Dynamics & Stability AE3-914

Gyrodynamics



 $T = \frac{1}{2} \left[I(\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) + I_s (\dot{\phi} \cos \theta + \dot{\psi})^2 \right]$

Steady precession



$$R(\theta, \dot{\theta}, C_{\phi}, C_{\psi}) = -\frac{1}{2}I\dot{\theta}^{2} + \frac{(C_{\phi} - C_{\psi}\cos\theta)^{2}}{2I\sin^{2}\theta} + \frac{C_{\psi}^{2}}{2I_{s}} + mgl\cos\theta$$
$$V_{eff}(\theta) = \frac{(C_{\phi} - C_{\psi}\cos\theta)^{2}}{2I\sin^{2}\theta} + \frac{C_{\psi}^{2}}{2I_{s}} + mgl\cos\theta$$
Eq. of motion:
$$\frac{d}{dt}\left(\frac{\partial R}{\partial \dot{\theta}}\right) - \frac{\partial R}{\partial \theta} = 0$$

There is an error in equation (4.38) and on top of page 223 of the textbook corresponding to this course.



Steady precession for $\theta = 90^{\circ}$? Steady precession for $\theta = 60^{\circ}$?

This slide corresponds to a sample problem that can be found in the assignments section of this course

Calculus of Variations



$$m\ddot{u} + \frac{3EI}{L^3}u = 0$$

 EI, L, ρ Ż

Equations of motion?



What is the shortest path between two points?

 $ds = \sqrt{1 + [y'(x)]^2} dx$ $s_{ab}(y) = \int \sqrt{1 + [y'(x)]^2} dx$ X_a = integral functional

Find
$$y(x)$$
 such that
$$\int_{x_a}^{x_b} \sqrt{1 + [y'(x)]^2} \, dx$$
 is minimal

= variational problem (*calculus of variations*)

What is the fastest path between two points?

$$dt = \frac{ds}{v}$$

$$v = \sqrt{2g \, y(x)}$$



$$t_{ab} = \int_{x_a}^{x_b} \frac{\sqrt{1 + [y'(x)]^2}}{\sqrt{2g \, y(x)}} \, dx$$

Find y(x) such that

$$t_{ab}(y) = \int_{x_a}^{x_b} \frac{\sqrt{1 + [y'(x)]^2}}{\sqrt{2g \ y(x)}} dx$$

is minimal

 $t_{ab} = t_{ab}(y)$ $s_{ab} = s_{ab}(y)$

This is what we call **functionals:** Real-valued expressions of functions defined within an interval



Calculus of variations

Find the function y(x) that minimizes a functional

$$I(y) = \int_{x_a}^{x_b} F(x, y, y') \, dx$$

For normal functions one has that if

 $f'(x^*) = 0$

then x* provides an extremum (maximum or minimum) to *f*



For functionals one needs to define what is understood as a variation



If y^* provides an extremal to a functional I_r

$$I(y^* + \varepsilon \eta) \ge I(y^*)$$

for any arbitrary perturbation η such that $\eta(x_a) = \eta(x_b) = 0$

$I = I(\varepsilon)$; if I is an extremal at γ^* then

$$\left. \frac{d}{d\varepsilon} I(y^* + \varepsilon \eta) \right|_{\varepsilon = 0} = 0$$

Fundamental lemma:

 $\int_{x_a}^{x_b} G(x)\eta(x)\,dx = 0 \quad \forall \eta \Big| \eta(x_a) = \eta(x_b) = 0$

implies that $G(x) \equiv 0 \quad \forall x \in [a, b]$

Euler-Lagrange equation

 $\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0$



Shape y(x) for minimal resistance?

(assume axial symmetry about *x*)









 $y = R\left(\frac{x}{l}\right)^{3/4}$

Variational operator

$$y(x) = y^*(x) + \varepsilon \eta(x)$$
$$= y^*(x) + \delta y^*(x)$$

$I(y + \delta y) = I(y) + \delta I$

Function y provides an extremal of I if

$\delta I = 0$

" δ " is comparable to a differential

$$\delta I = \int_{x_a}^{x_b} \delta F(x, y, y') dx$$

= $\int_{x_a}^{x_b} \left(\frac{\partial F}{\partial y} \delta y + \frac{\partial F}{\partial y'} \delta y' \right) dx$

$$= \int_{x_a}^{x_b} \left(\frac{\partial F}{\partial y} \delta y - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \delta y \right) \, dx + \left. \frac{\partial F}{\partial y'} \delta y \right|_{x_a}^{x_b}$$

Since δy represents any variation of yand $\delta y(x_a) = \delta y(x_b) = 0$ we end again with



Euler-Lagrange equation

$$\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) = 0$$

Natural boundary conditions

$$\delta I = \int_{x_a}^{x_b} \left[\frac{\partial F}{\partial y} - \frac{d}{dx} \left(\frac{\partial F}{\partial y'} \right) \right] \delta y \, dx + \left. \frac{\partial F}{\partial y'} \delta y \right|_{x_a}^{x_b}$$

where $y(x_a) = y_a$

but nothing is said about $y(x_b)$



$$\left. \frac{\partial F}{\partial y'} \right|_{x=x_b} = 0$$

is a natural boundary condition

