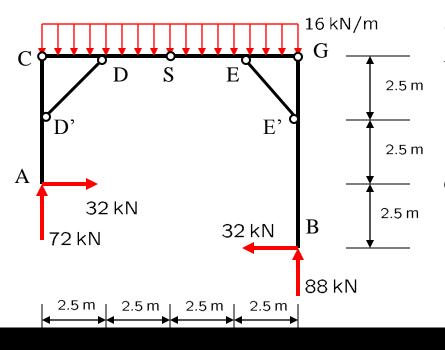
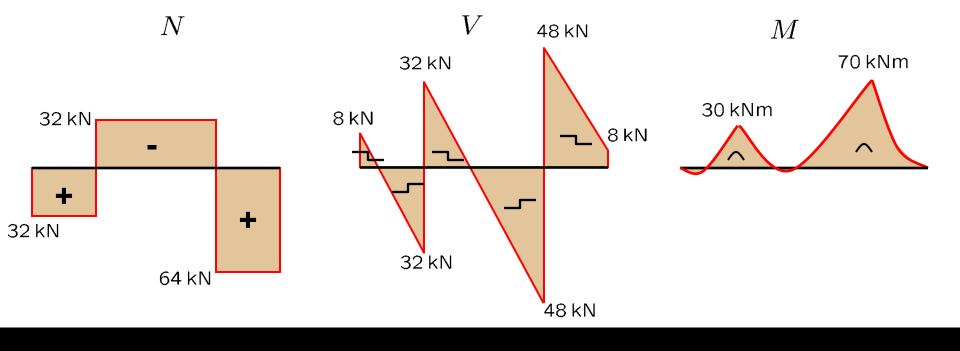
Today:

Virtual Work

Book: Chapter 11.1-11.3 + hand-out



- a) Calculate the reactions in A and B
- b) Calculate the normal forces in DD' and EE' with the correct signs for tension and compression.
- c) Draw the N, V and M lines for CDSEG



A few tips...

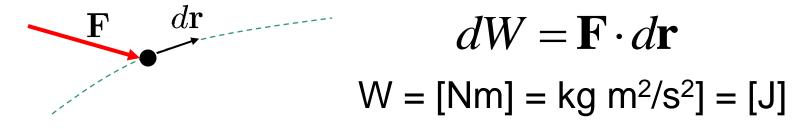
 When drawing N,V and M lines, clearly denote the jumps and kinks in the lines. Give the values of 'special' points on the curves (maxima, transition points).

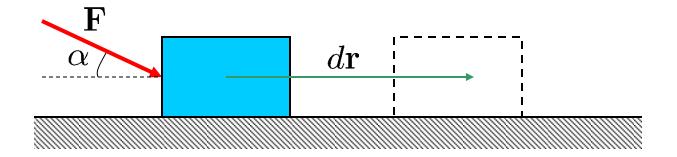
A few tips...

- Use enough paper, work neatly. It will reduce the number of unnecessary mistakes.
- Before filling in the answering sheet, draw the N,V and M diagrams on a piece of scrap paper.

Work of a force (infinitesimal movement)

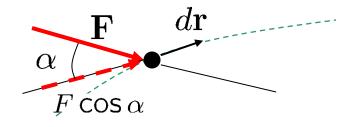
The work done by a force F acting on a particle with a differential displacement dr is defined as:



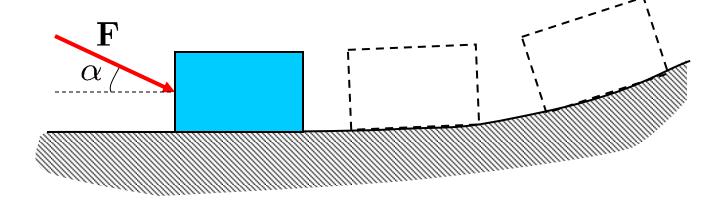


Work of a force (infinitesimal movement)

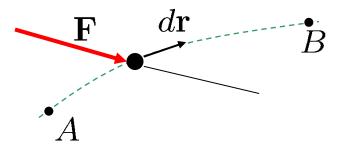
The work done by a force F acting on a particle with a differential displacement dr is defined as:



$$dW = |\mathbf{F}| |d\mathbf{r}| \cos \alpha$$



Work of a force (finite movement)



$$W = \int \mathbf{F} d\mathbf{r} = \int \left(F_x dr_x + F_y dr_y + F_z dr_z \right)$$

Static equilibrium of a particle

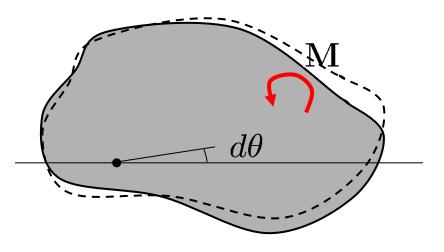
$$\sum \mathbf{F}_x = 0$$
$$\sum \mathbf{F}_y = 0$$
$$\sum \mathbf{F}_z = 0$$

The principle of virtual work (particle)

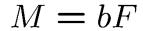
A particle is in equilibrium when for any variational displacement, the virtual work is equal to zero.

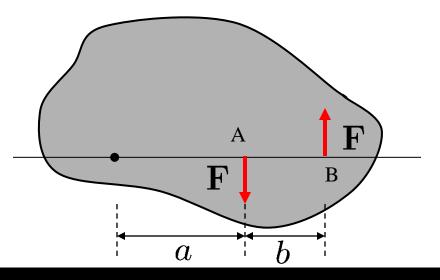
$$\delta W = \delta u_x \sum F_x + \delta u_y \sum F_y + \delta u_z \sum F_z = 0$$

Work of a concentrated moment



Work of a concentrated moment



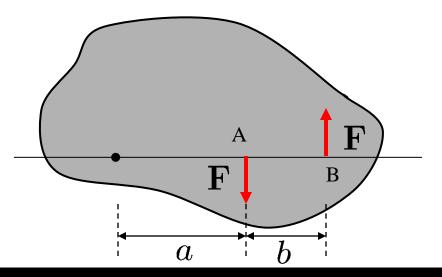


Small-Angle approximations

$$heta << 1 ext{ radians}$$
 $\sin heta pprox heta$ $an heta pprox heta$ $\cos heta pprox 1$

Work of a concentrated moment

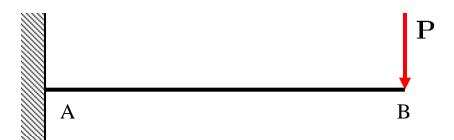




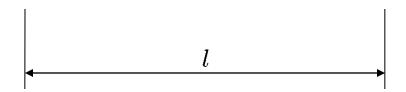
The principle of virtual work (body in two dimensions)

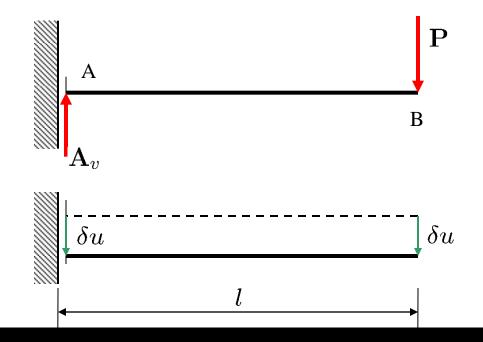
A particle is in equilibrium when for any variational displacement and/or rotation, the virtual work is equal to zero.

$$\delta W = \sum \delta u_{x_i} F_{x_i} + \sum \delta u_{y_i} F_{y_i} + \sum \delta \theta_i M_i = 0$$



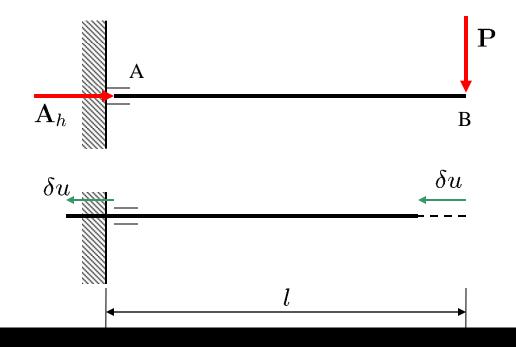
Calculate the reaction forces and moment in *A* using the principle of virtual work.





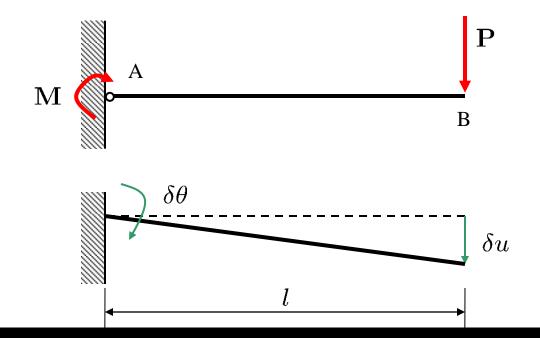
Calculate the reaction forces and moment in *A*.

Vertical reaction



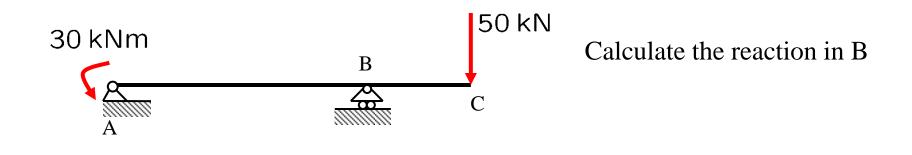
Calculate the reaction forces and moment in *A*.

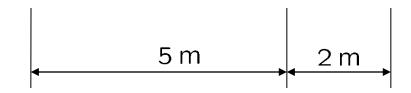
Horizontal reaction

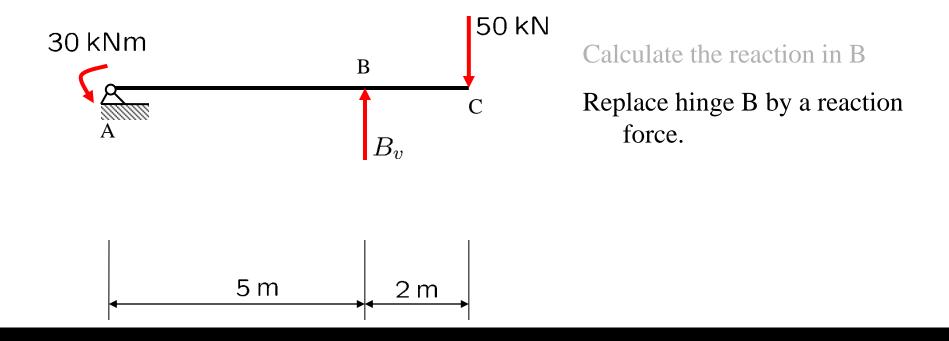


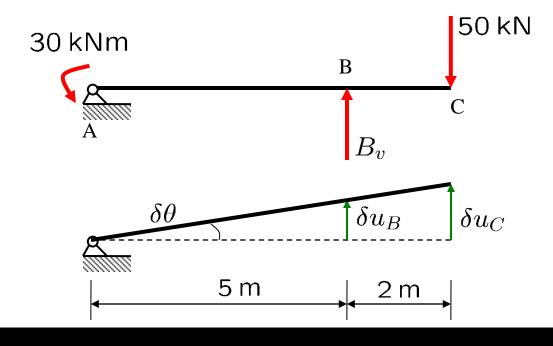
Calculate the reaction forces and moment in *A*.

Moment





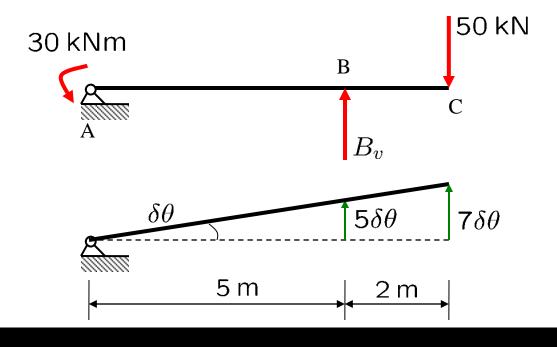




Calculate the reaction in B

Replace hinge B by a reaction force.

Due to the absence of hinge B, the beam can rotate

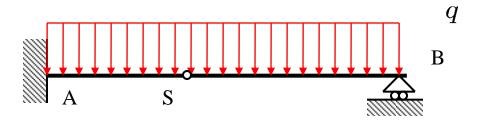


Calculate the reaction in B

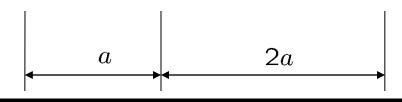
Replace hinge B by a reaction force.

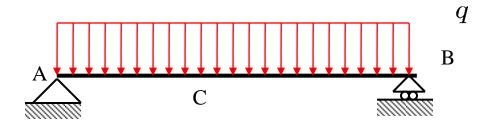
Due to the absence of hinge B, the beam can rotate

Express all virtual rotations in terms of $\delta\theta$

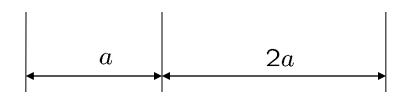


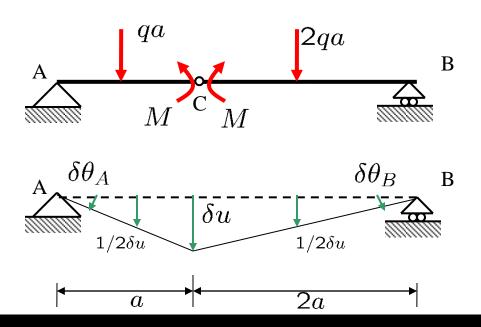
Calculate the reaction moment in A





Calculate the internal moment in C



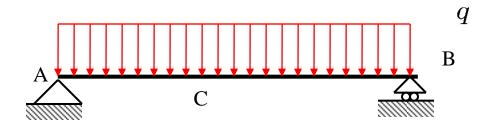


Calculate the internal moment in C

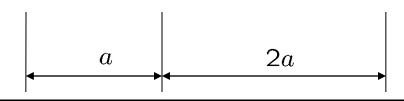
Internal moment

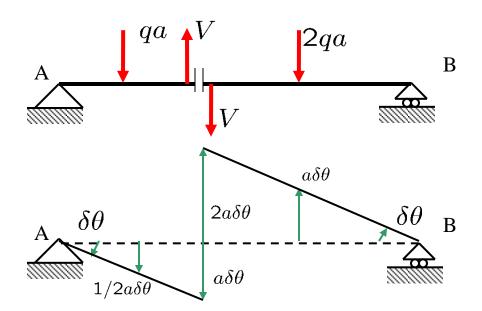
- **Hinge**: only different rotation angles on either side of the cut.
- Reaction moments M





Calculate the shear force in C

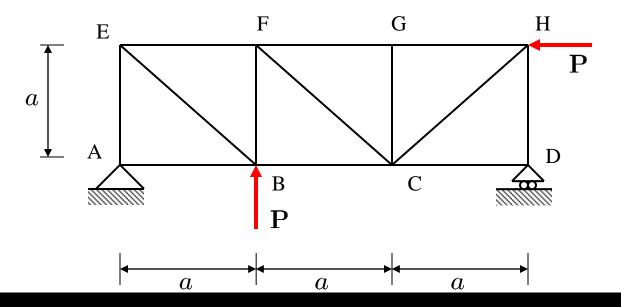




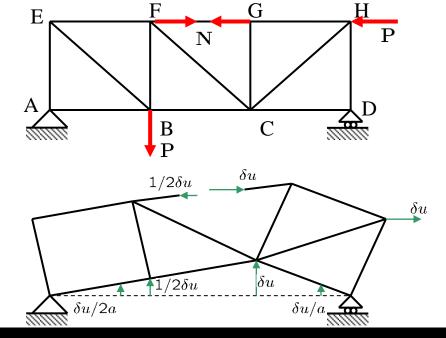
Calculate the shear force in C

Shear force

- **Shear hinge**: only different displacements perpendicular to the member on either side of the cut.
- Reaction forces V



Calculate the normal force in member FG of this truss structure.



Calculate the normal force in member FG of this truss structure.

Normal force

- Telescope hinge: only different displacements parallel to the member on either side of the cut
- Reaction forces N

