BIOMEDICAL ENGINEERING DESIGN

WB2308

TUDelft

Delft University of Technology

- CONCEPTUAL
- REPORT
- PRESENTATION



CONCEPTUAL PHASE:

- PROBLEM DEFINITION
- SEARCH FOR SOLUTIONS
- CHOICES



PROBLEM ANALYSIS:

- NOVEMBER 16, 2007; 08.45 hr.
- ROOM E



REPORT:

- ACCOUNT
- BRIEF: 10 12 PAGES



FINAL PRESENTATION:

- DECEMBER 21, 2007; 08.45 hr.
- ROOM E
- 10 MINUTES



SUPERVISION:

GABRIËLLE TUIJTHOF tel.: 86780 e-mail: g.j.m.tuijthof@tudelft.nl JUST HERDER tel.: 84713 e-mail: j.l.herder@wbmt.tudelft.nl DICK PLETTENBURG tel.: 85615 e-mail: d.h.plettenburg@wbmt.tudelft.nl



ASSIGNMENTS:

- REFILL UNIT CO2
- WRIST PROSTHESIS
- COUPLING MECHANISM ELBOW CONTROL
- GLOVELESS VC HAND PROSTHESES
- SHOULDER HARNESS BRASSIERE COMBI
- HAND GRIP
- SHOPPING CART
- SIMPLE ARMON
- MOBILE HEAD SUPPORT
- HAND PALM
- SIT-TO-STAND AID
- KNEE HOLDER FOR KNEE ARTHROSCOPY
- SHOULDER DISTRACTOR
- FOOT DISTRACTOR
- CORRECTION OSTEOTOMY
- SCREW FIXATION



REFILL UNIT CO₂

• Design a CO₂-cartridge that can be safely refilled





WRIST PROSTHESIS

• Design a wrist prosthesis with small axial length





COUPLING MECHANISM ELBOW CONTROL

 Design a mechanism that allows decoupling of elbow movements and hand movements





GLOVELESS HAND PROSTHESIS

• Design a gloveless hand with a high cosmetic value





SHOULDER HARNESS – BRASSIERE COMBINATION

• Design a shoulder harness – bra combination





13

HAND GRIP

• Design an a



r in beds



SHOPPING CART

• Design a shopping cart with integrated seat







MOBILE HEAD SUPPORT

• Design a compensation system for support of the head that provides a reasonable range of motion.





HAND PALM MECHANISM

• Design a mechanism that houses between three and five fingers and that distributes the operating force amongst the fingers.



SIMPLE ARMON

 Design an arm support device that is less complicated than ARMON, while providing reasonable range of motion.





SIT-TO-STAND AID

 Design a device that can help people getting up and sitting down. Consider the application of statically balanced spring mechanisms





KNEE HOLDER FOR KNEE ARTHROSCOPY

 Design a mechanism that compensates the mass of the lower leg, but still enables manipulation of the knee joint





SHOULDER DISTRACTOR

• Design a mechanism that enables manipulation of the shoulder joint and holds the joint in a desired position





FOOT DISTRACTOR

• Design a mechanism that enables distraction of the three main joints in the hindfoot/ankle joint





CORRECTION OSTEOTOMY

 Design a mechanism that enables precise sawing of the bones





SREW FIXATION

Design a mechanism that facilitates the placement of screws in bones



24

- TEAM UP: GROUPS of THREE
- INTERDISCIPLINARY [if possible]
- MAX. 2 GROUPS SAME ASSIGNMENT

