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 $\ddot{ax}(t) + \dot{bx}(t) + cx(t) = F(t)$

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 - a special solution (just a solution which satisfies the DE)
- Maple mostly (depending on F) gives this solution:

Example: We solve with Maple:

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$$x(t) = e^{1/2} \frac{\left(-b + \sqrt{b^2 - 4ca}\right)t}{a} - C2 + e^{-1/2} \frac{\left(b + \sqrt{b^2 - 4ca}\right)t}{a} - C1 + \frac{(c-a)\sin(t) - \cos(t)b}{b^2 + c^2 - 2ca + a^2}$$

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Remark

In the homogeneous part you see the expression $\sqrt{b^2 - 4 ca}$, in the case of a negative argument of the square root, Maple still gives an answer which is expressed in sin- and cos-functions.

An application part 1

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An application part 1

We investigate in Demo 2, part 1 with Maple some Mass, Spring and Damper systems without external forces

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We investigate in Demo 2, part 1 with Maple some Mass, Spring and Damper systems without external forces Examine the sheet especially the proper use of unapply (We define a function of four variables.)

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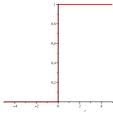
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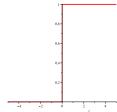
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The function has a derivative which is named as Dirac – δ-function. (In mathematical sense it is not normal function is an example of so called Distributions or Verallgemeinte Functionen (German)) For application of this see the Maple Demo part 2.

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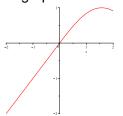
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Example 2:

Given on $[-2\pi, 2\pi]$ the function $g(x) = \sin(x)$ and glue function f(x) = -1 if g'(x) > 0 and f(x) = -1 if $g'(x) \le 0$

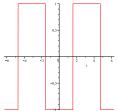


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Some special functions: mechanical friction



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Example 3:

You can describe the Dynamic Mechanical friction force MF(t) with magnitude 1 [N] for instance as MF(t) = -1 if x'(t) > 0 and MF(t) = 1 if x'(t) < 0 where x(t) is displacement function of a mass.

An application part 2

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We investigate in Demo 2, part 2 with Maple some Mass, Spring and Damper systems with external forces and the described special functions



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We investigate in Demo 2, part 2 with Maple some Mass, Spring and Damper systems with external forces and the described special functions Examine this!



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 $\ddot{x}(t)$ +0.1 $\dot{x}(t)$ +x(t) = 2(Heaviside(t-1)-Heaviside(t-5)+0.1MF(t))

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Answer:

The DE is a mathematical representation of a point mass (m = 1[kg]), attached on a spring (with constant 1[N/m]), with linear air drag, (constant 0.1[Ns/m]), exserted by a pulse force of magnitude of 2 [N] from second 1 to second 5, and influenced by a mechanical friction force of magnitude 0.1 [N].



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See last part of the Maple sheet for a numerical solution of the problem.