

wb1224 - Thermodynamics 2

Lecture 12 – Exergy Analysis 1

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Content

Lecture 12 - overview

- Definition and evaluation of exergy
- Examples
 - Improving the use of energy in a chemical process
 - Geothermally driven cooling system
- Control volume exergy analysis: exergy balance

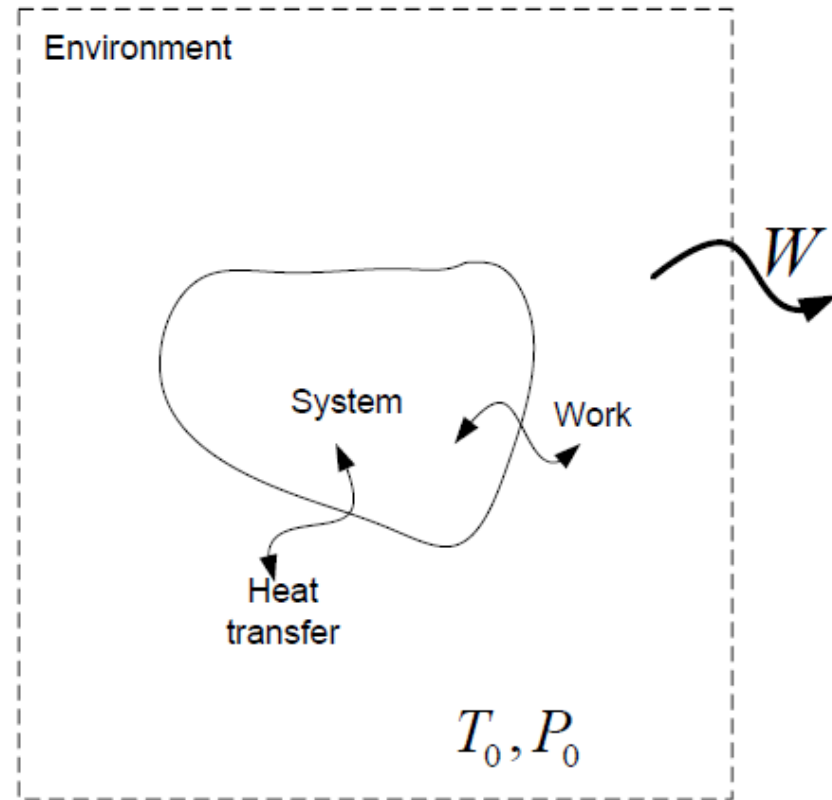
Definition of exergy

Generalizing from the previous example on the Available Energy

- **DEFINITION:** EXERGY is the maximum theoretical work that can be obtained from a system as it interacts with the environment and reaches equilibrium
- Environment: if the system is in equilibrium with it → NO work
- Environment in practical terms: at a certain distance from the system the environment is characterized by T_0 and P_0
- T_0 and P_0 do not change because of the system – env. interaction

Evaluation of exergy (1)

- From its definition: closed volume, system combined with surrounding, maximum work
- Volume is large enough: heat transfer between system and environment does not affect the latter
- System's volume can vary but not the total volume (sum)
- Interaction: initial state and final state



Evaluation of exergy (2)

- First law for combined system
- Energy of the system
- Variation of the energy of the total CV

Evaluation of exergy (3)

- Variation of the total energy of the environment
- Variation of the total energy of the system
(equilibrium in the final state → only internal energy)
- Variation of the total energy of the CV

Evaluation of exergy (4)

- Variation of internal energy of the environment ΔU_{env}
(from Gibbs equation $du = Tds - Pdv$)
- Variation of total energy for the control volume becomes
- Work for the control volume ($W_{\text{tot}} = - \Delta E_{\text{tot}}$)
- Change in volume of the environment

Evaluation of exergy (5)

- W_{tot} becomes
- Entropy balance for the control volume
- Entropy production
- Entropy change of the system
- Entropy change of the environment

Evaluation of exergy (6)

- Work is therefore
- Definition of exergy $\rightarrow \mathcal{P}_s = 0$
- Depends only on initial and final state
- Irreversibilities $T_0 \mathcal{P}_s$ depends on the process (path from initial to final)

Summary

$$\Delta E_{\text{TOT}} = \mathcal{Q}_{\text{TOT}} - W_{\text{TOT}}$$

$$E_{\text{SYS}} = U_{\text{SYS}} + E_{\text{SYS}}^{\text{KN}} + E_{\text{SYS}}^{\text{PT}}$$

convention (calculus): $\Delta E \equiv E_{\text{final}} - E_{\text{initial}}$

$$\Delta E_{\text{TOT}} = \Delta E_{\text{ENV}} + \Delta E_{\text{SYS}}$$

$$\Delta E_{\text{ENV}} = \Delta U_{\text{ENV}} \quad (\Delta E_{\text{ENV}}^{\text{KN}} = 0; \Delta E_{\text{ENV}}^{\text{PT}} = 0)$$

$$\Delta E_{\text{SYS}} = U_0 - E_{\text{SYS}}$$

$$\Delta E_{\text{TOT}} = \Delta U_{\text{ENV}} + (U_0 - E_{\text{SYS}})$$

$$\Delta U_{\text{ENV}} = T_0 \Delta S_{\text{ENV}} - P_0 \Delta V_{\text{ENV}}$$

$$\Delta E_{\text{TOT}} = (U_0 - E_{\text{SYS}}) + T_0 \Delta S_{\text{ENV}} - P_0 \Delta V_{\text{ENV}}$$

$$W_{\text{TOT}} = -\Delta E_{\text{TOT}} = (E_{\text{SYS}} - U_0) - (T_0 \Delta S_{\text{ENV}} - P_0 \Delta V_{\text{ENV}})$$

$$\Delta V_{\text{ENV}} = -(V_{\text{SYS}} - V_0)$$

$$W_{\text{TOT}} = (E_{\text{SYS}} - U_0) + P_0 (V_{\text{SYS}} - V_0) - T_0 \Delta S_{\text{ENV}}$$

$$\Delta S_{\text{TOT}} = \mathcal{P}_s$$

$$\mathcal{P}_s = \Delta S_{\text{SYS}} + \Delta S_{\text{ENV}}$$

$$\Delta S_{\text{SYS}} = (S_0 - S_{\text{SYS}})$$

$$\mathcal{P}_s = (S_0 - S_{\text{SYS}}) + \Delta S_{\text{ENV}}$$

$$\Delta S_{\text{ENV}} = \mathcal{P}_s - (S_0 - S_{\text{SYS}})$$

$$W_{\text{TOT}} = (E_{\text{SYS}} - U_0) + P_0 (V_{\text{SYS}} - V_0) - T_0 (S_{\text{SYS}} - S_0) - T_0 \mathcal{P}_s$$

$$\mathcal{E}_{\text{SYS}} = (E_{\text{SYS}} - U_0) + P_0 (V_{\text{SYS}} - V_0) - T_0 (S_{\text{SYS}} - S_0)$$

Forms of exergy

- Specific exergy function (not a function of state)

$$e = (e - u_0) + P_0 (v - v_0) - T_0 (s - s_0)$$

- Where

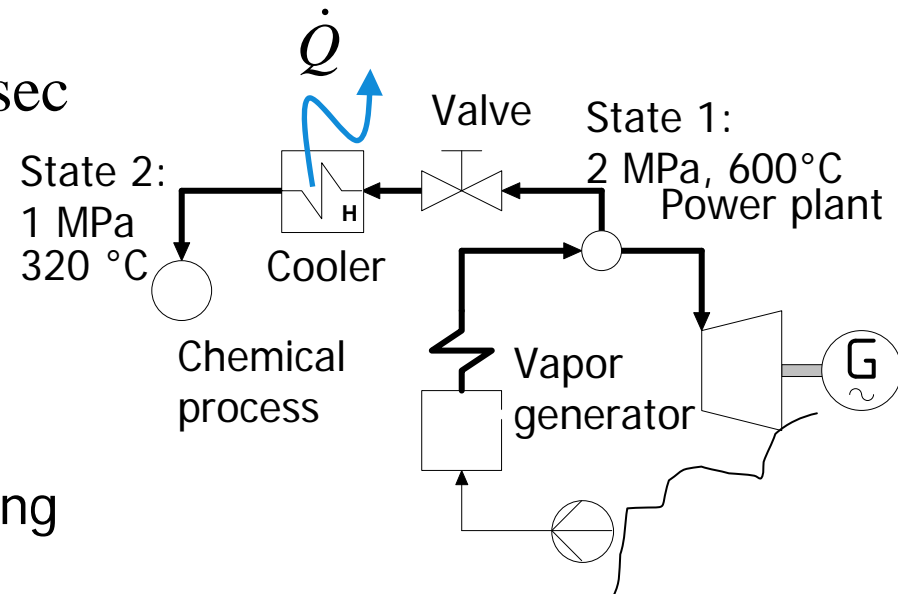
$$e = u + \frac{v^2}{2} + gz$$

- Physical exergy, potential exergy, kinetic exergy

$$e_{\text{SYS}}^{\text{PH}} = (u - u_0) + P_0 (v - v_0) - T_0 (s - s_0); \quad e_{\text{SYS}}^{\text{KN}} = \frac{v^2}{2}; \quad e_{\text{SYS}}^{\text{PT}} = gz$$

Example 1: improving the use of energy in a chemical process

- A chemical process needs 2 kg/sec steam at 1 MPa and 320 °C
- Nearby power plant: steam generator (2 MPa, 600 °C)
- First solution: spill the steam using a throttle valve and cool it down with a heat exchanger...not that smart!



$$T_0 = 20 \text{ °C} = 293.15 \text{ K}$$



How much power could be obtained?

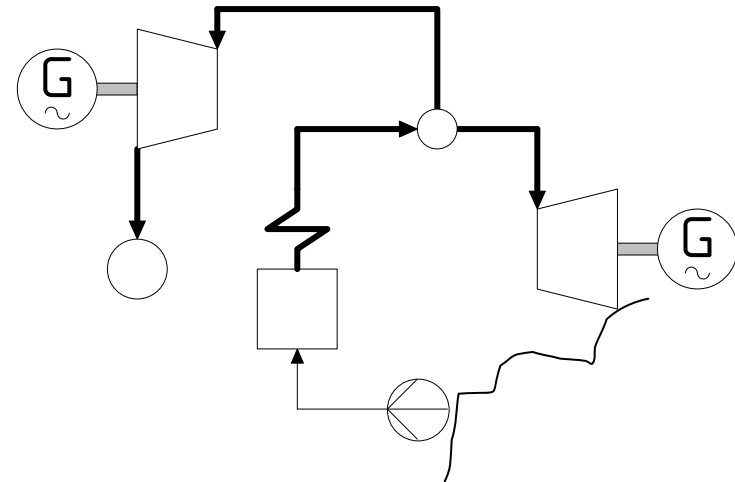
Enthalpy and entropy of state 1 and state 2:

Taking $T_0 = 20\text{ }^\circ\text{C} = 293.15\text{ K}$, exergy of state 1 and state 2:

Maximum power

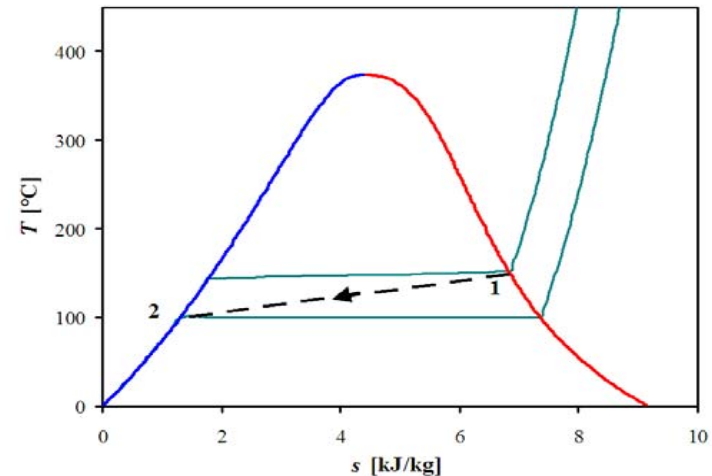
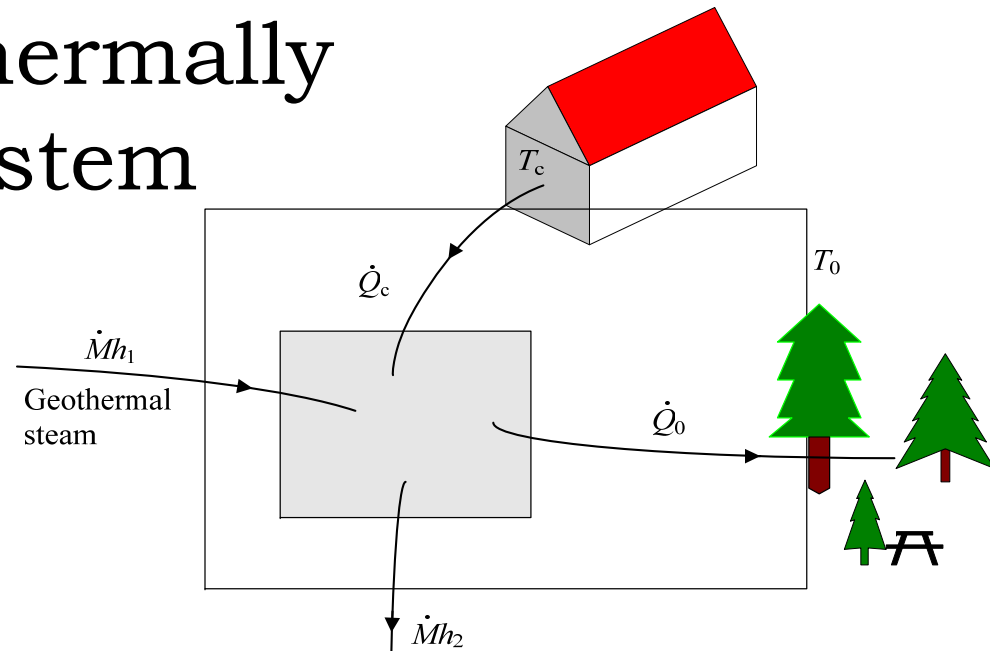
Better solution

- Turbine is 75% efficient
- At 0.1 €/kWh and utilization of 70%
- Value of electricity per year is 420 k€
- Decision: maintenance cost and security of supply



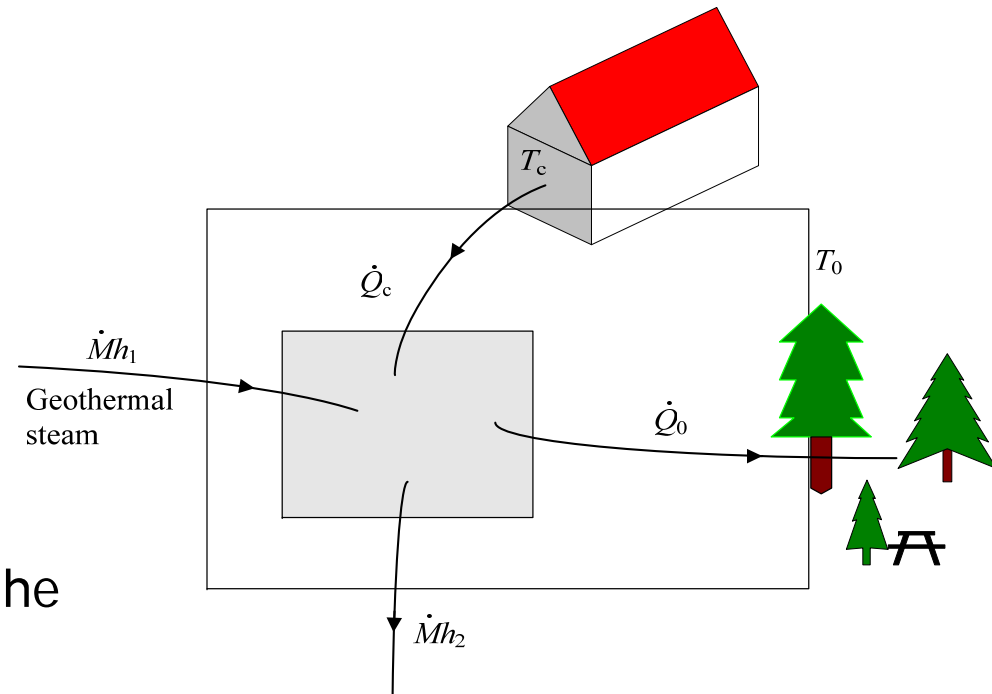
Example 2: geothermally driven cooling system

- Remote desert area: geothermal well makes 50 kg/h saturated steam at 150 °C.
- $T_{\text{env}} = 45 \text{ °C}$.
- Cooling for homes at 23 °C, steam from system is re-injected as condensate at 1 bar
- Maximum cooling rate?



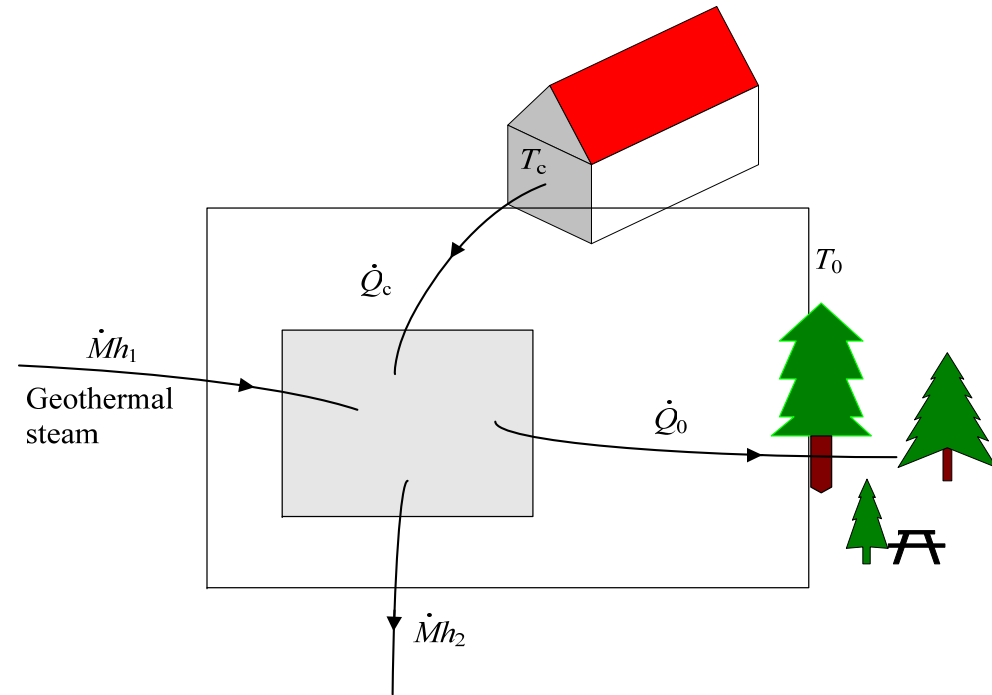
Problem setup

- Control volume definition
- Assumptions:
 - Steady flow, steady state
 - One-dimensional flow at the inlet and outlet
 - Neglect potential and kinetic energy changes of the flow



Exergy analysis

- Energy balance
- Entropy balance
- Cooling rate, maximum cooling rate



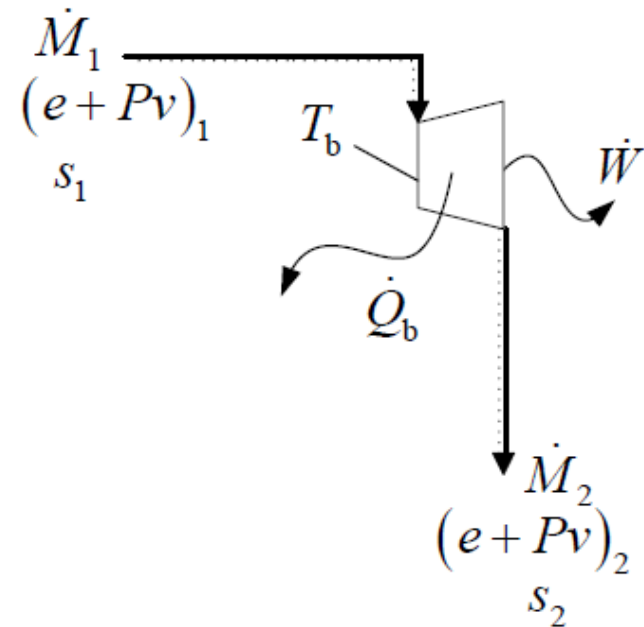
Calculation of the value

- State 1 ($h, s, e = h - T_0 s$):
- State 2:
- Maximum cooling rate
- Realistic cooling rate (50% of maximum)

Note: maximum performance does not depend on the process!

Control volume exergy analysis

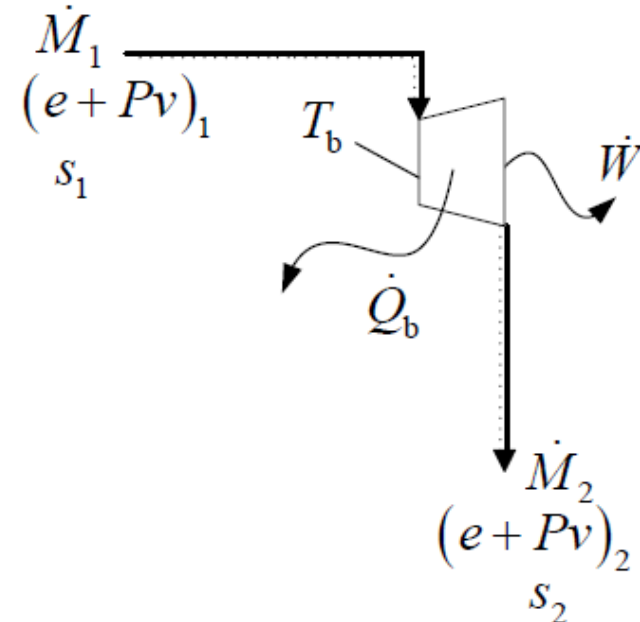
- General case (unsteady, time variant)
- CV exchanging mechanical power and transferring heat with the environment ($T_b > T_0$; $T_b = \text{const.}$)
- Apply first and second law of thermodynamics



Application of first and second law of thermodynamics to CV

$$\underbrace{\frac{dE_{CV}}{dt}}_{\text{rate of energy accumulation}} = \underbrace{(e + Pv)_1 \dot{M}_1}_{\text{rate of energy input}} - \underbrace{\left[(e + Pv)_2 \dot{M}_2 + \dot{W} + \dot{Q} \right]}_{\text{rate of energy output}}$$

$$\underbrace{\frac{dS_{CV}}{dt}}_{\text{rate of entropy accumulation}} = \underbrace{\dot{M}_1 s_1}_{\text{rate of entropy input}} - \underbrace{\left(\dot{M}_2 s_2 + \frac{\dot{Q}}{T_b} \right)}_{\text{rate of entropy output}} + \underbrace{\dot{\mathcal{P}}_s}_{\text{rate of entropy production}}$$



Subtract entropy balance multiplied by T_0 from the energy balance

$$\frac{dE_{CV}}{dt} - T_0 \frac{dS_{CV}}{dt} = (e + Pv)_1 \dot{M}_1 - \left[(e + Pv)_2 \dot{M}_2 + \dot{W} + \dot{Q} \right] - T_0 \left[\dot{M}_1 s_1 - \left(\dot{M}_2 s_2 + \frac{\dot{Q}}{T_b} \right) + \dot{\mathcal{P}}_s \right]$$

Rearrange terms and use exergy definition

Definition of exergy of a CV $\mathcal{E} \equiv (E - U_0) + P_0(V - V_0) - T_0S$

Differentiation wtr time $\frac{d\mathcal{E}}{dt} - P_0 \frac{dV}{dt} = \frac{dE}{dt} - T_0 \frac{dS}{dt}$

Therefore $\frac{dE}{dt} - T_0 \frac{dS}{dt} = \frac{d\mathcal{E}}{dt} - P_0 \frac{dV}{dt}$

$\frac{dV}{dt}$ only if the boundary moves in time (piston engine)

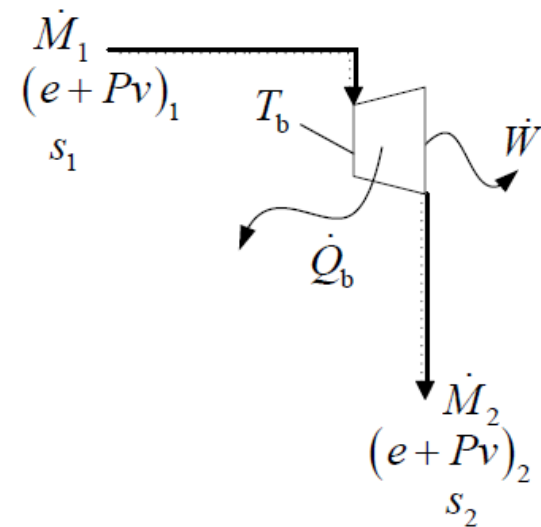
$$\frac{d\mathcal{E}_{CV}}{dt} = \dot{M}_1 \left[(e + Pv)_1 - T_0 s_1 \right] - \dot{M}_2 \left[(e + Pv)_2 - T_0 s_2 \right] - \left(1 - \frac{T_0}{T_b} \right) \dot{Q} - \left(\dot{W} - P_0 \frac{dV}{dT} \right) - T_0 \dot{\mathcal{P}}_s$$

Total specific energy: internal
+ kinetic + potential

Anticipation: specific flow exergy. It is the maximum potential of performing work by a fluid flow of 1 kg/s

$$e_f \equiv (h - h_0) + \frac{u^2}{2} + gz - T_0 (s - s_0)$$

Introducing the specific exergy flow



from

$$h \equiv u + Pv \quad ; \quad e = u + \frac{u^2}{2} + gz \quad ; \quad e_f \equiv (h - h_0) + \frac{u^2}{2} + gz - T_0 (s - s_0)$$

we have

$$(e + Pv) - T_0 s = e_f - (h_0 - T_0 s_0)$$

$$\frac{d\mathcal{E}_{CV}}{dt} = \dot{M}_1 \left[e_{f,1} - (h_0 - T_0 s_0) \right] - \dot{M}_2 \left[e_{f,2} - (h_0 - T_0 s_0) \right] - \left(1 - \frac{T_0}{T_b} \right) \dot{Q} - \left(\dot{W} - P_0 \frac{dV}{dT} \right) - T_0 \dot{\mathcal{P}}_s$$

Interpretation of exergy balance for CV

$$\frac{d\mathcal{E}_{CV}}{dt} = \dot{M}_1 \left[e_{f,1} - (h_0 - T_0 s_0) \right] - \dot{M}_2 \left[e_{f,2} - (h_0 - T_0 s_0) \right] - \left(1 - \frac{T_0}{T_b} \right) \dot{Q} - \left(\dot{W} - P_0 \frac{dV}{dT} \right) - T_0 \dot{\mathcal{P}}_s$$

Maximum amount of mech. power that could be extracted from \dot{Q}
 → Exergy transfer associated with heat transfer

Exergy transfer associated with work.
 (consider max work if no mass flows, no heat transfer and reversible process)

$\dot{\mathcal{E}}_d \equiv T_0 \dot{\mathcal{P}}_s$
 Rate of exergy destruction

Flow exergy $\dot{\mathcal{E}}_f \equiv \dot{M} e_f = \dot{M} \left[(h - h_0) + \frac{u^2}{2} + gz - T_0 (s - s_0) \right]$

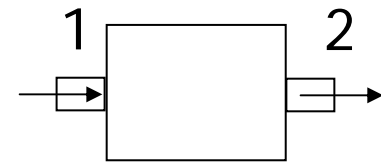
- Exergy per unit time associated with a mass flow of a simple compressible substance
- Interpretation: assume steady-state, no heat transfer. The maximum amount of work that the system can convert occurs for a reversible process, therefore

$$\dot{M}_1 = \dot{M}_2 = \dot{M}$$

$$\dot{\mathcal{P}}_s = 0$$

$$0 = \dot{\mathcal{E}}_{f,1} - \dot{\mathcal{E}}_{f,2} - \dot{W}_{\text{MAX}}$$

Max mech. power?



- Energy associated with mass transfer: $e + Pv$

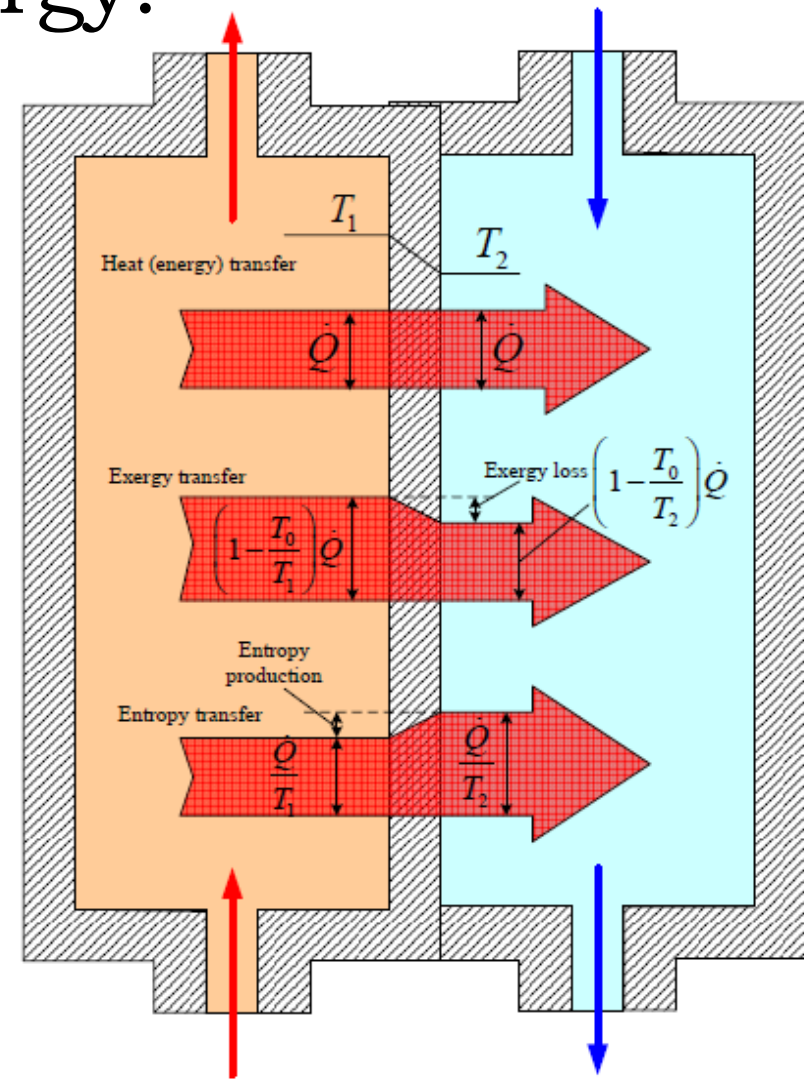
Specific flow exergy is exergy associated with mass transfer and flow work

Rate of exergy destruction

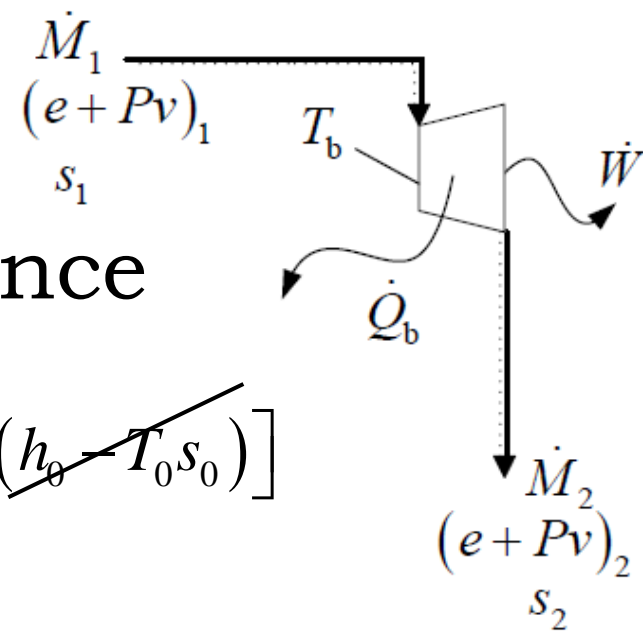
- Closely related to entropy production $\dot{\mathcal{E}}_d \equiv T_0 \dot{\mathcal{P}}_s$
- The exergy of a closed system always decreases (II law)
- Represents dissipation of mechanical power, due to the increase of disorder of molecules that always accompanies energy conversion
- Objective of energy systems design: minimize exergy destruction

Energy, entropy, exergy: example

- Steady-state, constant T at the interfaces
- Energy is transferred unaltered
- Because of the temperature difference, some exergy is lost (destroyed)
- Entropy is created



Steady-state exergy balance



$$\frac{d\mathcal{E}_{cv}}{dt} = \dot{M}_1 \left[e_{f,1} - (h_0 - T_0 s_0) \right] - \dot{M}_2 \left[e_{f,2} - (h_0 - T_0 s_0) \right] - \left(1 - \frac{T_0}{T_b} \right) \dot{Q} - \left(\dot{W} - P_0 \frac{dV}{dT} \right) - T_0 \dot{\mathcal{P}}_s$$

$$\dot{M}_1 = \dot{M}_2 = \dot{M}$$

$$\dot{M} (e_{f,1} - e_{f,2}) = \left(1 - \frac{T_0}{T_b} \right) \dot{Q} + \dot{W} + \dot{\mathcal{E}}_d$$

$$e_{f,2} - e_{f,1} = (h_2 - h_1) - T_0 (s_2 - s_1) + \left(\frac{u_2^2}{2} - \frac{u_1^2}{2} \right) + g (z_2 - z_1)$$