

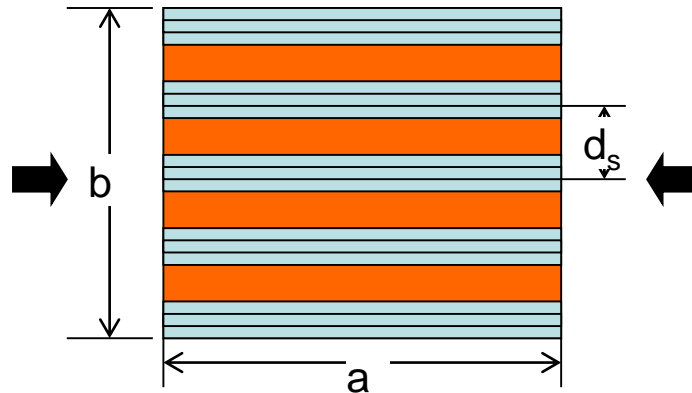
# Panel buckling=Bay buckling

- bay (skin between stiffeners) buckles when

$$N_{xskin} = \frac{\pi^2}{a^2} \left[ (D_{11})_{skin} k^2 + 2[(D_{12})_{skin} + 2(D_{66})_{skin}] (\overline{AR})^2 + (D_{22})_{skin} \frac{(\overline{AR})^4}{k^2} \right] \quad (5.4.2.3)$$

$$(\overline{AR}) = \frac{a}{d_s}$$

equation from before for buckling of ss plate under compression



# Panel Buckling = Bay Buckling

- panel as a whole buckles when

$$N_x = \frac{\pi^2}{a^2} \left\{ \left[ (D_{11})_{skin} + \frac{(EI)_{stif}}{d_s} \right] m^2 + 2 \left[ (D_{12})_{skin} + 2(D_{66})_{skin} \right] (AR)^2 + (D_{22})_{skin} \frac{(AR)^4}{m^2} \right\} \quad (5.4.2.4)$$

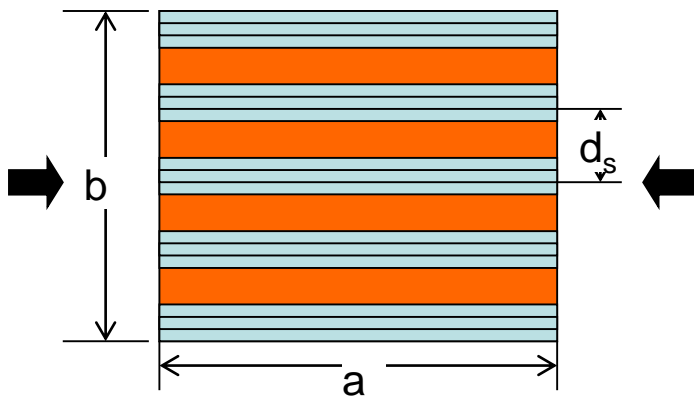
$$(AR) = \frac{a}{b}$$

stiffener contribution

$$N_x = \frac{F_{TOT}}{b}$$

(5.4.2.5)

it is assumed the stiffener has an open cross-section and, therefore,  $GJ \approx 0$



# Panel Buckling = Bay Buckling

- combining (5.4.2.2) with (5.4.2.3) and dropping the subscript “skin” from  $D_{ij}$ :

$$F_{TOT} = b \frac{\left( A_{11} + \frac{EA}{d_s} \right)}{A_{11}} \frac{\pi^2}{a^2} \left[ (D_{11})k^2 + 2[(D_{12}) + 2(D_{66})](\overline{AR})^2 + (D_{22})\frac{(\overline{AR})^4}{k^2} \right] \quad (5.4.2.6)$$

- combining (5.4.2.4) with (5.4.2.5) and dropping the subscript “skin” from  $D_{ij}$  :

$$F_{TOT} = b \frac{\pi^2}{a^2} \left\{ \left[ (D_{11}) + \frac{(EI)_{stif}}{d_s} \right] m^2 + 2[(D_{12}) + 2(D_{66})](AR)^2 + (D_{22})\frac{(AR)^4}{m^2} \right\} \quad (5.4.2.7)$$

# Panel Buckling = Bay Buckling

- combining (5.4.2.6) with (5.4.2.7) and rearranging a bit

$$\frac{\left( A_{11} + \frac{EA}{d_s} \right)}{A_{11}} \left[ D_{11}k^2 + 2[D_{12} + 2D_{66}](\bar{AR})^2 + D_{22} \frac{(\bar{AR})^4}{k^2} \right] = \left[ D_{11} + \frac{(EI)_{stif}}{d_s} \right] m^2 + 2[D_{12} + 2D_{66}](AR)^2 + D_{22} \frac{(AR)^4}{m^2}$$

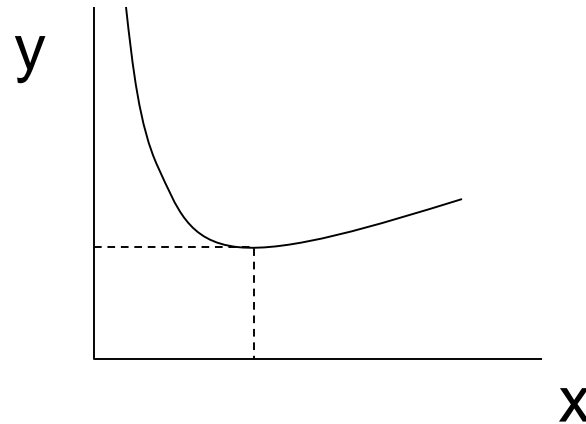
(5.4.2.8)

- to proceed, we need to decide on the values of k and m
- recall that k and m are integers that minimize the respective buckling loads in eqs (5.4.2.3) and (5.4.2.4)

# Panel Buckling = Bay Buckling

- consider the continuous function

$$y = D_{11}x^2 + D_{22} \frac{(\overline{AR})^4}{x^2}$$



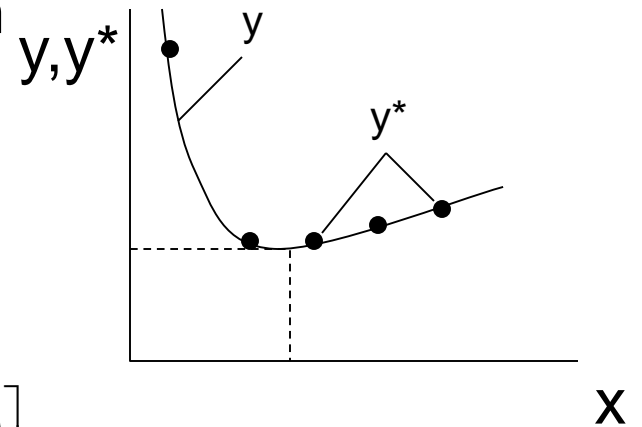
- this function has one and only one minimum determined by

$$\frac{dy}{dx} = 0 \Rightarrow x_{\min} = \left( \frac{D_{22}}{D_{11}} \right)^{1/4} (\overline{AR})$$

# Panel Buckling = Bay Buckling

- therefore, the discontinuous function

$$y^* = D_{11}k^2 + D_{22} \frac{(\overline{AR})^4}{k^2}$$



- is minimized when

$$k = \text{int} \left[ \left( \frac{D_{22}}{D_{11}} \right)^{1/4} (\overline{AR}) \right] \quad \text{or} \quad k = \text{int} \left[ \left( \frac{D_{22}}{D_{11}} \right)^{1/4} (\overline{AR}) \right] + 1$$

whichever makes  $y^*$  lowest, with one important note:

$$\text{if } \text{int} \left[ \left( \frac{D_{22}}{D_{11}} \right)^{1/4} (\overline{AR}) \right] = 0 \quad \text{then } k \text{ (or } m) = 1$$

# Panel Buckling = Bay Buckling

- for the case of  $m$ ,

$$x_{\min} = \left( \frac{D_{22}}{D_{11} + \frac{EI}{d_s}} \right)^{1/4} \left( \frac{a}{b} \right)$$

- for typical applications,  $x_{\min} < 1$   
because  $D_{11} > D_{22}$  and  $b > a$

- so setting  $m=1$  covers most cases of interest

# Panel Buckling = Bay Buckling

- now approximate k with its corresponding  $x_{\min}$

$$k \approx \left( \frac{D_{22}}{D_{11}} \right)^{1/4} (\overline{AR})$$

- and substitute for m and k in eq. (5.4.2.8)

$$D_{11} + \frac{(EI)_{stif}}{d_s} + 2[D_{12} + 2D_{66}](AR)^2 + D_{22}(AR)^4 = \frac{\left( A_{11} + \frac{EA}{d_s} \right)}{A_{11}} \left[ D_{11} \sqrt{\frac{D_{22}}{D_{11}}} \overline{AR}^2 + 2[D_{12} + 2D_{66}](\overline{AR})^2 + D_{22} \frac{(\overline{AR})^4}{\sqrt{\frac{D_{22}}{D_{11}}} \overline{AR}^2} \right]$$

$= \lambda, \lambda > 1$

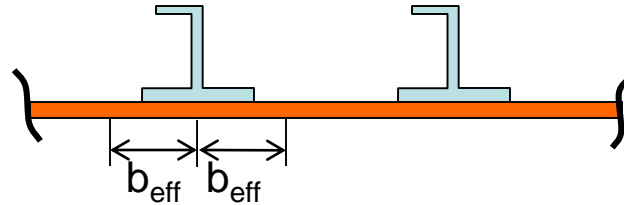
- solving for  $(EI)_{stif}$  and dropping the subscript “stiff”

$$EI = D_{11} d_s \left[ \sqrt{\frac{D_{22}}{D_{11}}} \left( 2\lambda \overline{AR}^2 - \sqrt{\frac{D_{22}}{D_{11}}} (AR)^4 \right) + \frac{2(D_{12} + 2D_{66})}{D_{11}} \left( \lambda \overline{AR}^2 - (AR)^2 \right) - 1 \right] \quad (5.4.2.9)$$

1<sup>st</sup> equation



# Stiffener buckling = PB x skin buckling



- in post-buckling regime, skin is replaced by the effective skin portion; strain compatibility then gives

$$F_{skin} = \frac{A_{11} \frac{b}{d_s} 2b_{eff}}{2A_{11} \frac{b}{d_s} b_{eff} + EA \frac{b}{d_s}} F_{TOT} \Rightarrow F_{skin} = \frac{A_{11} 2b_{eff}}{2A_{11} b_{eff} + EA} F_{TOT} \quad (5.4.2.10)$$

$$F_{stiffeners} = \frac{EA}{2A_{11} b_{eff} + EA} F_{TOT}$$

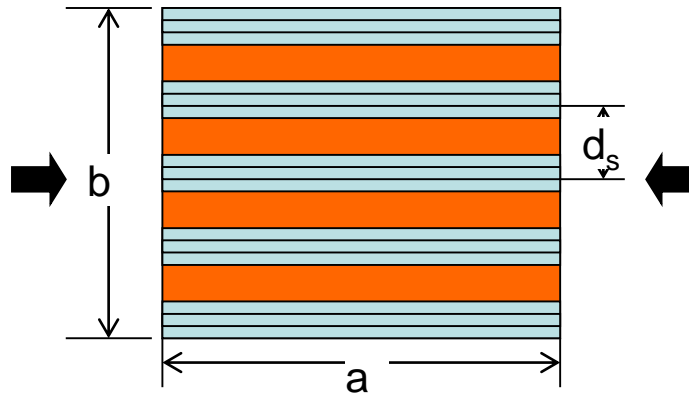
- and for a single stiffener, dividing by  $n_s = b/d_s$

$$F_{stif} = \frac{d_s}{b} \frac{EA}{2A_{11} b_{eff} + EA} F_{TOT} \quad (5.4.2.11)$$

# Stiffener buckling = PB x skin buckling

- single stiffener buckles when

$$F_{stif} = \frac{\pi^2 EI}{a^2}$$



$$(5.4.2.12)$$

- combining (5.4.2.11) and (5.4.2.12):

$$\frac{d_s}{b} \frac{EA}{2A_{11}b_{eff} + EA} F_{TOT} = \frac{\pi^2 EI}{a^2} \Rightarrow F_{TOT} = \frac{\pi^2 EI}{a^2} \frac{b}{d_s} \frac{2A_{11}b_{eff} + EA}{EA} \quad (5.4.2.13)$$

# Stiffener buckling = PB x skin buckling

- final failure occurs when the post-buckling factor (PB) is reached; the force in the skin at that load is given by

$$F_{skin} = F_{skin\ buckling} (PB) \quad (5.4.2.14)$$

- with the skin buckling load given by

$$F_{skin\ buckling} = b \frac{\pi^2}{a^2} \left[ (D_{11})k^2 + 2[(D_{12}) + 2(D_{66})](\bar{AR})^2 + (D_{22})\frac{(\bar{AR})^4}{k^2} \right] \quad (5.4.2.15)$$

- combining (5.4.2.10), (5.4.2.14), and (5.4.2.15)

$$F_{TOT} = \frac{2A_{11}b_{eff} + EA}{2A_{11}b_{eff}} b \frac{\pi^2}{a^2} \left[ (D_{11})k^2 + 2[(D_{12}) + 2(D_{66})](\bar{AR})^2 + (D_{22})\frac{(\bar{AR})^4}{k^2} \right] (PB) \quad (5.4.2.16)$$

# Stiffener buckling = PB x skin buckling

- Equations (5.4.2.13) and (5.4.2.16) are combined to give

$$\frac{EI}{d_s EA} = \frac{(PB)}{2A_{11}b_{eff}} \left[ D_{11}k^2 + 2[D_{12} + 2D_{66}](\overline{AR})^2 + D_{22} \frac{(\overline{AR})^4}{k^2} \right]$$

- use the definition of  $\lambda$  to simplify things

$$\lambda = \frac{A_{11} + \frac{EA}{d_s}}{A_{11}} \Rightarrow \lambda A_{11} - A_{11} = \frac{EA}{d_s} \Rightarrow A_{11}(\lambda - 1) = \frac{EA}{d_s} \Rightarrow \frac{EA}{A_{11}} = (\lambda - 1)d_s$$

- substitute in the above equation to obtain

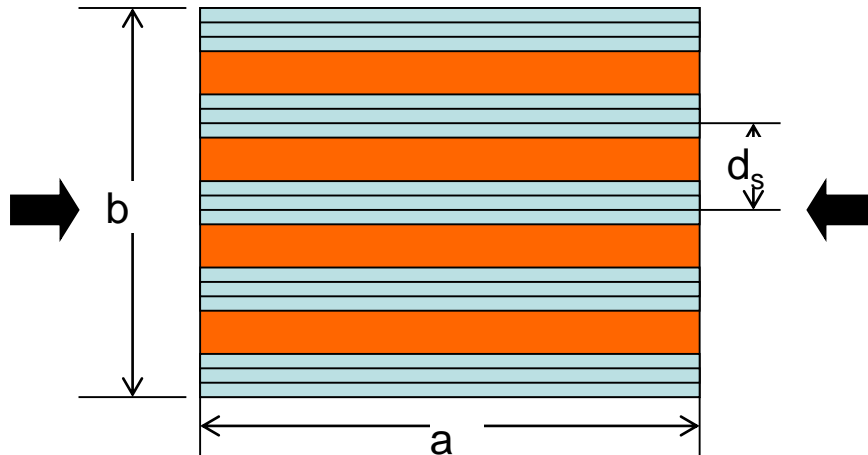
$$EI = (\lambda - 1)(PB)d_s \frac{d_s}{2b_{eff}} \left[ D_{11}k^2 + 2[D_{12} + 2D_{66}](\overline{AR})^2 + D_{22} \frac{(\overline{AR})^4}{k^2} \right] \quad (5.4.2.17)$$

# Stiffener buckling = PB x skin buckling

- from the expression for  $b_{eff}$  derived earlier,

$$\frac{d_s}{b_{eff}} = 2 \left[ 1 + 2 \left( 1 + \frac{A_{12}}{A_{11}} \right) \left( 1 - \frac{1}{(PB)} \right) \frac{A_{11}}{A_{11} + 3A_{22}} \right]$$

(note that instead of  $a$  in the original  $b_{eff}$  expression we have  $d_s$  because this is the width of the plate that buckles)



# Results: Min EI required for stiffeners

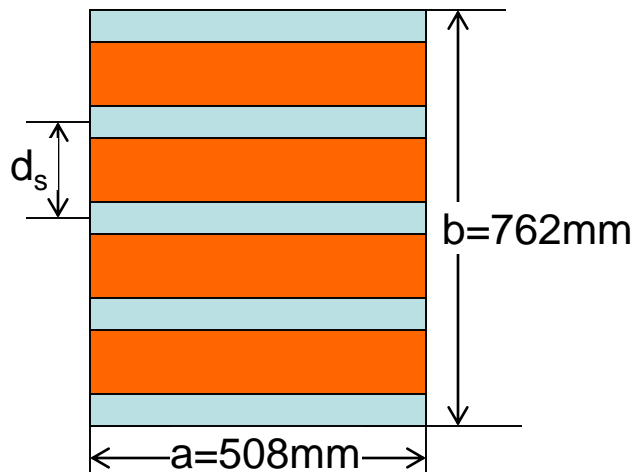
- eqns (5.4.2.9) and (5.4.2.17) are used to determine the minimum required bending stiffness for stiffeners
- EI is evaluated using both equations and the highest value is used
- Note that this does not guarantee that there is no crippling or inter-rivet buckling failure of the stiffener; separate checks must be made for these and they (usually) supersede the EI requirement (i.e. meeting the crippling and/or inter-rivet buckling requirements usually leads to higher EI than eqs (5.4.2.9) and (5.4.2.17))

# Example of min stiffener EI required

- $[(\pm 45)/(0/90)/(\pm 45)]$  skin

D11	659.7	Nmm
D12	466.9	Nmm
D22	659.7	Nmm
D66	494.0	Nmm

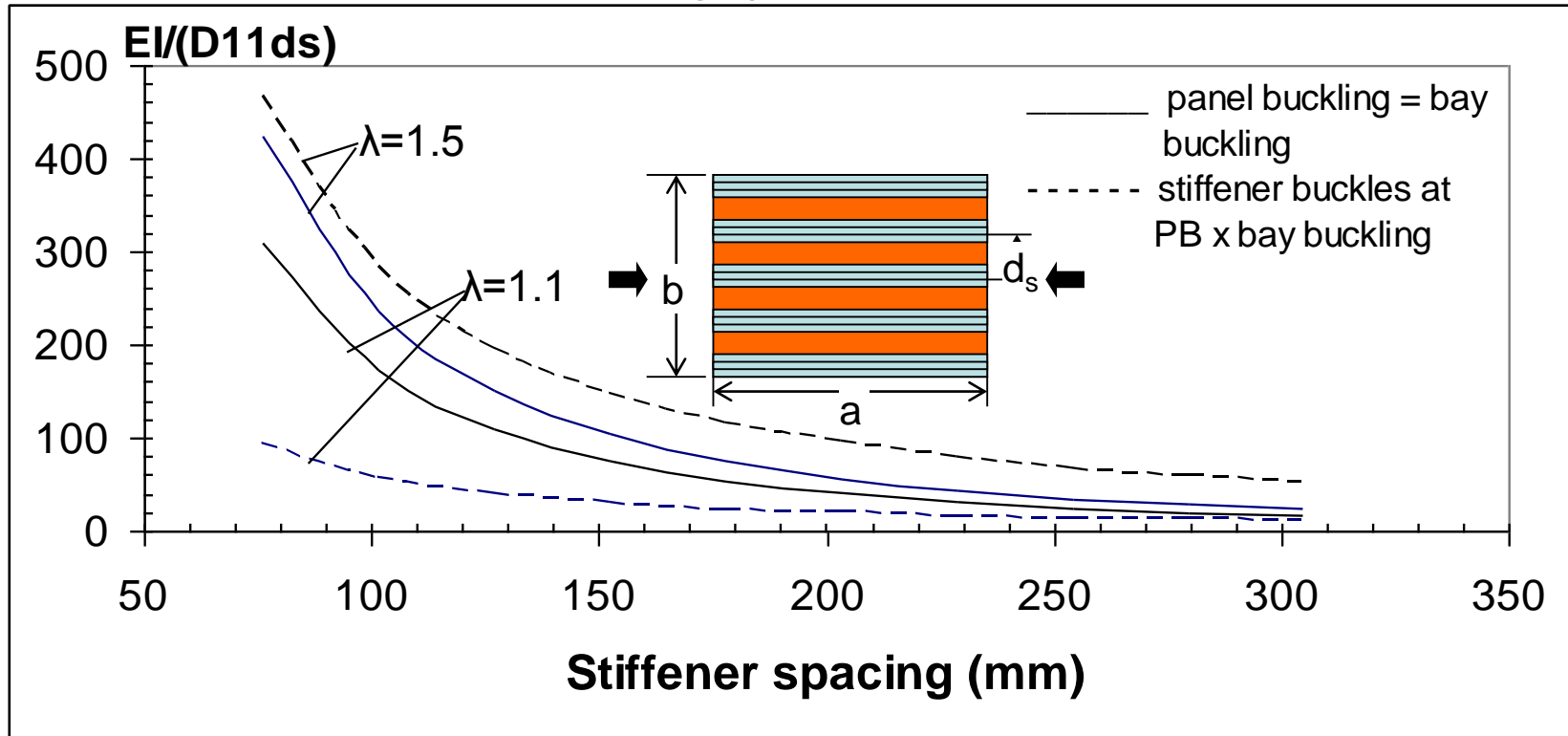
A11	28912.44	N/mm
A12	12491.43	N/mm
A22	28912.44	N/mm
A66	13468.58	N/mm



Stiffener geometry and spacing unknown. Determine minimum EI for the stiffeners

# Results: Min EI required for stiffeners

PB=5.0



- between  $\lambda=1.1$  and  $\lambda=1.5$ , stiffener buckling condition becomes more critical (design driver changes)

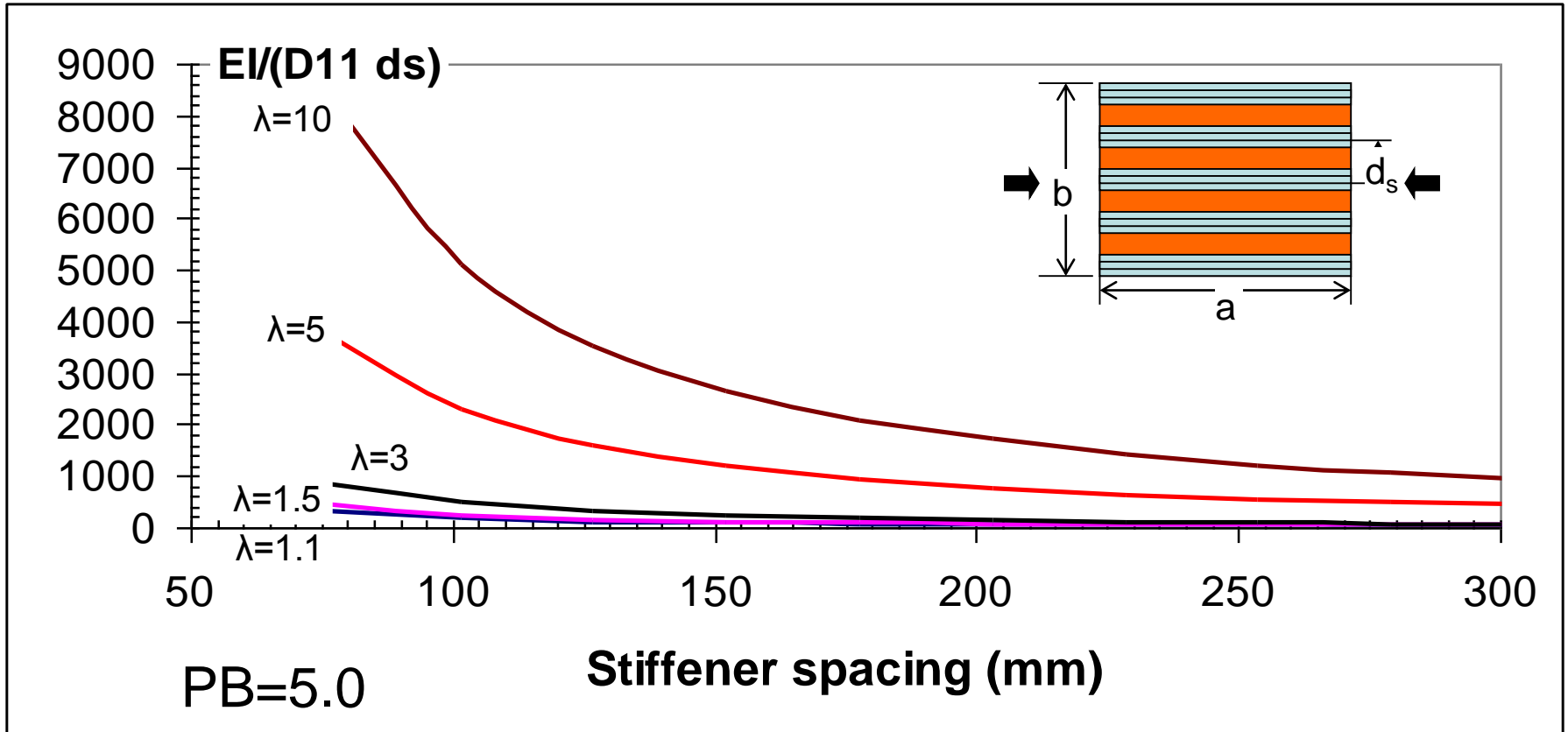
why?

- note that as  $d_s$  increases, the min req'd stiffness decreases



# Results: Min EI required for stiffeners

(using the more critical of the two conditions)



# Min stiffener EI: some notes

- comparing the min EI for  $PB=5$  and  $PB=1.5$  when  $\lambda=1.1$  we see that they are identical; the reason is that the “active” constraint is that bay buckling=panel buckling which is independent of post-buckling factor PB
- when the axial stiffness EA of the stiffeners is low ( $\lambda=1.1-1.2$ ) the min required bending stiffness for the stiffeners is independent of the ratio of the final failure load to the skin buckling load (PB)
- for higher axial stiffnesses ( $\lambda>1.2$ ) the higher the PB the higher the bending stiffness EI required for the stiffener