

# System Validation

Mohammad Mousavi

2. Strong behavioral equivalences and weak behavioral equivalences part 2.



# Weak Behavioral Equivalences

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TU/Eindhoven

System Validation, 2012-2013

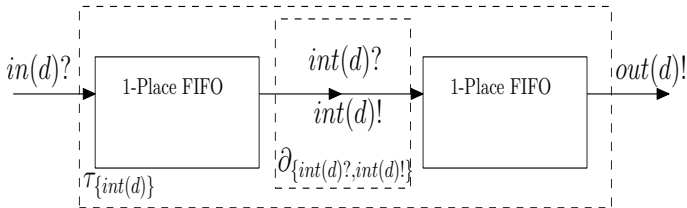
TU Delft

# Overview

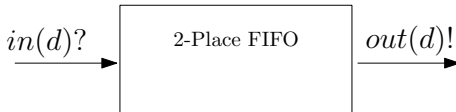
- ▶ Motivation
- ▶ Labelled Transition Systems,
- ▶ Strong equivalences:
  - ✓ trace equivalence,
  - ✓ language (completed trace) equivalence,
  - ✓ strong bisimilarity,
  - exercises.
- Weak equivalences:
  - ▶ weak trace equivalence,
  - ▶ branching bisimilarity,
  - ▶ root condition.
  - ▶ exercises

# Motivating Example

## Verifying a Two Place Buffer



$\equiv?$



# Recap

## Strong Equivalences

- ▶ Traces: sequences of actions originating from the **initial state**,

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- ▶ Language: sequences of actions originating from the initial state and **ending** in either **termination** or **deadlock**,

# Recap

## Strong Equivalences

- ▶ Traces: sequences of actions originating from the **initial state**,
- ▶ Language: sequences of actions originating from the initial state and **ending** in either **termination** or **deadlock**,
- ▶ Bisimulation relation: **related states** can **mimic** each others' transitions such that the targets are related by the **same relation**

# Weak Equivalences

## Idea

- ▶ **Internal** actions should be **invisible** to the outside world.



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- ▶  $\tau$ : The collective name for **all invisible actions**.

# Weak Equivalences

## Idea

- ▶ **Internal** actions should be **invisible** to the outside world.
- ▶  $\tau$ : The collective name for **all invisible actions**.
- ▶ Adapt behavioral equivalence to **neglect  $\tau$**

# Labeled Transition Systems

An LTS is a 5-tuple  $\langle S, Act, \rightarrow, s, T \rangle$ :

- ▶  $S$  is a set of *states*,
- ▶  $Act$  is a set of (*multi-*)*actions* (assumption:  $\tau \in Act$ )
- ▶  $\rightarrow \subseteq S \times Act \times S$  is the *transition relation*.
- ▶  $s \in S$  is the *initial* state,
- ▶  $T \subseteq S$  is the set of *terminating* states,

# Trace equivalence

## Traces of a State

For state  $t \in S$ ,  $\text{Traces}(t)$  is the minimal set satisfying:

1.  $\epsilon \in \text{Traces}(t)$ ,
2.  $\checkmark \in \text{Traces}(t)$  when  $t \in T$ ,
3.  $\forall t'_0 \in S, a \in \text{Act}, \sigma \in \text{Act}_{\checkmark}^* \quad a\sigma \in \text{Traces}(t)$  when  $\exists t' \in S \quad t \xrightarrow{a} t'$   
and  $\sigma \in \text{Traces}(t')$ .

## Trace Equivalence

For states  $t, t'$ ,  $t$  is trace equivalent to  $t'$  iff

$$\text{Traces}(t) = \text{Traces}(t').$$

# Weak Trace equivalence

## Weak Traces of a State

For state  $t \in S$ ,  $\text{Traces}(t)$  is the minimal set satisfying:

1.  $\epsilon \in W\text{Traces}(t)$ ,
2.  $\checkmark \in W\text{Traces}(t)$  when  $t \in T$ ,
3.  $\forall t'_0 \in S, a \in \text{Act} \setminus \{\tau\}, \sigma \in \text{Act}_{\checkmark}^* \quad a\sigma \in W\text{Traces}(t)$  when  $\exists t' \in S \quad t \xrightarrow{a} t'$  and  $\sigma \in W\text{Traces}(t')$ .
4.  $\forall t'_0 \in S, \sigma \in \text{Act}_{\checkmark}^* \quad \sigma \in W\text{Traces}(t)$  when  $\exists t' \in S \quad t \xrightarrow{\tau} t'$  and  $\sigma \in W\text{Traces}(t')$ .

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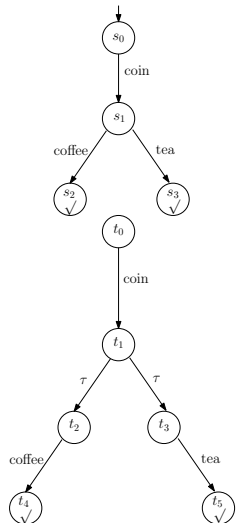
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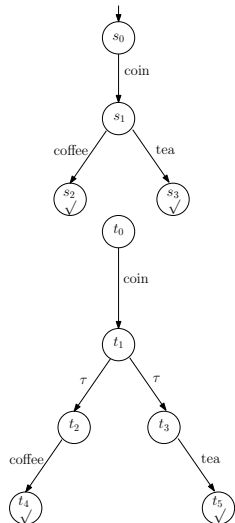
## Weak Traces: An Example



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## Weak Traces: An Example

- $\text{WTr}(s_2) = \text{WTr}(s_3) = \text{WTr}(t_4) = \text{WTr}(t_5) = \{\epsilon, \checkmark\}$ ,

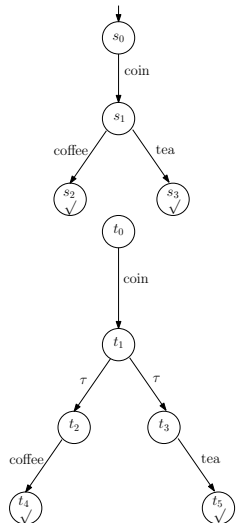




1.  $\epsilon \in \text{Traces}(t)$ ,
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## Weak Traces: An Example

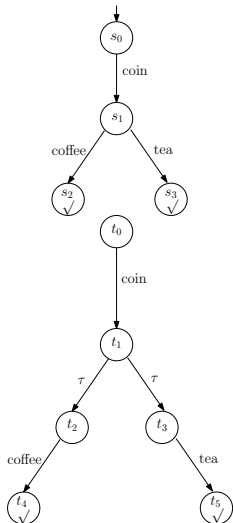
- ▶  $\text{WTr}(s_2) = \text{WTr}(s_3) = \text{WTr}(t_4) = \text{WTr}(t_5) = \{\epsilon, \checkmark\}$ ,
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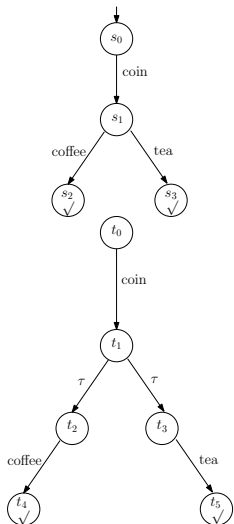
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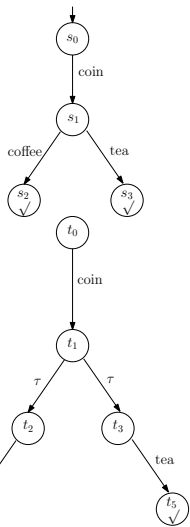
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- ▶  $\text{WTr}(s_0) = \text{WTr}(t_0) = \{\epsilon, \textit{coin}, \textit{coin coffee}, \textit{coin tea}, \textit{coin coffee}\checkmark, \textit{coin tea}\checkmark\}$ .



# Weak Trace Equivalence: An Observation

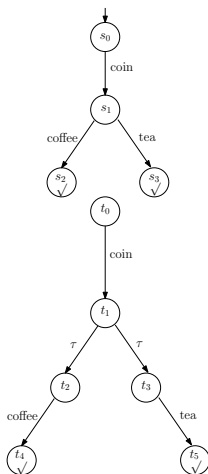
## Observation

$$WTr(s_0) = WTr(t_0) =$$

$$\{\epsilon, coin, coin\ coffee, coin\ tea, coin\ coffee\checkmark, coin\ tea\checkmark\}$$

## Moral of the Story

Weak Trace equivalence is usually **too coarse** for interacting (open) systems (neglects important differences).



# Weak Bisimulations

## Idea

1. An  $a$ -transition should be **mimicked** by the same transition possibly with **before and/or after (stuttering)  $\tau$ -transitions**;
2. A  $\tau$ -transition can be **mimicked** by remaining in the same state (**making no transition**).

# (Weak, Branching) Bisimulation

## Formal Definition:

- ▶  $R \subseteq S \times S$  is a relation
- ▶ all  $\forall (t_0, t_1) \in R$ 
  - ▶  $\forall t'_0 \in S, a \in A, t_0 \xrightarrow{a} t'_0 \Rightarrow$ 
    - ▶  $\exists t'_1 \in S, t_1 \xrightarrow{a} t'_1$   
 $\wedge (t'_0, t'_1) \in R$
  - ▶  $t_0 \in T \Rightarrow t_1 \in T$

and vice versa.

## Bisimulation

**bisimulation** relation when for

# (Weak, Branching) Bisimulation

## Formal Definition: Weak

## Bisimulation

- ▶  $R \subseteq S \times S$  is a **weak bisimulation** relation when for all  $\forall_{(t_0, t_1) \in R}$

- ▶  $\forall_{t'_0 \in S, a \in A} t_0 \xrightarrow{a} t'_0 \Rightarrow$ 
  - ▶  $a = \tau \wedge (t'_0, t_1) \in R$  or
  - ▶  $\exists_{t'_1, t'_2, t'_3 \in S} t_1 \xrightarrow{\tau} t'_1 \xrightarrow{a} t'_2 \xrightarrow{\tau} t'_3$   
 $\wedge (t'_0, t'_3) \in R$

- ▶  $t_0 \in T \Rightarrow \exists_{t'_1 \in S} t_1 \xrightarrow{\tau} t'_1 \wedge t'_1 \in T,$

and vice versa.



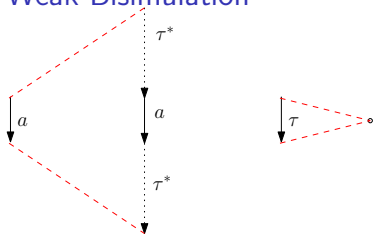
# (Weak, Branching) Bisimulation

## Formal Definition: Branching Bisimulation

- ▶  $R \subseteq S \times S$  is a **branching bisimulation** relation when for all  $\forall (t_0, t_1) \in R$ 
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      - ▶  $a = \tau \wedge (t'_0, t_1) \in R$  or
      - ▶  $\exists t'_1, t'_2 \in S, t_1 \xrightarrow{\tau} t'_1 \xrightarrow{a} t'_2$   
 $\wedge (t'_0, t'_2) \in R \quad \wedge (t_0, t'_1) \in R,$
    - ▶  $t_0 \in T \Rightarrow \exists t'_1 \in S, t_1 \xrightarrow{\tau} t'_1 \wedge (t_0, t'_1) \in R \wedge t'_1 \in T,$
- and vice versa.

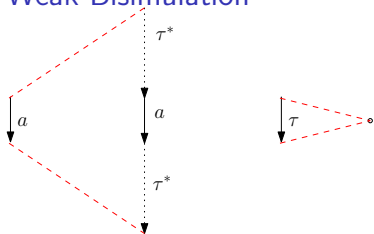
# Weak vs. Branching Bisimulation

## Weak Bisimulation

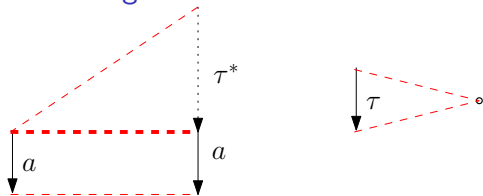


# Weak vs. Branching Bisimulation

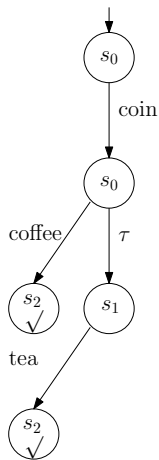
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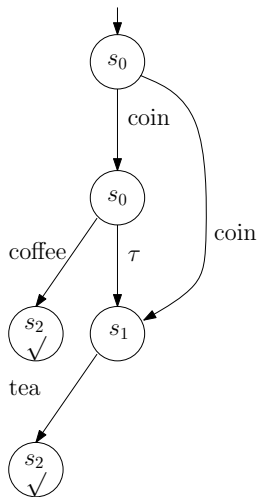
## Branching Bisimulation



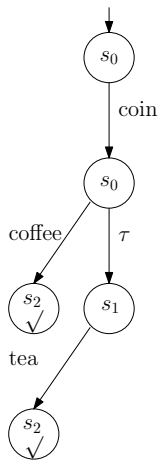
# Weak Vending Machines



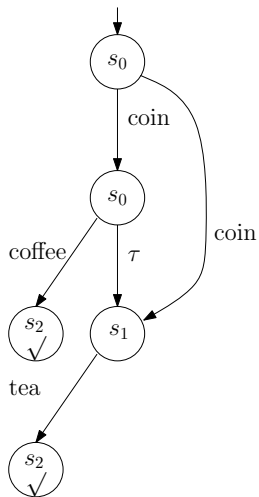
$\Leftrightarrow_w ?$



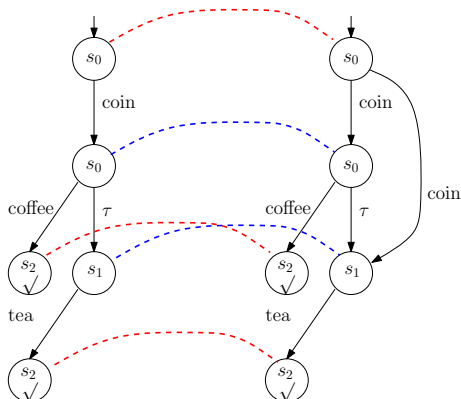
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$\Leftrightarrow_w$



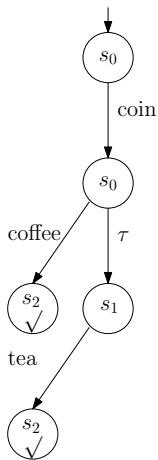
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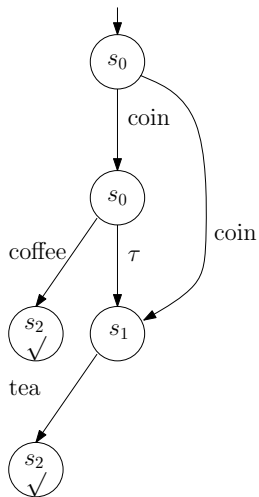
## Observation

Weak Bisimulation can be **too coarse**. It does not preserve the **branching structure**.

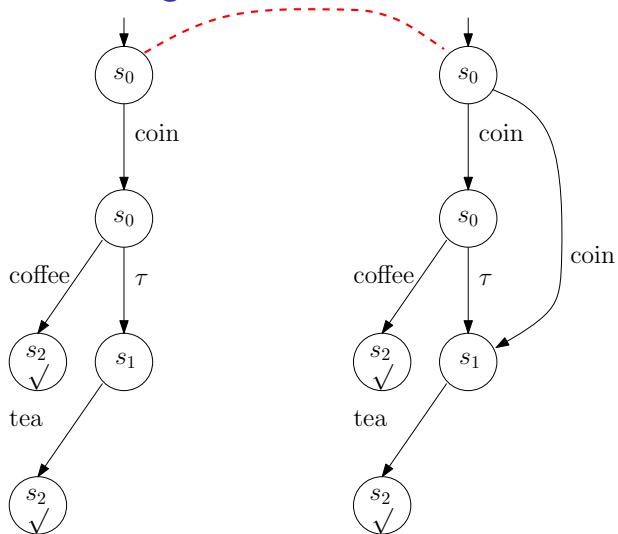
# Weak Vending Machines



$\Leftrightarrow_b ?$

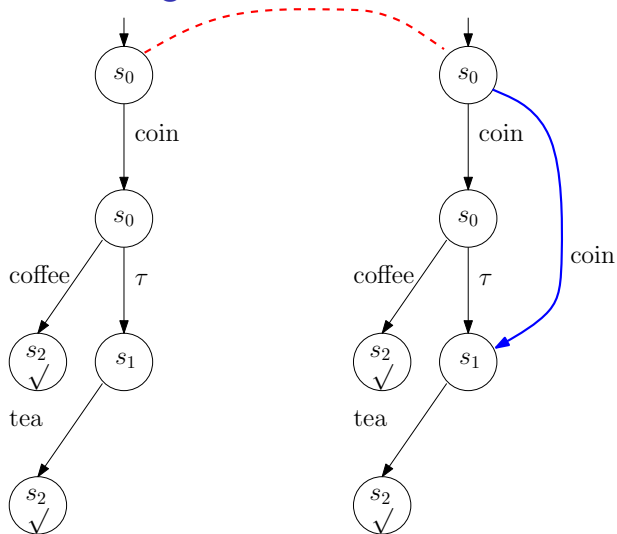


# Weak Vending Machines

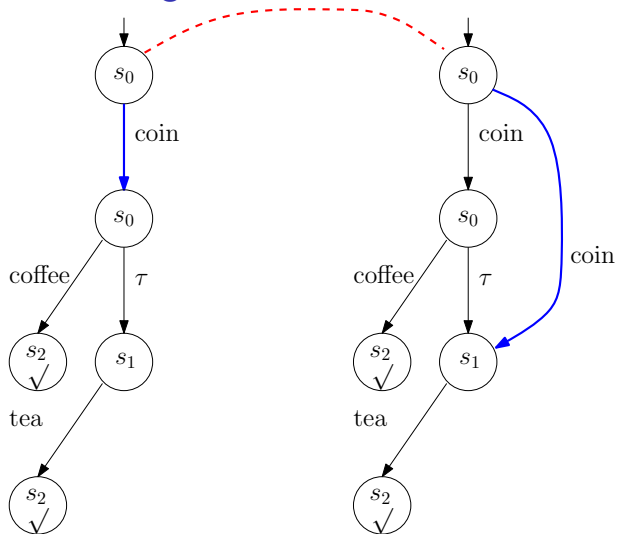




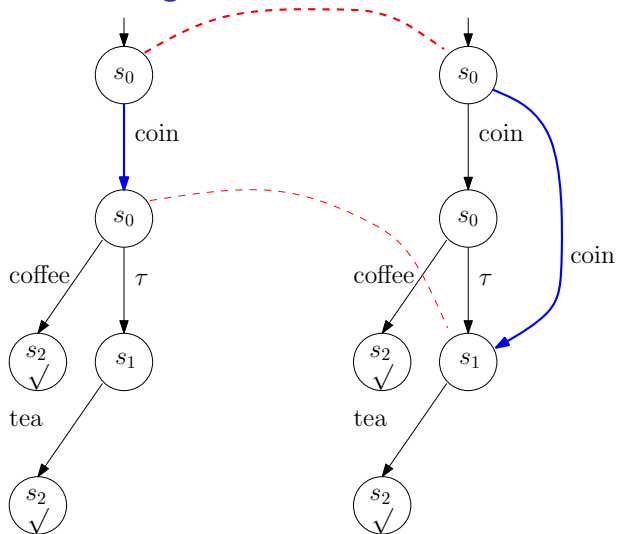
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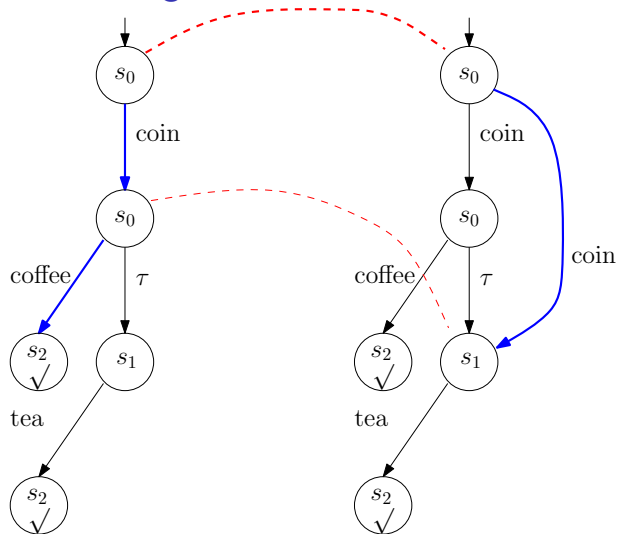
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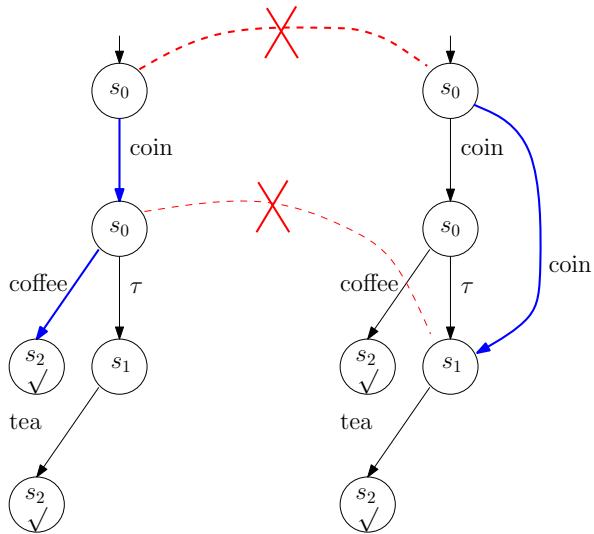
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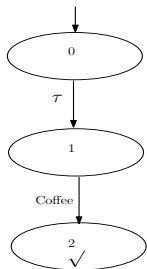
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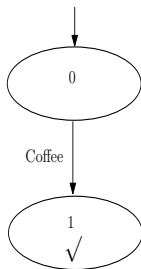
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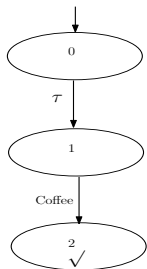
## Weak Bisimulations and Choice



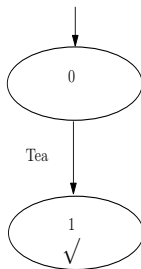
$\Leftrightarrow_{w,b}$



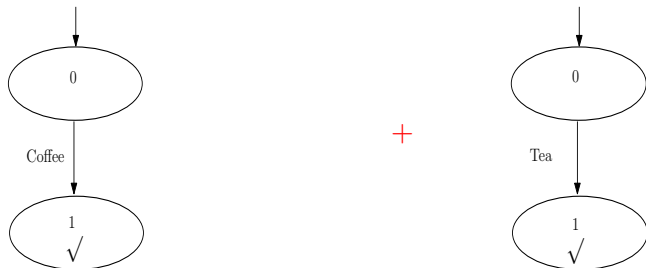
## Weak Bisimulations and Choice



+

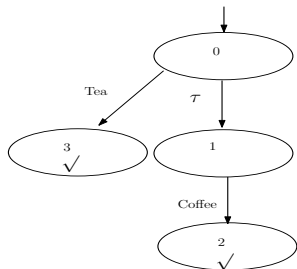


## Weak Bisimulations and Choice

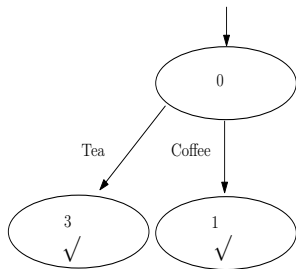




## Weak Bisimulations and Choice



$\neq$



# Weak Bisimulation Equivalence

## Conclusions

Weak bisimulation

1. does not preserve **branching structure** (solution: **branching bisimulation**);
2. **is not preserved** under **choice** (solution: **rootedness**).

# Root Condition

## Basic Idea

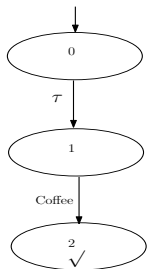
For a weak bisimulation to be a congruence with respect to choice, the **first  $\tau$ -transition** should be **mimicked** by a  **$\tau$  transition**.

## Formal Definition: Rootedness

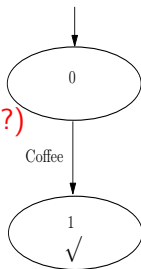
Two state  $s_0, s_1$  are **rooted** branching (weak) bisimilar if

- ▶ there exists a branching (weak) bisimulation relation  $R$  such that  $(s_0, s_1) \in R$  and
- ▶  $s_0$  and  $s_1$  are **only related to each other** (and not to any other state).

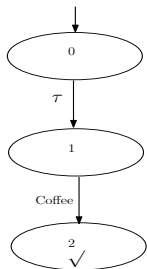
## Weak Bisimulations and Choice



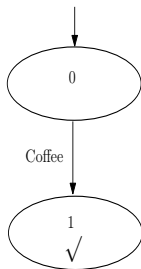
$\Leftrightarrow_{rw,rb} (?)$



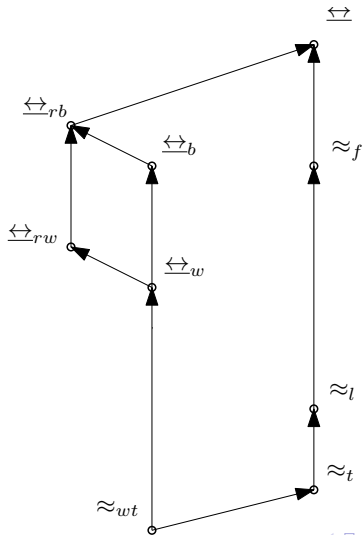
## Weak Bisimulations and Choice



$\neq$



# Van Glabbeek's Spectrum (The Treated Part)





# Remaining Exercises

- ▶ 2.4.6
- ▶ 2.4.7