

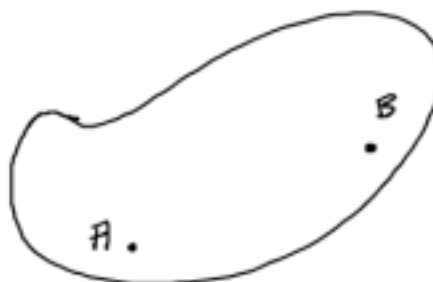
Deformation Gradient



undeformed

$$\underline{r}_A = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \underline{r}_B = \begin{pmatrix} x + dx \\ y + dy \\ z + dz \end{pmatrix}$$

$$\underline{e} = \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix}$$



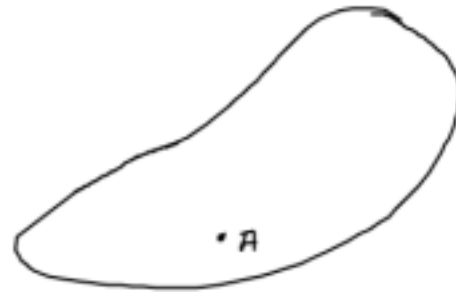
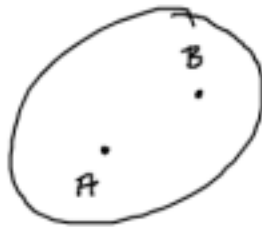
deformed

$$\underline{r}'_A = \begin{pmatrix} x + u_A \\ y + v_A \\ z + w_A \end{pmatrix} \quad \underline{r}'_B = \begin{pmatrix} x + dx + u_B \\ y + dy + v_B \\ z + dz + w_B \end{pmatrix}$$

$$\underline{e}' = \begin{pmatrix} dx + du \\ dy + dv \\ dz + dw \end{pmatrix}$$



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$$u(x, y, z)$$

$$v(x, y, z)$$

$$w(x, y, z)$$

$$du = u(x+dx, y+dy, z+dz) - u(x, y, z)$$

$$du = u_x dx + u_y dy + u_z dz$$

displacement gradient

$$\underline{\underline{H}} = \begin{bmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{bmatrix}$$

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$$\underline{e}' = \begin{pmatrix} dx + dv \\ dy + dv \\ dz + dv \end{pmatrix}$$

$$\underline{e} = \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix}$$

$$\underline{e}' = \underline{e} + \underline{H}\underline{e}$$

$$\begin{array}{c} \nearrow \text{deformed} \\ \underline{e}' = \underbrace{(\underline{I} + \underline{H})}_{\underline{F}} \underline{e} \\ \nearrow \text{undeformed} \end{array}$$

$$\ell^2 = \|\underline{e}\|^2 = \underline{e}^t \underline{e}$$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad (1 \ 2) \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 1^2 + 2^2 = 5$$

$$\|\underline{e}'\|^2 = \underline{e}'^t \underline{e}' = (\underline{F} \underline{e})^t (\underline{F} \underline{e})$$

$$\ell'^2 = \underline{e}^t (\underline{F}^t \underline{F}) \underline{e}$$

$$\underline{C} = \underline{F}^t \underline{F} \quad \text{Cauchy tensor}$$

$$r = \left(\frac{\underline{e}^t \underline{C} \underline{e}}{\underline{e}^t \underline{e}} \right)$$

$$(\underline{C} - \lambda \underline{I}) \underline{e} = \underline{0}$$

in principal strain directions

$$\underline{C} = \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_3 \end{bmatrix}$$

$$\underline{U} = \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_3 \end{bmatrix}$$

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stretch tensor $\underline{\underline{U}}$

$$\underline{\underline{U}}^2 = \underline{\underline{C}}$$

$$A = F U^{-1} \quad A^t A = U^{-1} F^t F U^{-1} = \underline{\underline{U}}^{-1} \underline{\underline{C}} \underline{\underline{U}}^{-1} = \underline{\underline{I}}$$

$$R = F U^{-1}$$

$$\underline{\underline{F}} = \underline{\underline{R}} \underline{\underline{U}}$$

rigid rotation

a stretch

Polar decomposition

$$\underline{\underline{I}} + \underline{\underline{H}} = \underline{\underline{R}} \underline{\underline{U}}$$

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$$\underline{U} = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & 0 \\ 0 & & \lambda_3 \end{bmatrix}$$

$$\underline{E} = \begin{bmatrix} \lambda-1 & & \\ & \lambda-1 & 0 \\ 0 & & \lambda-1 \end{bmatrix}$$

$$\textcircled{1} \quad \underline{E} = \underline{U} - \underline{I}$$

$$\underline{C} = \begin{bmatrix} \lambda^2 & & \\ & \lambda^2 & 0 \\ 0 & & \lambda^2 \end{bmatrix}$$

$$\underline{E}_g = \begin{bmatrix} \frac{(\lambda^2-1)}{2} & & \\ & \frac{\lambda^2-1}{2} & 0 \\ 0 & & \frac{\lambda^2-1}{2} \end{bmatrix}$$

$$\textcircled{2} \quad \underline{E}_g = \frac{1}{2} (\underline{C} - \underline{I})$$

$$\underline{C} = \underline{F}^t \underline{F}, \quad \underline{F} = \underline{I} + \underline{H}$$

$$\underline{E}_g = \frac{1}{2} (\underline{H} + \underline{H}^t) + \frac{1}{2} \underline{H}^t \underline{H}$$