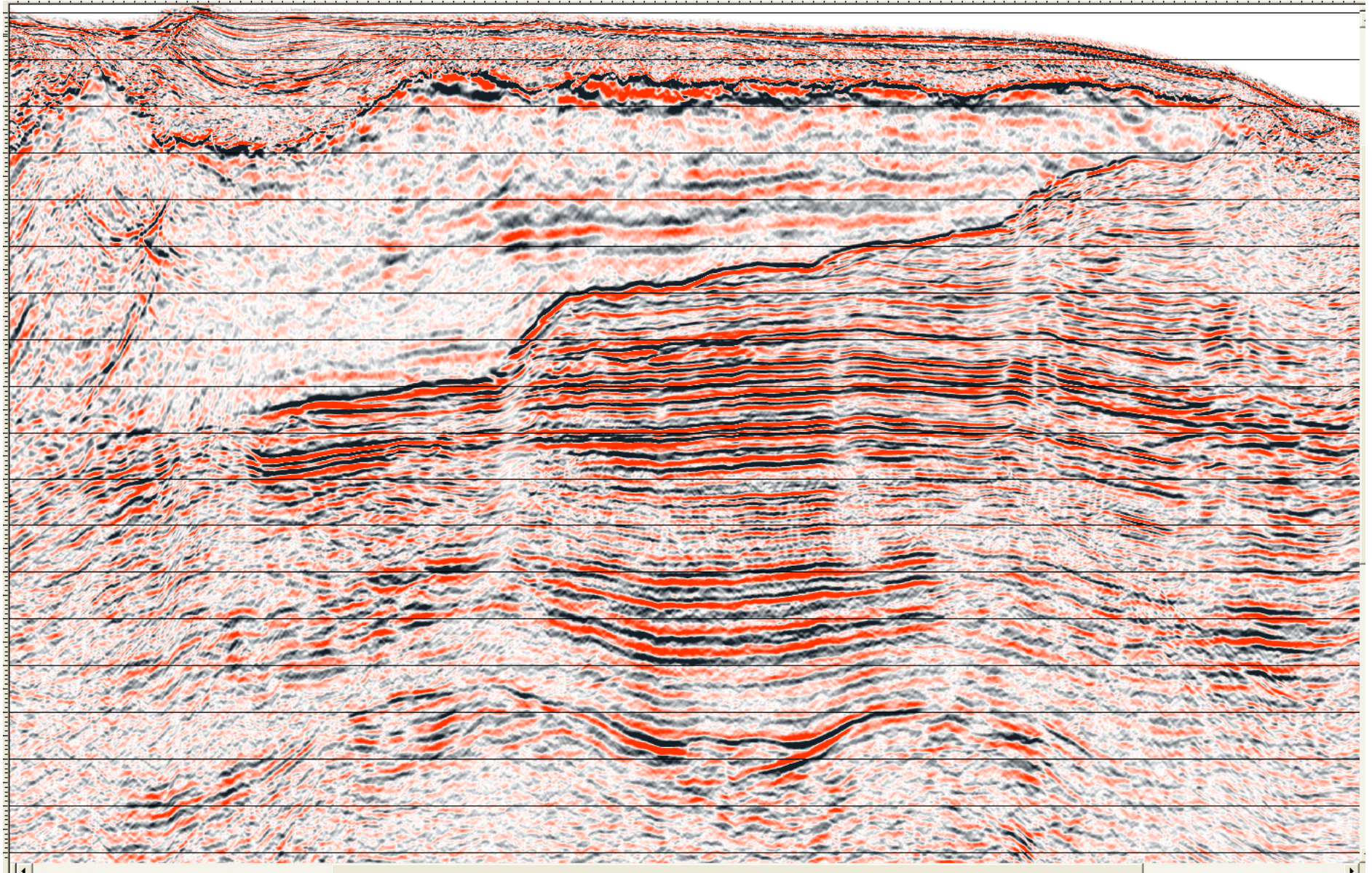
Kirchhoff Pre-stack Depth Migration



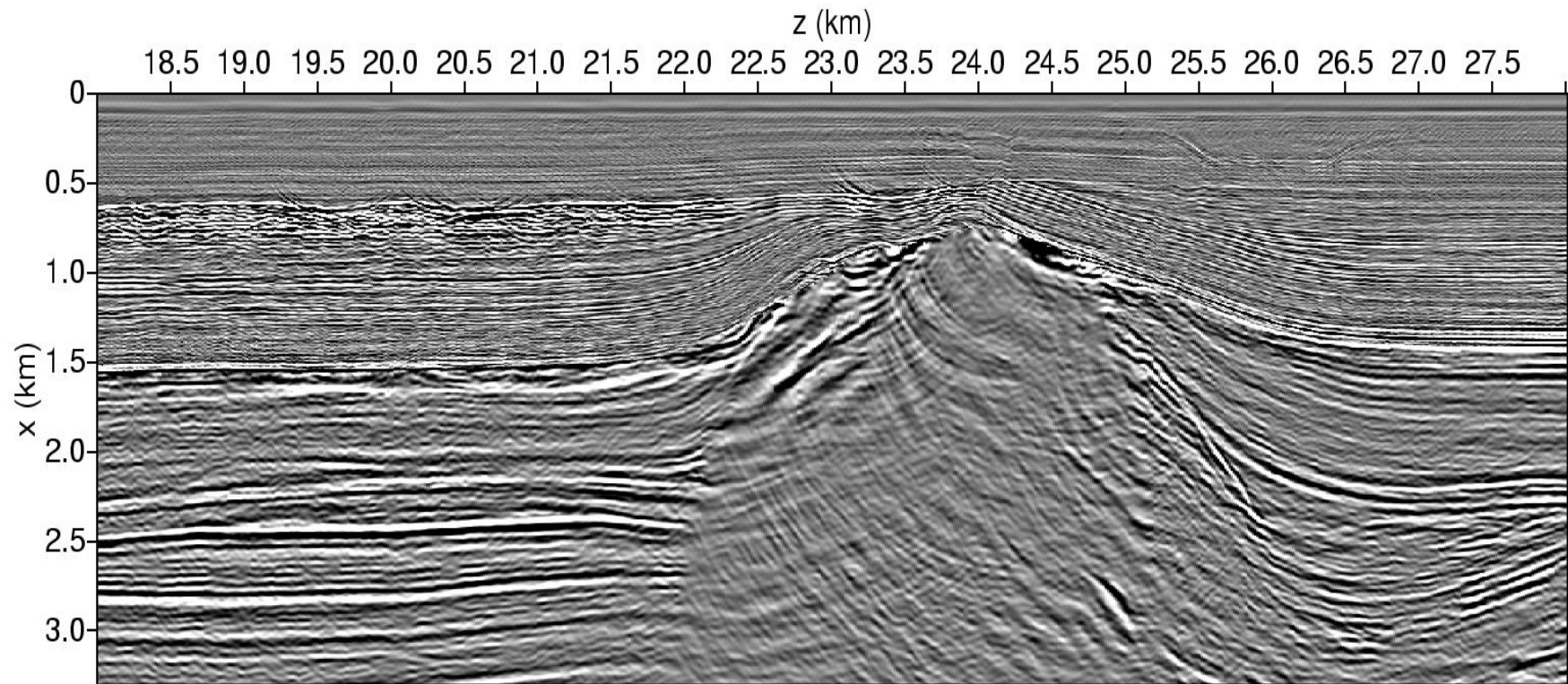
Kirchhoff Pre-stack Time Migration



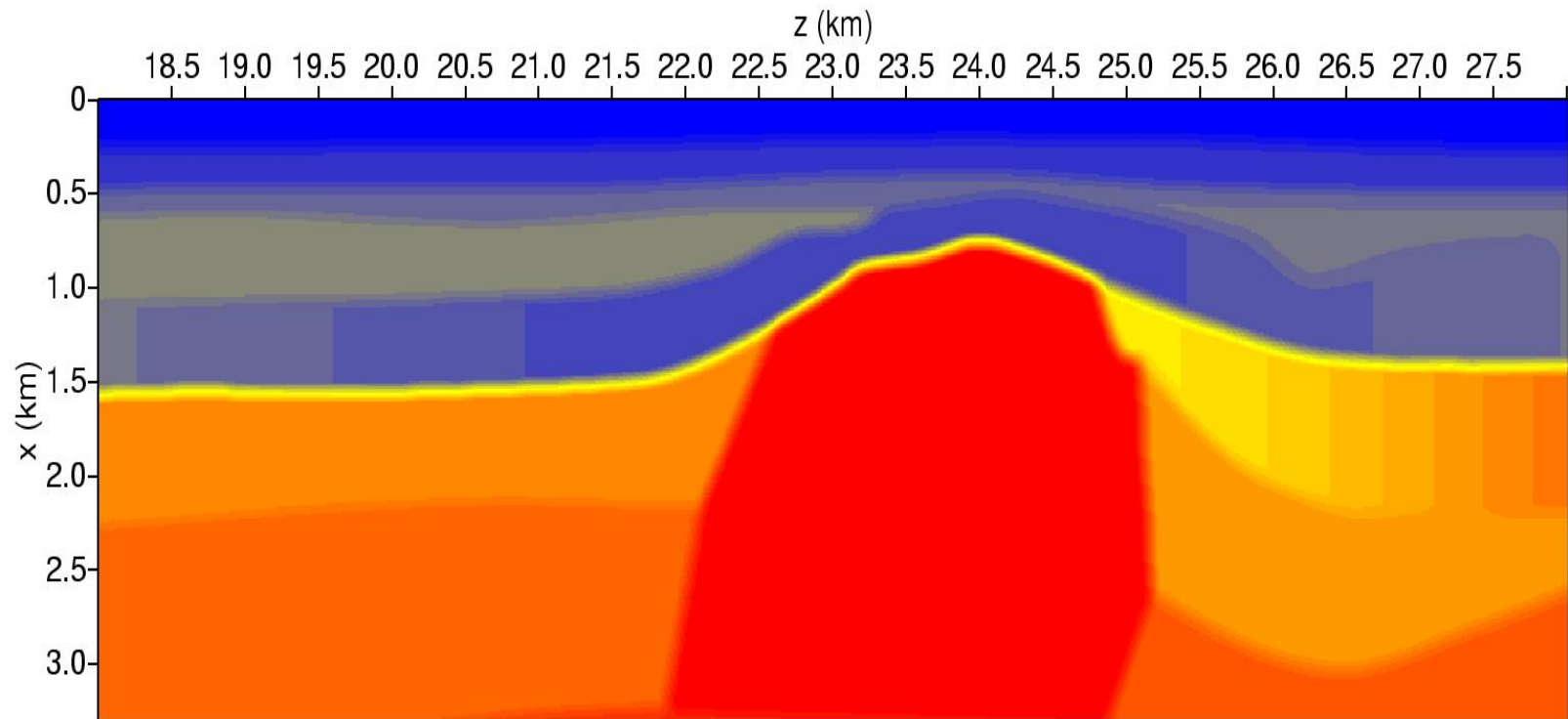
Wave Equation PSDM



Large lateral velocity variations and complex structure

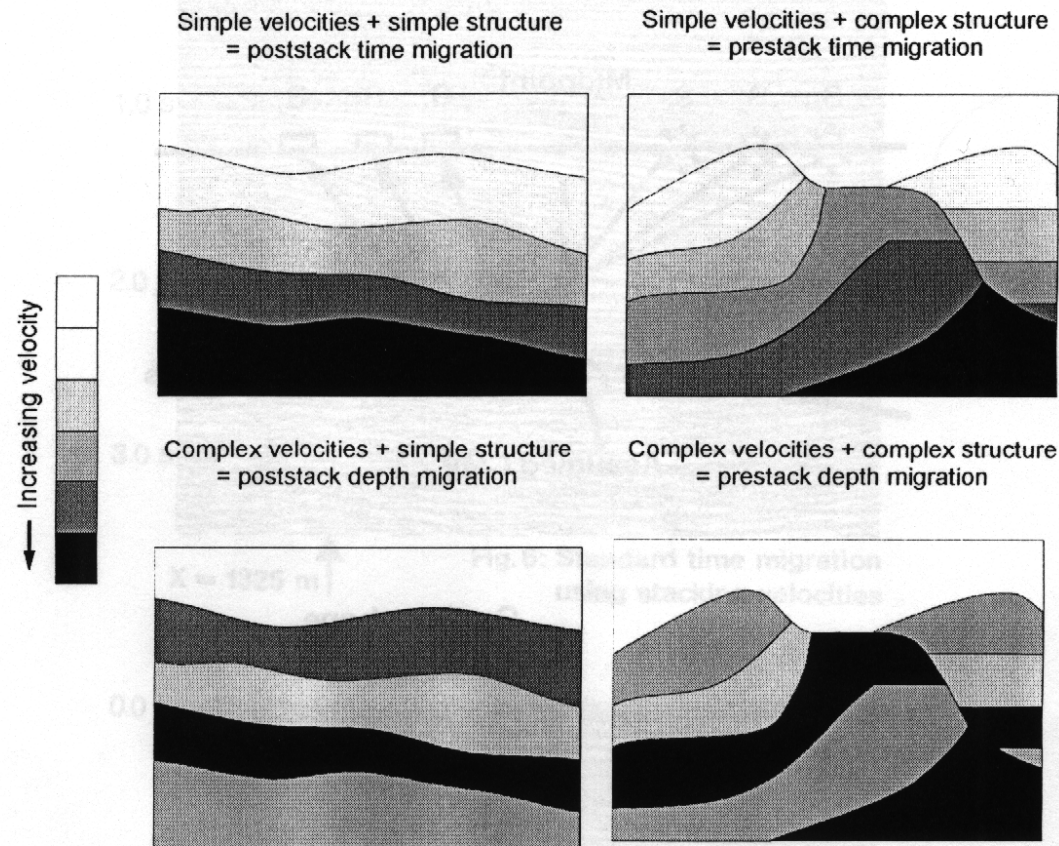


Large lateral velocity variations and complex structure



(Interval-) velocity model

Velocities/Structures and migration



Sketches showing typical subsurface situations and the recommended imaging solutions (After Farmer et al. 1993).

Strategy for seismic migration

- Simple structure, small lateral velocity variations:
post-stack time migration
- Complex structure, small lateral velocity variations:
pre-stack time migration (generalisation DMO)
- Simple structure, large lateral velocity variations:
post-stack **depth** migration (pull-up effect)
- Complex structure, large lateral velocity variations :
pre-stack depth migration (e.g. side of salt domes)

Migration: wave theory

Migration is:

$$(X, Y, \textcolor{red}{T}) \rightarrow (X, Y, \textcolor{red}{Z})$$

or, better,

$$(X, Y, \textcolor{red}{Z=0}, \textcolor{red}{T}) \rightarrow (X, Y, \textcolor{red}{Z}, \textcolor{red}{T=0})$$

Migration: wave theory

Transform measurements at $z=0$ for all t
into measurements for $t=0$ for all z !

Two-step procedure:

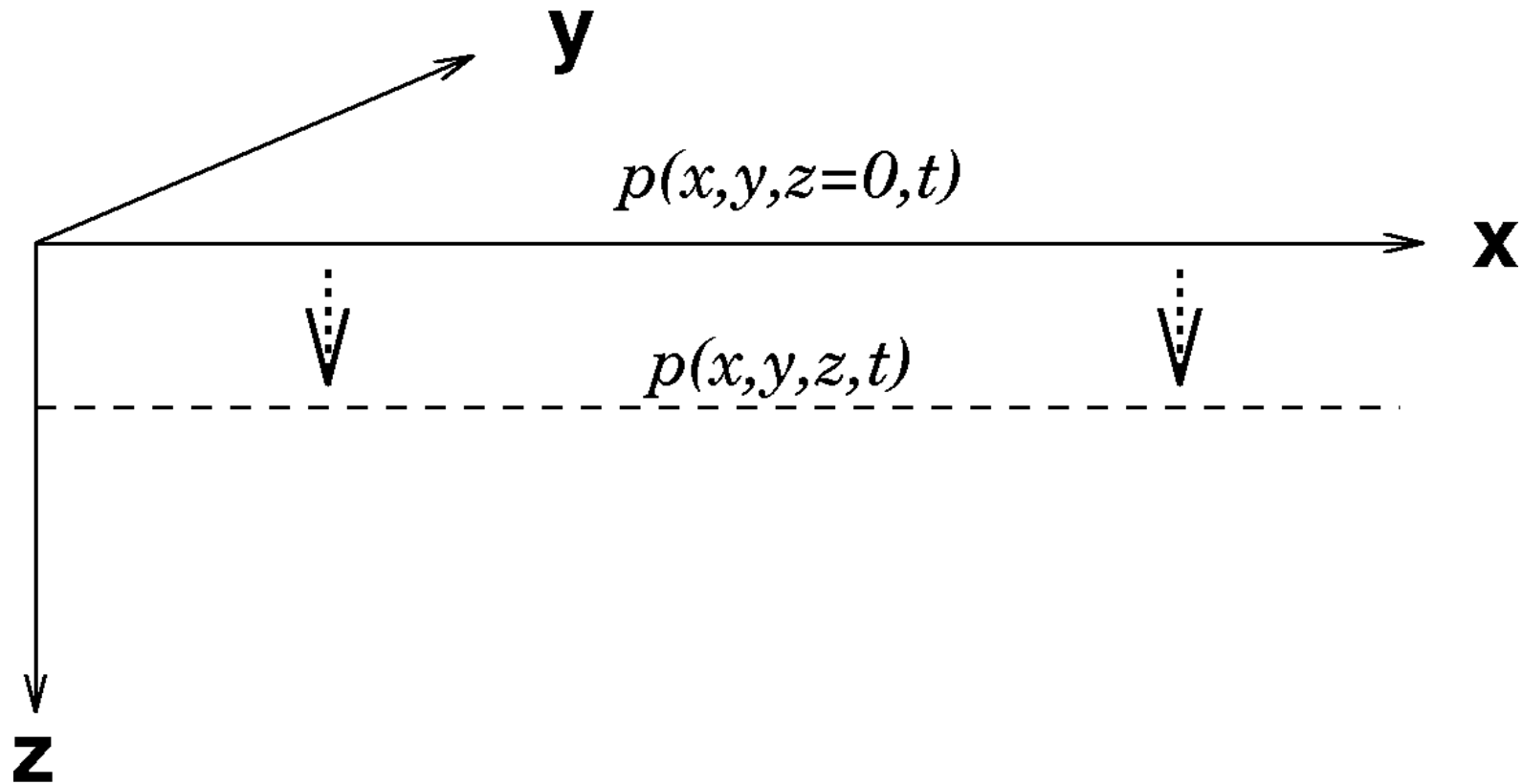
1: Extrapolation:

Bring $P(x, y, z=0, t)$ to $P(x, y, z=z_m, t)$

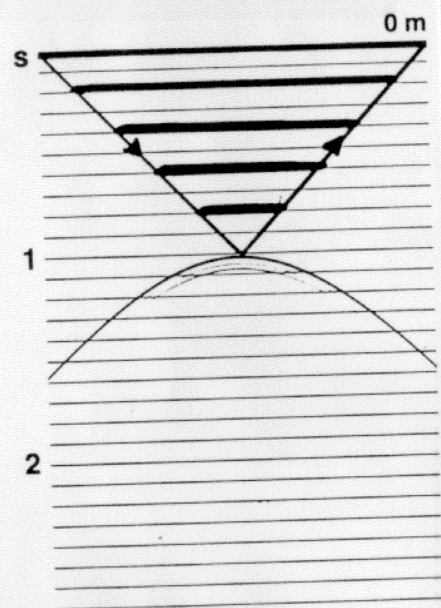
2: Imaging = Select only $t=0$:

$$P_{migr}(x, y, z=z_m, t) = P(x, y, z=z_m, t=0)$$

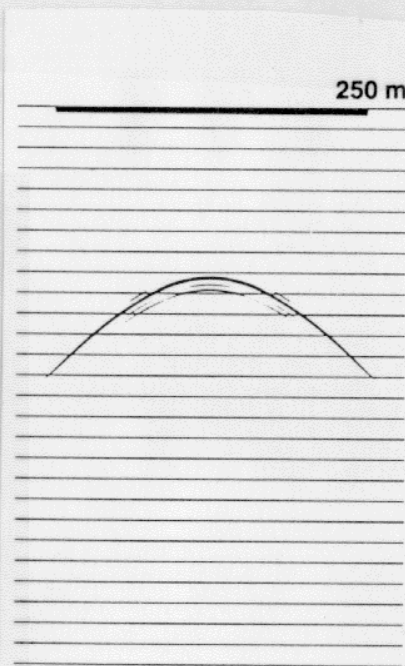
Wavefield extrapolation



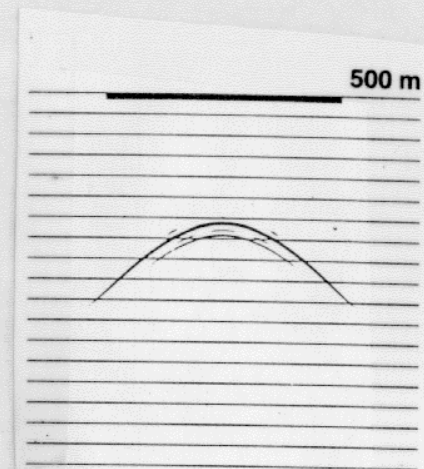
Wavefield extrapolation



(a)

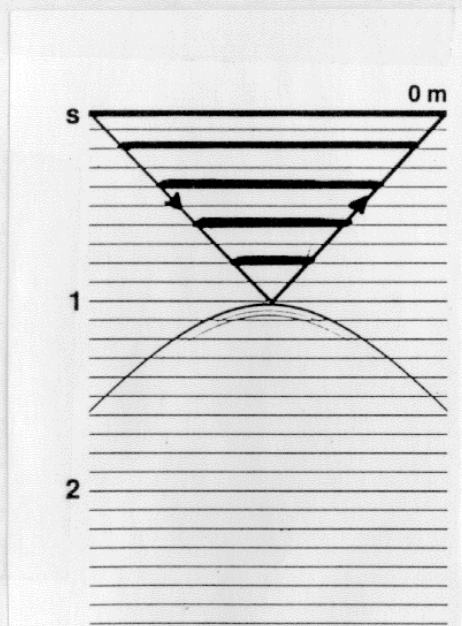


(b)

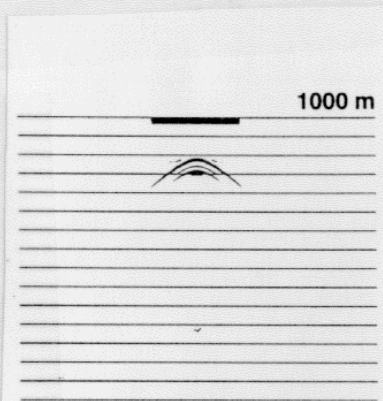


(c)

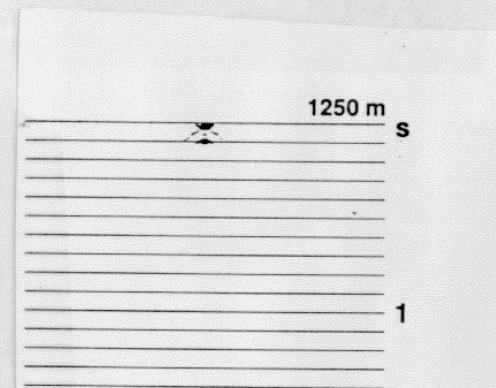
Wavefield extrapolation (2)



(a)



(e)



(f)

Zero-offset migration scheme

Zero-offset migration can be applied by:

- Consider zero-offset data as exploding reflector measurements in medium with half the true velocity
- Extrapolating surface data into subsurface
- At $t=0$, the imaged reflector should appear at correct depth
(Imaging condition)

Often for geological interpretation, the output is calculated as a function of time.

Ideal migration when velocity model is known

Pre-stack Depth Migration:

- Inverse wavefield extrapolation receivers into medium
- Forward wavefield extrapolation source into medium
- Correlate two resulting wavefield
- Extract $t=0$ component