

$$G(s) = \frac{Y(s)}{U(s)} = \frac{B(s)}{A(s)} = \frac{(s-z_1)(s-z_2)\dots}{(s-p_1)(s-p_2)\dots}$$

$$A(s) \cdot Y(s) = B(s) \cdot U(s)$$

$$U(s) = 0 \Rightarrow A(s) \cdot Y(s) = 0$$

$$G(s) = \frac{1 \cdot s}{s+1} \quad (s+1) \cdot Y(s) = \textcircled{S} \cdot U(s) \quad U(s) = \frac{1}{s}$$

$$= s \cdot \frac{1}{s}$$

$$Y(s) = G(s) \cdot U(s) = \frac{1}{\tau s + 1} \cdot \frac{1}{s} = \frac{k_1}{s} + \frac{k_2}{\tau s + 1}$$

$$= \frac{1}{s} + \frac{-\tau}{\tau s + 1} \cdot \frac{-1}{s + \frac{1}{\tau}} \quad s = -\frac{1}{\tau}$$

$$\frac{1}{s+a}$$

$$y(t) = 1 - e^{-\frac{t}{\tau}}$$

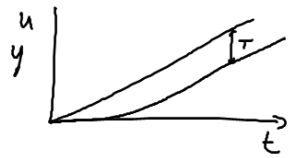


$$t = \tau \Rightarrow y(t) = 1 - e^{-1}$$

$$\frac{1}{s} = \frac{Y(s)}{U(s)} \Rightarrow s Y(s) = U(s)$$

$$\dot{y}(t) = u(t)$$

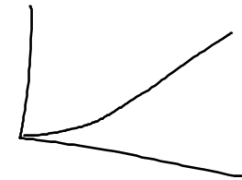
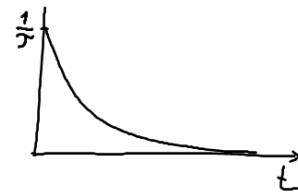
$$y(t) = \int u(t) dt$$



$$\frac{1}{s^2}$$

$$\frac{1}{Ts+1} \cdot \frac{1}{s^2}$$

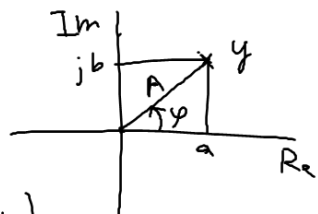
$$\boxed{\frac{1}{(Ts+1)s}} \cdot \frac{1}{s}$$



$$y = a + jb$$

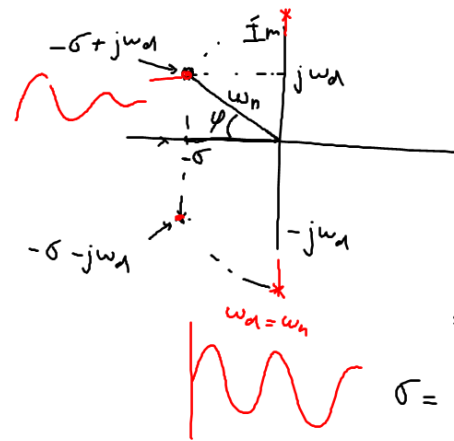
$$\boxed{y = A e^{j\varphi}}$$

$$y = A (\cos \varphi + j \sin \varphi)$$



$$a = A \cos \varphi$$

$$b = A \sin \varphi$$



$$\omega_n^2 = \sigma^2 + \omega_d^2$$

$$s^2 + 2\zeta \omega_n s + \omega_n^2$$

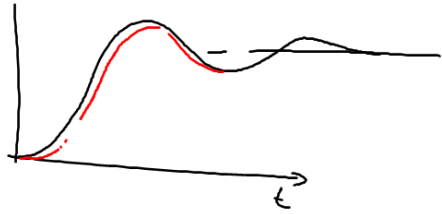
$$\underbrace{(s + \sigma + j\omega_d)}_a \cdot \underbrace{(s + \sigma - j\omega_d)}_b$$

$$(s + \sigma)^2 + \omega_d^2$$

$$= s^2 + 2\sigma s + \underbrace{\sigma^2 + \omega_d^2}_{\omega_n^2}$$

$$\sigma = \zeta \omega_n$$

$$\sigma = \underbrace{\cos \varphi}_\zeta \cdot \omega_n$$



$$\frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$\frac{1}{s + j\omega_n}$$

