

# **Ships: Loads, stability and erosion**

## **Chapter 9**

**ct4310 Bed, bank and shoreline protection**

**H.J. Verhagen**

**June 3, 2012**

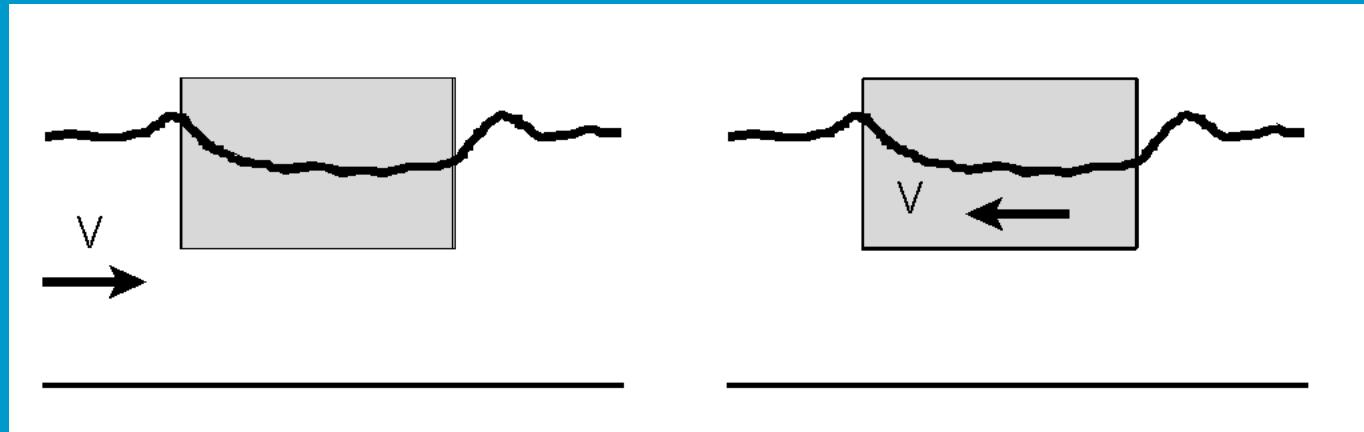
**Faculty of Civil Engineering and Geosciences  
Section Hydraulic Engineering**

**1**

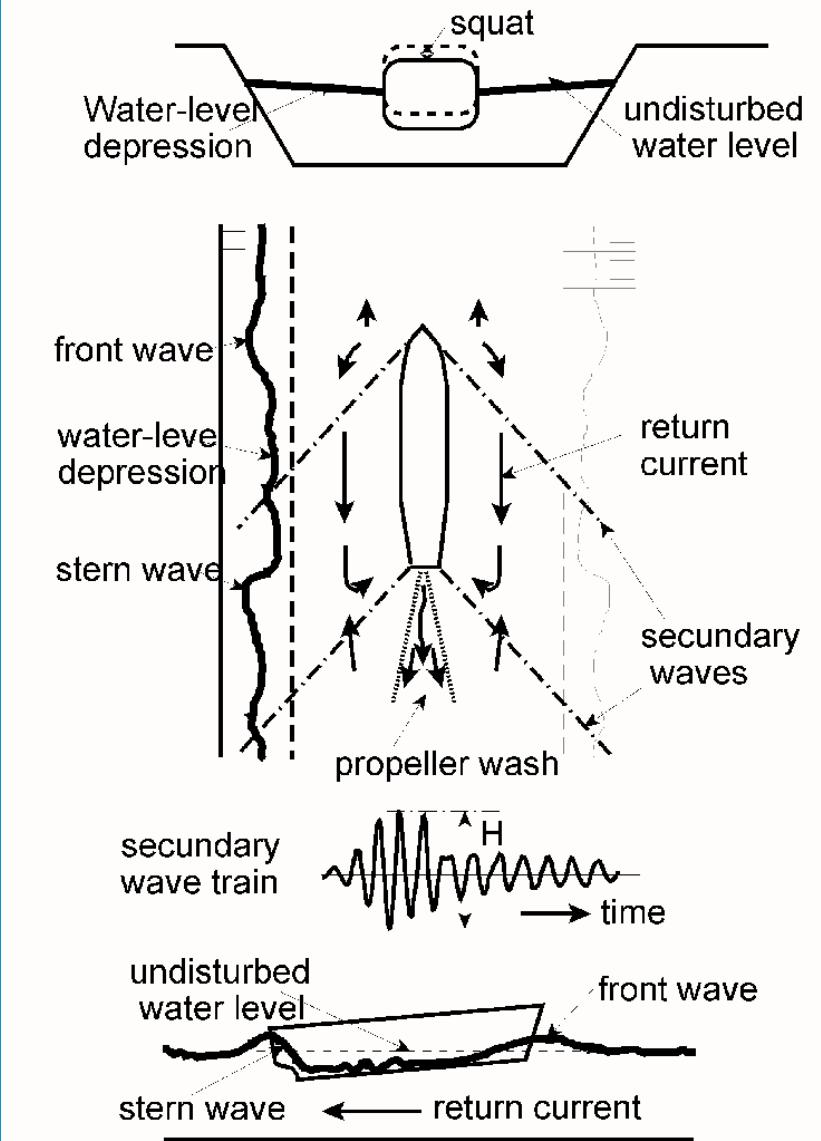
# Introduction

- In inland waterways ships may cause waves
  - primary wave
  - secondary waves
  - propeller wash

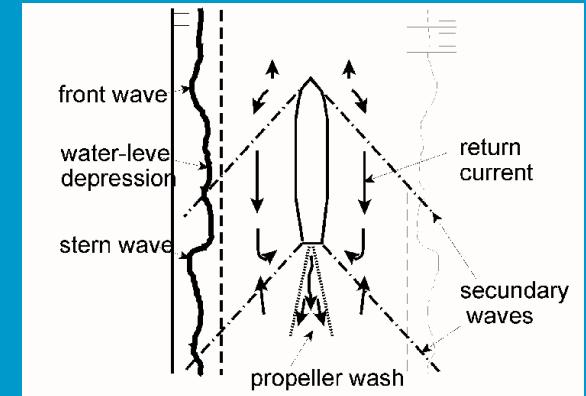
# flow around fixed object & moving object in stagnant water



# Phenomena around a moving ship in a waterway



# Return current and primary wave



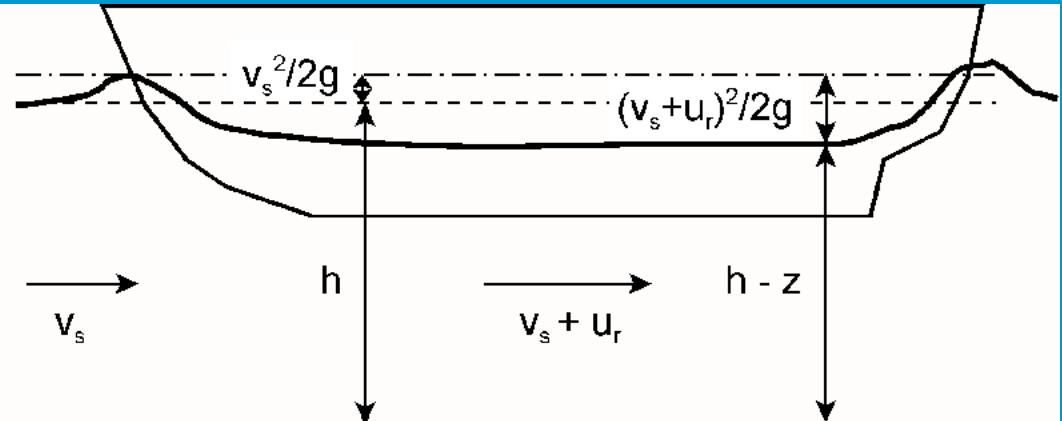
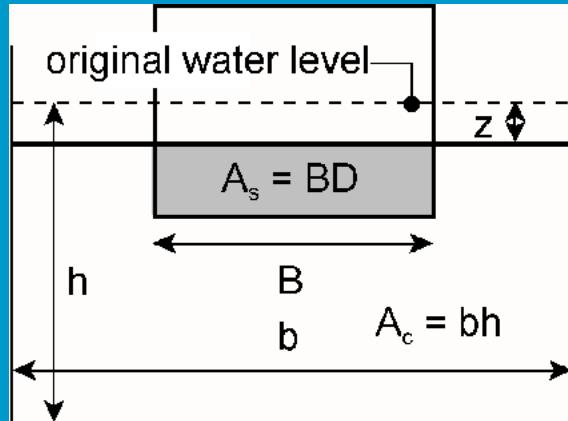
Ship in Elbe river, courtesy prof. Erik Pasche, TU Hamburg

# propeller wash

June 3, 2012

6

# Definition in 1-d approach



$$\left. \begin{aligned} c &= \frac{gT}{2\pi} \tanh \frac{2\pi h}{L} \\ L &= cT \end{aligned} \right\} \quad V_l = c = \sqrt{\frac{gL}{2\pi} \tanh \frac{2\pi h}{L}}$$

# limit speed

Bernoulli :

$$h + \frac{v_s^2}{2g} = h - z + \frac{(v_s + u_r)^2}{2g}$$

continuity:

$$b h v_s = (b h - B D - b z)(v_s + u_r) = Q$$

Maximum speed is reached when return flow becomes critical,  
i.e. when derivative of return flow to waterlevel becomes zero

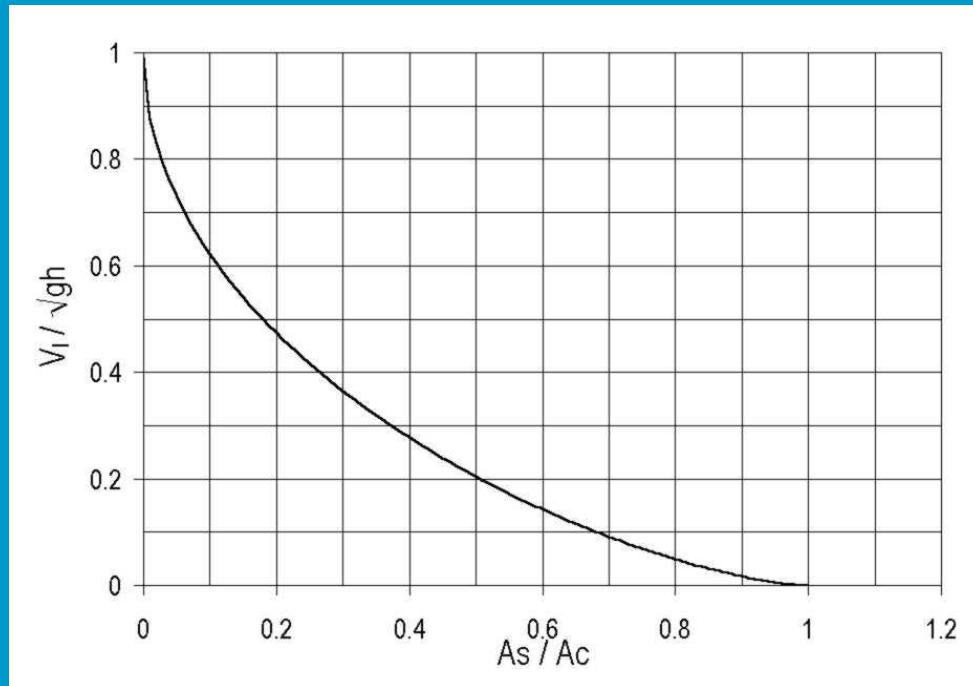
$$\frac{dQ}{dz} = \frac{d(v_s + u)(A_c - A_s - bz)}{dz} = 0$$

Combine this with Bernoulli:

$$\frac{A_s}{A_c} - \frac{V_l^2}{2gh} + \frac{3}{2} \frac{V_l^{2/3}}{(gh)^{1/3}} = 1$$

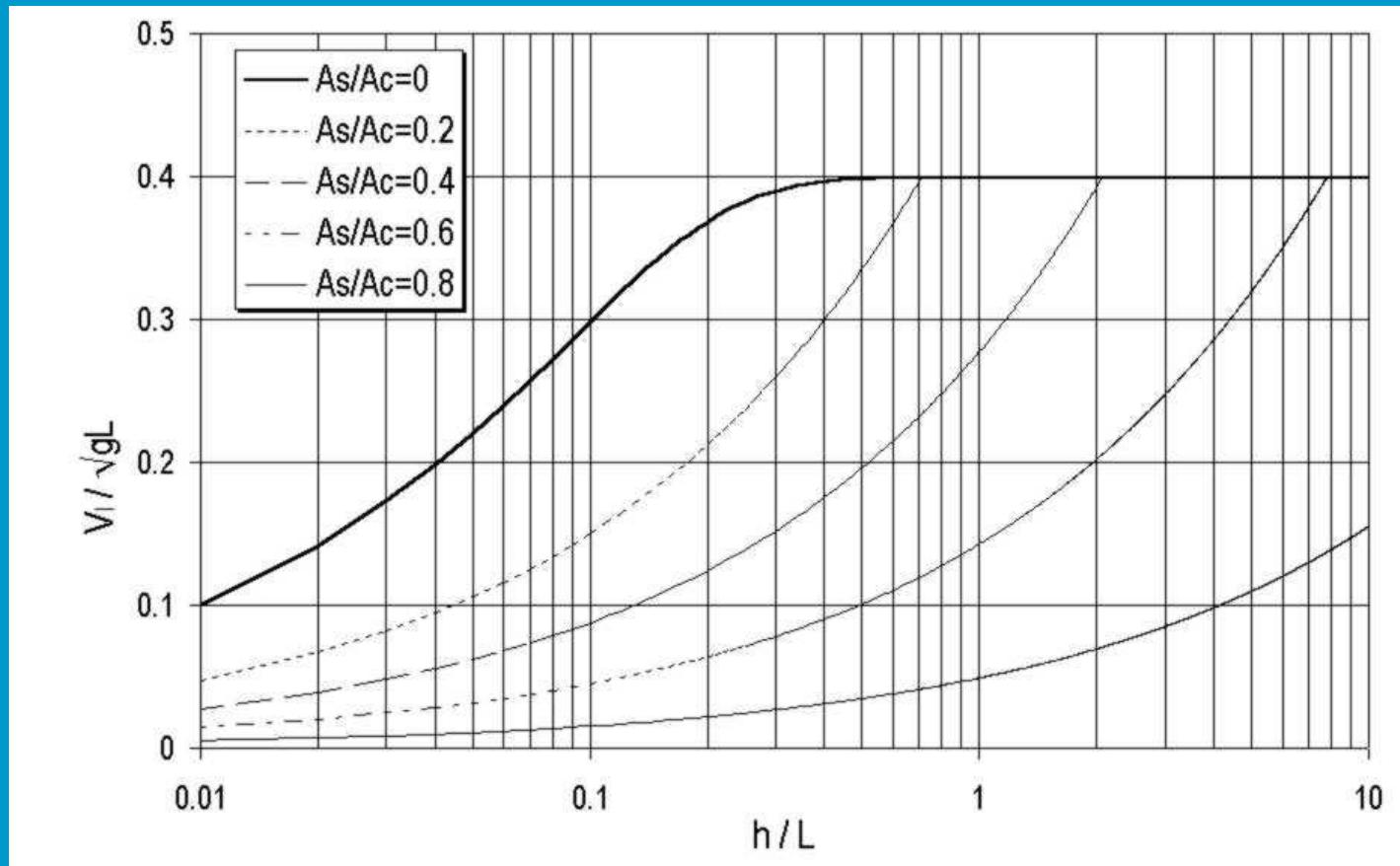
# limit speed as a function of blockage

$A_s/A_c$



$$\frac{A_s}{A_c} - \frac{V_l^2}{2gh} + \frac{3}{2} \frac{V_l^{2/3}}{(gh)^{1/3}} = 1$$

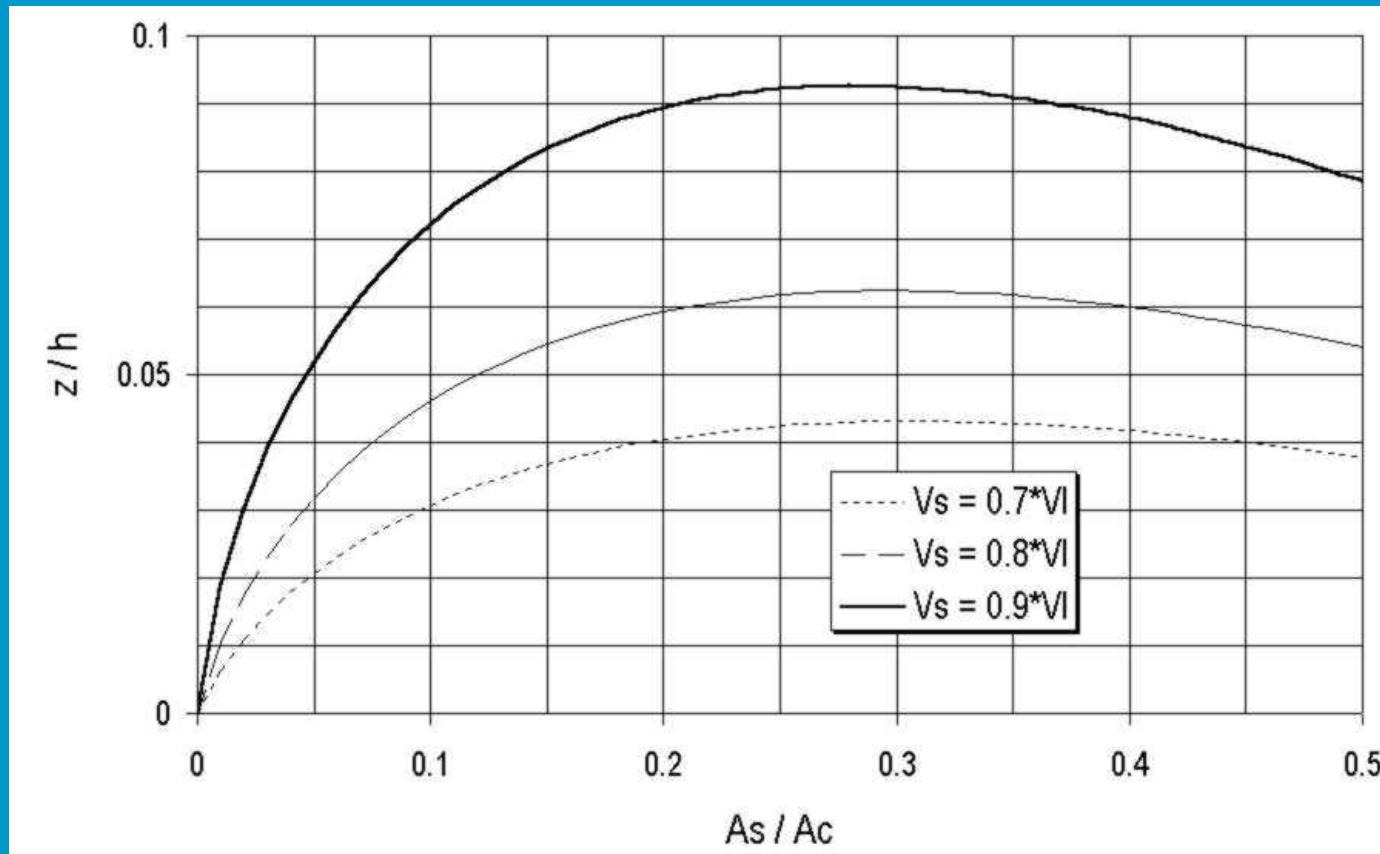
# limit speed as a function of waterdepth and blockage



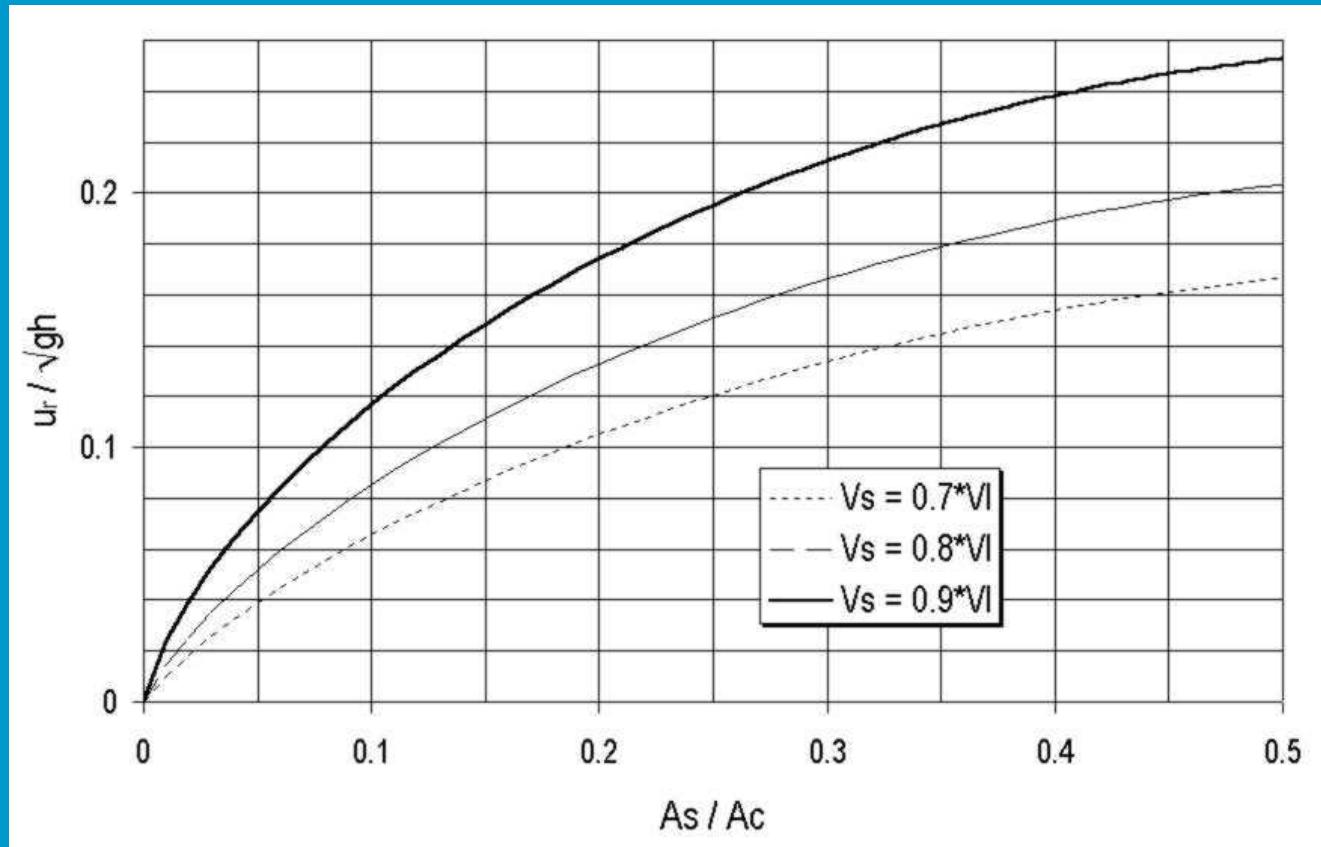
# primary waves

$$\frac{v_s^2}{gh} = \frac{2z/h}{(1 - A_s/A_c - z/h)^{-2} - 1}$$
$$\frac{u_r}{\sqrt{gh}} = \left[ \frac{1}{1 - A_s/A_c - z/h} - 1 \right] \frac{v_s}{\sqrt{gh}}$$

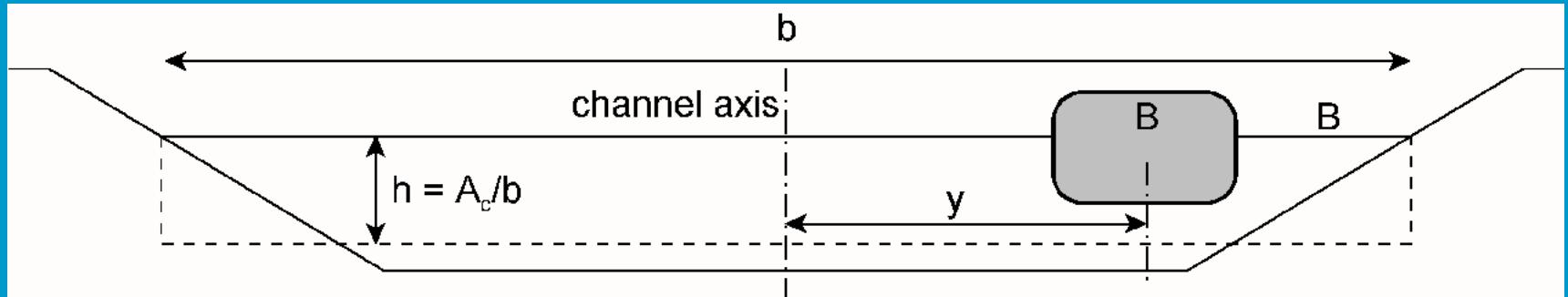
# waterlevel depression as a function of blockage



# return flow velocity as function of blockage



# deviation from the 1-d case

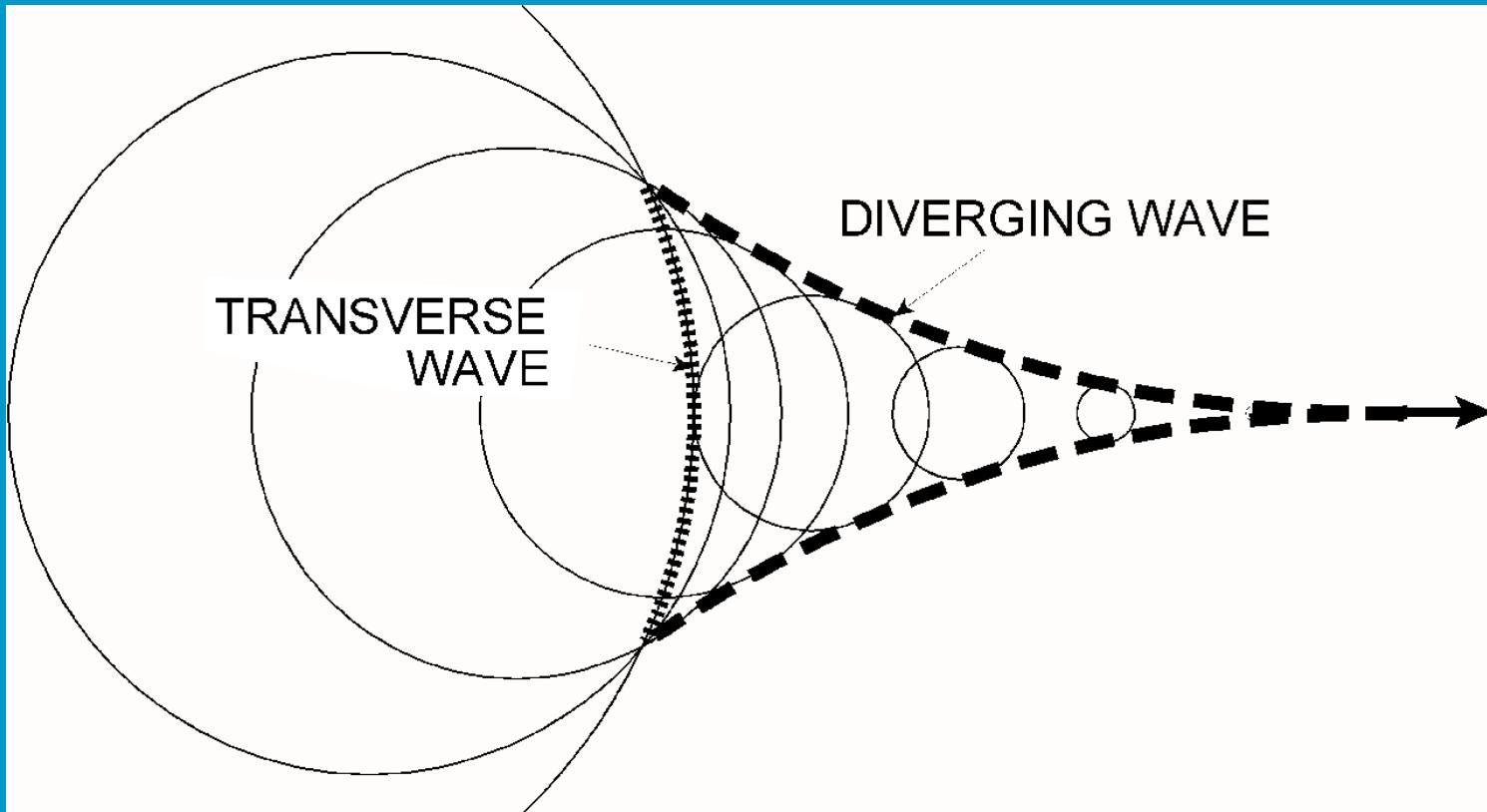


$$z_{ecc} = \left(1 + \frac{2y}{b}\right) z$$

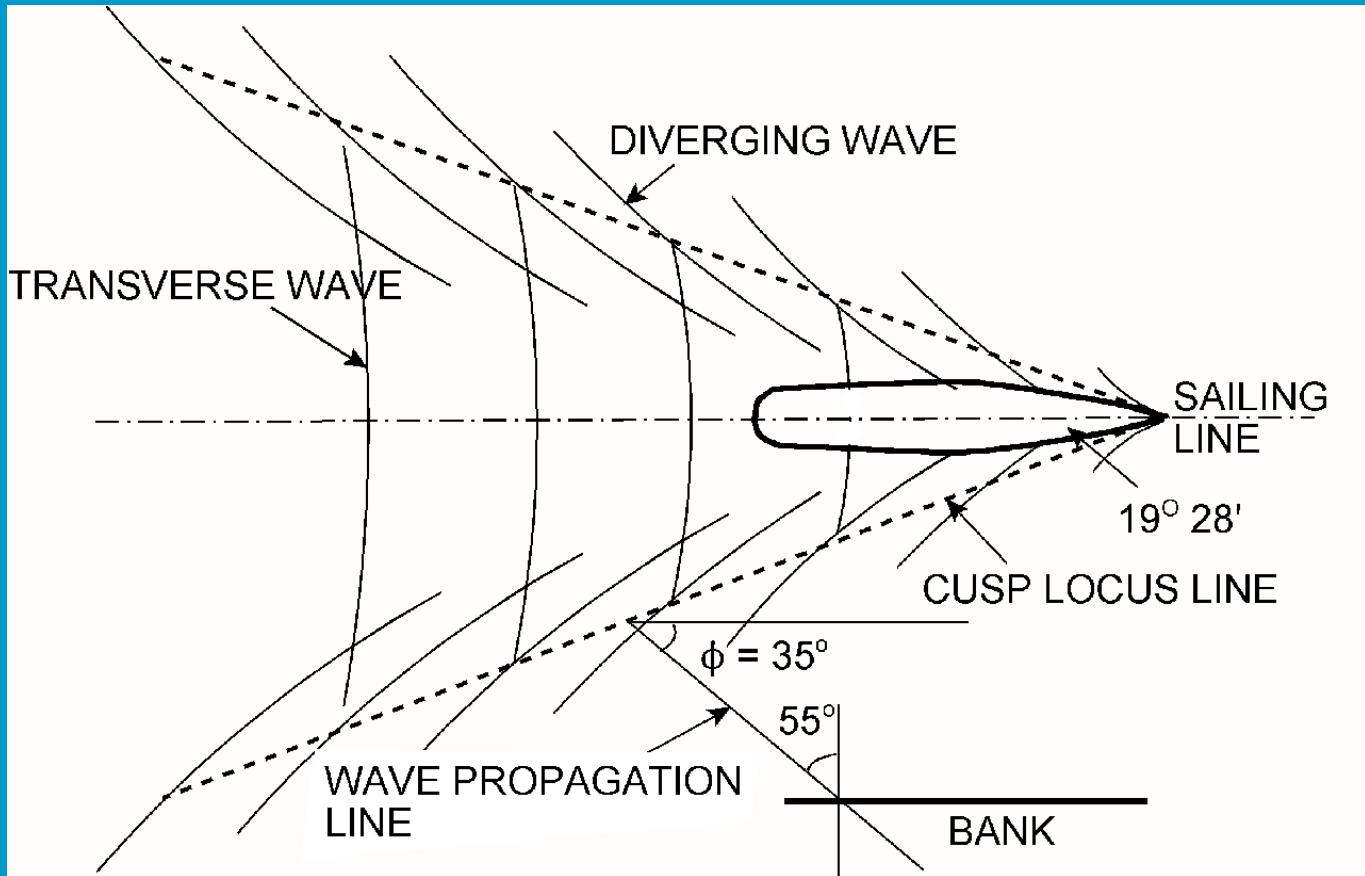
$$u_{r-ecc} = \left(1 + \frac{y}{b}\right) u_r$$

$$z_{\max} = 1.5 z_{ecc}$$

# origin of diverging and transverse waves



# secondary wave pattern



# Kelvin wave

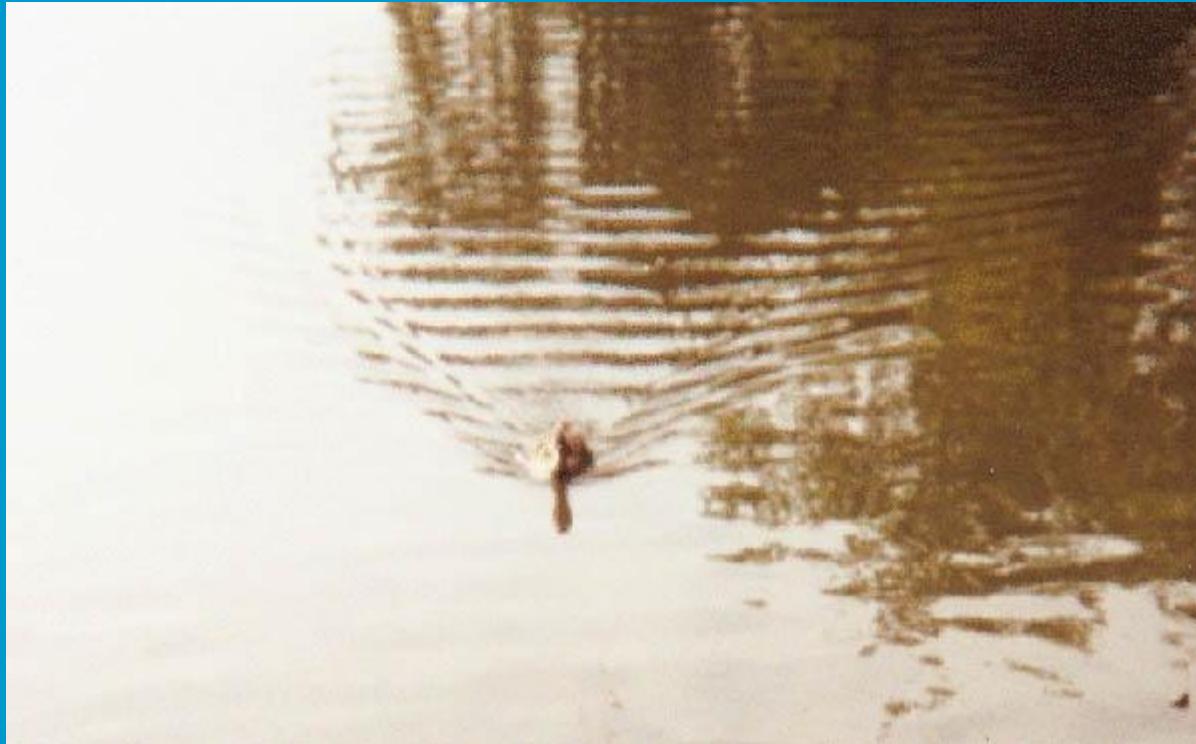


Christian Eskelund US Navy

June 3, 2012

17

# Kelvin Duck wave

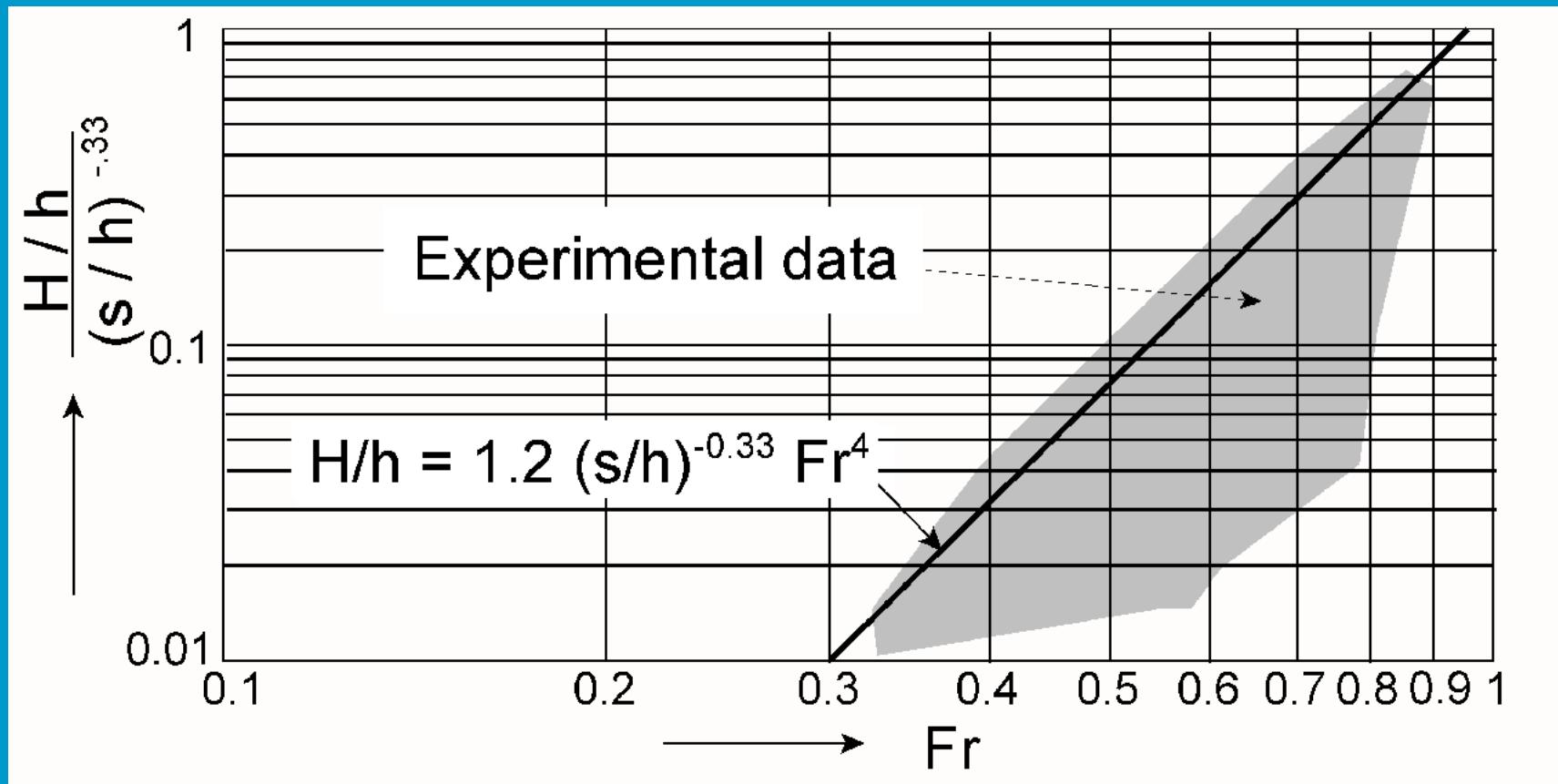


M.S.Cramer, Virginia Tech Duck Pond

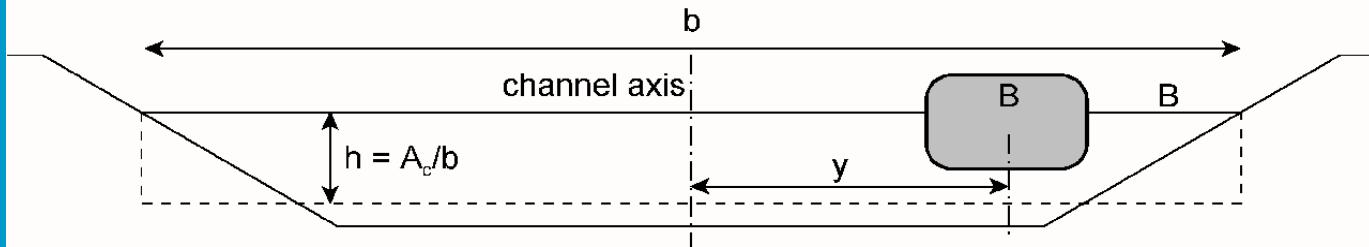
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18

# secondary wave height measurements



# example



Given: ship 10 m wide, draught 3 m  
canal 40 m wide, 5 m deep

Limit speed:  $A_s/A_c = (10*3) / (40*5) = 0.15$  fig 9.4

$V_l/\sqrt{gh} = 0.55 \rightarrow V_l = 3.8 \text{ m/s}$  design speed  $0.9*3.8=3.4 \text{ m/s}$

Use fig. 9.6  $z/h = 0.083 \rightarrow z = 0.42 \text{ m}$

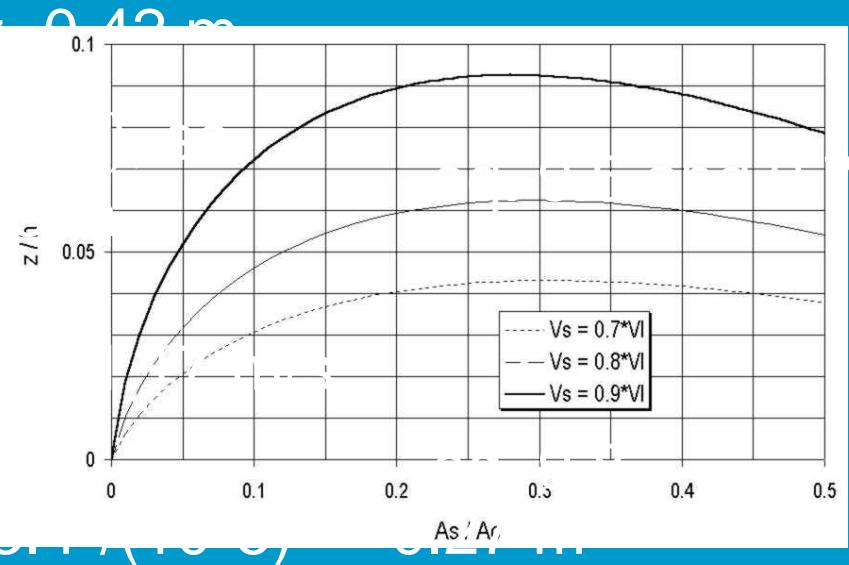
Ship sails 10 m from bank ( $y =$ )

$$z_{\max} = 1.5((1+2*5/40)*0.42 = 0.7)$$

$$u_r = 0.15 * \sqrt{gh} = 1.04 \text{ m}$$

$$\text{incl. excentricity: } (1+5/40)*1.04$$

$$H = 1.2 h(s/h)^{-0.33} v^4 / (gh)^2 = \\ 1.2 * 5 * (10/5)^{-0.33} * 3.4^4 / (5 * 9.81) = 0.27 \text{ m}$$



# standard values in the Netherlands

	Wave heights (m)		Currents (m/s)	
	Wind waves	Ship waves	Natural current	Return current
Lakes	0.25 – 1.00	0.10 – 0.50	0.1 – 0.5	0.1 – 0.25
Canals	0.10 – 0.25	0.25 – 0.75	0.5 – 1.0	0.5 – 1.0
Rivers	0.25 – 1.00	0.25 – 0.75	1.0 – 2.0	0.5 – 1.0
Small waters	0.10 – 0.20	n.a.	0.2 – 1.0	n.a.

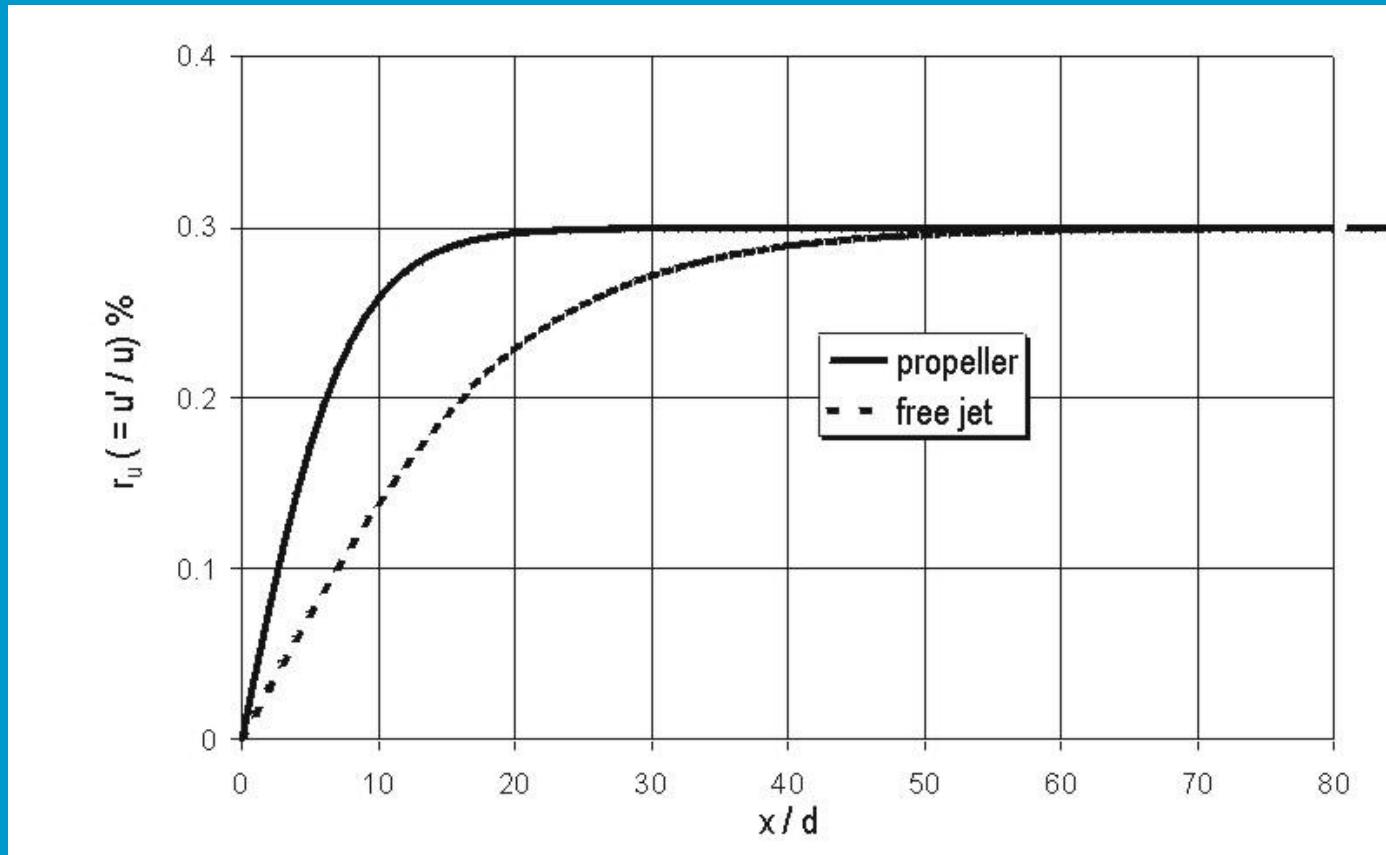
Data from CUR 197  
“Breuksteen in de praktijk”

# Propeller action

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23

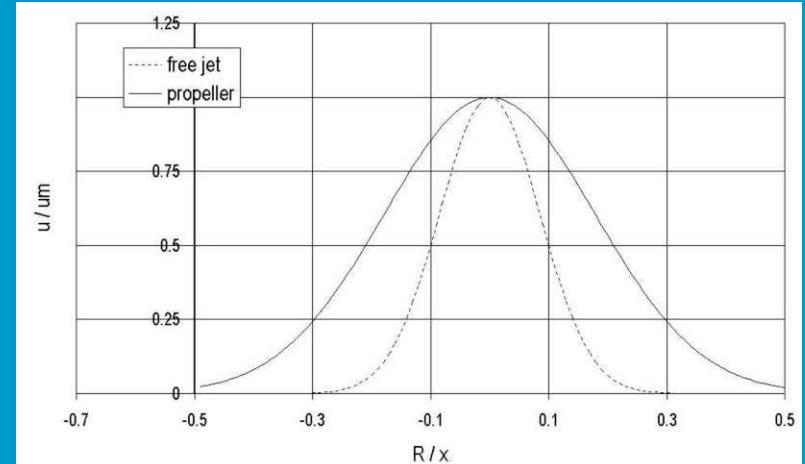
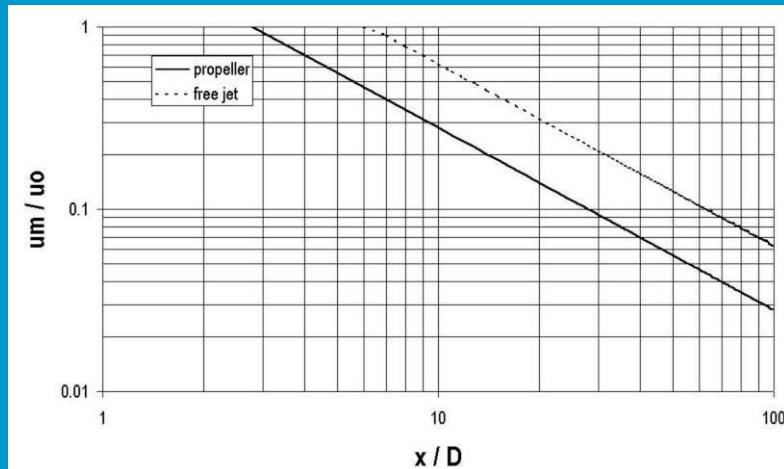
# turbulence in propeller wash and in free circular jet



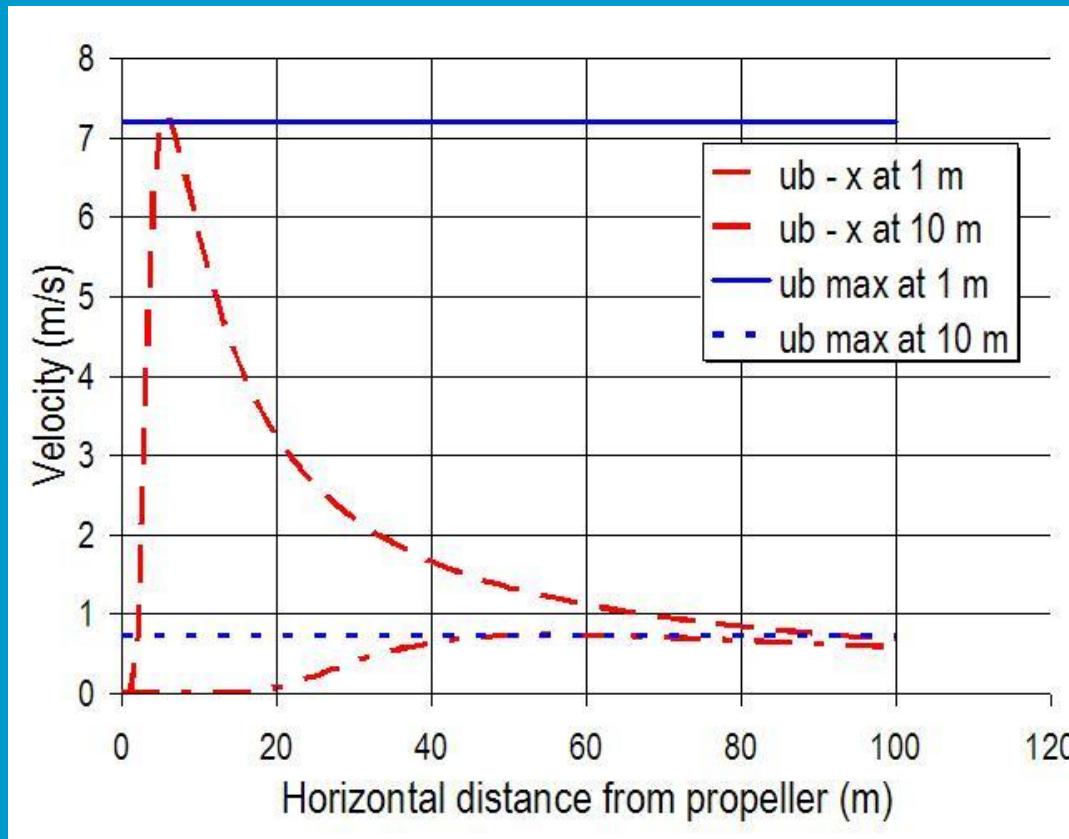
# equations for propeller jets

$$\left. \begin{array}{l} u_m = \frac{2.8u_0}{x/d} \\ b = 0.21x \\ u = u_m e^{-0.69\left(\frac{r}{b}\right)^2} \end{array} \right\} u = \frac{2.8u_0}{x/d} e^{-15.7\left(\frac{r}{x}\right)^2}$$

# velocity distribution in propeller wash and free jets



# velocities behind propeller

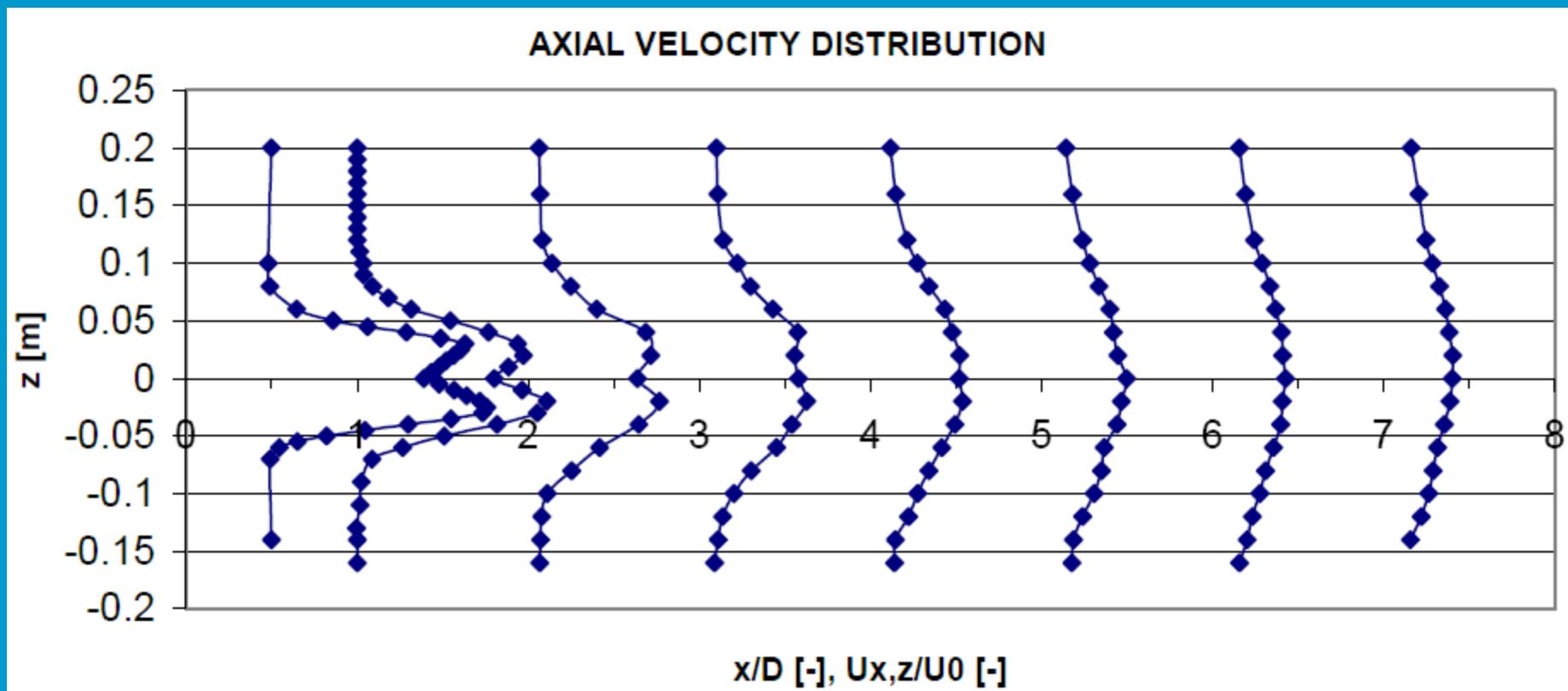


$$u_0 = 1.15 \left( \frac{P}{\rho d^2} \right)^{1/3}$$

$$u_{b-\max} = 0.3u_0 \frac{d}{z_b}$$

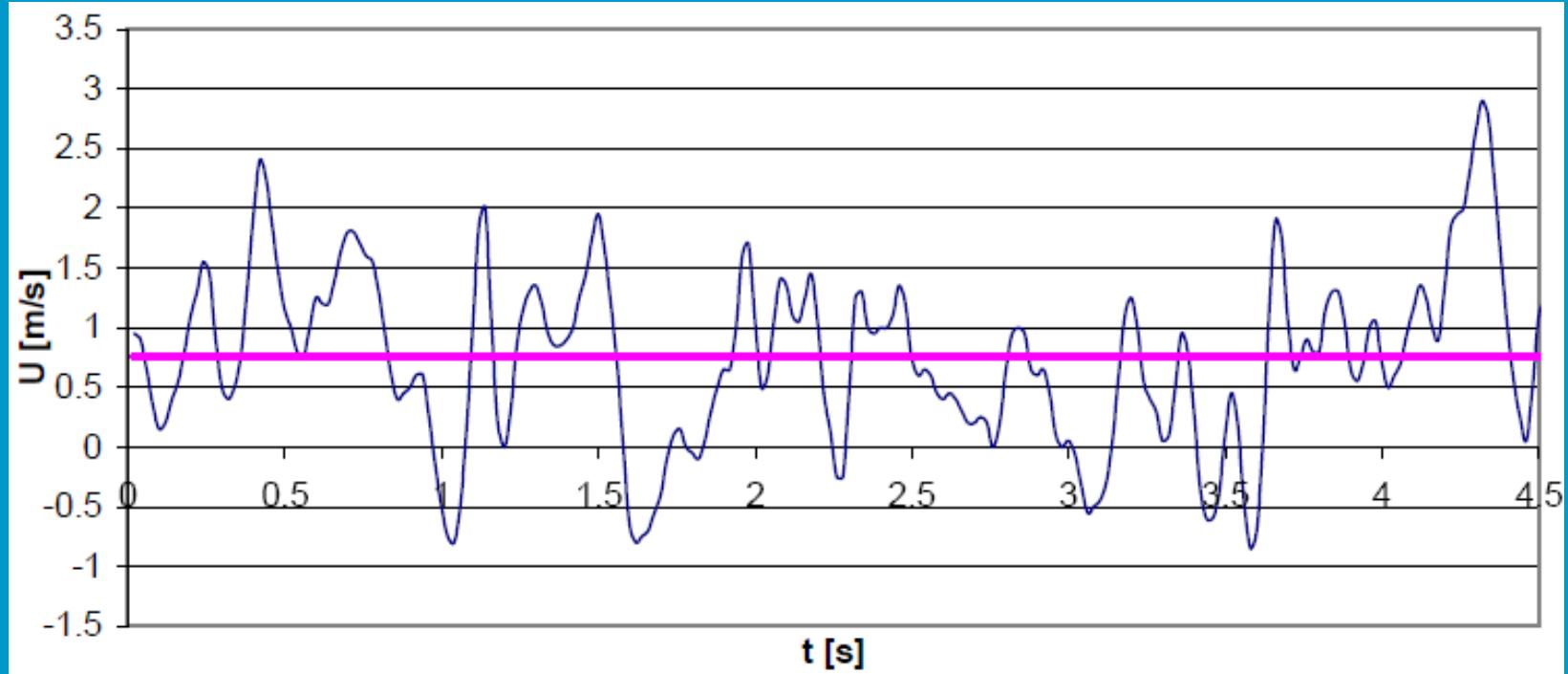
see also section 2.4.2.

# measured flow in a propeller jet



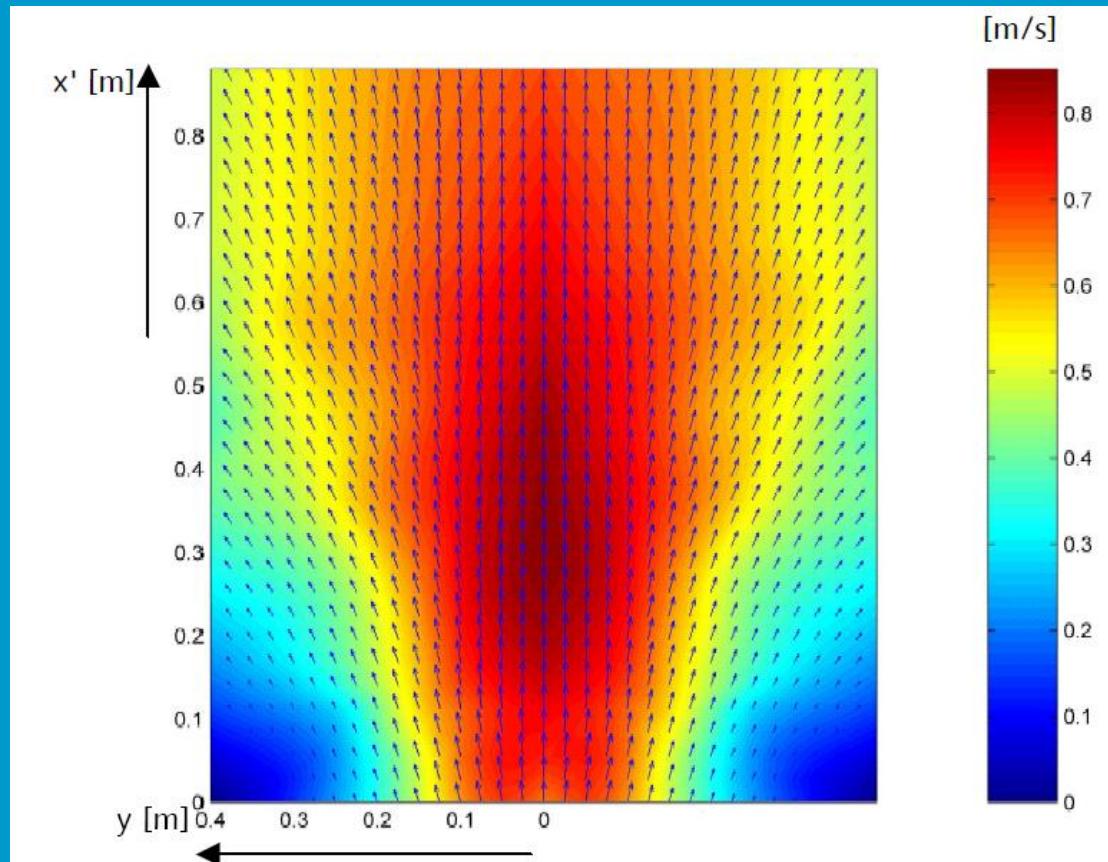
data from thesis Schokkink, 2003

# Turbulence in a propeller jet



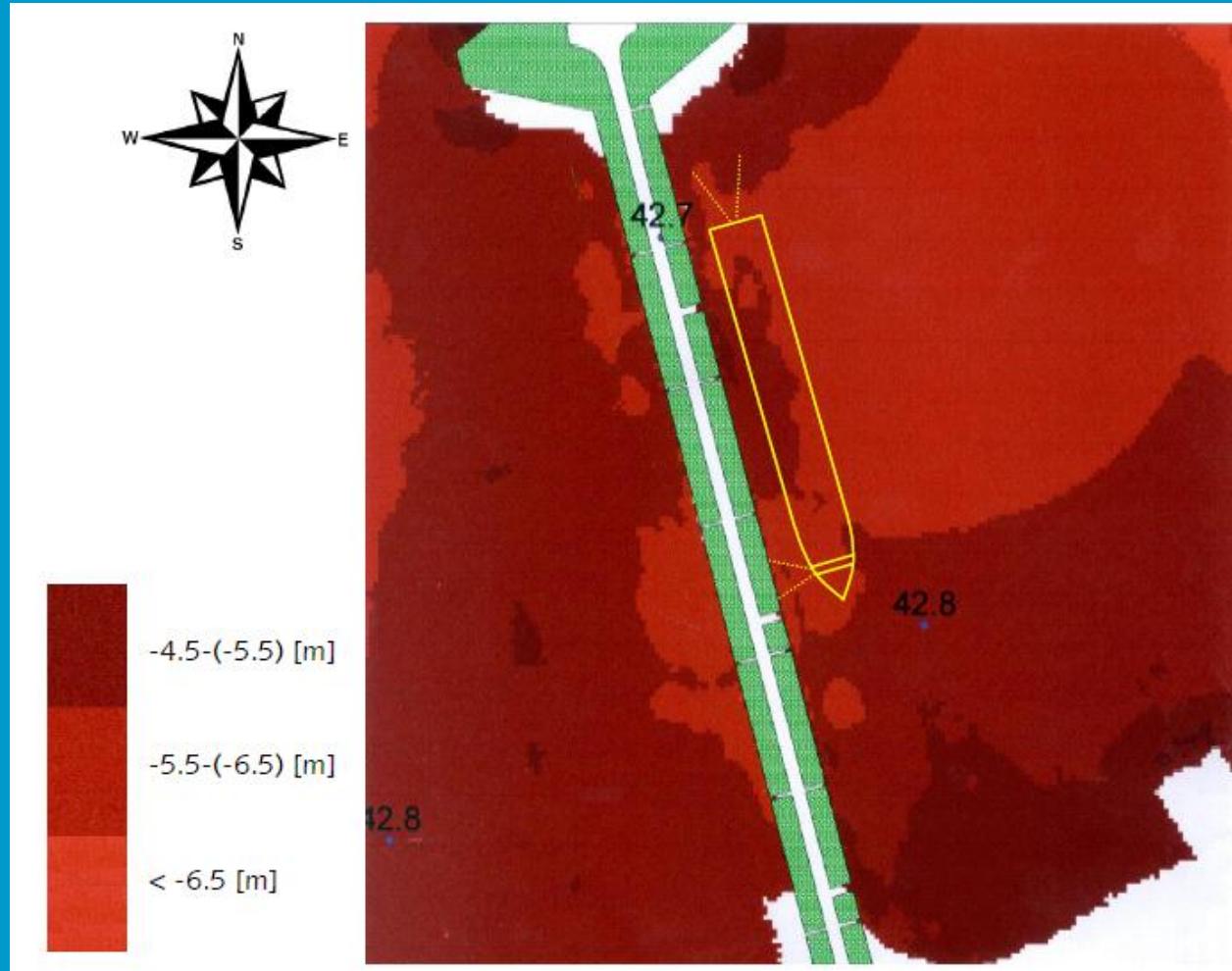
data from thesis Schokkink, 2003

# Flow caused by a propeller on an inclined slope



data from thesis Schokkink, 2003

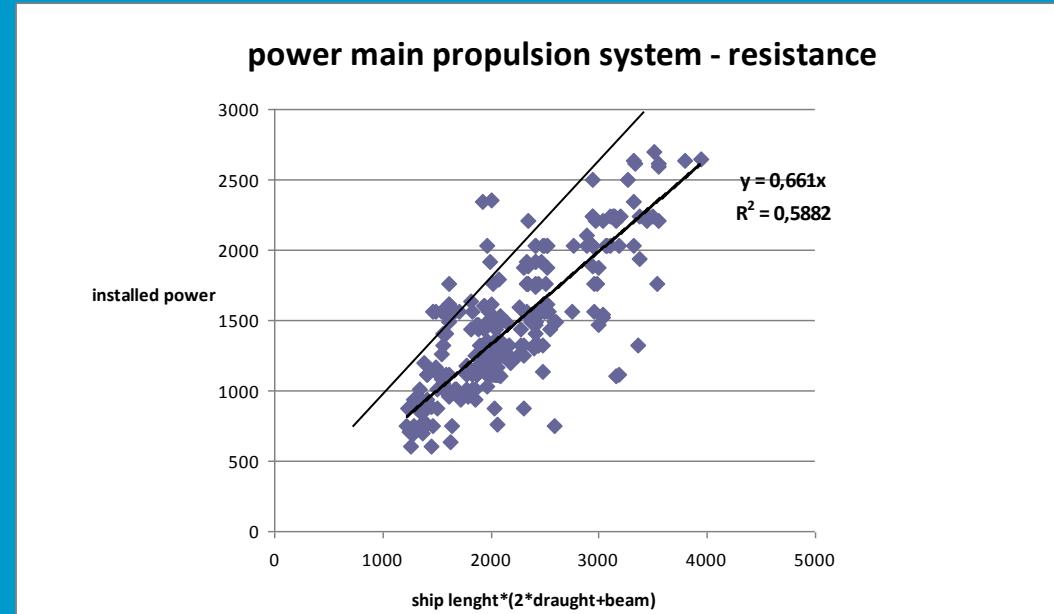
# erosion due to bowthrusters



June 3, 2012

31

# Ship engines



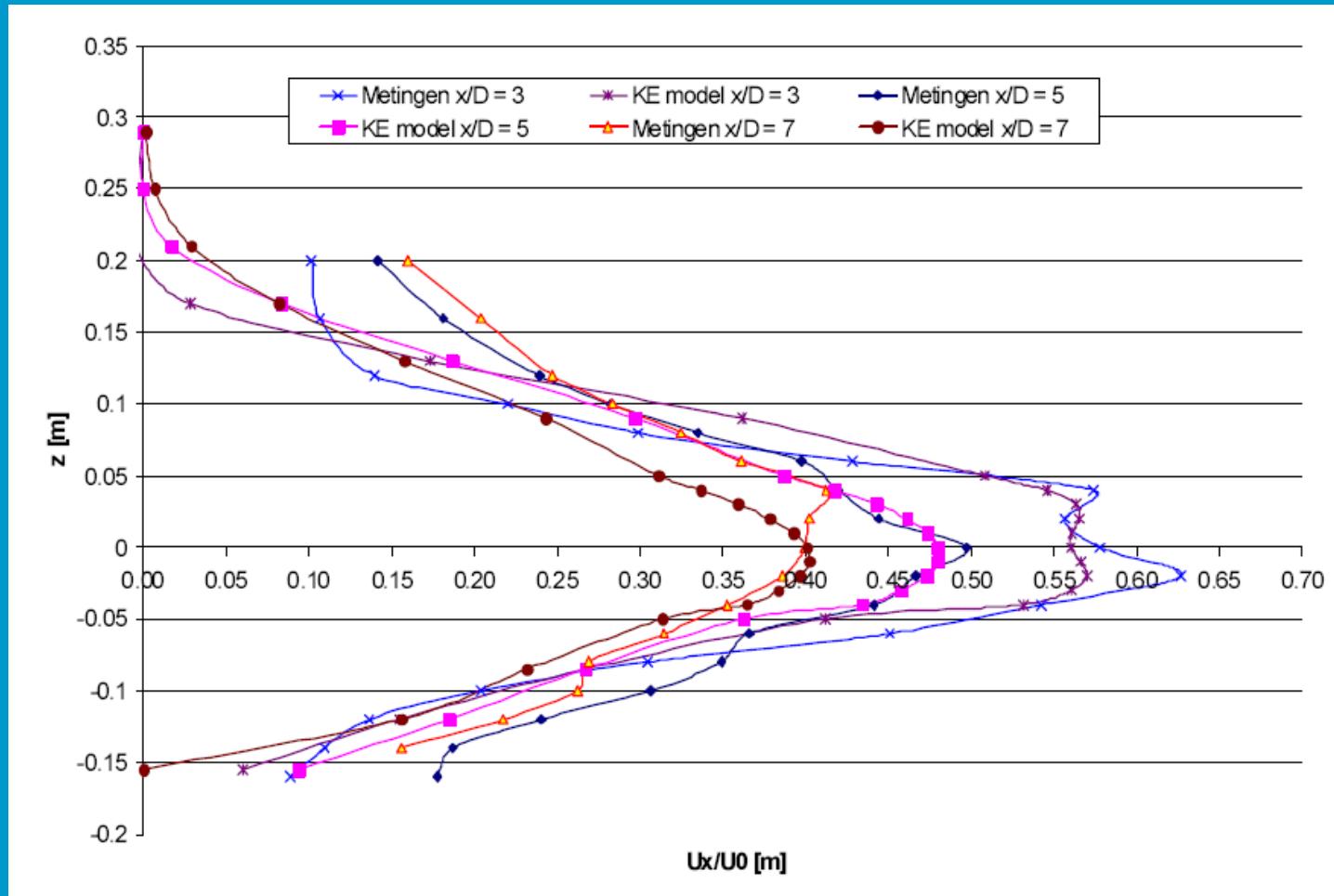
Type of ship	Power of engine (kW)
Small ships	100
Spits	200
Kempenaar	350
Dortmund-Ems Kanal	500
Rhein-Herne Kanal	700
Large Rhine vessel	1400
2 barge pushboat	1500

$$P_{\text{mean}} = 0.66L(2D+B)$$
$$P_{10\%} = 1.25 P_{\text{mean}}$$

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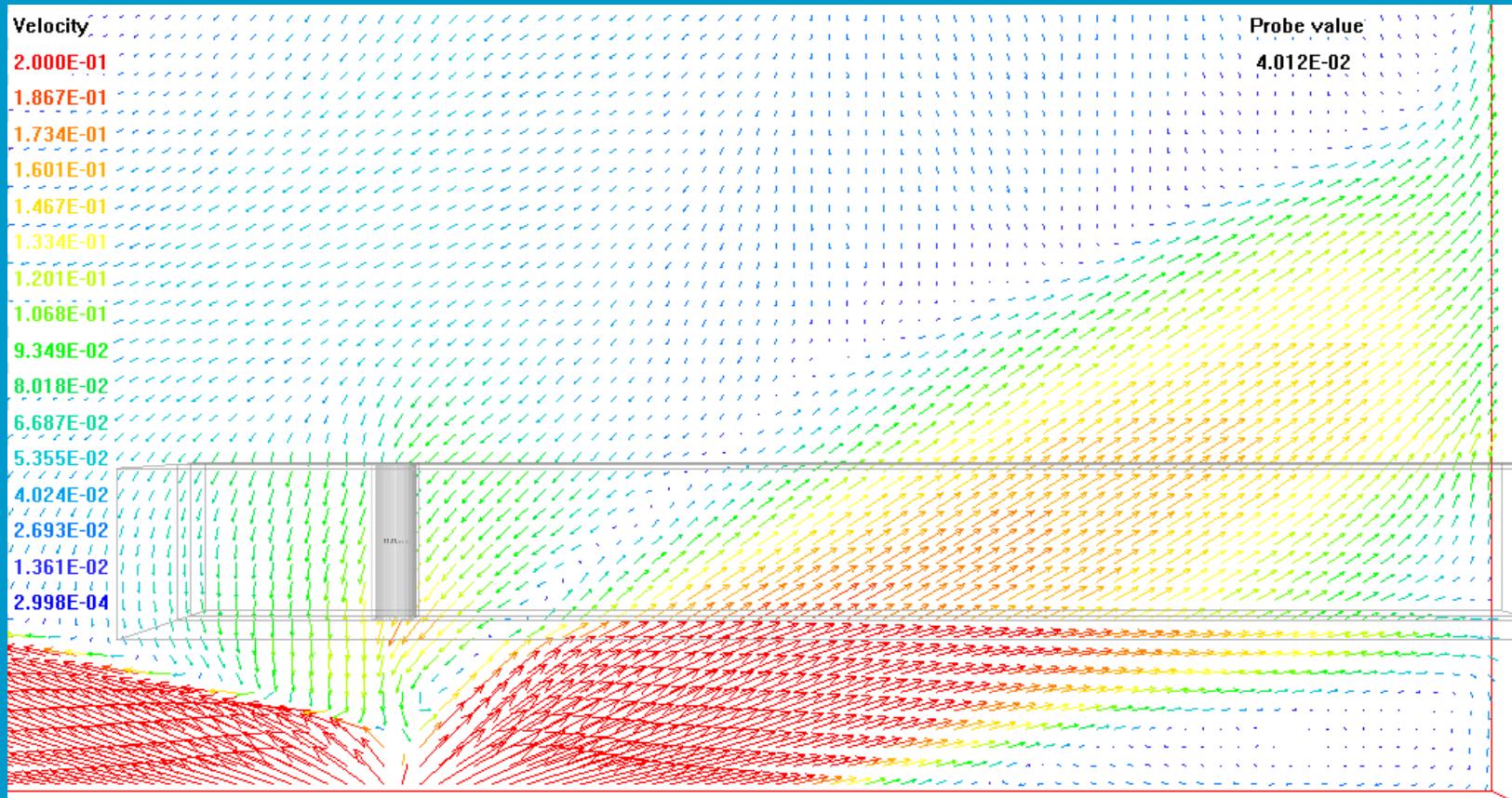
32

# Simulation of a propeller jet



Model by De Jong [2003], measurements by Schokking [2002]

# Model simulation with Phoenicx



Data from Van der Laan [2005]

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34

# The physical model

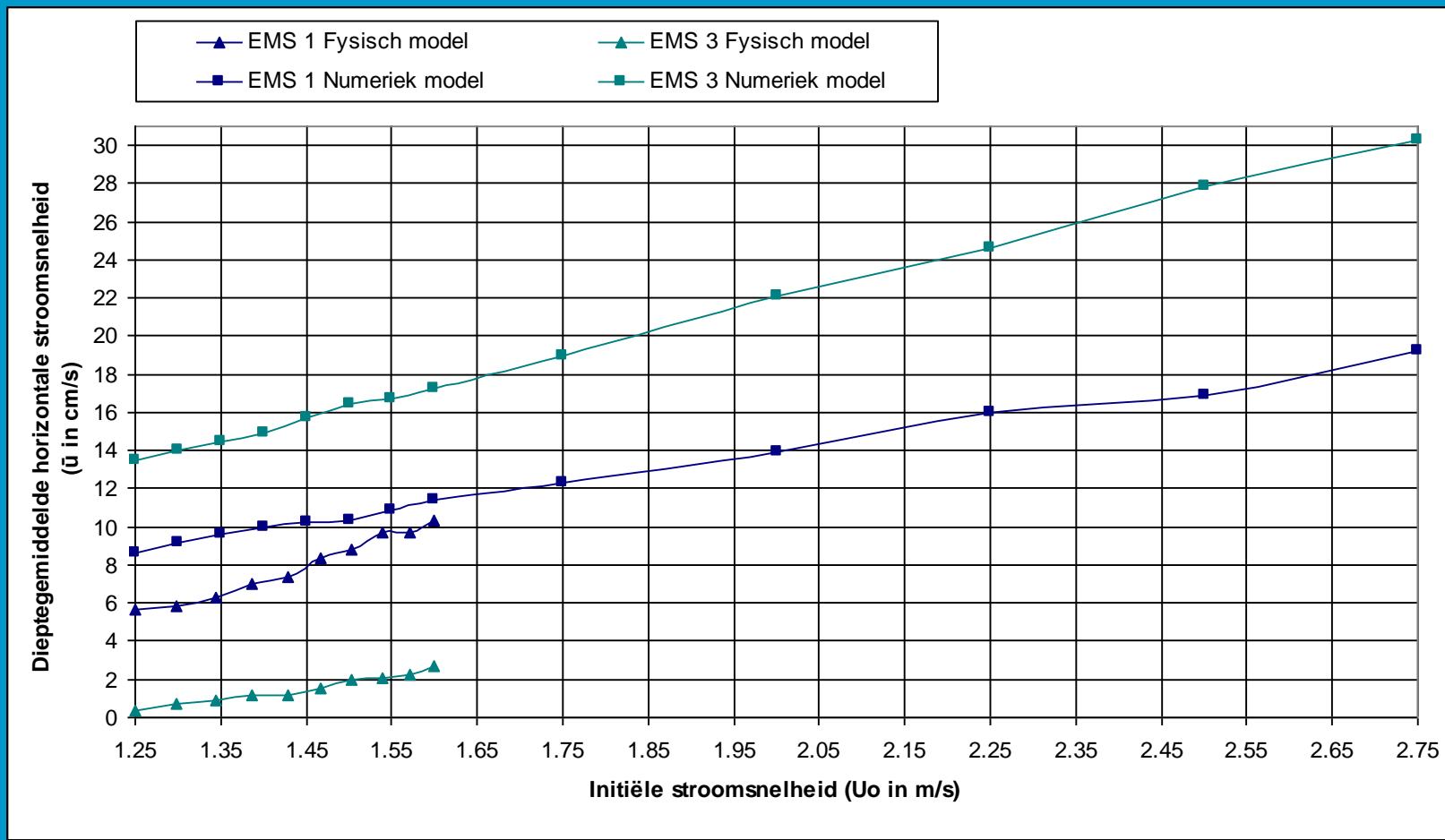


Van der Laan [2005]

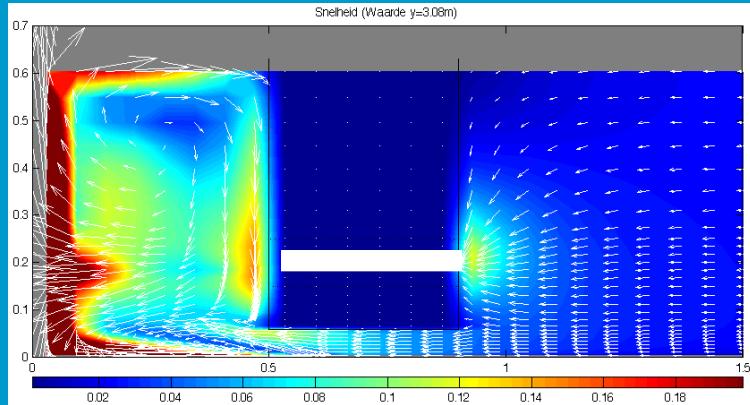
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35

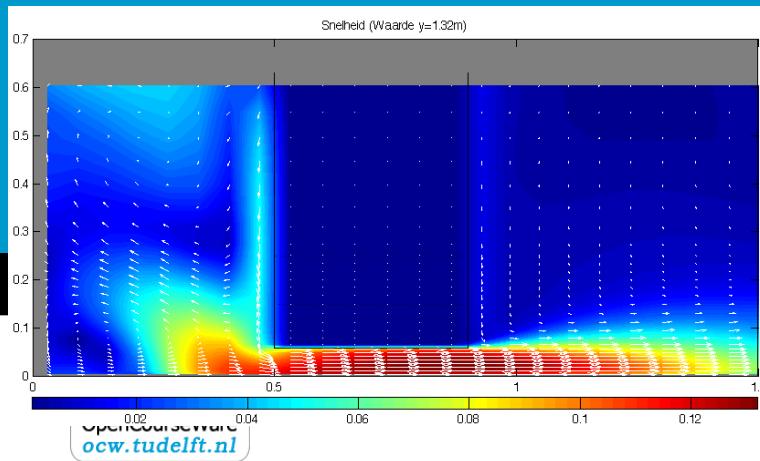
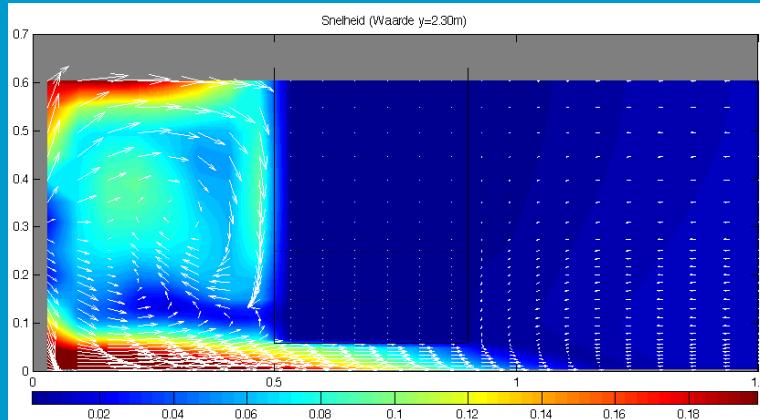
# Mathematical vs. Physical model



Van der Laan [2005]



# flow under ship

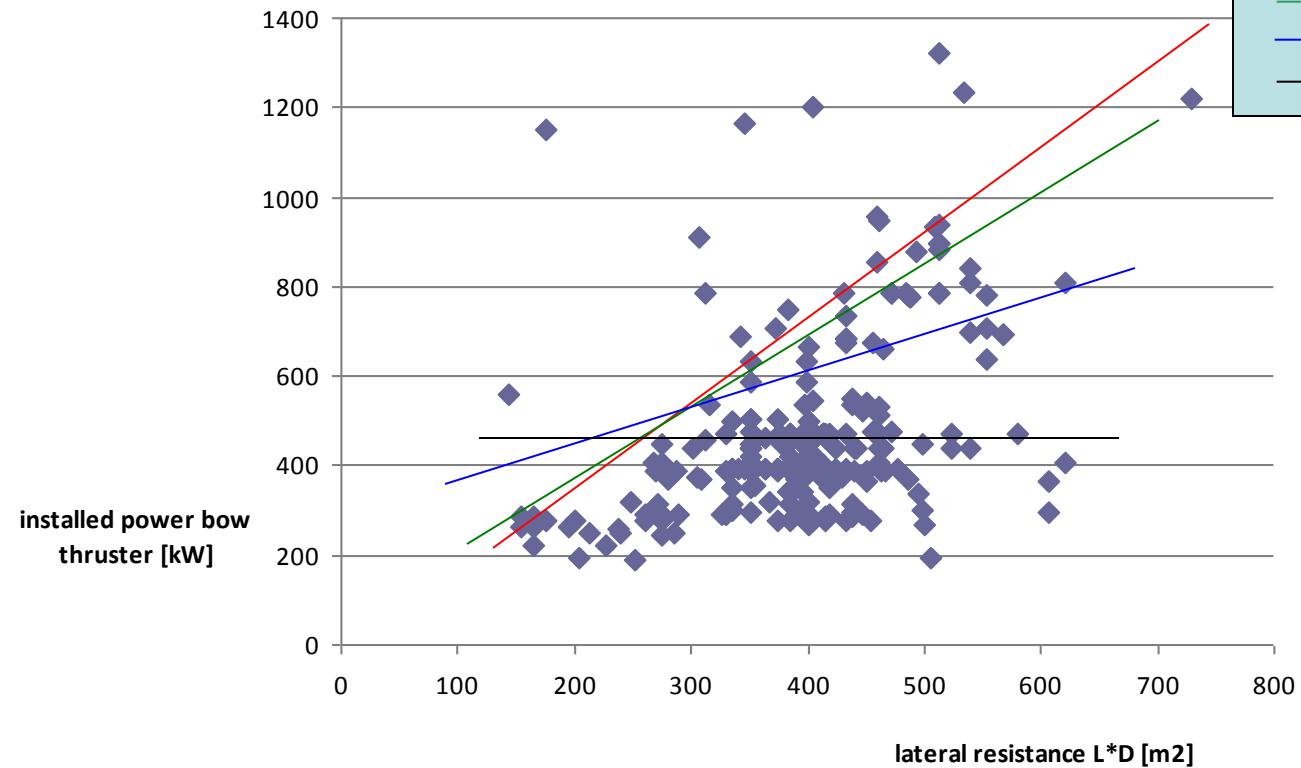


Egbert van Blaaderen, 2006

37

# Data of all inland vessels - $P_{\text{mean}} = A_1 LD + A_2$

power bow thruster - lateral resistance



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38

# stability of bed protection

- important are:
  - return flow
  - stern wave (depression)
  - secondary waves
  - propeller wash
- Relations based on Izbash + experimental data
- Hartelkanaal tests provided good data
  - M1115 1980-1988
  - Q908 1990
- Dipro

# bow thrusters

$$P_d = A_1(LD) + A_2$$

$$D_0 = 0.068 P_d^{0.5}$$

$$v_p = 1.15 \zeta \left( \frac{P_d}{D_0^2} \right)^{1/3}$$

$$v_b = 1.03 v_p \frac{D_0}{z_p}$$

$P_d$  = Power of engine  
 $L$  = lenght of ship  
 $D$  = draught of ship  
 $D_0$  = diameter of propeller  
 $v_p$  = velocity behind thruster  
 $v_b$  = velocity near the bed  
 $\zeta$  = loss factor = 0.9  
 $z_p$  = distance propeller axis  
and bottom of channel

The axis of the thruster is  $\alpha D_p$  above the bed, but for  $\alpha$  there is no default given.

# stability (primary waves)

$$\Delta d_{n50} = 1.2 \frac{u_r^2}{2g} \frac{1}{\sqrt{1 - \frac{\sin^2 \alpha}{\sin^2 \phi}}}$$

$$\frac{z_{\max}}{\Delta d_{n50}} = 1.8 \cot \alpha^{0.33}$$

# stability (secondary waves)

$$\frac{H\sqrt{\cos 55^\circ}}{\Delta d_{n50}} = 2.7 \xi^{-0.5} \rightarrow \frac{H}{\Delta d_{n50}} = 3.6 \xi^{-0.5}$$

# stability (propeller wash)

$$\Delta d_{n50} = 2.5 \frac{u_b^2}{2g} \frac{1}{\sqrt{1 - \frac{\sin^2 \alpha}{\sin^2 \phi}}}$$

given: depression = 0.78 m

$$H = 0.27, \quad T = 1.8 \text{ s}$$

$$u_r = 1.17 \text{ m/s} \quad \tan \alpha = 1/3$$

stern wave effect:

$$\frac{z_{\max}}{\Delta d_{n50}} = 1.8 \cot \alpha^{0.33}$$

return flow effect:

$$\Delta d_{n50} = 1.2 \frac{u_r^2}{2g} \frac{1}{\sqrt{1 - \frac{\sin^2 \alpha}{\sin^2 \phi}}}$$

secondary wave effect:

$$\frac{H}{\Delta d_{n50}} = 3.6 \xi^{-0.5}$$

## example (2)

$$d_{n50} = \frac{0.78}{1.65 * 1.8 * 3^{0.33}} = 0.18m$$

$$d_{n50} = \frac{1.2 * 1.17^2}{1.65 * 2 * 9.81 * \sqrt{1 - 0.31^2}} = 0.06m$$

$$d_{n50} = \frac{0.27 \sqrt{\xi}}{1.65 * 3.6} = 0.06m$$

# example (3)

- stern wave dominates problem
- action of stern wave only at waterline
- at deeper water return flow dominates
- at more spacious water bodies secondary waves become dominant

# example (4)

Ship 10 m wide, d3 m draught, 1000 kW engine (1370 hp), propeller diameter 1.4 m, propeller 1.5 m above bed

Effective jet = 70% of real diameter, so  $d = 1 \text{ m}$

$$u_0 = 1.15 \left( \frac{P}{\rho d^2} \right)^{1/3}$$

$$u_0 = 1.15 \left( \frac{10^6}{1000 * 1^2} \right)^{0.33} = 11.2 \text{ m/s}$$

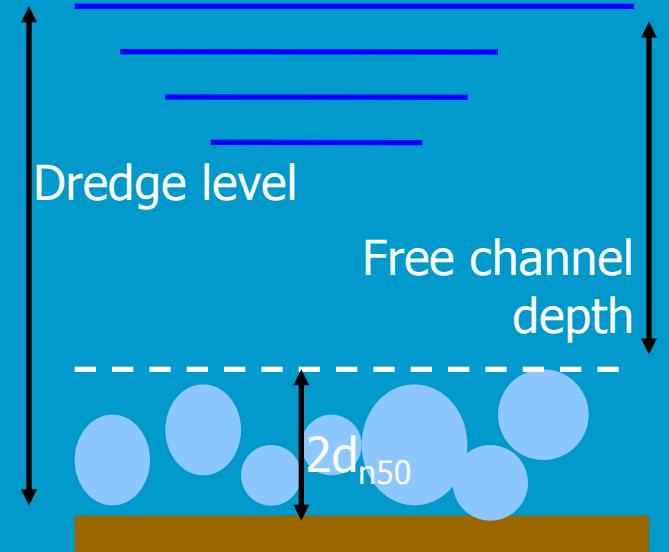
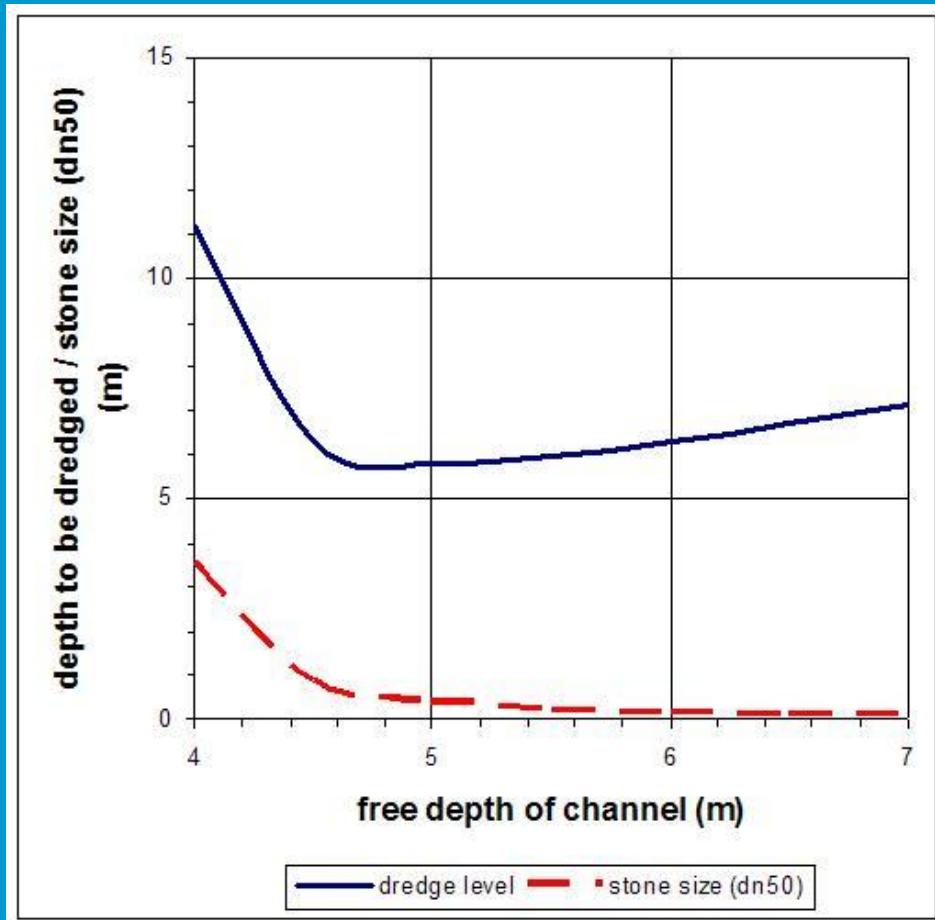
$$u_{b-\max} = 0.3u_0 \frac{d}{z_b}$$

$$u_b = 0.3 * 11.2 \frac{1}{1.5} = 2.25 \text{ m/s}$$

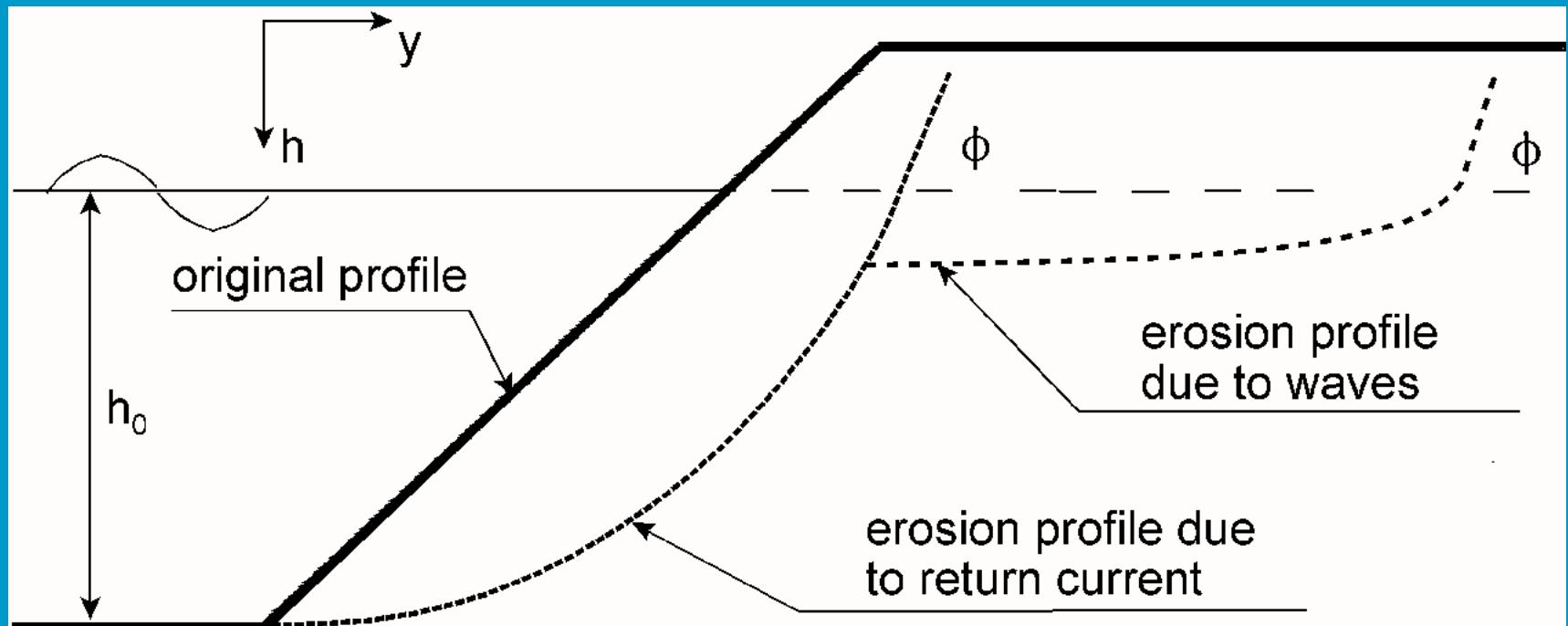
$$\Delta d_{n50} = 2.5 \frac{u_b^2}{2g} \frac{1}{\sqrt{1 - \frac{\sin^2 \alpha}{\sin^2 \phi}}}$$

$$d_{n50} = \frac{2.5 * 2.25^2}{1.65 * 9.8} = 0.4 \text{ m } (60/300 \text{ kg})$$

# Optimal depth of a channel

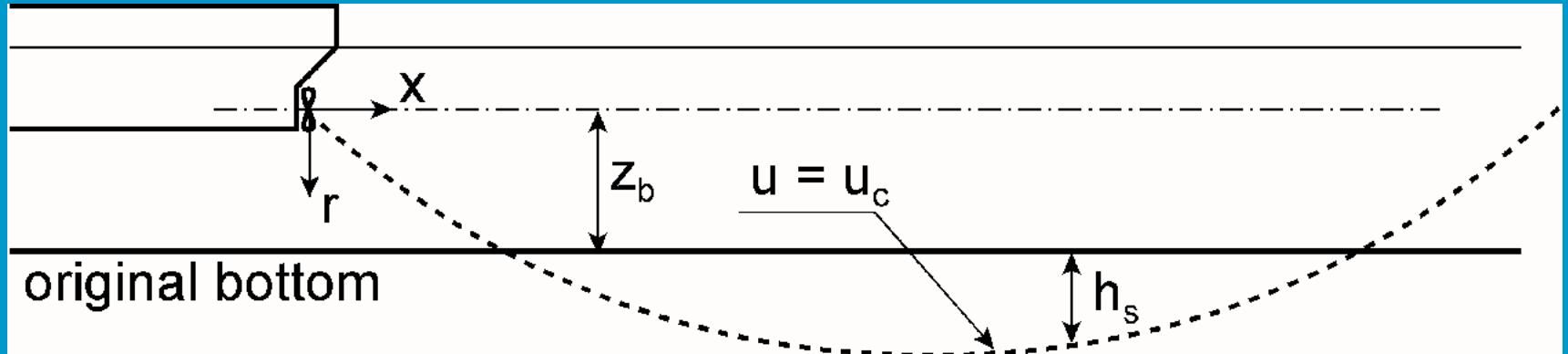


# erosion



$$h = h_0 \cos \left( \tan(\phi) \frac{y}{h_0} \right)$$

# bed erosion due to propeller wash



$$h_s = x \sqrt{\frac{-\ln\left(\frac{u_c x}{5.6 u_0 d}\right)}{15.7}} - z_b$$

# Dipro - Cress

About Dipro+



## DIPRO<sup>+</sup>

Dimensioning protections



DIPRO+ is developed by IKM Engineering  
by order from Rijkswaterstaat DwW.

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